PROGRAM 01

1. Implement A* Search Algorithm

```
def aStarAlgo(start_node, stop_node):
  open_set = set(start_node)
  closed\_set = set()
  g = \{\}
                  #store distance from starting node
  parents = {}
                    # parents contains an adjacency map of all nodes
  #distance of starting node from itself is zero
  g[start\_node] = 0
  #start_node is root node i.e it has no parent nodes
  #so start_node is set to its own parent node
  parents[start_node] = start_node
  while len(open\_set) > 0:
     n = None
     #node with lowest f() is found
     for v in open_set:
       if n == None or g[v] + heuristic(v) < g[n] + heuristic(n):
          n = v
     if n == stop_node or Graph_nodes[n] == None:
       pass
     else:
       for (m, weight) in get_neighbors(n):
          #nodes 'm' not in first and last set are added to first
          #n is set its parent
          if m not in open_set and m not in closed_set:
            open_set.add(m)
            parents[m] = n
            g[m] = g[n] + weight
          #for each node m,compare its distance from start i.e g(m) to the
```

```
#from start through n node
       else:
          if g[m] > g[n] + weight:
            #update g(m)
            g[m] = g[n] + weight
            #change parent of m to n
            parents[m] = n
            #if m in closed set,remove and add to open
            if m in closed_set:
              closed_set.remove(m)
              open_set.add(m)
  if n == None:
     print('Path does not exist!')
     return None
  # if the current node is the stop_node
  # then we begin reconstructin the path from it to the start_node
  if n == stop_node:
     path = []
     while parents[n] != n:
       path.append(n)
       n = parents[n]
     path.append(start_node)
     path.reverse()
     print('Path found: { }'.format(path))
     return path
  # remove n from the open_list, and add it to closed_list
  # because all of his neighbors were inspected
  open_set.remove(n)
  closed_set.add(n)
print('Path does not exist!')
```

```
return None
#define fuction to return neighbor and its distance
#from the passed node
def get_neighbors(v):
  if v in Graph_nodes:
     return Graph_nodes[v]
  else:
     return None
#for simplicity we ll consider heuristic distances given
#and this function returns heuristic distance for all nodes
def heuristic(n):
  H_dist = {
     'A': 11,
     'B': 6,
     'C': 5,
     'D': 7,
     'E': 3,
     'F': 6,
     'G': 5,
     'H': 3,
     'I': 1,
     'J': 0
  return H_dist[n]
#Describe your graph here
Graph_nodes = {
  'A': [('B', 6), ('F', 3)],
  'B': [('A', 6), ('C', 3), ('D', 2)],
  'C': [('B', 3), ('D', 1), ('E', 5)],
  'D': [('B', 2), ('C', 1), ('E', 8)],
```

```
'E': [('C', 5), ('D', 8), ('I', 5), ('J', 5)],

'F': [('A', 3), ('G', 1), ('H', 7)],

'G': [('F', 1), ('I', 3)],

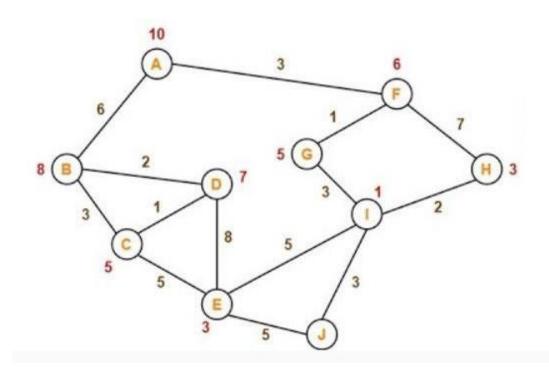
'H': [('F', 7), ('I', 2)],

'I': [('E', 5), ('G', 3), ('H', 2), ('J', 3)],
}

aStarAlgo('A', 'J')
```

Output:

```
Path found: ['A', 'F', 'G', 'I', 'J']
['A', 'F', 'G', 'I', 'J']
```



PROGRAM 02

2. Implement AO* Search Algorithm

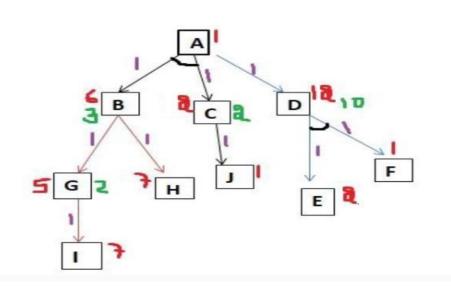
```
class Graph:
  def__init_(self, graph, heuristicNodeList, startNode): #instantiate graph object with
graph topology, heuristic values, start node
     self.graph = graph
     self.H=heuristicNodeList
     self.start=startNode
     self.parent={ }
     self.status={}
     self.solutionGraph={}
  def applyAOStar(self): # starts a recursive AO* algorithm
     self.aoStar(self.start, False)
  def getNeighbors(self, v): # gets the Neighbors of a given node
     return self.graph.get(v,")
  def getStatus(self,v): # return the status of a given node
     return self.status.get(v,0)
  def setStatus(self,v, val): # set the status of a given node
     self.status[v]=val
  def getHeuristicNodeValue(self, n):
     return self.H.get(n,0) # always return the heuristic value of a given node
  def setHeuristicNodeValue(self, n, value):
     self.H[n]=value # set the revised heuristic value of a given node
```

```
def printSolution(self):
    print("FOR GRAPH SOLUTION, TRAVERSE THE GRAPH FROM THE START
NODE:",self.start)
    print("_____")
    print(self.solutionGraph)
    print("_____")
  def computeMinimumCostChildNodes(self, v): # Computes the Minimum Cost of child
nodes of a given node v
    minimumCost=0
    costToChildNodeListDict={}
    costToChildNodeListDict[minimumCost]=[]
    flag=True
    for nodeInfoTupleList in self.getNeighbors(v): # iterate over all the set of child node/s
      cost=0
      nodeList=[]
      for c, weight in nodeInfoTupleList:
        cost=cost+self.getHeuristicNodeValue(c)+weight
        nodeList.append(c)
        if flag==True: # initialize Minimum Cost with the cost of first set of child node/s
           minimumCost=cost
        costToChildNodeListDict[minimumCost]=nodeList # set the Minimum Cost child
node/s
        flag=False
      else: # checking the Minimum Cost nodes with the current Minimum Cost
        if minimumCost>cost:
          minimumCost=cost
          costToChildNodeListDict[minimumCost]=nodeList # set the Minimum Cost
child node/s
    return minimumCost, costToChildNodeListDict[minimumCost] # return Minimum Cost
and Minimum Cost child node/s
```

```
def aoStar(self, v, backTracking): # AO* algorithm for a start node and backTracking
status flag
    print("HEURISTIC VALUES :", self.H)
    print("SOLUTION GRAPH:", self.solutionGraph)
    print("PROCESSING NODE :", v)
    print("_____")
    if self.getStatus(v) \geq= 0: # if status node v \geq= 0, compute Minimum Cost nodes of v
       minimumCost, childNodeList = self.computeMinimumCostChildNodes(v) \\
       print(minimumCost, childNodeList)
       self.setHeuristicNodeValue(v, minimumCost)
       self.setStatus(v,len(childNodeList))
       solved=True # check the Minimum Cost nodes of v are solved
       for childNode in childNodeList:
         self.parent[childNode]=v
         if self.getStatus(childNode)!=-1:
           solved=solved & False
       if solved==True: # if the Minimum Cost nodes of v are solved, set the current node
status as solved(-1)
         self.setStatus(v,-1)
         self.solutionGraph[v]=childNodeList # update the solution graph with the solved
nodes which may be a part of solution
       if v!=self.start: # check the current node is the start node for backtracking the current
node value
         self.aoStar(self.parent[v], True) # backtracking the current node value with
backtracking status set to true
       if backTracking==False: # check the current call is not for backtracking
         for childNode in childNodeList: # for each Minimum Cost child node
           self.setStatus(childNode,0) # set the status of child node to 0(needs exploration)
           self.aoStar(childNode, False) # Minimum Cost child node is further explored
with backtracking status as false
#for simplicity we ll consider heuristic distances given
```

```
print ("Graph - 1")
h1 = {'A': 1, 'B': 6, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G': 5, 'H': 7, 'I': 7, 'J': 1}
graph1 = {
 'A': [[('B', 1), ('C', 1)], [('D', 1)]],
 'B': [[('G', 1)], [('H', 1)]],
 'C': [[('J', 1)]],
 'D': [[('E', 1), ('F', 1)]],
 'G': [[('I', 1)]]
}
G1= Graph(graph1, h1, 'A')
G1.applyAOStar()
G1.printSolution()
Output:
Graph - 1
HEURISTIC VALUES : {'A': 1, 'B': 6, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G
': 5, 'H': 7, 'I': 7, 'J': 1}
SOLUTION GRAPH : {}
PROCESSING NODE : A
------
_____
7 ['D']
HEURISTIC VALUES : {'A': 7, 'B': 6, 'C': 2, 'D': 12, 'E': 2, 'F': 1, 'G
': 5, 'H': 7, 'I': 7, 'J': 1}
SOLUTION GRAPH : {}
PROCESSING NODE : D
3 ['E', 'F']
HEURISTIC VALUES: {'A': 7, 'B': 6, 'C': 2, 'D': 3, 'E': 2, 'F': 1, 'G'
: 5, 'H': 7, 'I': 7, 'J': 1}
SOLUTION GRAPH : {}
PROCESSING NODE : A
______
4 ['D']
HEURISTIC VALUES : {'A': 4, 'B': 6, 'C': 2, 'D': 3, 'E': 2, 'F': 1, 'G'
: 5, 'H': 7, 'I': 7, 'J': 1}
SOLUTION GRAPH : {}
PROCESSING NODE : E
_____
HEURISTIC VALUES : {'A': 4, 'B': 6, 'C': 2, 'D': 3, 'E': 0, 'F': 1, 'G'
: 5, 'H': 7, 'I': 7, 'J': 1}
```

```
SOLUTION GRAPH : {'E': []}
PROCESSING NODE : D
_____
1 ['E', 'F']
HEURISTIC VALUES : {'A': 4, 'B': 6, 'C': 2, 'D': 1, 'E': 0, 'F': 1, 'G'
: 5, 'H': 7, 'I': 7, 'J': 1}
SOLUTION GRAPH : {'E': []}
PROCESSING NODE : A
2 ['D']
HEURISTIC VALUES : {'A': 2, 'B': 6, 'C': 2, 'D': 1, 'E': 0, 'F': 1, 'G'
: 5, 'H': 7, 'I': 7, 'J': 1}
SOLUTION GRAPH : {'E': []}
PROCESSING NODE : F
HEURISTIC VALUES : {'A': 2, 'B': 6, 'C': 2, 'D': 1, 'E': 0, 'F': 0, 'G'
: 5, 'H': 7, 'I': 7, 'J': 1}
SOLUTION GRAPH : {'E': [], 'F': []}
PROCESSING NODE : D
1 ['E', 'F']
HEURISTIC VALUES: {'A': 2, 'B': 6, 'C': 2, 'D': 1, 'E': 0, 'F': 0, 'G'
: 5, 'H': 7, 'I': 7, 'J': 1}
SOLUTION GRAPH : {'E': [], 'F': [], 'D': ['E', 'F']}
PROCESSING NODE : A
2 ['D']
FOR GRAPH SOLUTION, TRAVERSE THE GRAPH FROM THE START NODE: A
{'E': [], 'F': [], 'D': ['E', 'F'], 'A': ['D']}
```



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```
In [22]:
          import numpy as np
          import pandas as pd
          # Loading Data from a CSV File
          data = pd.DataFrame(data = pd.read_csv("Training1.csv"))
          # Separating concept features from Target
          concepts = np.array(data.iloc[:,0:-1])
          target = np.array(data.iloc[:,-1])
          def learn(concepts, target):
              specific_h = concepts[0].copy()
              general_h = [["?" for i in range(len(specific_h))] for i in range(len(specific_h
          # The learning iterations
              for i, h in enumerate(concepts):
                   if target[i] == "Yes":
                       for x in range(len(specific_h)):
                           if h[x] != specific_h[x]:
                               specific_h[x] = '?'
                               general_h[x][x] = '?'
                   if target[i] == "No":
                       for x in range(len(specific_h)):
                           print(f"specific={specific h[x]}")
              # For negative hyposthesis change values only in G
                           if h[x] != specific_h[x]:
                               general_h[x][x] = specific_h[x]
                               #print(f"general{x}={general_h[x][x]}")
                           else:
                               general_h[x][x] = '?'
          # find indices where we have empty rows, meaning those that are unchanged
              indices = [i for i,val in enumerate(general_h) if val == ['?', '?', '?', '?', '?', '?', '?']
              for i in indices:
                   # remove those rows from general h
                   general_h.remove(['?', '?', '?', '?', '?'])
          # Return final values
              return specific_h, general_h
          s_final, g_final = learn(concepts, target)
          s_final
          g final
          specific=Sunny
          specific=Warm
          specific=?
          specific=Strong
          specific=Warm
          specific=Same
         [['Sunny', '?', '?', '?', '?'], ['?', 'Warm', '?', '?', '?', '?']]
Out[22]:
 In [ ]:
```

PROGRAM 04

4.Write a program to demonstrate the working of the decision tree based ID3 algorithm. Use an appropriate data set for building the decision tree and apply this knowledge to classify a new sample.

```
# import libraries
import numpy as np
import pandas as pd
#load dataset
from sklearn.datasets import load_breast_cancer
data = load_breast_cancer()
data.data
data.feature names
data.target
data.target_names
#create dataframe
df = pd.DataFrame(np.c_[data.data, data.target],
columns=[list(data.feature_names)+['target']])
df.head()
df.tail()
row1=df.iloc[3]
row1
df.shape
#Split Data
X = df.iloc[:, 0:-1]
y = df.iloc[:, -1]
from sklearn.model_selection import train_test_split
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=2)
print('Shape of X_train = ', X_train.shape)
print('Shape of y_train = ', y_train.shape)
print('Shape of X_test = ', X_test.shape)
```

```
print('Shape of y_test = ', y_test.shape)
#Train Decision Tree Classification Model
from sklearn.tree import DecisionTreeClassifier
classifier = DecisionTreeClassifier(criterion='gini')
classifier.fit(X_train, y_train)
classifier.score(X_test, y_test)
classifier_entropy = DecisionTreeClassifier(criterion='entropy')
classifier_entropy.fit(X_train, y_train)
classifier_entropy.score(X_test, y_test) #Feature Scaling
from sklearn.preprocessing import StandardScaler
sc = StandardScaler()
sc.fit(X_train)
X_train_sc = sc.transform(X_train)
X_{test_sc} = sc.transform(X_{test_sc})
classifier_sc = DecisionTreeClassifier(criterion='gini')
classifier_sc.fit(X_train_sc, y_train)
classifier_sc.score(X_test_sc, y_test)
#Predict Cancer
patient 1 = [17.99,
0.38,
122.8,
1001.0,
0.1184,
0.2776,
0.3001,
0.1471,
0.2419,
0.07871,
1.095,
0.9053,
```

```
8.589,
153.4,
0.006399,
0.04904,
0.05373,
0.01587,
0.03003,
0.006193,
25.38,
17.33,
184.6,
2019.0,
0.1622,
0.6656,
0.7119,
0.2654,
0.4601,
0.1189]
patient1 = np.array([patient1])
patient1
classifier.predict(patient1)
data.target_names
pred = classifier.predict(patient1)
if pred[0] == 0:
  print('Patient has Cancer (malignant tumor)')
else:
  print('Patient has no Cancer (malignant benign)')
```

Output:

```
Shape of X_train = (455, 30)
Shape of y_train = (455,)
Shape of X_test = (114, 30)
Shape of y_test = (114,)
Patient has Cancer (malignant tumor)
```

PROGRAM 04

4. Build an Artificial Neural Network by implementing the Backpropagation algorithm and test the same using appropriate data sets.

import numpy as np

```
X = \text{np.array}(([2, 9], [1, 5], [3, 6]), \text{dtype=float})
y = np.array(([92], [86], [89]), dtype=float)
X = X/np.amax(X,axis=0) #maximum of X array longitudinally
y = y/100
#Sigmoid Function
def sigmoid (x):
  return 1/(1 + np.exp(-x))
#Derivative of Sigmoid Function
def derivatives_sigmoid(x):
  return x * (1 - x)
#Variable initialization
epoch=5 #Setting training iterations
lr=0.1 #Setting learning rate
inputlayer_neurons = 2 #number of features in data set
hiddenlayer_neurons = 3 #number of hidden layers neurons
output_neurons = 1 #number of neurons at output layer
#weight and bias initialization
wh=np.random.uniform(size=(inputlayer_neurons,hiddenlayer_neurons))
bh=np.random.uniform(size=(1,hiddenlayer_neurons))
```

```
wout=np.random.uniform(size=(hiddenlayer_neurons,output_neurons))
bout=np.random.uniform(size=(1,output_neurons))
#draws a random range of numbers uniformly of dim x*y
for i in range(epoch):
  #Forward Propogation
  hinp1=np.dot(X,wh)
  hinp=hinp1 + bh
  hlayer_act = sigmoid(hinp)
  outinp1=np.dot(hlayer_act,wout)
  outinp= outinp1+bout
  output = sigmoid(outinp)
  #Backpropagation
  EO = y-output
  outgrad = derivatives_sigmoid(output)
  d_output = EO * outgrad
  EH = d\_output.dot(wout.T)
  hiddengrad = derivatives_sigmoid(hlayer_act)#how much hidden layer wts contributed to
  d_hiddenlayer = EH * hiddengrad
  wout += hlayer_act.T.dot(d_output) *lr # dotproduct of nextlayererror and currentlayerop
  wh += X.T.dot(d_hiddenlayer) *lr
  print ("------Epoch-", i+1, "Starts -----")
  print("Input: \n'' + str(X))
  print("Actual Output: \n" + str(y))
  print("Predicted Output: \n",output)
  print ("------Epoch-", i+1, "Ends -----\n")
print("Input: \n'' + str(X))
```

```
print("Actual Output: \n" + str(y))
print("Predicted Output: \n" ,output)
```

Output:

```
-----Epoch- 1 Starts-----
Input:
[[0.66666667 1.
[0.33333333 0.55555556]
           0.66666667]]
Actual Output:
[[0.92]
[0.86]
[0.89]]
Predicted Output:
[[0.87134038]
[0.85505899]
[0.86918134]]
-----Epoch- 1 Ends-----
-----Epoch- 2 Starts-----
Input:
[[0.66666667 1.
[0.33333333 0.55555556]
           0.66666667]]
Actual Output:
[[0.92]
 [0.86]
[0.89]]
Predicted Output:
[[0.87152832]
[0.85524601]
[0.86936978]]
-----Epoch- 2 Ends-----
-----Epoch- 3 Starts-----
Input:
[[0.66666667 1.
[0.33333333 0.55555556]
           0.66666667]]
[1.
Actual Output:
[[0.92]
 [0.86]
[0.89]]
Predicted Output:
[[0.8717144]
[0.85543121]
[0.86955637]]
-----Epoch- 3 Ends-----
-----Epoch- 4 Starts-----
Input:
[[0.66666667 1.
 [0.33333333 0.55555556]
```

```
[1.
          0.66666667]]
Actual Output:
[[0.92]
[0.86]
[0.89]]
Predicted Output:
[[0.87189864]
[0.8556146]
[0.86974111]]
-----Epoch- 4 Ends-----
-----Epoch- 5 Starts-----
Input:
[[0.66666667 1. ]
[0.33333333 0.55555556]
[1.
          0.66666667]]
Actual Output:
[[0.92]
[0.86]
[0.89]]
Predicted Output:
[[0.87208107]
[0.85579622]
[0.86992403]]
-----Epoch- 5 Ends-----
Input:
[[0.66666667 1.
[0.33333333 0.55555556]
[1.
           0.66666667]]
Actual Output:
[[0.92]
[0.86]
 [0.89]]
Predicted Output:
[[0.87208107]
 [0.85579622]
 [0.86992403]]
```

Training Examples:

Example	Sleep	Study	Expected % in Exams
1	2	9	92
2	1	5	86
3	3	6	89

Normalize the input

Example	Sleep	Study	Expected % in Exams
1	2/3 = 0.66666667	9/9 = 1	0.92
2	1/3 = 0.33333333	5/9 = 0.5555556	0.86
3	3/3 = 1	6/9 = 0.66666667	0.89

PROGRAM 06

6. Write a program to implement the naïve bayesian classifier for a sample training data set stored as a .CSV file. Compute the accuracy of the classifier, considering few test data sets.

```
# import necessary libarities
import pandas as pd
from sklearn import tree
from sklearn.preprocessing import LabelEncoder
from sklearn.naive_bayes import GaussianNB
# load data from CSV
data = pd.read_csv('tennisdata.csv')
print("THe first 5 values of data is :\n",data.head())
# obtain Train data and Train output
X = data.iloc[:,:-1]
print("\nThe First 5 values of train data is\n", X.head())
y = data.iloc[:,-1]
print("\nThe first 5 values of Train output is\n",y.head())
# Convert then in numbers
le_outlook = LabelEncoder()
X.Outlook = le_outlook.fit_transform(X.Outlook)
le_Temperature = LabelEncoder()
X.Temperature = le Temperature.fit transform(X.Temperature)
le_Humidity = LabelEncoder()
```

```
X.Humidity = le_Humidity.fit_transform(X.Humidity)
le_Windy = LabelEncoder()
X.Windy = le Windy.fit transform(X.Windy)
print("\nNow the Train data is :\n",X.head())
le_PlayTennis = LabelEncoder()
y = le_PlayTennis.fit_transform(y)
print("\nNow the Train output is\n",y)
from sklearn.model selection import train test split
X_train, X_test, y_train, y_test = train_test_split(X,y, test_size=0.20)
classifier = GaussianNB()
classifier.fit(X train,y train)
from sklearn.metrics import accuracy_score
print("Accuracy is:",accuracy_score(classifier.predict(X_test),y_test))
Output:
The first 5 values of data is:
      Outlook Temperature Humidity Windy PlayTennis
Osunny Hot High False No
Sunny Hot High True No
Overcast Hot High False Yes
Rainy Mild High False Yes
Rainy Cool Normal False Yes
The First 5 values of train data is
       Outlook Temperature Humidity Windy
0 Sunny Hot High False
1 Sunny Hot High True
2 Overcast Hot High False
3 Rainy Mild High False
4 Rainy Cool Normal False
```

```
The first 5 values of Train output is
   No
1
    No
2
   Yes
3 Yes
   Yes
Name: PlayTennis, dtype: object
Now the Train data is:
  Outlook Temperature Humidity Windy
0 2 1 0 0
1 2 1 0 1
2 0 1 0 0
               1
3
      1
                2
                        0
                              0
                       1
     1
                0
```

Now the Train output is [0 0 1 1 1 0 1 0 1 1 1 1 1 0]

Dataset:

3

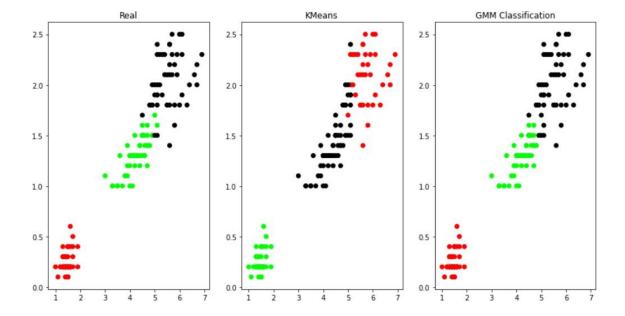
J					
1	Outlook	Temperature	Humidity	Windy	PlayTennis
2	Sunny	Hot	High	False	No
3	Sunny	Hot	High	True	No
4	Overcast	Hot	High	False	Yes
5	Rainy	Mild	High .	False	Yes
6	Rainy	Cool	Normal	False	Yes
7	Rainy	Cool	Normal	True	No
8	Overcast	Cool	Normal	True	Yes
9	Sunny	Mild	High	False	No
10	Sunny	Cool	Normal	False	Yes
11	Rainy	Mild	Normal	False	Yes
12	Sunny	Mild	Normal	True	Yes
13	Overcast	Mild	High	True	Yes
14	Overcast	Hot	Normal	False	Yes
15	Rainy	Mild	High	True	No

PROGRAM 08

8. Apply EM algorithm to cluster a set of data stored in a .CSV file. Use the same dataset for clustering using k-means algorithm. Compute the results of these two algorithms and comment on the quality of clustering. You can add Java/ Python ML library classes/API in the program.

```
from sklearn.cluster import KMeans
from sklearn.mixture import GaussianMixture
import sklearn.metrics as metrics
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
names = ['Sepal_Length', 'Sepal_Width', 'Petal_Length', 'Petal_Width', 'Class']
dataset = pd.read_csv("8-dataset.csv", names=names)
X = dataset.iloc[:, :-1]
label = {'Iris-setosa': 0,'Iris-versicolor': 1, 'Iris-virginica': 2}
y = [label[c] \text{ for c in dataset.iloc}[:, -1]]
plt.figure(figsize=(14,7))
colormap=np.array(['red','lime','black'])
# REAL PLOT
plt.subplot(1,3,1)
```

```
plt.title('Real')
plt.scatter(X.Petal_Length,X.Petal_Width,c=colormap[y])
# K-PLOT
model=KMeans(n_clusters=3, random_state=0).fit(X)
plt.subplot(1,3,2)
plt.title('KMeans')
plt.scatter(X.Petal_Length,X.Petal_Width,c=colormap[model.labels_])
print('The accuracy score of K-Mean: ',metrics.accuracy_score(y, model.labels_))
print('The Confusion matrix of K-Mean:\n',metrics.confusion_matrix(y, model.labels_))
# GMM PLOT
gmm=GaussianMixture(n_components=3, random_state=0).fit(X)
y_cluster_gmm=gmm.predict(X)
plt.subplot(1,3,3)
plt.title('GMM Classification')
plt.scatter(X.Petal_Length,X.Petal_Width,c=colormap[y_cluster_gmm])
print('The accuracy score of EM: ',metrics.accuracy_score(y, y_cluster_gmm))
print('The Confusion matrix of EM:\n',metrics.confusion_matrix(y, y_cluster_gmm))
Output:
The accuracy score of K-Mean: 0.09333333333333333
The Confusion matrixof K-Mean:
 [[ 0 50 0]
 [ 2 0 48]
 [36 0 14]]
The accuracy score of EM: 0.966666666666667
The Confusion matrix of EM:
  [[50 0 0]
 [ 0 45 5]
 [ 0 0 50]]
```



PROGRAM 08

8. Write a program to implement k- nearest neighbour algorithm to classify the iris data set. Print both correct and wrong predictions. Java/ Python ML library classes can be used for this problem.

import numpy as np
import pandas as pd
from sklearn.neighbors import KNeighborsClassifier
from sklearn.model_selection import train_test_split
from sklearn import metrics
names = ['sepal-length', 'sepal-width', 'petal-length', 'petal-width', 'Class']
Read dataset to pandas dataframe
dataset = pd.read_csv("9-dataset.csv", names=names)
X = dataset.iloc[:, :-1]
y = dataset.iloc[:, -1]
print(X.head())
Xtrain, Xtest, ytrain, ytest = train_test_split(X, y, test_size=0.10)
classifier = KNeighborsClassifier(n_neighbors=5).fit(Xtrain, ytrain)
<pre>ypred = classifier.predict(Xtest)</pre>
i = 0
print ("\n")
print ('%-25s %-25s %-25s' % ('Original Label', 'Predicted Label', 'Correct/Wrong'))

```
for label in ytest:
  print ('%-25s %-25s' % (label, ypred[i]), end="")
  if (label == ypred[i]):
    print (' %-25s' % ('Correct'))
  else:
    print (' %-25s' % ('Wrong'))
 i = i + 1
print ("_____")
print("\nConfusion Matrix:\n",metrics.confusion_matrix(ytest, ypred))
print ("_____")
print("\nClassification Report:\n",metrics.classification_report(ytest, ypred))
print ("_____")
print('Accuracy of the classifer is %0.2f' % metrics.accuracy_score(ytest,ypred))
Output:

    sepal-length
    sepal-width
    petal-length
    petal-width

    0
    5.1
    3.5
    1.4
    0.2

    1
    4.9
    3.0
    1.4
    0.2

                          3.2
                                         1.3
            4.7
                          3.1
                                         1.5
            4.6
                                                        0.2
            5.0
                          3.6
                                          1.4
                                                        0.2
Original Label Predicted Label Correct/Wrong
Iris-virginica
                         Iris-virginica
Iris-versicolor
                                                       Correct
Iris-versicolor
                                                       Correct
Iris-versicolor
                           Iris-versicolor
Iris-setosa
                           Iris-setosa
Iris-setosa
                           Iris-setosa
                                                        Correct
```

Iris-setosa	Iris-setosa	Correct	
Iris-virginica	Iris-virginica	Correct	
Iris-versicolor	Iris-versicolor	Correct	
Iris-setosa	Iris-setosa	Correct	
Iris-virginica	Iris-virginica	Correct	
Iris-setosa	Iris-setosa	Correct	
Iris-versicolor	Iris-versicolor	Correct	
Iris-setosa	Iris-setosa	Correct	
Iris-versicolor	Iris-versicolor	Correct	
Iris-virginica	Iris-virginica	Correct	

--

Confusion Matrix:

[[6 0 0] [0 5 0]

[0 0 4]]

--

Classification Report:

Iris-setosa 1.00 1.00 1.00	6
Iris-versicolor 1.00 1.00 1.00	5
Iris-virginica 1.00 1.00 1.00	4
accuracy 1.00	15
macro avg 1.00 1.00 1.00	15
weighted avg 1.00 1.00 1.00	15

.....

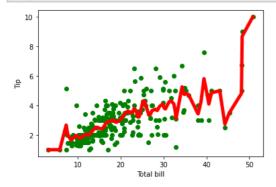
--

Accuracy of the classifer is 1.00

--

In [7]:

```
#9. Implement the non-parametric Locally Weighted Regression algorithm in
    #order to fit data points. Select appropriate data set for your experiment and draw graphs.
   import matplotlib.pyplot as plt
 4
    import pandas as pd
   import numpy as np
    def kernel(point, xmat, k):
 8
        m,n = np.shape(xmat)
 9
        weights = np.mat(np.eye((m)))
10
        for j in range(m):
11
            diff = point - X[j]
12
            weights[j,j] = np.exp(diff*diff.T/(-2.0*k**2))
13
        return weights
14
15
    def localWeight(point, xmat, ymat, k):
16
        wei = kernel(point,xmat,k)
        W = (X.T*(wei*X)).I*(X.T*(wei*ymat.T))
17
        return W
18
19
20
   def localWeightRegression(xmat, ymat, k):
       m,n = np.shape(xmat)
21
        ypred = np.zeros(m)
22
        for i in range(m):
23
24
           ypred[i] = xmat[i]*localWeight(xmat[i],xmat,ymat,k)
25
        return ypred
26
27
   # Load data points
   data = pd.read_csv('tips.csv')
28
   bill = np.array(data.total_bill)
29
30
   tip = np.array(data.tip)
31
    #preparing and add 1 in bill
32
   mbill = np.mat(bill)
33
34
   mtip = np.mat(tip)
35
36
   m= np.shape(mbill)[1]
37
   one = np.mat(np.ones(m))
38
   X = np.hstack((one.T,mbill.T))
39
40
41
    ypred = localWeightRegression(X,mtip,0.5)
42
    SortIndex = X[:,1].argsort(0)
43
    xsort = X[SortIndex][:,0]
44
45
   fig = plt.figure()
46
   ax = fig.add_subplot(1,1,1)
47
    ax.scatter(bill,tip, color='green')
   ax.plot(xsort[:,1],ypred[SortIndex], color = 'red', linewidth=5)
   plt.xlabel('Total bill')
plt.ylabel('Tip')
49
   plt.show();
```



```
In [ ]:

1
```