

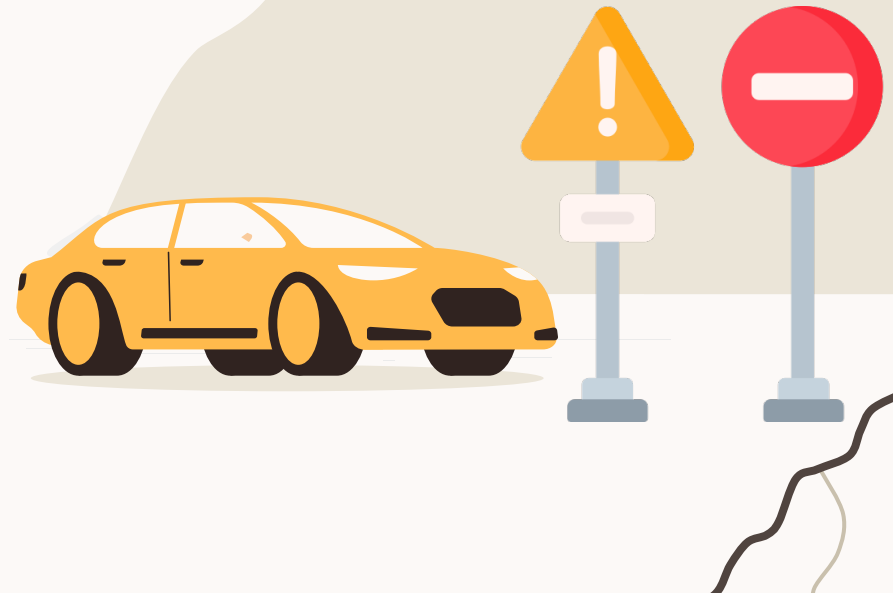
# Traffic Signs Recognition

By Mada Abudahish and Asrar Abdulrhman

# Introduction

In the world of **Artificial Intelligence** and advancement in technologies, many researchers and big companies are working on autonomous vehicles and self-driving cars.

So, for achieving accuracy in this technology, the vehicles should be able to interpret traffic signs and make decisions accordingly.





# Problem Statement

Given a various traffic signs along with images dataset , we are challenged to classify traffic signs present in the image into different categories.

# Dataset

Contains different traffic signs.  
classified into 43 different classes.

## size

50,000 images

## Source

From [Kaggle](#)



# Tools

Data manipulation and Preprocessing ML libraries:



Visualization libraries:



Deep learning:



# workflow

01

Data Loading

02

Preprocessing

03

Baseline Model

04

Build Deep Learning  
Model

05

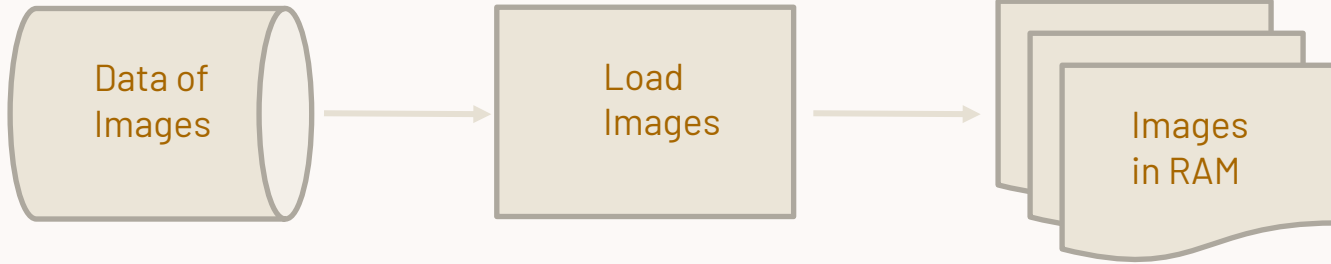
Applying Transfer  
Learning

06

Future work

01

# Data Loading



02



## Image Preprocessing

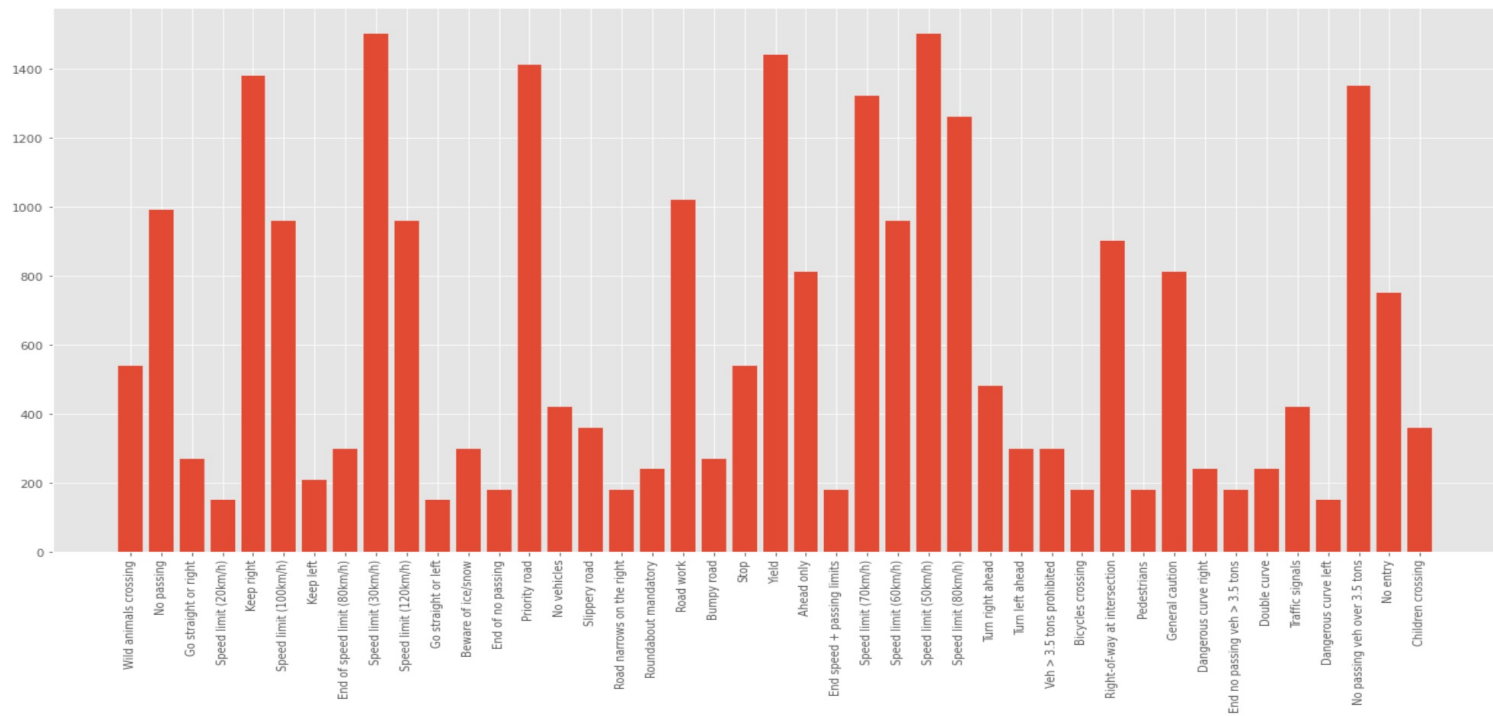
- Set height and width to be 32x32
- Normalization, Divide by 255

## Model Preprocessing

- Splitting the Data
- Sets the labels and check the distribution.
- Labels Encoded



# Class Imbalance Struggle



03

## Baseline Model

### Logistic Regression

- Reshape the image size to be in 2d array
- Scaling using Stander Scaler

Accuracy

91%

Val

92%

Test



The background features abstract, organic shapes in light beige and cream tones, with dark brown and light tan wavy lines flowing across the frame. Centered in the upper half is an orange rounded square with a thin dark border containing the number 04.

04

# Build Deep Learning Model

# Convolutional Neural Networks

## hyperparameter

### Hidden layer :

- Three Convolution Layers
- Two simple NN layers

**Kernel size:** 3

**Dropout:** 0.25

### Activation Function:

- Relu
- Softmax

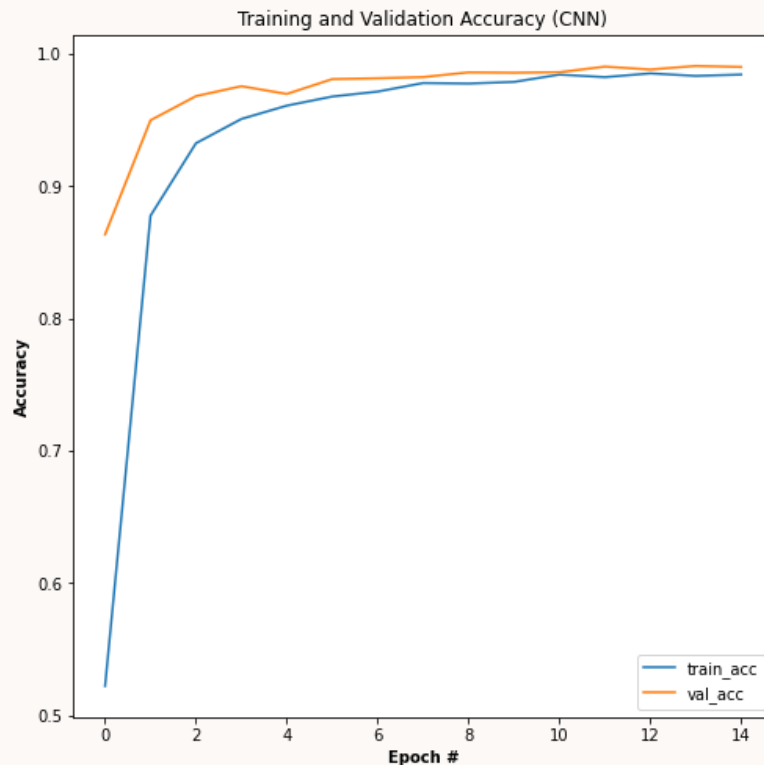
**Epochs:** 15

**Class Weight:**

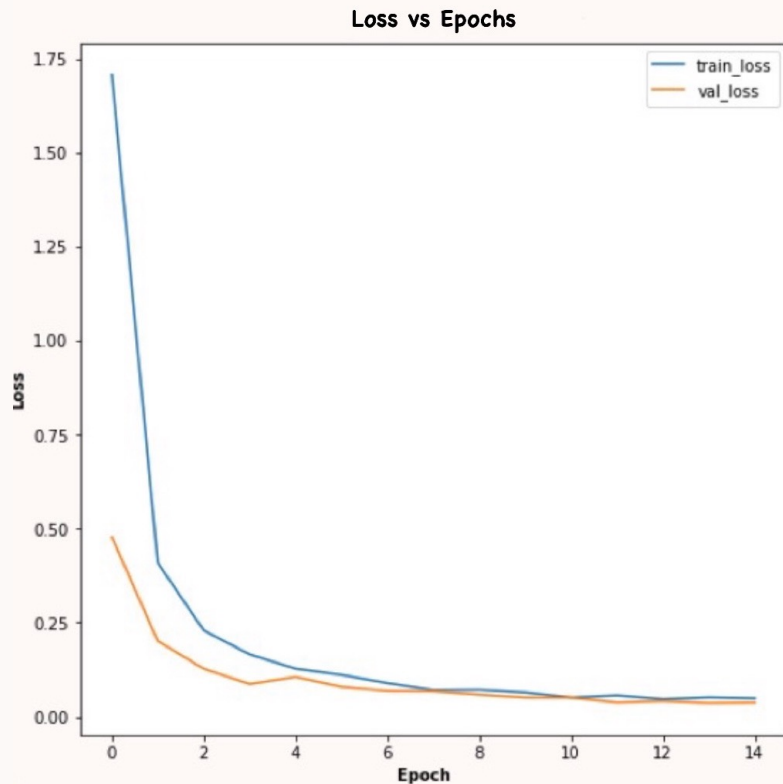
- Balanced

Val Accuracy: **0.9920**

Test Accuracy: **0.9843**



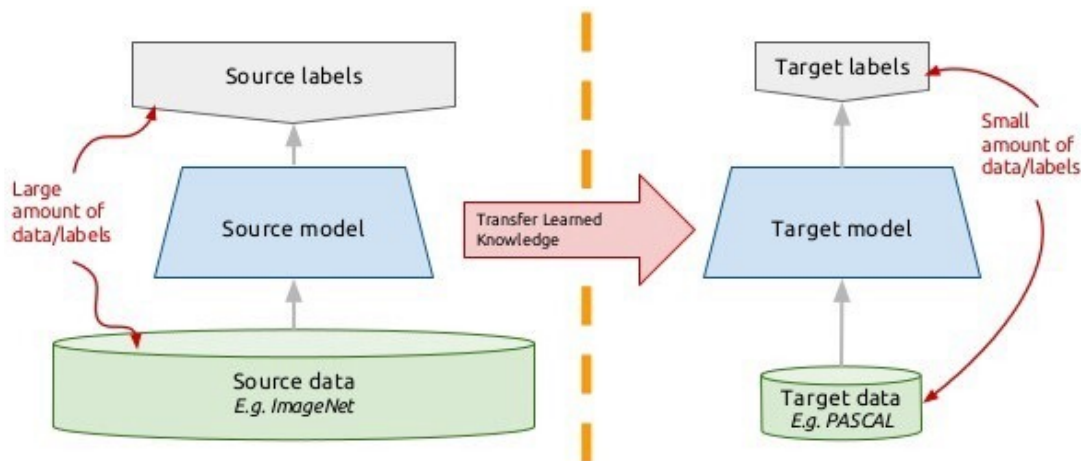
# Convolutional Neural Networks



**Loss:** Categorical Crossentropy  
**Optimizer:** Adam  
**Metrics:** Accuracy

# Applying Transfer Learning

## Transfer learning: idea



# Applying Transfer Learning

**VGG16:** (CNN )architecture which was used to win ILSVR(ImageNet) competition in 2014. It is considered to be one of the excellent vision model architecture till date.

val Accuracy:  
**0.99**

Test Accuracy:  
**0.99**

**MobileNets:** Efficient Convolutional Neural Networks for Mobile Vision Applications

val Accuracy:  
**0.91**

Test Accuracy:  
**0.96**



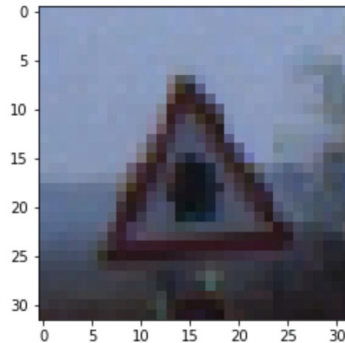
# Predicting with one Image from Test Dataset

```
In [83]: image_index = 11
```

```
In [84]: plt.imshow(X_test[image_index])  
n = np.array(X_test[image_index])  
print(n.size)  
p = n.reshape(1, 32, 32, 3)  
pred = classes[model.predict(p).argmax()]  
print("The predicted image is {}".format(pred))
```

3072

The predicted image is Right-of-way at intersection



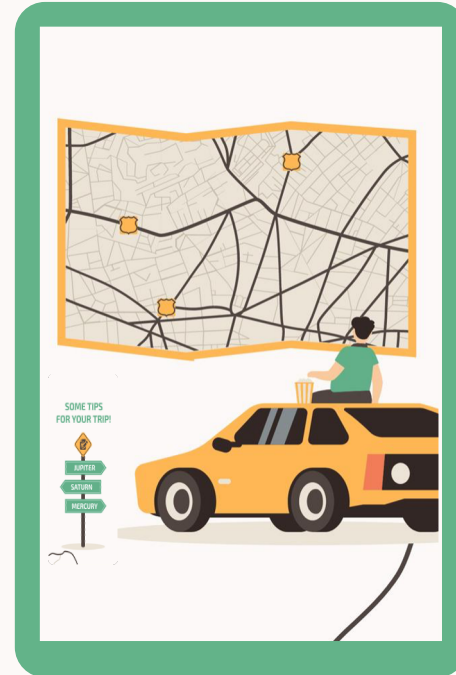
JUPITER

SATURN



## Future Work

- Increase the obtained result by using different DL approaches which are supported by extra feature extraction methods.
- Autonomous car system to Recognize Traffic Signs.



Thank you..

