



```
int led = 8;
```

```
int trig = 2;
```

```
int echo = 5;
```

```
int buzzer = 4;
```

```
void setup()
```

```
{
```

```
  Serial.begin(9000);
```

```
  pinMode(led,OUTPUT);
```

```
  pinMode(trig,OUTPUT);
```

```
  pinMode(echo,INPUT);
```

```
  pinMode(buzzer,OUTPUT);
```

```
}
```

```

void loop()
{
    double a = analogRead(A2);
    double v = a / 1024;
    double tvolt = v * 5;
    double o = tvolt - 0.5;
    double t = 0 * 100;
    Serial.print("Temperature in degree");
    Serial.println(t);
    if(t >= 50)
    {
        digitalWrite(led,HIGH);
    }
    else
    {
        digitalWrite(led,LOW);
    }
    digitalWrite(trig,LOW);
    digitalWrite(trig,HIGH);
    delayMicroseconds(10);
    digitalWrite(trig,LOW);
    float dur = pulseIn(echo,HIGH);
    float dist = (dur * 0.343)/2;
    Serial.print("Distance");
    Serial.println(dist);
    if(dist >= 17)
    {
        digitalWrite(buzzer,HIGH);
    }
    else

```

```
{  
    digitalWrite(buzzer,LOW);  
}  
}
```