

MATH 185: Homework 2

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1.

Definition 1. A set $S \subset \mathbb{C}$ is bounded if and only if there exists $z \in \mathbb{C}$ such that for every $s \in S$, $|s| \leq |z|$

Definition 2. Alternatively, a set $S \subset \mathbb{C}$ is bounded if and only if there is an r such that $S \subset B_r(0)$, where $B_s(z)$ is the ball of radius s with center z .

Theorem 1. If $(z_n)_{n=1}^{\infty}$ is a convergent sequence of complex numbers, then the sequence is bounded.

Proof. Take the value set $S = \{z_n\}$. Then suppose there were no r such that $S \subset B_r(0)$. If this is the case, the countability of S implies that for every n , $S \cap B_n(0)$ is finite. Since $z_n \rightarrow z$, take $N \in \mathbb{N}$ such that $N > |z|$. Such an n exists by the archimedean principle of \mathbb{R} . Then $S \cap B_N(0)$ must be finite.

Take $\epsilon = N - |z|$, then there is an M such that for all $m > M$, $d(z_n, z) < \epsilon$. That is there are infinite elements within ϵ of z , and thereby there are infinite elements in $S \cap B_N(0)$. This is a contradiction to its finiteness.

Therefore it must be that the value set is contained within the N ball, and therefore, (z_n) is bounded. \square

2. Exercise II.1.11

Theorem 2. The function $\text{Arg} : \mathbb{C} \rightarrow \mathbb{R}$ is continuous except for along the line $L = \{z : \text{Im}(z) = 0 \wedge \text{Re}(z) < 0\}$.

Proof. A function is continuous if and only if it preserves limits. Specifically, if $\lim_{h \rightarrow x} f(h) = f(x)$ implies that f is continuous at h . Consider the restricted Arg function, say $A : \mathbb{C} \setminus L \rightarrow \mathbb{R}$. Then it is clear that $\lim_{\mathbb{C} \setminus L} A(h) = (-\pi, \pi)$, since if a point is within an ϵ neighborhood of another point, its gradial distance is proportionate to \sin^{-1} of its ϵ distance, (a continuous function).

However consider any $z \in L$. Such that $h \rightarrow z$ approaches from the upper half plane and $g \rightarrow z$ from the lower. Clearly $\text{Arg}(h) \rightarrow \pi$ and $\text{Arg}(g) \rightarrow -\pi$, so no limit exists and the function is not continuous at z . This completes the proof. \square

3. Exercise II.1.16

Theorem 3. *The punctured plane $\mathbb{C} \setminus L = \mathbb{C}_P$ is star shaped but not convex.*

Proof. Take any $z \in \mathbb{C}_P$. Then for any $r \geq 1$, z/r is clearly in \mathbb{C}_P since r is always positive and the imaginary part of z is always non-zero or its real part is non-negative. In the first case z/r is never in L for all finite r , and when $r \rightarrow \infty$, then $r = 0 \in \mathbb{C}_P$. In the second case, its real part is always positive or 0 until it reaches 0 by the same logic. In the case that both are true, we consider again the same logic. If $z = 0$, we are done.

Clearly, \mathbb{C}_P is not convex when considering the line, $B = \{x + iy : x = -1\}$ which contains $-1 \in L$. \square

Definition 3. *A space X is contractible if the identity map is homotopic to some constant map.*

Definition 4. *A homotopy between two continuous functions f, g from a topological space X to a topological space Y is a continuous function $H : X \times [0, 1] \rightarrow Y$, such that if $x \in X$ then, $H(x, 0) = f(x)$, $H(x, 1) = g(x)$. [Wikipedia]*

Theorem 4. *Every homeomorphism is a homotopy equivalence.*

Theorem 5. *A star-shaped space X is homotopic to a point.*

Proof. Let $H(x, t) = x(1 - t) + z_0 t$, then $H(x, 0) = id_X$, and $H(x, 1)$ is the constant identity. H is continuous by the definition of H as a star shaped space. Therefore, the star-shaped space is homotopic to a point. \square

Theorem 6. *The space $\gamma = \mathbb{C} \setminus [-1, 1]$ is not star shaped.*

Proof. The set γ is not homeomorphic to the open unit ball B^2 since it is homeomorphic to the open annulus. Therefore, γ is not homotopic to B^2 which is homotopic to a point since B^2 is star shaped. The space γ could not be star shaped since if it were it would be homotopic to a point which it is not. Therefore, γ is not star shaped. \square

Theorem 7. *The punctured disk is not star shaped.*

Proof. The punctured disk is not homeomorphic to B^2 for the same reason as the previous proof. Therefore it is not homotopic, and by the logic of the above proof, it is not homotopic to a point, and so it could not possibly be star shaped as that would lead to a contradiction. This completes the proof. \square

4.

Theorem 8. *The functions $x = \operatorname{Re} z$ and $y = \operatorname{Im} z$ are not complex differentiable at any point.*

Proof. Suppose those functions were differentiable. Then it follows that there partials as functions of \mathbb{R}^2 should be

$$Dx(p) = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, Dy(p) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}. \quad (1)$$

This is a contradiction to the Cauchy-Rieman equations. \square

5. We take the derivative as follows

$$f' = a2z + b\bar{z} + bz(\bar{z})' + 2c\bar{z}(\bar{z})'. \quad (2)$$

This only makes sense where the terms containing \bar{z}' are not a part of the equation, since the complex conjugate is not complex differentiable. This occurs when $\bar{z}'(bz + 2c\bar{z}) = 0$. So it must be that $bx + 2cx = 0, by - 2cy = 0$ which implies that the differentiability of f does not depend on z but on b, c .

Setting up a linear system, we get

$$Aa = 0 = \begin{bmatrix} 1 & 2 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \implies \begin{bmatrix} a \\ b \end{bmatrix} \in \text{Nul}(A). \quad (3)$$

And f is analytic every where in this case!

6. Exercise II.2.5

Theorem 9. Suppose that $f : \mathbb{C} \rightarrow \mathbb{C}$ is analytic on D . Then let $g = \bar{f}$ is analytic on $D^* = \{\bar{z} : z \in D\}$. It follows that, $g'(w) = f'(\bar{w})$.

Proof. Take $w \in D^*$, so that there exists a $z \in D$ so that $\bar{z} = w, \bar{w} = z$. Consider the standard limit definition of the derivative.

$$\begin{aligned} \lim_{\Delta w \rightarrow w} \frac{g(w + \Delta w) - g(w)}{\Delta w} &= \lim_{\Delta w \rightarrow w} \frac{\overline{f(w + \Delta w)} - \overline{f(w)}}{\Delta w} \\ &= \lim_{\Delta z \rightarrow z} \frac{\overline{f(z + \Delta z)} - \overline{f(z)}}{\Delta z} \\ &= \lim_{\Delta z \rightarrow z} \frac{\overline{f(z + \Delta z) - f(z)}}{\Delta z} \\ &= \lim_{\Delta z \rightarrow z} \frac{\overline{f(z + \Delta z) - f(z)}}{\Delta z} \\ &= \overline{f'(z)} = \overline{f'(\bar{w})}, \end{aligned} \quad (4)$$

which is the statement of the theorem. \square

7. Validation:

$$Df(p) = \begin{bmatrix} \cos x \sinh y & \sin x \cosh y \\ -\sin x \cosh y & \cos x \sinh y \end{bmatrix} \quad (5)$$

The complex function is $f = \sin x \sinh y, v = \cos x \cosh y$. It follows that, $f = ie^z + e^{-z}$; So I estimate this function is a rotated cosine.

8. Exercise II.3.3

Theorem 10. If f and \bar{f} are analytic on D , then f is constant.

Proof. If f and \bar{f} are analytic for all $z \in D \subset \mathbb{C}$,

$$Df(z) = \begin{bmatrix} u_x(z) & u_y(z) \\ -u_y(z) & u_x(z) \end{bmatrix}, D\bar{f}(z) = \begin{bmatrix} u_x(z) & -v_y(z) \\ u_y(z) & -v_x(z) \end{bmatrix} \quad (6)$$

So by the cauchy riemann equations we have that, \bar{f} and f analytic implies

$$-v_y = u_y, -v_y = u_x \quad (7)$$

$$v_x = u_y, v_y = u_x \quad (8)$$

So, $-v_y = v_y$ and $-v_x = v_x$ gives

$$Df(z) = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \quad (9)$$

Which from multivariable calculus, we know is true if and only if f is a constant map! \square

9. Exercise II.3.8

Theorem 11. *Let $f : \mathbb{C} \rightarrow \mathbb{C}$ be an analytic function. Then if $z = re^{i\vartheta}$ f satisfies*

$$u_r = \frac{1}{r}v_\vartheta, u_\vartheta = -rv_r. \quad (10)$$

Proof. By the chain rule of partial derivatives,

$$u_r = u_x x_r + u_y y_r = u_x \cos \vartheta + u_y \sin \vartheta \quad (11)$$

and identically by the Cauchy-Riemann equations,

$$\begin{aligned} v_\vartheta &= v_x x_\vartheta + v_y y_\vartheta = -v_x r \sin \vartheta + v_y r \cos \vartheta \\ &= r(-v_x \sin \vartheta + v_y \cos \vartheta) \\ &= r(u_x \cos \vartheta + u_y \sin \vartheta) \\ &= ru_r. \end{aligned} \quad (12)$$

So it follows that $u_r = \frac{1}{r}v_\vartheta$. Likewise,

$$u_\vartheta = r(u_x x_\vartheta + u_y y_\vartheta) = r(-u_x \sin \vartheta + u_y \cos \vartheta) \quad (13)$$

and identically by the Cauchy-Riemann equations,

$$v_r = v_x x_r + v_y y_r = v_x \cos \vartheta + v_y \sin \vartheta = -u_y \cos \vartheta + u_x \sin \vartheta \quad (14)$$

So it follows that $-rv_r = u_\vartheta$. This completes the proof. \square