



University of
Pittsburgh

Algorithms and Data Structures 1

CS 0445



Fall 2022

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(Slides are adapted from Dr. Ramirez's and Dr. Farnan's CS 0445 slides.)

Announcements

- Upcoming Deadlines:
 - Lab 8: next Monday 11/14 @ 11:59 pm
 - Homework 8: next Monday 11/14 @ 11:59 pm
 - Midterm reattempts: tonight @ 11:59 pm

Today ...

- Sorting Algorithms

Muddiest Points

- **Q: Request some guidance on Lab 8. Just like Lab 7 the provided PowerPoint and PDF provides very unclear (to no!) instruction.**
- **The PowerPoint, the PDF, and your recitation TA should give you a clear idea of how to finish the lab in a short amount of time**

Muddiest Points

- **Q: I was confused why you had to switch all your instances of Node to Node<T>**
- Since Node was a static class, it cannot use any non-static data and types, including the type parameter T of class SortingAlgorithms<T>
- So, we had to define another (static) type parameter for the static Node class
 - The type parameter could also have been named S or any other name

Muddiest Points

- **Q: Why the keyword "static" was tripping up your code? I don't think I have a firm understanding on when static should/is required to be used.**
- I had to use static because I was calling the sorting methods from the static method main
- Alternatively, I could have called the methods from the class constructor, in which case static won't be needed
 - `SortingAlgorithms.java` now uses that approach

Muddiest Points

- **Q: Can you post the code you did today in class? My code doesn't compile and for some reason it isn't working.**
- The code is always accessible from the [Draft Slides and Code Handouts](#) link on Canvas

Sorting Algorithms

- $O(n^2)$
 - Selection Sort
 - Insertion Sort
 - Shell Sort
- $O(n \log n)$
 - Merge Sort
 - Quick Sort
- $O(n)$ Sorting
 - Radix Sort

Sorting Algorithms

- For each algorithm
 - understand the main concept using an example
 - implement the algorithm
 - on an Array
 - iterative
 - recursive
 - on a linked list
 - iterative
 - recursive

Recursive Insertion Sort

- This pseudocode describes a recursive insertion sort.

```
Algorithm insertionSort(a, first, last)  
// Sorts the array entries a[first] through a[last] recursively.  
  
if (the array contains more than one entry)  
{  
    Sort the array entries a[first] through a[last - 1]  
    Insert the last entry a[last] into its correct sorted position within the rest of the array  
}
```

Recursive Insertion Sort

- Implementing the algorithm in Java

```
public static <T extends Comparable<? super T>>
    void insertionSort(T[] a, int first, int last)
{
    if (first < last)
    {
        // Sort all but the last entry
        insertionSort(a, first, last - 1);

        // Insert the last entry in sorted order
        insertInOrder(a[last], a, first, last - 1);
    } // end if
} // end insertionSort
```

Recursive Insertion Sort

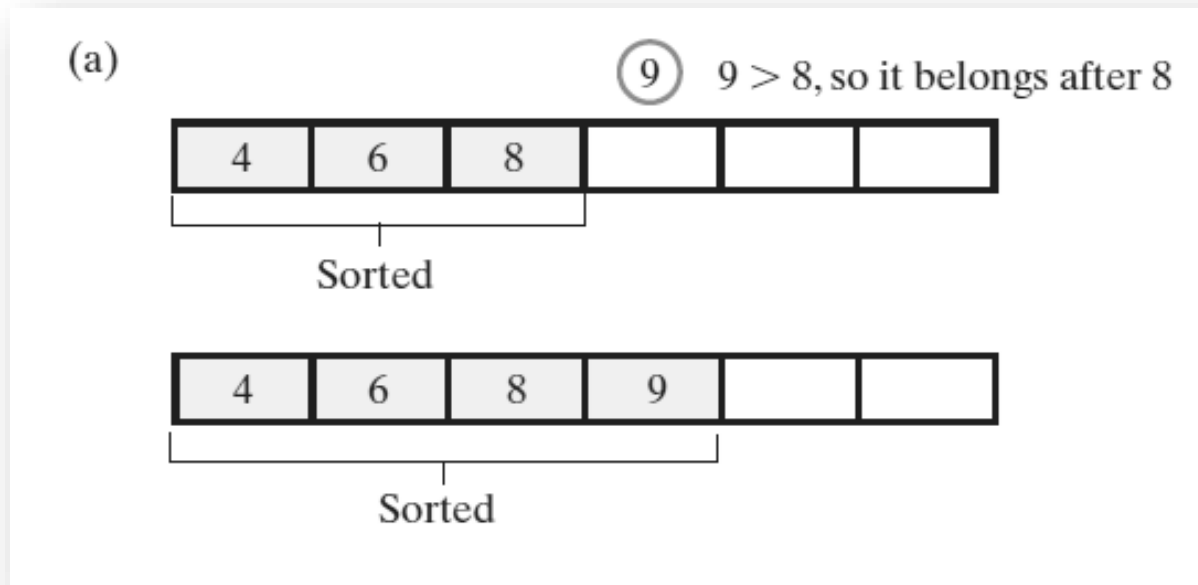
- First draft of `insertInOrder` algorithm.

```
Algorithm insertInOrder(anEntry, a, begin, end)
// Inserts anEntry into the sorted array entries a[begin] through a[end].
// First draft.

if (anEntry >= a[end])
    a[end + 1] = anEntry
else
{
    a[end + 1] = a[end]
    insertInOrder(anEntry, a, begin, end - 1)
}
```

Recursive Insertion Sort

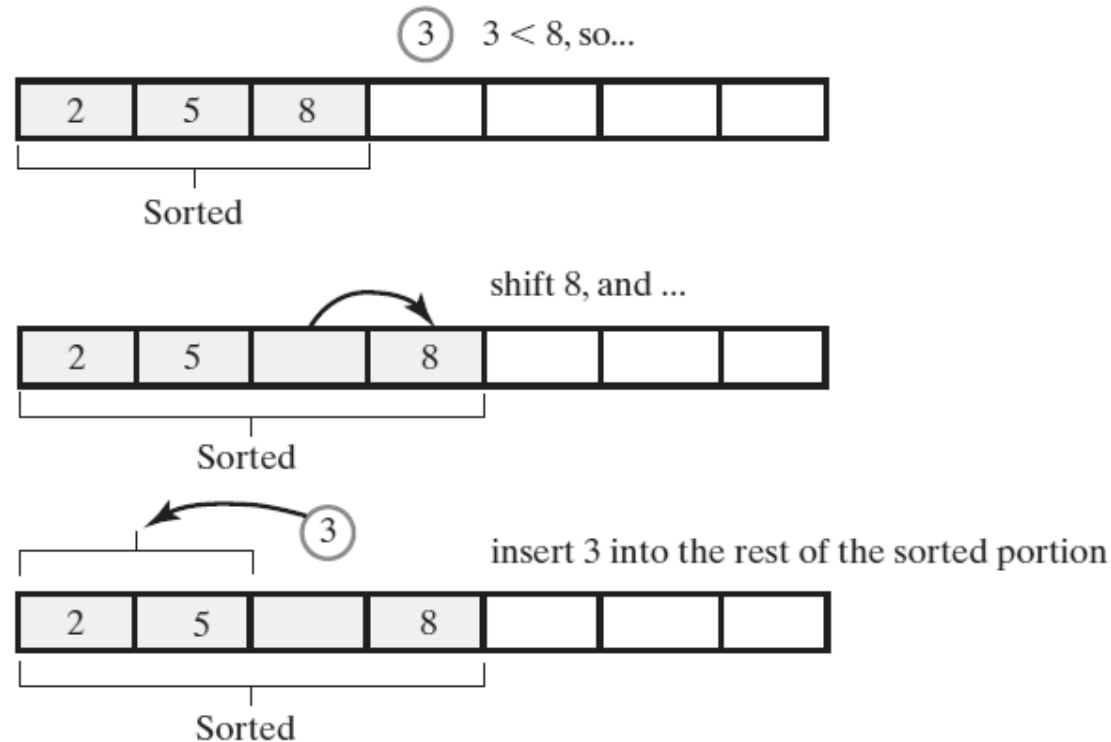
- FIGURE 8-8 Inserting the first unsorted entry into the sorted portion of the array. (a) The entry is greater than or equal to the last sorted entry



Recursive Insertion Sort

- FIGURE 8-8 Inserting the first unsorted entry into the sorted portion of the array (b) the entry is smaller than the last

(b)



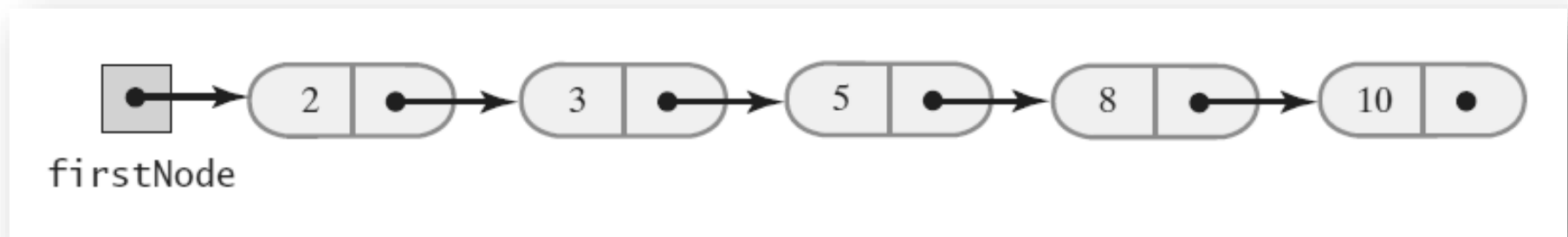
Recursive Insertion Sort

- The algorithm **insertInOrder**: final draft.
Note: insertion sort efficiency (worst case) is $O(n^2)$

```
Algorithm insertInOrder(anEntry, a, begin, end)  
// Inserts anEntry into the sorted array entries a[begin] through a[end].  
// Revised draft.  
  
if (anEntry >= a[end])  
    a[end + 1] = anEntry  
  
    else if (begin < end)  
    {  
        a[end + 1] = a[end]  
        insertInOrder(anEntry, a, begin, end - 1)  
    }  
    else // begin == end and anEntry < a[end]  
    {  
        a[end + 1] = a[end]  
        a[end] = anEntry  
    }  
}
```

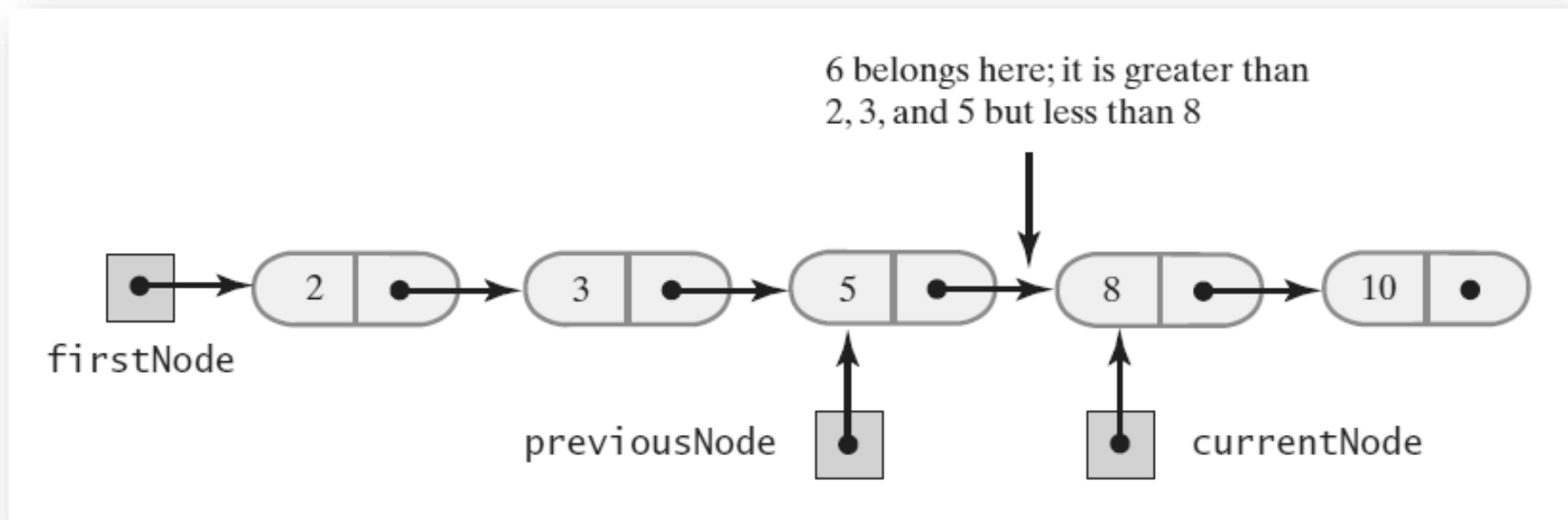
Insertion Sort of a Chain of Linked Nodes

- A chain of integers sorted into ascending order



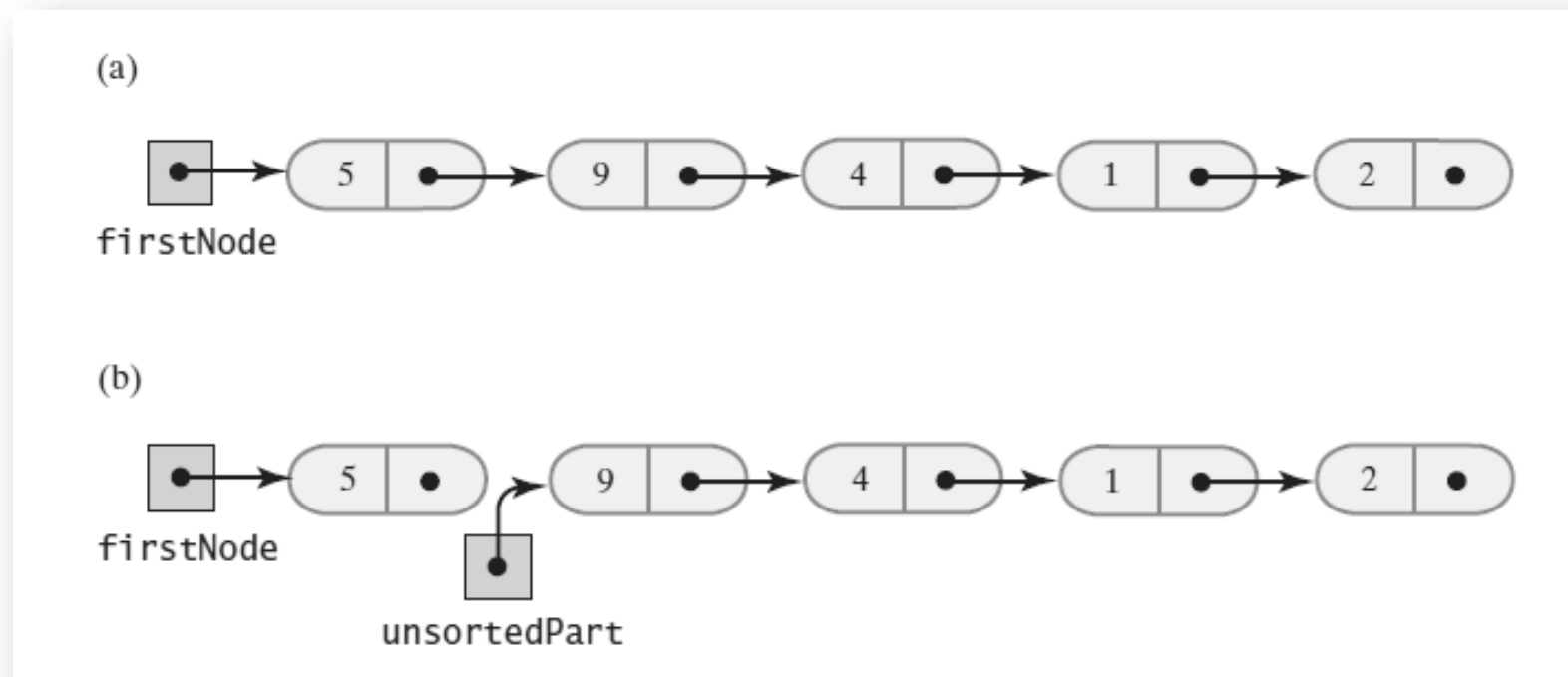
Insertion Sort of a Chain of Linked Nodes

- During the traversal of a chain to locate the insertion point, save a reference to the node before the current one



Insertion Sort of a Chain of Linked Nodes

- Breaking a chain of nodes into two pieces as the first step in an insertion sort: (a) the original chain; (b) the two pieces



Insertion Sort of a Chain of Linked Nodes

- Define an inner class **Node** that has set and get methods

```
private void insertInOrder(Node nodeToInsert)
{
    T item = nodeToInsert.getData();
    Node currentNode = firstNode;
    Node previousNode = null;

    // Locate insertion point
    while ( (currentNode != null) &&
            (item.compareTo(currentNode.getData()) > 0) )
    {
        previousNode = currentNode;
        currentNode = currentNode.getNextNode();
    } // end while

    // Make the insertion
```

Insertion Sort of a Chain of Linked Nodes

```
} // end while  
  
// Make the insertion  
if (previousNode != null)  
{ // Insert between previousNode and currentNode  
    previousNode.setNextNode(nodeToInsert);  
    nodeToInsert.setNextNode(currentNode);  
}  
else // Insert at beginning  
{  
    nodeToInsert.setNextNode(firstNode);  
    firstNode = nodeToInsert;  
} // end if  
} // end insertInOrder
```

Insertion Sort of a Chain of Linked Nodes

- The method to perform the insertion sort.

```
public void insertionSort()
{
    // If zero or one item is in the chain, there is nothing to do
    if (length > 1)
    {
        assert firstNode != null;
        // Break chain into 2 pieces: sorted and unsorted
        Node unsortedPart = firstNode.getNextNode();
        assert unsortedPart != null;
        firstNode.setNextNode(null);
        while (unsortedPart != null)
        {
            Node nodeToInsert = unsortedPart;
            unsortedPart = unsortedPart.getNextNode();
            insertInOrder(nodeToInsert);
        } // end while
    } // end if
} // end insertionSort
```

Efficiency of Selection and Insertion Sorts

- Selection sort is $O(n^2)$ regardless of the initial order of the entries.
 - Requires $O(n^2)$ comparisons
 - Does only $O(n)$ swaps
- Insertion sort is $O(n^2)$ in the worst-case
 - Requires $O(n^2)$ comparisons and swaps
 - $O(n)$ in the best case

Some properties of Selection and Insertion Sorts

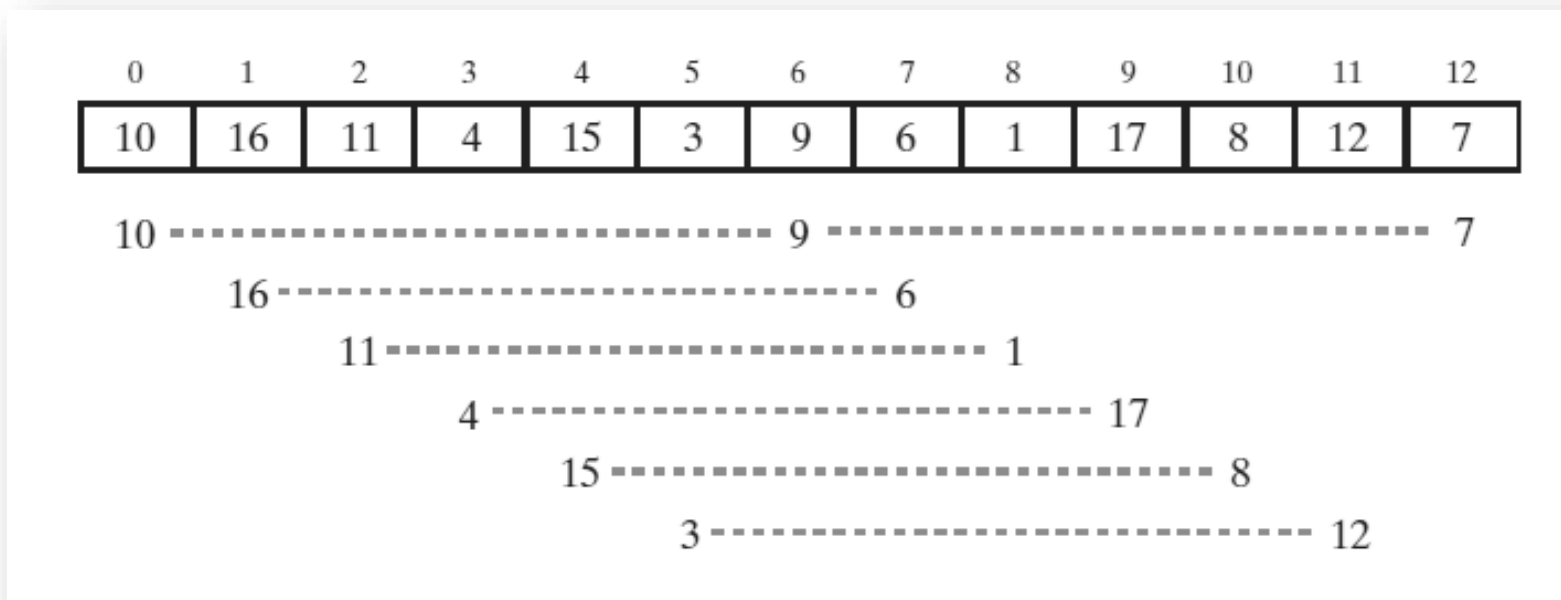
- Selection sort is
 - not stable
 - in-place
 - non-adaptive
 - provides partial solution when interrupted in the middle of execution
- Insertion sort
 - stable
 - in-place
 - adaptive
 - the more sorted an array is, the less work `insertInOrder` must do
 - very fast on small arrays
 - small constant factors

Shell Sort

- Algorithms seen so far are simple but inefficient for large arrays
- Improved insertion sort developed by Donald Shell

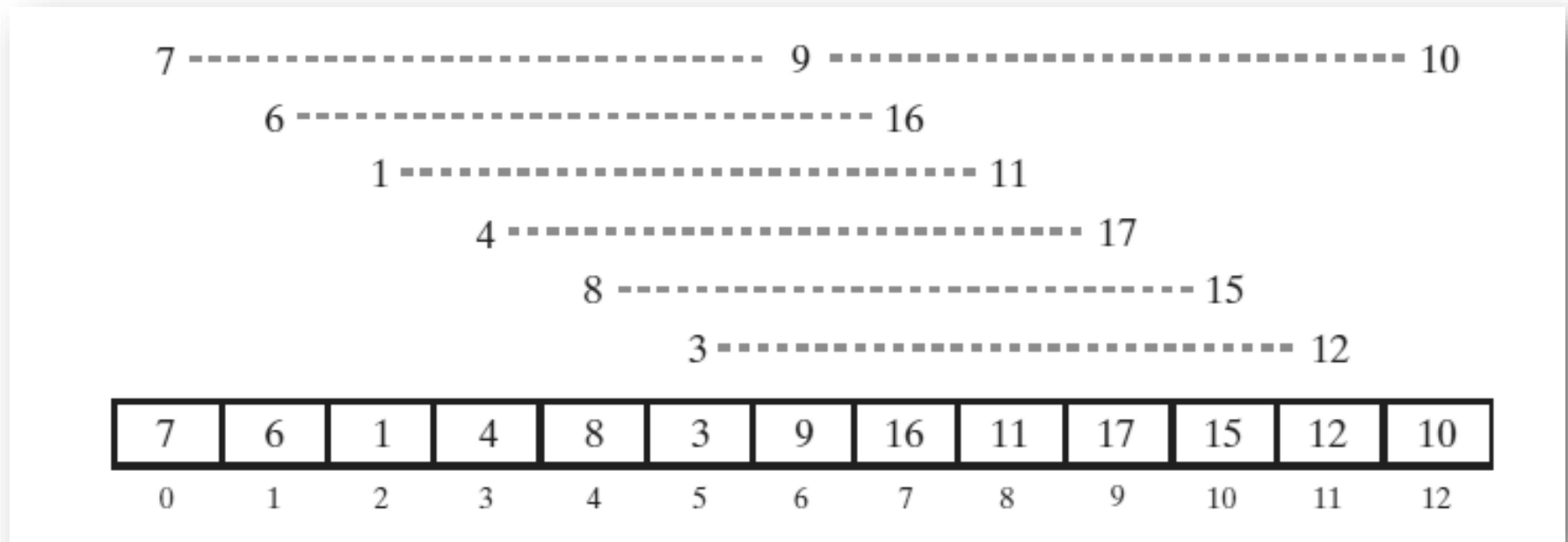
Shell Sort

- An array and the subarrays formed by grouping entries whose indices are 6 apart.



Shell Sort

- The subarrays of after each is sorted, and the array that contains them



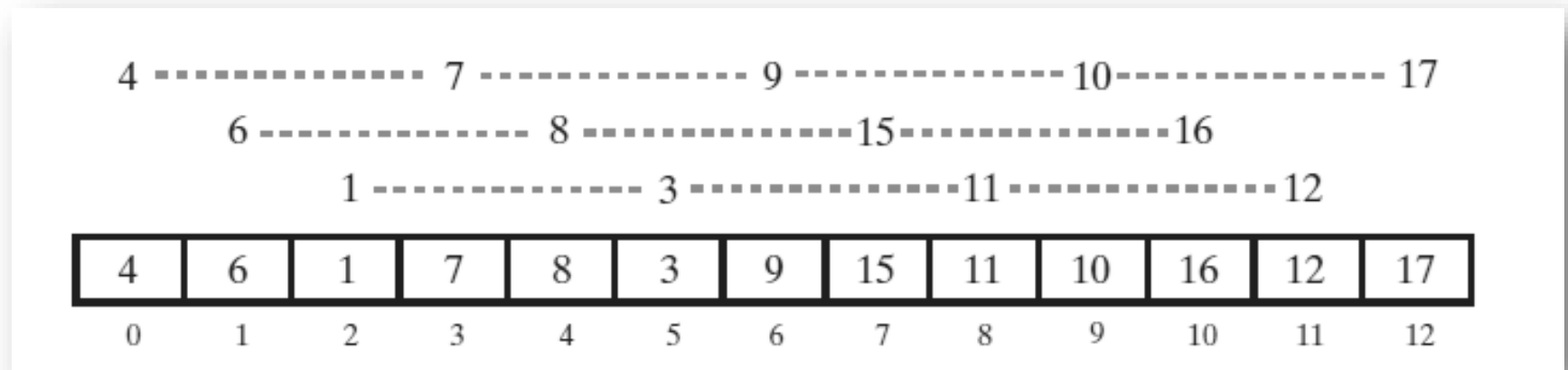
Shell Sort

- The subarrays formed by grouping entries whose indices are 3 apart

0	1	2	3	4	5	6	7	8	9	10	11	12	
7	6	1	4	8	3	9	16	11	17	15	12	10	
7	-----		4	-----			9	-----		17	-----		10
6		-----		8	-----			16	-----		15		
1			-----		3	-----			11	-----		12	

Shell Sort

- The subarrays after each is sorted, and the array that contains them



Shell Sort

- Algorithm that sorts array entries whose indices are separated by an increment of **space**.

```
Algorithm incrementalInsertionSort(a, first, last, space)
// Sorts equally spaced entries of an array a[first..last] into ascending order.
// first >= 0 and < a.length; last >= first and < a.length;
// space is the difference between the indices of the entries to sort.

for (unsorted = first + space through last at increments of space)
{
    nextToInsert = a[unsorted]
    index = unsorted - space
    while ( (index >= first) and (nextToInsert.compareTo(a[index]) < 0) )
    {
        a[index + space] = a[index]
        index = index - space
    }
    a[index + space] = nextToInsert
}
```

Shell Sort

- Algorithm to perform a Shell sort will invoke **incrementalInsertionSort** and supply any sequence of spacing factors.

```
Algorithm shellSort(a, first, last)
// Sorts the entries of an array a[first..last] into ascending order.
// first >= 0 and < a.length; last >= first and < a.length.

n = number of array entries
space = n / 2
while (space > 0)
{
    for (begin = first through first + space - 1)
    {
        incrementalInsertionSort(a, begin, last, space)
    }
    space = space / 2
}
```

Efficiency of Shell Sort

- Efficiency highly depends on the spacing
 - Average case $O(n \sqrt{n})$
- Best case
 - $O(n)$ when the number of spaces is constant
 - $O(n \log n)$ when space is divided by 2 in each iteration

Comparing the Algorithms

- The time efficiencies of three sorting algorithms, expressed in Big Oh notation

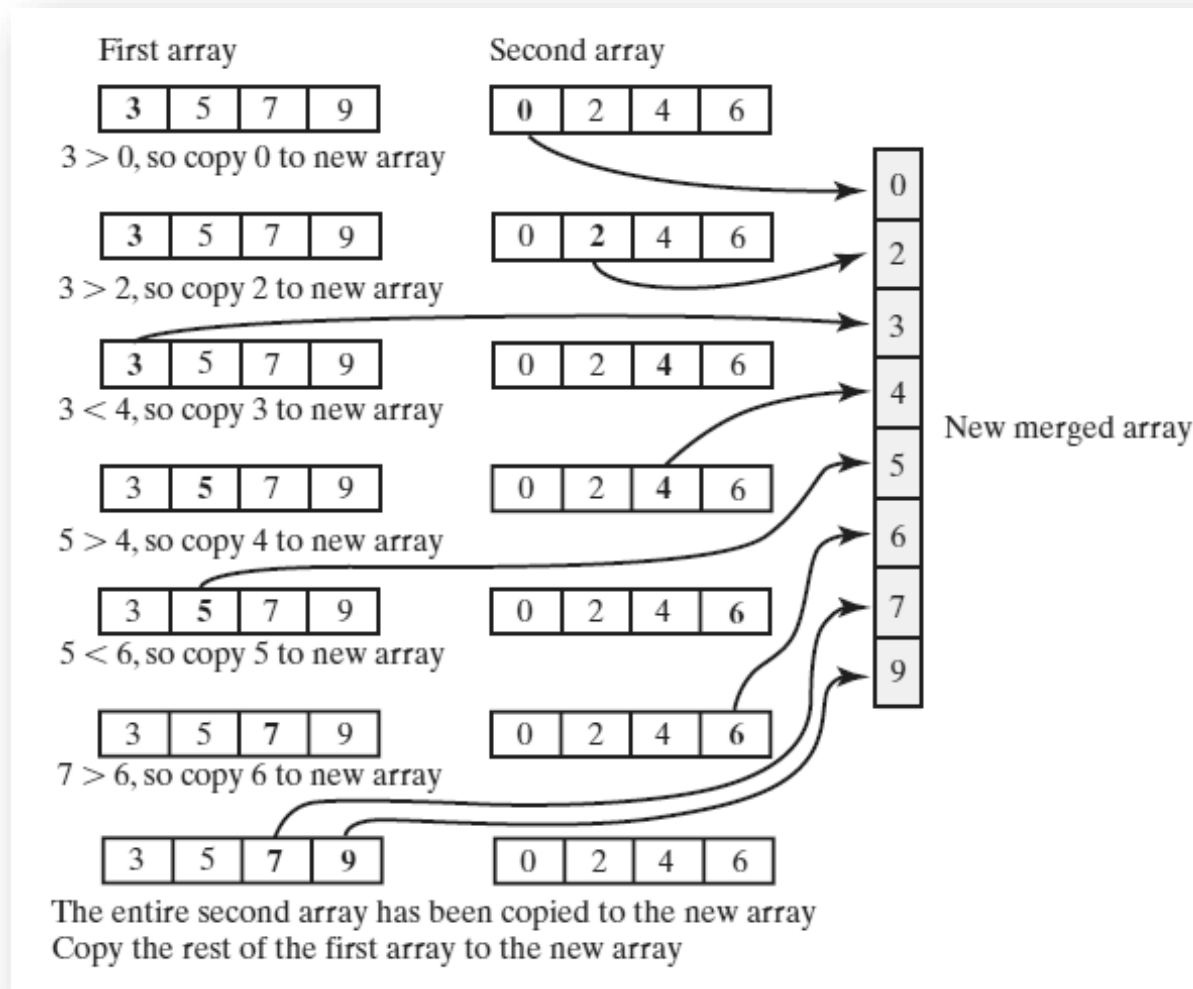
	Best Case	Average Case	Worst Case
Selection sort	$O(n^2)$	$O(n^2)$	$O(n^2)$
Insertion sort	$O(n)$	$O(n^2)$	$O(n^2)$
Shell sort	$O(n)$	$O(n^{1.5})$	$O(n^2)$ or $O(n^{1.5})$

Merge Sort

- Divides an array into halves
- Sorts the two halves,
 - Then merges them into one sorted array.
- The algorithm for merge sort is usually stated recursively.
- Major programming effort is in the merge process

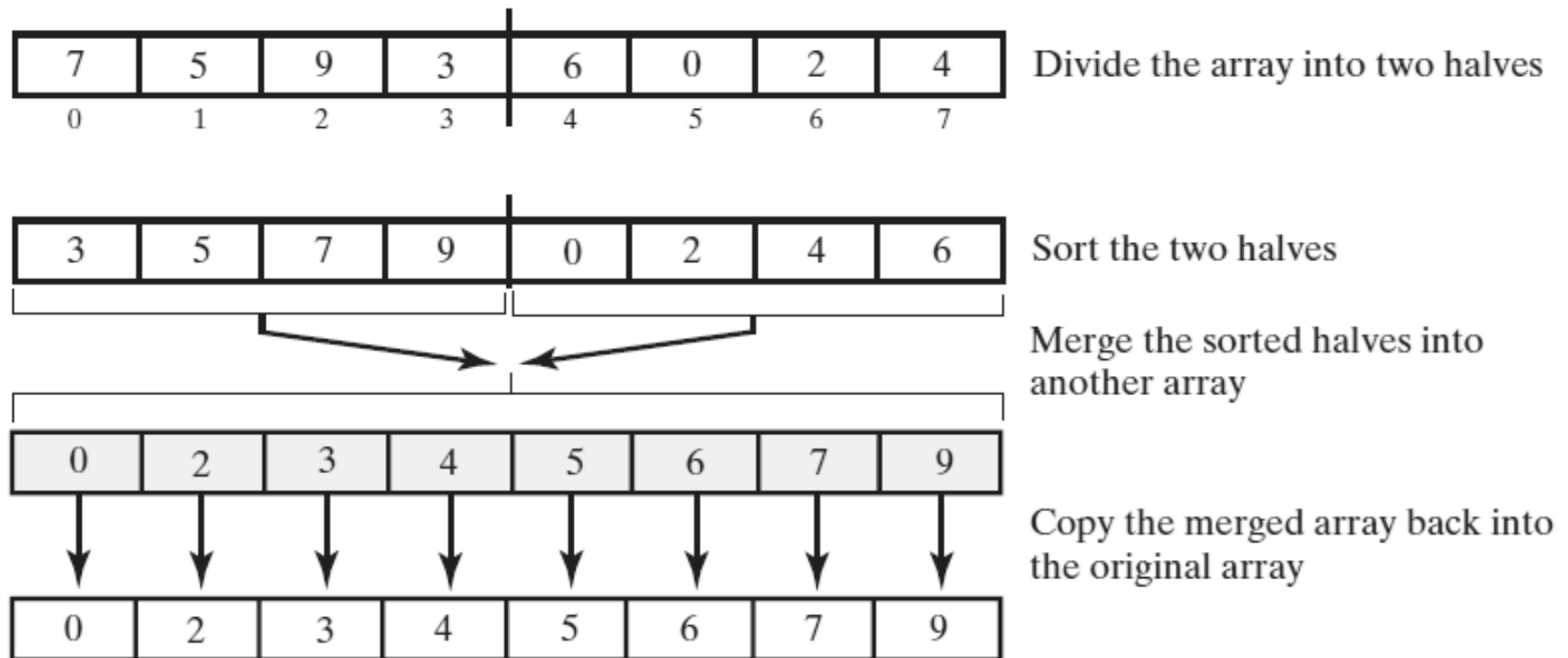
Merging Arrays

- Merging two sorted arrays into one sorted array



Recursive Merge Sort

- The major steps in a merge sort



Recursive Merge Sort

- Recursive algorithm for merge sort.

```
Algorithm mergeSort(a, tempArray, first, last)
// Sorts the array entries a[first] through a[last] recursively.
if (first < last)
{
    mid = approximate midpoint between first and last
    mergeSort(a, tempArray, first, mid)
    mergeSort(a, tempArray, mid + 1, last)
    Merge the sorted halves a[first..mid] and a[mid + 1..last] using the array tempArray
}
```

Recursive Merge Sort

- Pseudocode which describes the merge step.

```
Algorithm merge(a, tempArray, first, mid, last)  
// Merges the adjacent subarrays a[first..mid] and a[mid + 1..last].  
beginHalf1 = first  
endHalf1 = mid  
beginHalf2 = mid + 1  
endHalf2 = last  
// While both subarrays are not empty, compare an entry in one subarray with  
// an entry in the other; then copy the smaller item into the temporary array  
index = 0 // Next available location in tempArray  
while ( (beginHalf1 <= endHalf1) and (beginHalf2 <= endHalf2) )  
{  
    if (a[beginHalf1] <= a[beginHalf2])  
    {  
        tempArray[index] = a[beginHalf1]  
        beginHalf1++  
    }  
}
```

Recursive Merge Sort

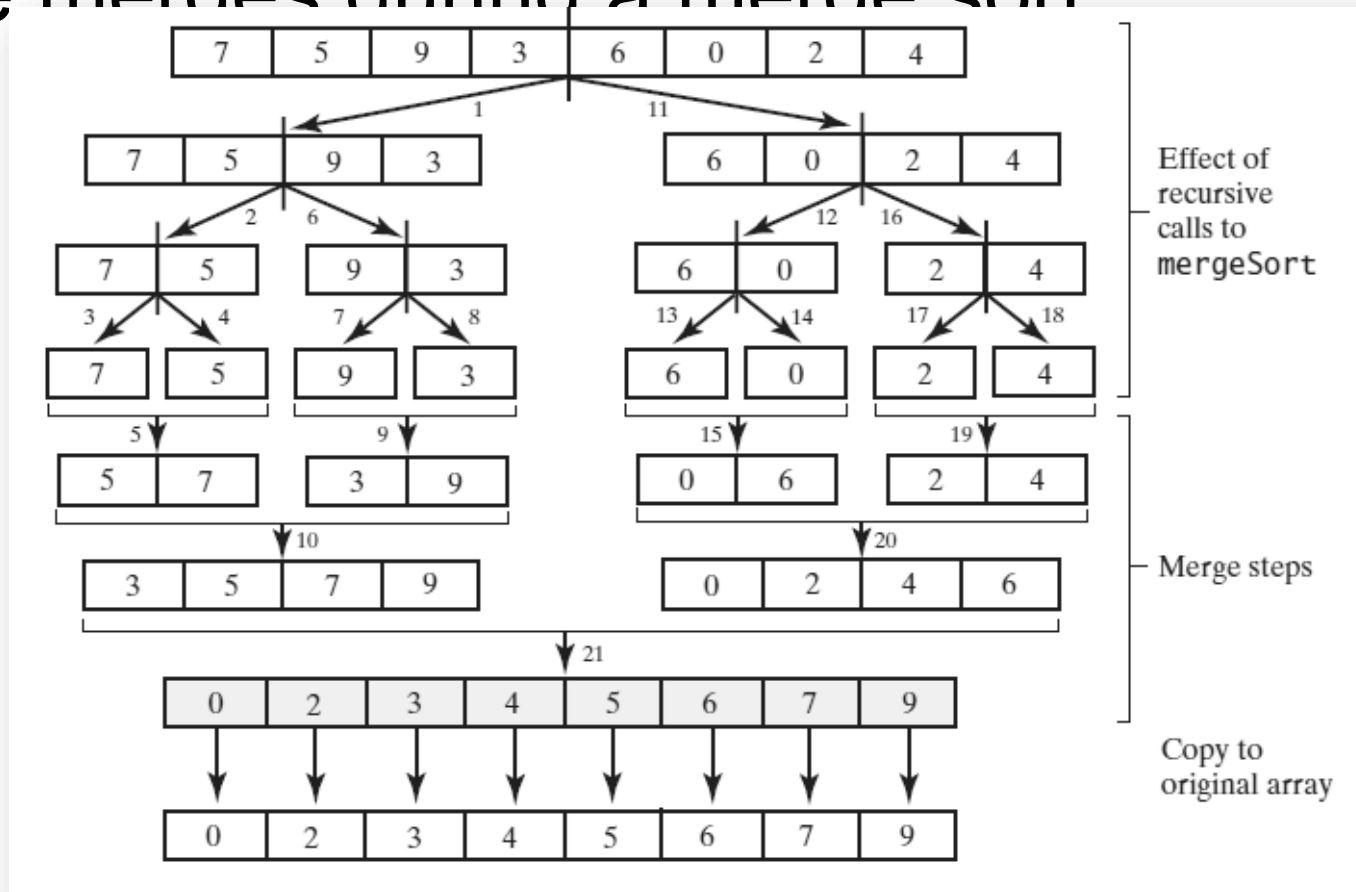
- Pseudocode which describes the merge step.

```
        tempArray[index] = a[beginHalf1]
        beginHalf1++
    }
    else
    {
        tempArray[index] = a[beginHalf2]
        beginHalf2++
    }
    index++
}
// Assertion: One subarray has been completely copied to tempArray.

Copy remaining entries from other subarray to tempArray
Copy entries from tempArray to array a
```

Recursive Merge Sort

- FIGURE 9-3 The effect of the recursive calls and the merges during a merge sort



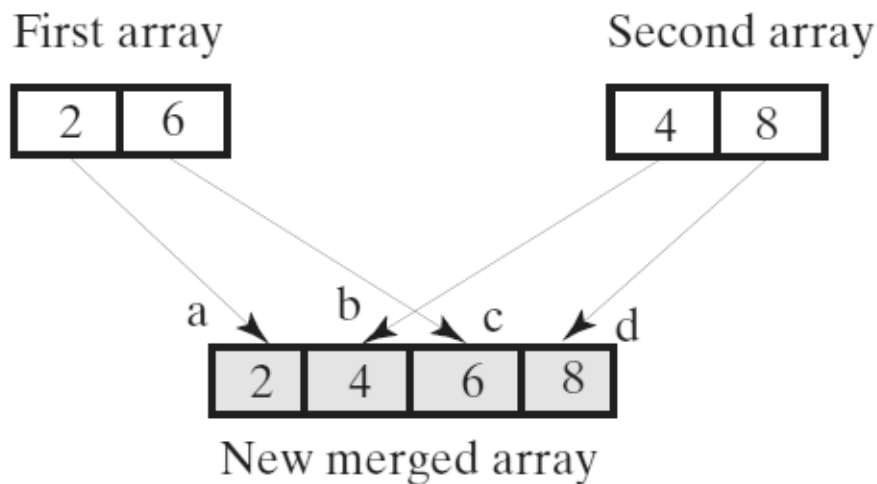
Recursive Merge Sort

- Be careful to allocate the temporary array only once.

```
public static <T extends Comparable<? super T>>
    void mergeSort(T[] a, int first, int last)
{
    // The cast is safe because the new array contains null entries
    @SuppressWarnings("unchecked")
    T[] tempArray = (T[])new Comparable<?>[a.length]; // Unchecked cast
    mergeSort(a, tempArray, first, last);
} // end mergeSort
```


Efficiency of Merge Sort

- A worst-case merge of two sorted arrays.
- Efficiency is $O(n \log n)$.



- a. $2 < 4$, so copy 2 to new array
- b. $6 > 4$, so copy 4 to new array
- c. $6 < 8$, so copy 6 to new array
- d. Copy 8 to new array

Iterative Merge Sort

- Less simple than recursive version.
 - Need to control the merges.
- Will be more efficient of both time and space.
 - But, trickier to code without error.

Iterative Merge Sort

- Starts at beginning of array
 - Merges pairs of individual entries to form two-entry subarrays
- Returns to the beginning of array and merges pairs of the two-entry subarrays to form four-entry subarrays
 - And so on
- After merging all pairs of subarrays of a particular length, might have entries left over.

Merge Sort in the Java Class Library

- Class **Arrays** in the package **java.util** defines versions of a static method **sort**

```
public static void sort(Object[] a)
```

```
public static void sort(Object[] a, int first, int after)
```

Merge Sort Properties

- stable
- not in-place
- can be made adaptive

Quick Sort

- Divides an array into two pieces
 - Pieces are not necessarily halves of the array
 - Chooses one entry in the array—called the pivot
- Partitions the array into
 - \leq pivot
 - \geq pivot
 - places pivot in between the two parts
- Recursively sorts each part

Quick Sort

- When pivot chosen, array rearranged such that:
 - Pivot is in position that it will occupy in final sorted array
 - Entries in positions before pivot are less than or equal to pivot
 - Entries in positions after pivot are greater than or equal to pivot

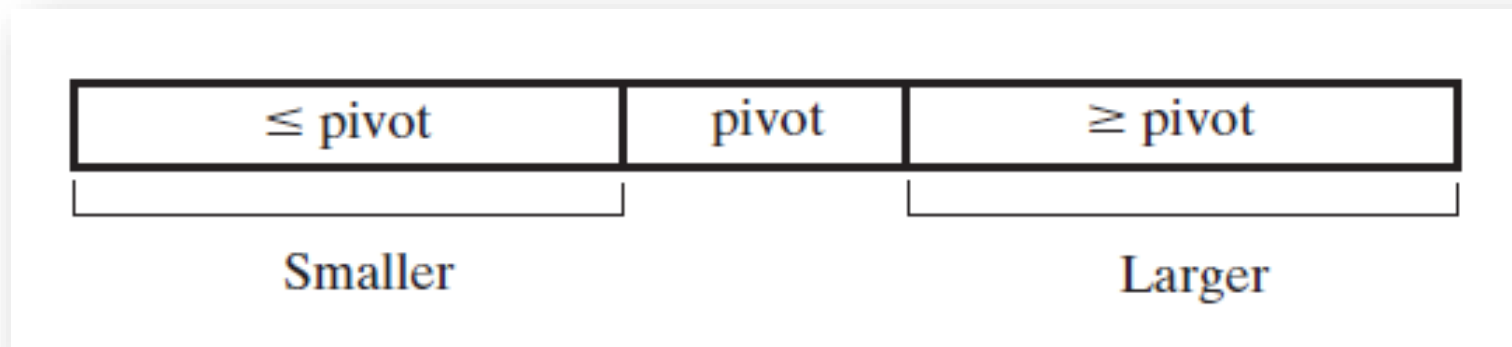
Quick Sort

- Algorithm that describes our sorting strategy:

```
Algorithm quickSort(a, first, last)  
// Sorts the array entries a[first] through a[last] recursively.  
if (first < last)  
{  
    Choose a pivot  
    Partition the array about the pivot  
    pivotIndex = index of pivot  
    quickSort(a, first, pivotIndex - 1) // Sort Smaller  
    quickSort(a, pivotIndex + 1, last) // Sort Larger  
}
```

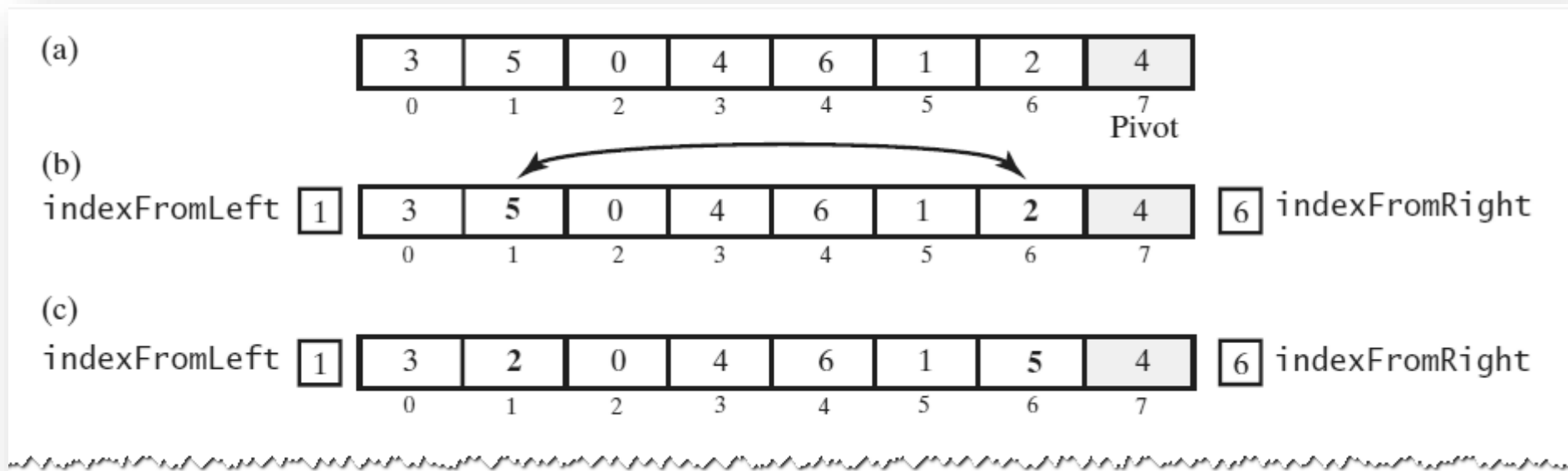

Quick Sort

- A partition of an array during a quick sort



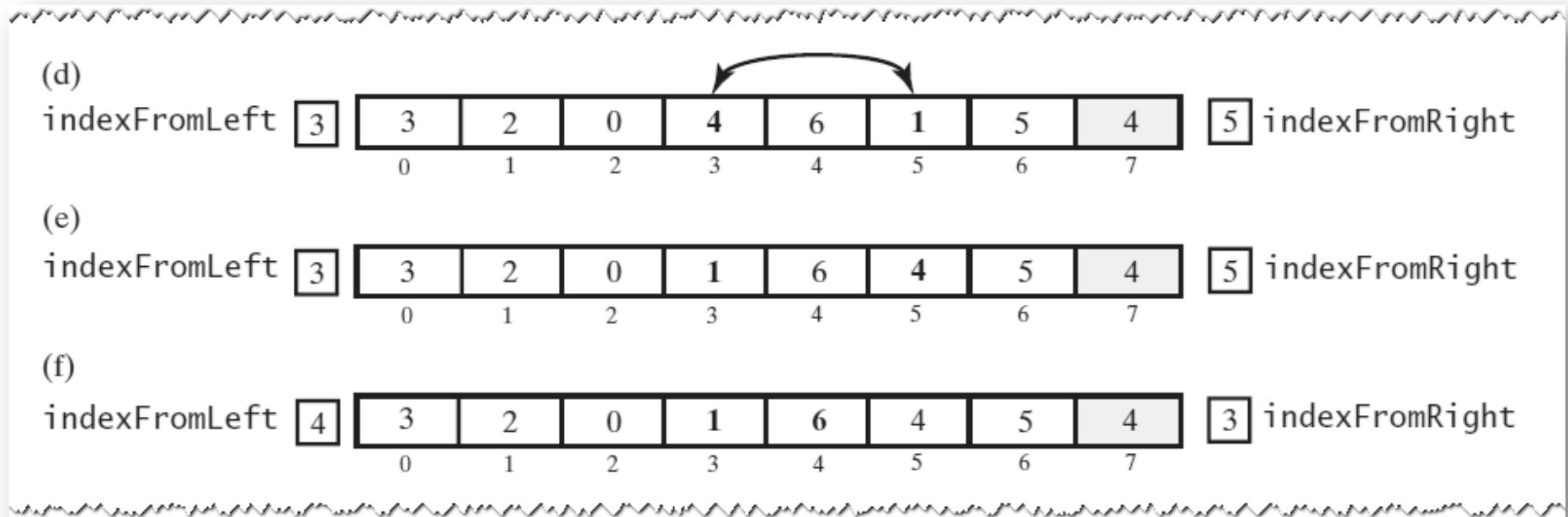
Creating the Partition

- A partitioning strategy for quick sort



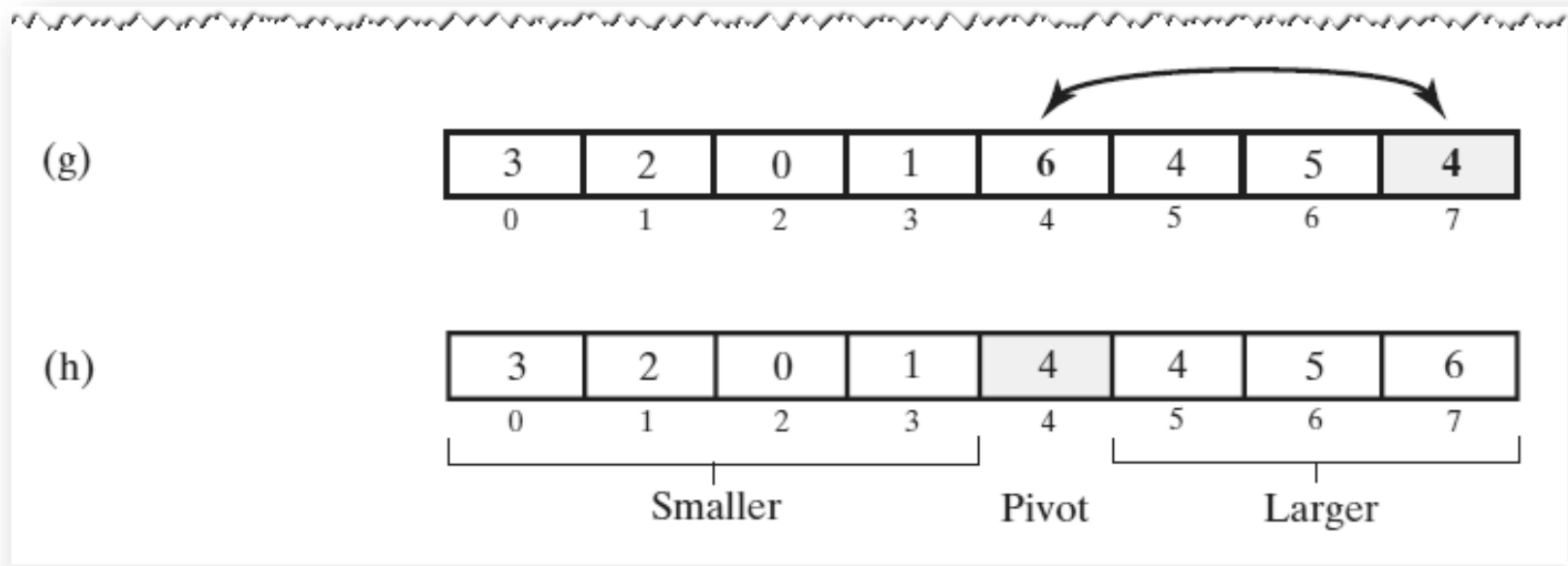
Creating the Partition

- A partitioning strategy for quick sort



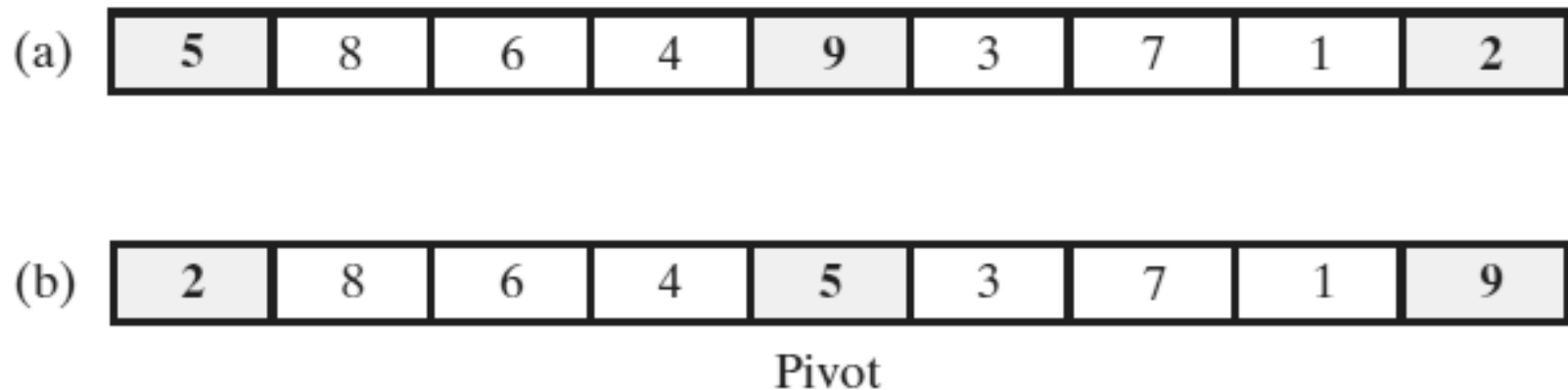
Creating the Partition

- A partitioning strategy for quick sort



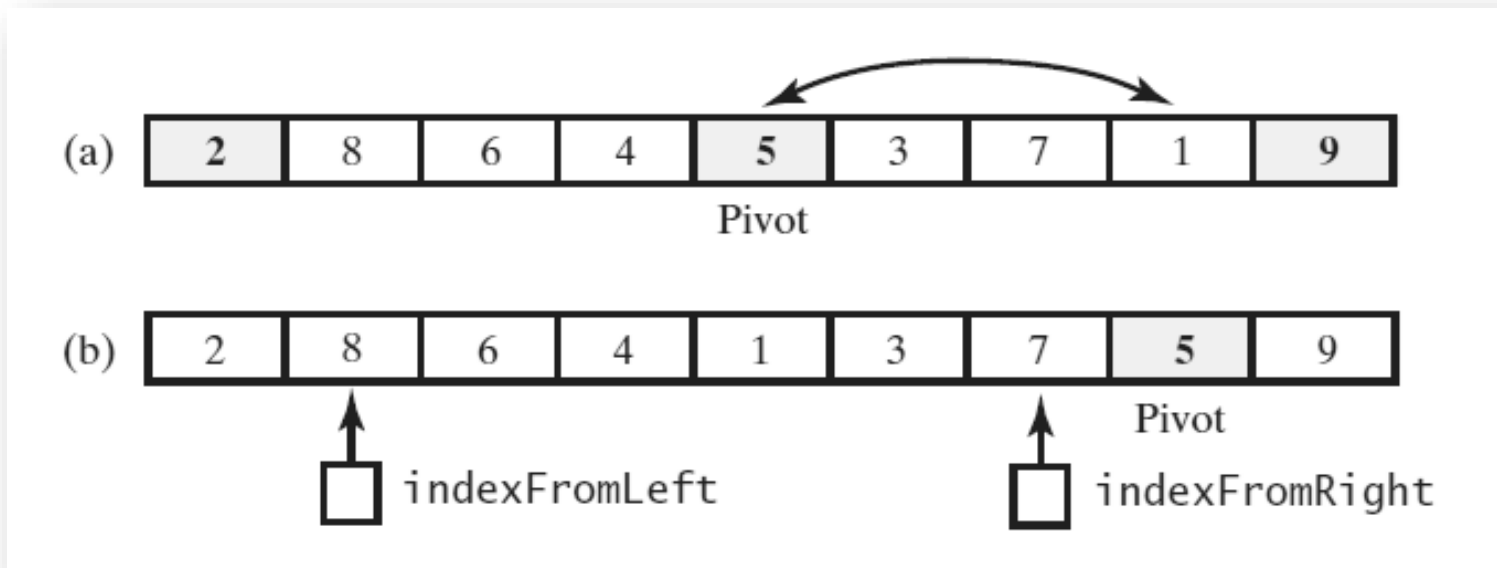
Creating the Partition

- Median-of-three pivot selection: (a) The original array; (b) the array with its first, middle, and last entries sorted



Adjusting the Partition Algorithm

- The array with its first, middle, and last entries sorted;
(b) the array after positioning the pivot and just before partitioning



Adjusting the Partition Algorithm

Algorithm partition(a, first, last)

// Partitions an array a[first..last] as part of quick sort into two subarrays named

// Smaller and Larger that are separated by a single entry—the pivot— named pivotValue.

// Entries in Smaller are \leq pivotValue and appear before pivotValue in the array.

// Entries in Larger are \geq pivotValue and appear after pivotValue in the array.

// first ≥ 0 ; first $<$ a.length; last - first ≥ 3 ; last $<$ a.length.

// Returns the index of the pivot.

mid = index of the array's middle entry

sortFirstMiddleLast(a, first, mid, last)

// Assertion: a[mid] is the pivot, that is, pivotValue;

// a[first] \leq pivotValue and a[last] \geq pivotValue, so do not compare these two

// array entries with pivotValue.

// Move pivotValue to next-to-last position in array

Adjusting the Partition Algorithm

```
// Move pivotValue to next-to-last position in array  
Exchange a[mid] and a[last - 1]  
pivotIndex = last - 1  
pivotValue = a[pivotIndex]  
  
// Determine two subarrays:  
//   Smaller = a[first..endSmaller] and  
//   Larger  = a[endSmaller+1..last-1]  
// such that entries in Smaller are <= pivotValue and  
// entries in Larger are >= pivotValue.  
// Initially, these subarrays are empty.  
indexFromLeft = first + 1  
indexFromRight = last - 2  
done = false  
while (!done)
```


Adjusting the Partition Algorithm

```
while (!done)
{
    // Starting at the beginning of the array, leave entries that are < pivotValue and
    // locate the first entry that is >= pivotValue. You will find one, since the last
    // entry is >= pivotValue.
    while (a[indexFromLeft] < pivotValue)
        indexFromLeft++

    // Starting at the end of the array, leave entries that are > pivotValue and
    // locate the first entry that is <= pivotValue. You will find one, since the first
    // entry is <= pivotValue.
    while (a[indexFromRight] > pivotValue)
        indexFromRight--

    // Assertion: a[indexFromLeft] >= pivotValue and
    //             a[indexFromRight] <= pivotValue
    if (indexFromLeft < indexFromRight)
```

Adjusting the Partition Algorithm

```
//          a[indexFromRight] <= pivotValue
if (indexFromLeft < indexFromRight)
{
    Exchange a[indexFromLeft] and a[indexFromRight]
    indexFromLeft++
    indexFromRight--
}
else
    done = true
}

Exchange a[pivotIndex] and a[indexFromLeft]
pivotIndex = indexFromLeft

// Assertion: Smaller = a[first..pivotIndex-1]
//          pivotValue = a[pivotIndex]
//          Larger = a[pivotIndex+1..last]
return pivotIndex
```

The Quick Sort Method

- Above method implements quick sort.

```
/** Sorts an array into ascending order. Uses quick sort with
    median-of-three pivot selection for arrays of at least
    MIN_SIZE entries, and uses insertion sort for smaller arrays. */
public static <T extends Comparable<? super T>>
    void quickSort(T[] a, int first, int last)
{
    if (last - first + 1 < MIN_SIZE)
    {
        insertionSort(a, first, last);
    }
    else
    {
        // Create the partition: Smaller | Pivot | Larger
        int pivotIndex = partition(a, first, last);
        // Sort subarrays Smaller and Larger
        quickSort(a, first, pivotIndex - 1);
        quickSort(a, pivotIndex + 1, last);
    } // end if
} // end quickSort
```

QuickSort in the Java Class Library

- Class **Arrays** in the package **java.util** uses a quick sort to sort arrays of primitive types into ascending order

```
public static void sort(type[] a)
```

```
public static void sort(type[] a, int first, int after)
```