

How Does Visualising Path-finding in an NPC Affect How Players Explore a Game Level?

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Abstract—This paper looks at the use of path-finding and *Artificial Intelligence* (AI) visualisation in digital games. Specifically at the foregrounding AI and the visualisation of path-finding. While previous papers have researched AI visualisation and how to achieve it there does not appear to be many papers on the field of visualising AI in video games. There has been research into the visualisation of path-finding. However, the focus was most commonly on the use of visualisation in game design. This paper looks at visualising various methods of path-finding on enemy NPCs in a 3D Metroidvania game developed in Unity. The results found a number of cases where player exploration was affected by either a change in path-finding method or whether the path-finding is visualised. This suggests that these factors affect player exploration and could be taken into account when designing games.

I. INTRODUCTION

THIS project looks at visualising the path-finding of an enemy *Non Player Character* (NPC) using *Rapidly-exploring Random Tree* (RRT) path-finding and Unity's *Navigation Meshes* (NavMeshes). Figure 2 shows an example of RRT path-finding. Here the RRT explores the area and then draws a path along the tree between the start and the goal nodes [1].

This paper looks at visualising the tree produced by RRT and the process taken to produce it. The visualisation is around an enemy NPC. This allows the players to see where the enemy NPC is going and where it could go.

Implementation of the visualisation was developed in a level of a 3D game made in Unity 5.6¹. Logging tools in the play-testing software export the amount of time the players spent in a level and what percent of the level they explored. Analysis of this data found that only two cases had an effect on player exploration. These two were the visualisation of the Unity navmeshes had a negative correlation with the amount of the level explored and the use of RRT path-finding increasing the amount of the level explored. This is analysed in more detail in section VII.

Previous papers have researched visualising *Artificial Intelligence* (AI) and foregrounding AI. However, there is little on what effect this has on how the players explore the game. The research question proposed in this project is: how does visualising RRT path-finding in an NPC affect how a player explores a game level?

II. ROADMAP

Section III is a review of the literature on existing relevant work. The areas reviewed are A* path-finding, RRT path-

finding, path-finding, foregrounding AI and exploring game environments. Section IV details the methodology used in the experiments in this study. Section V details the development of the software used for the experiments in this study. Section VI details the data collected and how it was filtered and section VII looks at the analysis of this data and what the results imply. Section VIII details the potential issues and ways to address them in future work. Section IX looks at future research that could be done on this subject.

III. RELATED WORK

The focus of this paper is on path-finding so that is the main focus of the literature review. The path-finding methods looked at are A* path-finding in section III-A and RRT path-finding in section III-B. Section III-C looks at applications of path-finding in games. Section III-D looks at foregrounding and visualising AI. While there is research on AI visualisation there is a lack of it for digital games and what research is on games often focuses on game development and level design as can be seen in section III-D. This literature review shows that while there are many papers on AI visualisation there are few on AI visualisation in digital games and many of the ones on games are on visualising AI to aid development, not for the end user.

A. A* Path-finding

A* path-finding is widely used in both robotics and digital games [2]. In games, A* appears to be the most commonly used path-finding algorithm [2].

Hart *et al* [3] first proposed A* path-finding in 1968 as an improvement on Dijkstra's algorithm. A* aims to expand the fewest nodes possible to minimise the cost of the path where the cost is the distance between the start and goal nodes. Figure 1 shows pseudo-code for implementing A*.

Algfoor *et al* [2] survey numerous papers on path-finding. Their focus is on the use of different grid shapes in path-finding and the numerous algorithms available [2]. The most popular being the A* algorithm for use in both digital games and robotics. They survey many grid types and gave the advantages of each.

Nash *et al* [5] say that A* cannot always find the true shortest path as it is limited to the grid. The shortest path can be found A* with post-smoothing paths or by using A* variants such as Theta* [5], [6]. Theta* expands on A* as it allows for all edges and angles in the grid to be used. Therefore, a path with a more optimal distance can be found.

¹Unity 5.6 Available: <https://unity3d.com/get-unity/download/archive>

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1 Put node_start in the OPEN list with f(node_start) = h(node_start) (initialization)
2 while the OPEN list is not empty {
3   Take from the open list the node node_current with the lowest
4   f(node_current) = g(node_current) + h(node_current)
5   if node_current is node_goal we have found the solution; break
6   Generate each state node_successor that comes after node_current
7   for each node_successor of node_current {
8     Set successor_current_cost = g(node_current) + w(node_current, node_successor)
9     if node_successor is in the OPEN list {
10       if g(node_successor) ≤ successor_current_cost continue (to line 20)
11     } else if node_successor is in the CLOSED list {
12       if g(node_successor) ≤ successor_current_cost continue (to line 20)
13       Move node_successor from the CLOSED list to the OPEN list
14     } else {
15       Add node_successor to the OPEN list
16       Set h(node_successor) to be the heuristic distance to node_goal
17     }
18     Set g(node_successor) = successor_current_cost
19     Set the parent of node_successor to node_current
20   }
21   Add node_current to the CLOSED list
22 }
23 if(node_current != node_goal) exit with error (the OPEN list is empty)

```

Fig. 1. Pseudo-code for A* path-finding [3] [4].

Firmansyah *et al* [6] compare A* with Theta*. They found that they performed similarly time wise. However, A* produces a path with fewer nodes expanded and Theta* produces a shorter path.

Hu *et al* [7] propose an implementation of A* path-finding in the Unity engine, the engine used in this project. While their implementation is in an older version Unity the implementation in Unity 5.6 should still be similar. A further paper on path-finding is Wang and Lu's [8] paper which looks at path-finding in a 3-Dimensional environment. While again they were using A* they look at using A* in 3D and suggest using nodes instead of a grid.

Tremblay *et al* [9] look at the use of path-finding algorithms in level design. They compared 2-Dimensional A*, 3-Dimensional A*, RRT using A* for motion planning, RRT using *Monte Carlo Tree Search* (MCTS) and MCTS alone. 2-Dimensional A* consistently gave the fastest result with the highest success rate. As this was for game level design instead of gameplay they ran the algorithms 1000 times on high specification computers.

For this project, the algorithm will only be run once as it is being used at runtime in the game instead of in the game design stage that Tremblay *et al* [9] tested in. As A* has a 100 percent chance of finding the shortest path this should not cause an issue.

B. RRT and Path-finding

Rapidly Exploring Random Trees (RRT) is a search method used more in robotics than in digital games [10], [1]. Kuffner and LaValle [1] first proposed RRT in 2000. They intended to produce a random algorithm more efficient than the other search algorithms available at the time. Figure 2 shows Kuffner and LaValle's [1] RRT Path Planner. Path Planner is a variant of RRT which has the intended use of finding paths from the generated tree.

The process for RRT involves the random placement of nodes. A parent is then selected by finding the closest pre-existing node [1]. Algorithm 1 shows the pseudo-code for the RRT algorithm.

RRTs goal is to find a path between two points with no collisions. The path found may not be the optimal path

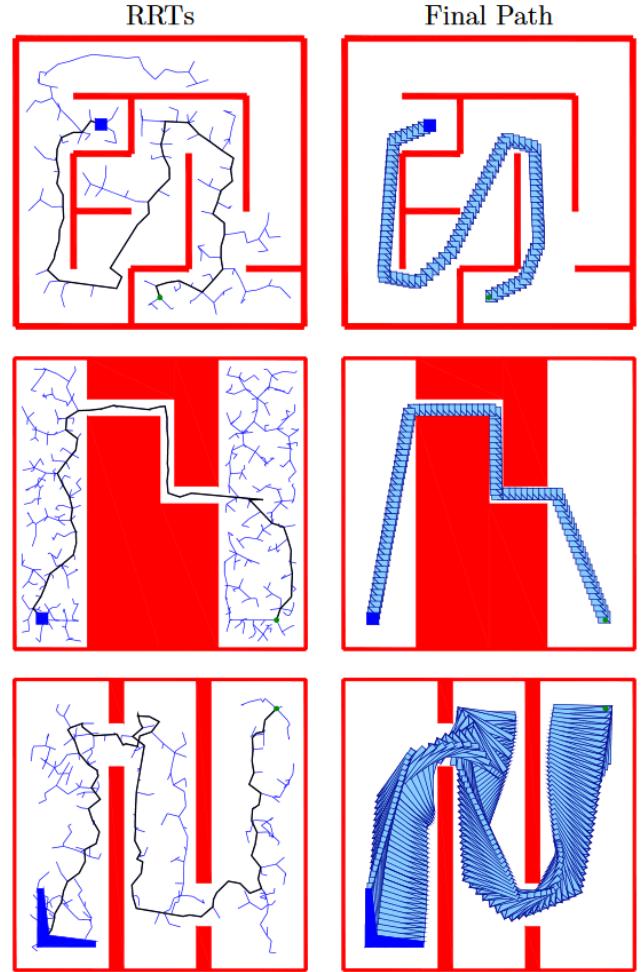


Fig. 2. Kuffner and LaValle's RRT path planner building a tree and plotting a path through it [1].

though [1], [11]. Karaman and Sertac [12] say that the chance of RRT finding an optimal path is very unlikely [12], [9]. Where A* is guaranteed to find the shortest path as seen in section III-A, RRT is unlikely to find the shortest path and may not even find a path at all. Karaman *et al* propose a variant of RRT called RRT*. RRT* starts the same as RRT, however, when a new node has to choose a parent node instead of selecting the nearest node it evaluates the cost of the nodes in regards to reaching its goal. Each iteration re-evaluates the parent nodes to reduce the cost. Rewiring of the tree happens when a lower cost path is found.

C. Applications of Path-finding

Bauer and Popovic [13] use RRT for level design in digital games. Like other papers mentioned in section III-D, they visualise the data to aid users [13], [14]. This data visualisation is for use in game development to aid game developers or to analyse procedurally generated levels.

Their focus is on level design, not game-play. They propose a tool that analyses a level generated by PCG or a level designer. They then use RRT to calculate possible routes the

Algorithm 1 RRT Pseudo Code

```

BUILD_RRT( $q_{init}$ )
 $T.init(q.init)$ 
for  $k = 1$  to  $K$  do
     $grand \leftarrow RANDOM\_CONFIG()$ 
    EXTEND ( $T$ ,  $grand$ )
end for



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EXTEND( $T$ ,  $q$ )
 $qnear \leftarrow NEAREST\_NEIGHBOR(q, T);$ 
if NEW_CONFIG( $q$ ,  $qnear$ ,  $qnew$ ) then
     $T.add\_vertex(qnew);$ 
     $T.add\_edge(qnear, qnew);$ 
    if  $qnew = q$  then
        Return Reached;
    else
        Return Advanced;
    end if
    Return Trapped
end if

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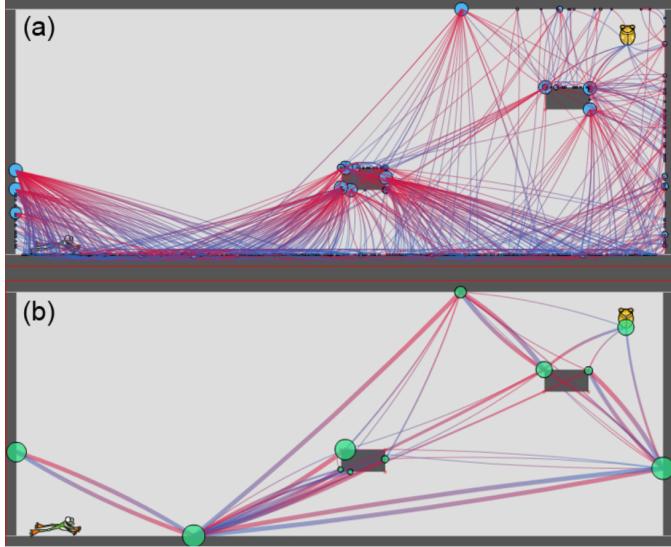


Fig. 3. Bauer *et al*'s[13] graph-based representation of RRT with and without clustering.

player could take when playing. Figure 3 shows the output of the tool once it has been run on a basic level design. Figure 3(a) may be difficult to for designers to interpret. So, they use van Dongen's method [15] for graph clustering to make the output more legible as shown in Figure 3(b) [13].

Mendoza *et al* [16] look at path-finding both in robotics and digital games. Their focus is on stealth path-finding in games and applying that to robotics. Like RRT, the methods they propose do not necessarily find the shortest path [12], [16]. Instead, they try to find the path where the agent spends most of the time in cover. They generate custom *navigation meshes* (navmeshes). Then they assign a weight to each polygon in the navmesh depending on how close it is to being behind

cover.

As Mendona *et al* [16] use path-finding to find a stealth orientated path. The path with the optimal distance may not always be the path with the lowest cost in relation to the AI agent being in cover. Therefore, a requirement might not always be the shortest path.

Tremblay *et al* [17], like Bauer and Popovic [13], also use RRT visualisations to aid level design. They use RRT to visualise possible moves the player could make. Then they use clustering to make the results less cumbersome to the user [17]. Similar to Mendona *et al* [16], they focus on designing stealth games and finding stealth orientated paths in the game levels [17]. Figure 5 shows the basic level design they used with three areas for the AI agent to take cover. This allows level designers to see where players are likely to go and adjust the level design accordingly [17]. The use of RRT, in this case, is because it is flexible and inexpensive. Also, its random nature allows for the mimicking of a wider range of player behaviours [17].

This project uses RRT but not for reflecting player behaviour. Instead, its use is for creating a visualisation that fits with the game and that may be interesting for the player to interact with. A path that is interesting to play with is more important in this project than a path with an optimal distance. There is then a comparison between a visualisation of the Unity navmeshes against the RRT visualisation.

While the use of RRT to find a stealth orientated paths is different to its use in this project a potential problem is that Tremblay *et al*'s results showed that the chances of their RRT implementation finding a path decreased as the grid size increased. It also decreased as the number of attempts decreased as shown in Figure 4. This suggests that a potential issue with RRT is that it may not always find a path.

Tremblay *et al* [9] again look at the use of search algorithms for use in game development. This work builds on their 2013 paper on RRT in stealth games. As previously mentioned in section III-A they look at the use of A*, MCTS and RRT to visualise player behaviour in platform games similar to Bauer [9] [13]. RRT is limited to drawing straight lines between the nodes, as straight lines are not always possible in RRT. Tremblay *et al* [9] also use either A* or MCTS to find a path to the node and ensure that it is reachable. While A* is consistently fast with high success rates, RRT has varying results. RRT using MCTS for motion planning varied between 35 and 84 percent success rates and had the longest run times. In comparison, RRT with A* motion planning consistently had a success rate of over 60 percent. However, the run times for this combination varied. Both of Tremblay *et al*'s [9], [17] papers showed that a potential issue with the use of RRT is that it may not find a path. Both papers ran RRT combinations over 1000 times. In comparison, this paper runs RRT at runtime and only runs the algorithm once unless an RRT variant such as RRT* is used. If a path is not found a tree is still produced and visualised so may still influence players.

Section III-D looks at Third Eye Crime in more detail for its use of AI visualisation. However, it also uses visualisation of enemy paths as an important mechanic [19], [20]. Isla [19] uses Occupancy Maps to show where the enemy NPC thinks

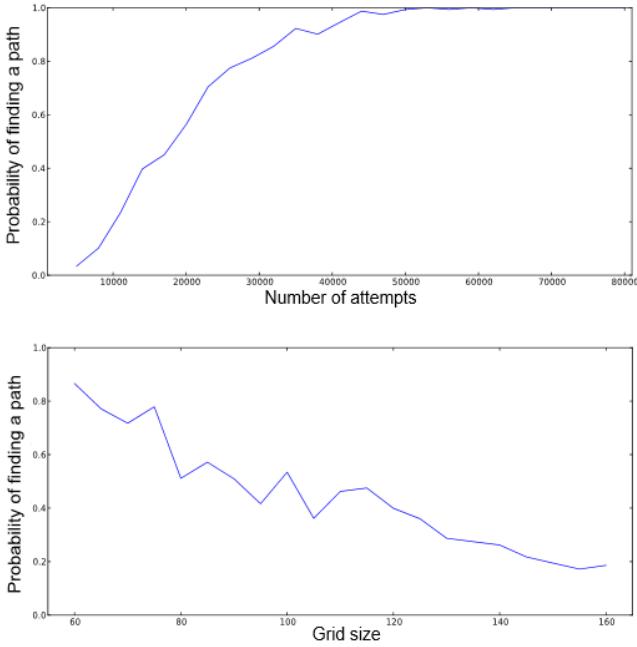


Fig. 4. Performance analysis of Tremblay *et al*'s [17] RRT when running on a Metal Gear Solid level [18].

the player could be, as can be seen in figure 6. Occupancy or Influence Maps do not produce a path instead they show the probability of the player being in different locations across the map [19], [21]. The enemy then moves to investigate that area reducing the probability of the player being there. Similarly, Miles and Louis [21] also used influence maps. While their example is specific to *Real Time Strategy* (RTS) games, like Isla they used Occupancy Maps. They used them as a base for A* path-finding instead of A* using the map itself for path-finding.

D. Foregrounding and Visualising AI

Most modern digital games make use of AI. However, it is rarely foregrounded or visualised in those games. Treanor *et al* [22] say that often the design of AI in games is to fit the game and complement gameplay. These AI are supporting the gameplay rather than being central to it.

Treanor *et al* [22] surveyed many games that foreground or visualise AI in different ways. From this, they propose a series of design patterns for foregrounding AI in digital games. The two design patterns relevant to this project are “AI as a Villain” and “AI is Visualised”. They describe the first pattern as having the AI try to not outright defeat the player. Instead, it is designed to create an experience like in the game Alien Isolation [22], [23]. In Alien Isolation the enemy AI hunts the player. This is foregrounding as the player must observe the AI and learn how to avoid it. There is also some visualisation as the player has a scanner that informs them of the enemy’s position.

This paper uses the “AI as a villain” pattern as each enemy NPC has their path-finding visualised around them. The players can consider this when exploring a level so they do not

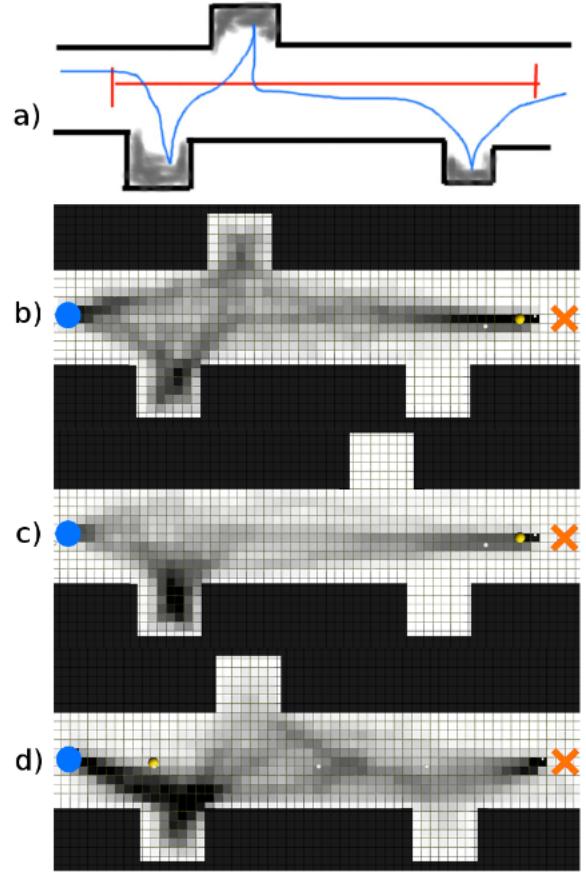


Fig. 5. Heat maps of a single level where the design has been changed each time [17].

get attacked by the enemy. The use of this pattern also aims to have an NPC that creates an experience rather than one that always finds the player, similar to Alien Isolation [23], [22]. While the player likely does not want to be caught by the enemy NPC they may want it to chase them so they can learn its patterns or lead it away from other enemies to make it easier to attack.

The second relevant design pattern is “AI is Visualised”. This is where there is a visual representation of the AI’s state or decision making in the game [22]. Most games hide this from the player but this design pattern visualises it making it mechanic. The example given by Treanor *et al* [22] is the game Third Eye Crime. Third Eye Crime is a game that follows the “AI is Visualised” design pattern [19], [20]. The game uses probabilistic object tracking through Occupancy Maps. As the enemy moves around the map it removes areas where the player is not from the Occupancy Map [19]. Generally, stealth games involve avoiding enemies. This design encourages the player to trigger the mechanic, allowing them to use the visualisation to mislead and avoid the enemy [19], [20].

This pattern is relevant to this project as the enemy NPCs have RRT path-finding visualised around it allowing the player to see where the enemy is searching and decide how to overcome or outsmart it.

While Haworth *et al* [14] do not visualise an AI decision-



Fig. 6. A screen-shot from Third Eye Crime [20].

making process they do visualise the possible decisions available to the player in a game on a tree structure. They research visualising decision trees in a game to see what effect it had on gameplay and the analytical reasoning of children. Their study does not come to any definite conclusions. However, their results suggest that the trees aided players as in the later levels of the game the children without the visualised decision tree struggled to beat the game. However, they noted this could also be due to unbalanced difficulty in the later levels. This makes the usefulness of the visualised tree questionable in this example.

A potential issue with this study is that Haworth *et al* [14] only tested the tree on a simple 2-Dimensional maze game for school children. Of these children, only a few had experienced playing digital games before. This could mean that the data is not relevant for 3D games or games available to buy on the market. In contrast, Isla's [19] visualised Occupancy Maps are in the game Third Eye Crime which is available for purchase on Steam, IOS and Android [19], [20].

Like Haworth *et al* [14], Bauer *et al* [13] also research visualising tree structures [13]. However, they used RRT which is an AI technique.

Another use of visualisation, mentioned in earlier sections, is in game design. Often to check player behaviour in player testing or to aid the design of levels [24], [13], [17], [9].

E. Exploring Game Environments

One method of guiding players through games is to use wayfinding. Wayfinding in games is often architectural differences or visual cues in the environment that guide the player to an area of interest [25], [26]. Wayfinding cues are often subtle cues in the environment such as ivy growing up a wall to suggest the player can climb there.

The intention of visualising path-finding in this project is not to guide the players. However, like Si *et al* [25] it observes how players navigate and explore levels and whether, like the presence of wayfinding cues, it affects player behaviour. Moura and Bartram [27] investigate the effects of different wayfinding cues on players. They looked at methods used in AAA games and mimicked them in their own game. Their results show that the absence of wayfinding cues was obvious to players. In contrast, the version with wayfinding cues does

not have enough cues to sufficiently guide the player. These results suggest that way-finding cues alone may not be enough to guide the player. They concluded that there is a need for more research as the results were inconclusive.

While this project focuses on enemy NPC path-finding this could be another interesting application of path-finding and visualisation. The path-finding could remain hidden from the player, as it normally is in digital games, but way-finding cues could be placed based on the path. This could then subtly guide the player through the game.

Si *et al* [25] investigated how players explore virtual environments. While their experiments were specific to Real Time Strategy (RTS) games the results may apply to other game types. Si *et al* [25] say that three common types of spatial exploration are; environment mapping, bonus item collecting and location/landmark discovery. The relevant exploration type for this project is spatial mapping. Firstly, as it logs what the enemy NPC is doing. Secondly, as it is the player behaviour that is being measured by the logging tool in the software.

A paper looked at in section III-D was Haworth *et al*'s [14] study. While they do not look at player exploration the game they used involved a map where participants had to explore a maze. Participants who had the decision tree visualisation found it easier to navigate the maze. While Moura and Bartram [27] suggested way-finding alone was not enough to guide a player this suggests that visualisation could aid the exploration process [14].

IV. METHODOLOGY

The research question addressed in this project is: how does visualising path-finding in an NPC affect how players explore a game level? The hypotheses drawn from this question are listed in subsection IV-A.

An A priori power analysis was performed to determine how many participants were required for an effect size of 0.4. 0.4 was chosen as a larger percentage would have a more significant impact on gameplay. An effect size of 0.3 would have also found a large enough difference to impact gameplay. However, a power analysis for an effect size of 0.3 found that 90 participants would have been required, which was not feasible in the given time frame of this study.

The results showed that a minimum of 52 participants was required. As not all datasets were complete further participants were tested resulting in 62 sets of results. The play-testing was completed by participants both online and in person to reach the required sample size. Both participant types were given the same instructions and questionnaire.

Of the play-tests done in person, a large majority of the players were students on game development-related courses, the potential issues relating to this are discussed in section VIII.

TABLE I
SUBREDDITS USED FOR PLAY-TESTING

Subreddit	Subject
r/SampleSize	Finding participants
r/UniUK	Thread on finding participants
r/gamedev	Game Development
r/Unity3D	Game Development
r/playmygame	Finding game play-testers
r/playtesters	Finding game play-testers

The rest of the play-tests were done online through Reddit and Twitter. Many of the subreddits it was posted on were related to gaining participants and play-testers. This could have affected the results as only a certain type of person would go online looking for surveys and play-tests to complete. Again some of the subreddits listed were related to game development and therefore the feedback given was related to the state of the game, not the path-finding.

While 21 play-tests were completed online 10 of them have incomplete or invalid data. Therefore, those participants results were filtered out of the final dataset more tests were done in person to reach the sample size, the filtration of the data is discussed in more detail in section VI.

TABLE II
PLAY-TEST VARIATIONS

Play-test Variations	RRT Used	Path-finding Visualised
Variation 1	X	X
Variation 2	X	
Variation 3		X
Variation 4		

A. Hypothesis:

Table III shows the hypotheses that are tested in this experiment. The methodologies that are used to test these hypotheses were play-testing and a questionnaire. This required human participants for both parts. Ethics approval for this methodology was gained from Falmouth University's Research Ethics Board.

The game the path-finding variations have been tested in is 'Gates of Amenti' a 3D Metroidvania game which has been designed with a focus on exploration. A Metroidvania game is an action-adventure game with a focus on exploration to discover new areas and power-ups [28].

Players were given one of the game variations to play and then asked to complete a questionnaire on their experience. The game also logged the player's position at regular intervals to calculate what percent of the level they explore. How long a participant spent exploring the level was also logged.

B. Play-testing

There are four variations of the game that can be seen in table II. A random number generator was used to randomly select a game version for each participant.

During the play-tests players were randomly assigned one of the four variations of the game. The players were asked to play that version for as long as they wanted. While playing the software logged the time the player spent in the level per life and what percent to the level they explored. The percent explored was calculated by recording how many doors the player walked through as the game requires players to unlock doors to progress. This data is then exported into a .CSV. The .CSV is then analysed using the R statistical package² in R Studio³.

The primary statistical test used was a T-Test alongside correlations.

After completing a play-test of the game participants were asked to complete a questionnaire on their thoughts on parts of the game and Yee's taxonomy to determine their player type.

C. Questionnaire

Alongside play-testing, participants were also asked to fill out a questionnaire on the game online using Google Forms. Nordin *et al* [29] say that questionnaires are vital for understanding how players feel when playing digital games [29], [30]. They can also help give uniformity and consistency to the data gathered from participants [30].

Questionnaires are also beneficial as they can prompt players to give answers they may not have given spontaneously. The two options here are to either create a questionnaire specifically for the experiment or to use an existing one. There are a wide variety of questionnaires that already exist to measure players experiences in play testing [29], [31]. These come with the benefit of being more likely to be thoroughly tested such as the *Immersive Experience Questionnaire* (IEQ) which uses Likert scale responses or Yee's taxonomy [29], [31], [32], [33].

However, Nordin *et al* [29] say there are many issues with using pre-existing questionnaires. Firstly, many of these questionnaires are not readily available. Another issue is that not all questionnaires have been thoroughly checked for validity. There is also the potential issue of a researcher not fully understanding the questions put forward by another researcher or they may not understand what data that question is intended to get.

Another potential issue with the questionnaire is self-report bias. Some of the hypotheses being tested relate to the player being confused or not understanding the visualisations. Players are unlikely to admit to not understanding the game making the data gained invalid.

FIND REF

Most of the hypotheses require quantitative data from the play-tests. However, some require qualitative data so a questionnaire was necessary. In addition to the hypotheses based questions, there were also questions to determine the participants player type, as some players are more interested in exploration in games than others and that could influence the results. Firstly Bartle's Taxonomy [34] was looked at,

²R Available at: <https://www.r-project.org/>

³R Studio Available at: <https://www.rstudio.com/products/rstudio/download/>

TABLE III
HYPOTHESES

	Hypothesis	Null Hypothesis	Data Collection Source
1	Visualising path-finding has an effect on the percent of the level the participant explores.	Visualising path-finding has no effect on the percent of the level the participant explores.	Game Data
2	In comparison to RRT visualisation, Unity NavMeshes visualisation has an effect on the percent of the level the participant explores.	In comparison to RRT visualisation, Unity NavMeshes visualisation has no effect on the percent of the level the participant explores.	Game Data
3	Using RRT path-finding has an effect on the percent of the level the participant explores.	Using RRT path-finding has no effect on the percent of the level the participant explores.	Game Data
4	Using NavMesh path-finding has an effect on the percent of the level the participant explores.	Using NavMesh path-finding has no effect on the percent of the level the participant explores.	Game Data
5	Visualising path-finding has an effect on the length of time the participant spends in the level.	Visualising path-finding has no effect on the length of time the participant spends in the level.	Game Data
6	Using RRT path-finding finding has an effect on the length of time the participant spends in the level.	Using RRT path-finding finding has no effect on the length of time the participant spends in the level.	Game Data
7	Visualising Unity NavMeshes has an effect on the length of time the participant spends in the level.	Visualising Unity NavMeshes has no effect on the length of time the participant spends in the level.	Game Data
8	Visualising RRT path-finding has an effect on the length of time the participant spends in the level.	Visualising RRT path-finding has no effect on the length of time the participant spends in the level.	Game Data
9	Visualising path-finding has an effect on the number of times the player died.	Visualising path-finding has no effect on the number of times the player died.	Game Data
10	Using RRT path-finding has an effect on the number of times the player died.	Using RRT path-finding has no effect on the number of times the player died.	Game Data
11	The visualisation of Unity NavMeshes is comprehensible to players.	The visualisation of Unity navmeshes is not comprehensible to players.	Questionnaire Data
12	The visualisation of RRT path-finding is comprehensible to players.	The visualisation of RRT path-finding is not comprehensible to players.	Questionnaire Data
13	The comprehensibility of the visualisation of RRT path-finding is no different to Unity NavMesh visualisation to players.	The comprehensibility of the visualisation of RRT path-finding is different to Unity NavMesh visualisation to players.	Questionnaire Data

this taxonomy appears to be widely used but is not validated. Instead Yee's player taxonomy Yee's questionnaire for player taxonomies is used in combination with questions based on the hypotheses that require qualitative data.

V. SOFTWARE DEVELOPMENT

The software used to develop the play-testing software was Unity 5.6.3f1³ and Visual Studio Community 2017 15.5.4⁴. The analysis was carried out and the graphs were produced in R version 3.4 in R Studio.

The base game 'Gates of Amenti' was developed with the student-led games studio Bears are OP⁵. The game was developed over the course of seven months using Agile and Scrum project management techniques. The game was still in development while being adapted for use in the play-testing so was unfinished. This is a potential issue looked at in section VIII. For use in the play-testing for this experiment the Prototyping lifecycle method was used [35]. Prototyping was used as a majority of the game itself had already been

developed. Therefore, only a few new features required implementation. These features were; RRT path-finding, path-finding visualisation, data recording and data exporting. A basic version of these features were added to the game and then improved on until the game was suitable for play testing. In this case suitable means that all features worked and players could play through the level with minimal glitches.

The first feature implemented was the RRT. This was developed in a separate scene in the game at first. The first iteration of the RRT built an RRT in 2 dimensions in a cube. This was to test the implementation of RRT before trying it in a more complex environment. In the game, the basic data recording functionality was added early on but the ability to export it and view it as a part of the UI was added near the end of the development cycle. The first iteration of the NavMesh visualisation was implemented using Unity's low-level graphics library, GL⁵. This was only used for testing as it could only be observed using the in-game camera, it was not visible in screen view. This was a test to see how the navmesh could look. This was remade to use Unity line renderers to draw the polygons of the NavMesh, as can be seen in figure 10. The RRT was then visualised in a similar manner using line renderers to draw the branches.

³Unity 5.6 Available: <https://unity3d.com/get-unity/download/archive>

⁴Visual Studio Community 2017 Available: <https://www.visualstudio.com/downloads/>

⁵Gates of Amenti: <https://bearsareop.itch.io/>

⁵Unity GL Library: <https://docs.unity3d.com/ScriptReference/GL.html>

A. Software Testing

To test the play-testing software was working as required a simple bot was developed. All the bot needed to do was move forward to test whether the doors registered when walked through and then whether the timer and data export worked.

1) *Doors*: The first bot was to test whether the doors recorded whether the player had moved through them. Whether a door has been walked through is used to determine what percent of the level the player explored. Figure 7 shows an example of the code used in the bot to disable the door trigger collider after use. The test for the doors was a bot moving through the door and checking that the GameState class recorded it.

```

18     private void Start()
19     {
20         doorCollider = this.GetComponent<Collider>();
21     }
22
23     void OnTriggerEnter(Collider collision)
24     {
25         if (collision.gameObject.name == "Player")
26         {
27             doorWalkedThrough = true;
28             doorCollider.enabled = false;
29         }
30     }

```

Fig. 7. A segment of the DoorState class that updates the door when the player walks through.

2) *Timer and Data Export*: The second bot was to check whether the software could successfully export the necessary data to a .CSV file. This bot is the same as the door testing bot. Figure 8 shows an example of the data exported from the game.

A	B	C	D	E
1	Player number	Pathfinding Visualised	RRT Used	Time in Level
2	0	True	True	98.78061
				0.3809524

Fig. 8. An example of the data exported from the game.

3) *Visualisations*: The final test was whether the pathfinding visualisation worked as intended. This does not require a bot it can be seen tested by observing the scene in Unity. Figure 9 shows the visualisation of the Unity navmesh working in the engine. Figure 10 shows the visualisation of the RRT path-finding working in engine.



Fig. 9. The navmesh visualisations shown both in editor and in scene.



Fig. 10. The RRT visualisations shown both in editor and in scene.

VI. DATA COLLECTION AND FILTERING

All the data used either came from the game's exported data or from the questionnaire. Play-testing gave 107 datasets from 62 participants. However, as not all participants gave complete datasets 10 datasets have been removed leaving 97 datasets from 52 participants.

When the player dies in-game the game resets, this lead to a number of results having 0 percent explored and low play times. As these were not proper play-tests the 11 instances of this were removed from the dataset leaving 86 datasets. Many players also died within the first few minutes of playing, giving a play-test with a low time and exploration amount, the 34 instances of this were also removed from the dataset. Removing these left 52 datasets; one per player. There is a potential issue here where the player may not explore and area again if they have already explored it before dying. However, data from playthroughs where the player died in the first 5 minutes would have been more likely to have had an effect.

VII. ANALYSIS AND INTERPRETATION

All the data analysis was conducted using R in R Studio. The results gathered can be seen in Table IV. Figure 11 shows an example of the code ran in R, it shows a correlation and a T-Test that have been run.

```

> cor(PF_VisData$Percent_Explored,PF_VisData$RRT_Used)
[1] 0.5500408
> t.test(PF_VisData$Percent_Explored~PF_VisData$RRT_Used)

Welch Two Sample t-test

data: PF_VisData$Percent_Explored by PF_VisData$RRT_Used
t = -3.2666, df = 20.61, p-value = 0.003752
alternative hypothesis: true difference in means is not equal to 0
95 percent confidence interval:
-0.4918121 -0.1089206
sample estimates:
mean in group FALSE mean in group TRUE
0.4139194 0.7142858

```

Fig. 11. An example of the R code used for calculating T-Tests and Correlations.

Table IV shows the correlations and P-Values from the T-Test results calculated using R. In a majority of cases there was insufficient evidence to reject the null hypothesis. However, there are some cases that have a P-Value of less than 0.05 and are thus statistically significant.

A. RRT and the Percent of the Level Explored

The first significant correlation is a small positive correlation of 0.2807 between the percent of the level explored and the

TABLE IV
T-TEST AND CORRELATION RESULTS

Independent Variable	Dependent Variable	Correlation	T-Test - P Values
Visualising Path-finding	Percent Explored	-0.1766742	0.2009
Visualised Path-Finding Methods	Percent Explored	0.5500408	0.003752
RRT Used	Percent Explored	0.2807048	0.04425
Non-Visualised RRT Use	Percent Explored	0.2807048	0.04425
Visualised RRT	Percent Explored	0.1697141	0.4229
Visualised NavMesh	Percent Explored	-0.4893995	0.01176
Visualised Path-finding	Time	0.0002296794	0.9987
RRT Used	Time	0.06559258	0.6445
Visualised RRT	Time	-0.0153404	0.9384
Visualised NavMesh	Time	0.001491802	0.9943
Visualised Path-finding	Understandable Visuals	0.1627247	0.2731
RRT Used	Understandable Visuals	0.1910156	0.3341
Path-finding Visualised	Logical Enemy Movement	-0.2728879	0.06224
RRT Used	Logical Enemy Movement	-0.01419318	0.9234
RRT Used	Deaths	-0.2656382	0.05917
Visualised Path-finding	Deaths	0.318452	0.01833

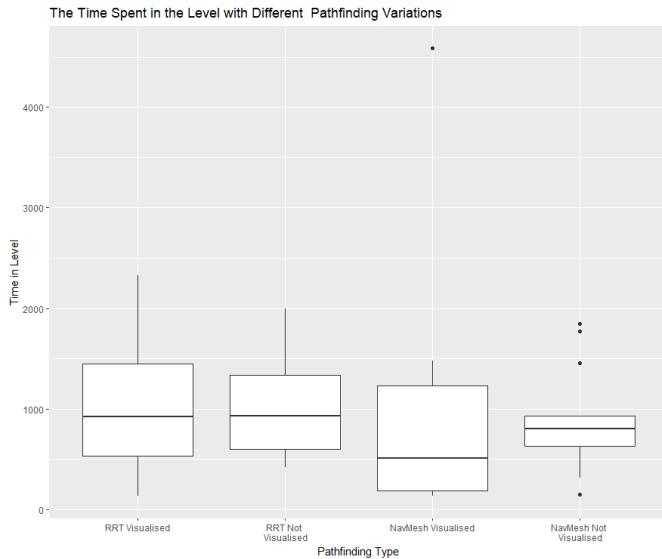


Fig. 12. Box and Whisker plot of the time spent in the level with the 4 game variations.

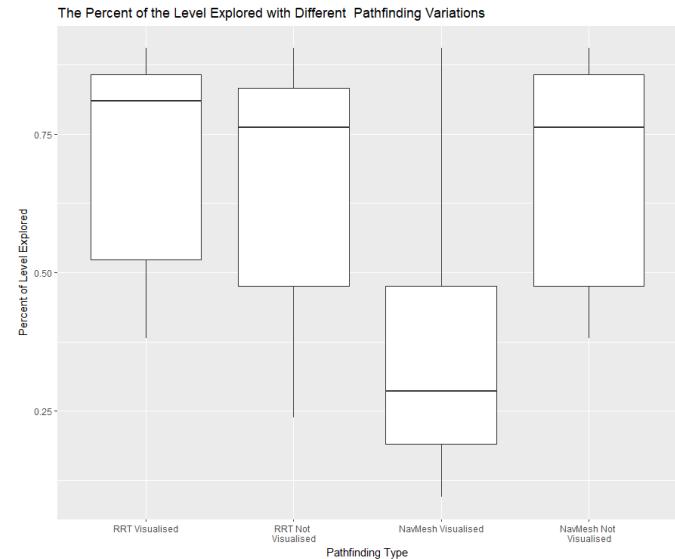


Fig. 13. Box and Whisker plot of the percent of the level explored with the 4 game variations.

use RRT path-finding. This suggests that players explore more in the RRT variations.

The graph in figure 13 shows that the percent explored between the two RRT variations are both close, with the not visualised variation being slightly lower.

There is no significant correlation between the RRT being visualised and the percent which would suggest that visualising the RRT does not affect the percent of the level explored. However, when just looking at visualised path-finding there is another significant correlation between the type of visualised path-finding used and the percent of the level explored. There is a strong positive correlation of 0.55 which again suggests

that players explore more when RRT is used in comparison to NavMeshes. Another RRT related significant correlation is between non-visualised RRT and the percent explored which has a positive correlation of 0.281.

There is also no significant correlation between RRT use and the time spent in the level. This suggests while the players explored more when the RRT was used they do not spend more time in the level.

Some participants commented that they thought the RRT was leading somewhere and followed it through the level or went to it when they saw it. However this only accounts for when the RRT is visualised. Another possibility is the RRT

itself was spawned in a square and often did not fill a room which may encourage players to move around the edge of the room rather than down the middle they may have been more likely to find hidden doors increasing their exploration percentage.

Another reason for this could be that in the play-testing software each RRT was limited to a single room as enemies could not follow players out of rooms this may have allowed them to avoid combat, or make combat faster, allowing them to explore more.

B. NavMesh Visualisation and the Percent of the Level Explored

The second case was a negative correlation of -0.4894 between the percent explored and the NavMesh path-finding being visualised. This suggests that players explored less when the NavMesh was visualised. As many play-testers were game development students using Unity they may have known what the visualisation was of the NavMesh was. This may have helped them find a quicker route through the level or lead them to avoid rooms with enemies in. Another reason could be that seeing the pathfinding showed them the possible pathways aiding them in finding a more direct path through the level

C. Visualised Path-Finding and Player Deaths

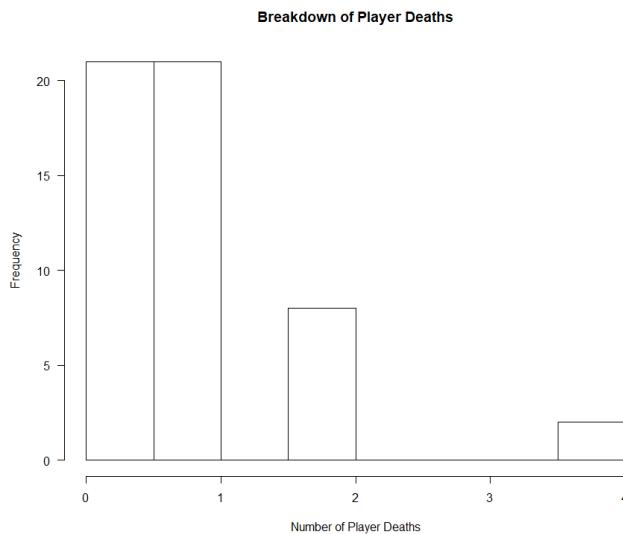


Fig. 14. Histogram of the frequency of the number of player deaths.

Another significant correlation is the positive correlation between the visualised path-finding and the number of player deaths. This means that players with the variations with visualised path-finding died more than players without it. One reason for this could be the player being distracted by the visualisation and therefore did not focus on enemies.

In the RRT variation, the tree visuals are only in areas where there are enemies, as some players claim to move to the RRT whenever they saw it they could have been more likely to find enemies than players without the visualisation.

As can be seen in the graph in figure 14 an equal number of players died 0 or 1 time. The one death could likely be due to the player not knowing how to play the game and learning and may have skewed the results. A smaller number of players died 2 or 4 times.

There is no correlation or statistical significance between the questionnaire data and the exported game data. This could potentially be due to poorly worded questions or players not understanding what the visualisation, as mentioned in more detail in section VIII. Many players claimed to understand the path-finding visualisation. However, the comments after playing suggested that they do not as many believed it was an aesthetic choice.

Apart from the cases above, there was insufficient evidence to reject the null hypothesis..... This suggests that neither of the visualisations was more understandable than one another to the player. Also, neither the change in path-finding method or the visualisation affected the time spent in the level even when the percent explored increased.

Figure 12 shows that the times for all four variations were close. However, unlike figure 13 there are a number of outliers on the NavMesh variations. Firstly, on visualised NavMeshes, there was an outlier with over 4000 seconds spent in the level where a majority of the other play-tests for all four variations were under 2000. Finding this outlier in the play-test data showed that this player has a very high play time with a low exploration percent. As this was a remote player this suggests that the player just launched the level and left the game running without playing. Though the player did die so they may have made some attempt to play.

VIII. POTENTIAL ISSUES AND FUTURE WORK

While the methodology of the study worked, in this case, there were many areas that could be improved in future work to improve the quality of the data collected. This section identifies a number of weaknesses in this study and how they could be improved on.

A. Play-testing Game

A first potential issue with the play-testing is that the game was not specifically designed for this paper. While the game is a Metroidvania game with a focus on exploration a few participants noted the enemies in the game were very aggressive and a majority of players died at least once which could have affected their desire to explore. In a future study, a game would either be designed specifically for the play-testing or altered more to suit the study.

B. Participants

Another issue with using the game ‘Gates of Amenti’ is that many of the play-testers were game development students who have play-tested other levels of the game or seen the game trailer during the university show and tell day. This meant that they could have been looking for things they have previously seen in the trailer as opposed to exploring or being affected by the visualisation.

In future work the player would also be selected randomly and from a larger pool of people. In this study, a majority of players were students studying a game development course.

C. Performance Issues

A second issue was the RRT variations of the game were more resource intensive to run than the Navmesh versions. This lead to a slight frame rate drop at the start of the game. Many of the play-tests used Falmouth Games Academy's computers which were capable of running both versions well. However, some play-tests were done remotely and therefore their computer specification and therefore the performance of the game is unknown. In future studies, this would be combated by either doing all the play-tests in one location ensuring everyone uses similar computers or to expand on the games data collection to include the frame rate or expand the questionnaire to include player's computer specifications.

D. Visualisation

The visualisation itself was also potentially an issue as many players do not know what it was or they assumed it was part of the games aesthetic and ignored it. However, visualisation could still affect the player even if they do not understand the visualisation. Many participants suggested they do not understand the RRT visualisation but the results still showed their exploration was effected.

However, as many players do not understand the visualisation it suggests that the questionnaire should have explained it to some extent to get better answers. This also combined with the issue of self-report bias as many players answered the questionnaire saying they understood the visualisation but when spoken to afterwards it became apparent they do not.

While the RRT visualisation worked as intended in future work an area to explore would be increasing the RRT size. In this experiment, the RRT was performance heavy so in future work the RRT could be made more optimised and then the RRT can be increased in size and clustering could be used to filter the tree.

E. Collected Data

While the data collected from the game was usable it could be refined to get more data that would allow for more in-depth analysis. For example, currently the game only records how many doors the player walks through, an improvement on this would be to record what doors they walked through to create heat maps and perform more statistical analysis to see whether players explore differently in the different game variations or if the player's died in similar locations. Another issue with the collected data is that with the questionnaire relied on players being honest. There could have been self-report bias where players gave different answers, for example, players were asked if they understood the visualisation and they were unlikely to admit to not understanding. This could be addressed in future work by relying more on in-game data and wording the questions differently.

F. Random Nature of RRT

As RRT randomly selects where to place its node each player would have a different RRT. This affects the enemy movement as it leads them to move in different ways. Also, some areas had clutter objects such as crates in them, if the path went through the crates they could be knocked over causing the enemy to have to move a different way and affecting how the player can move. While A* always find the shortest path between two points it is very unlikely that players and enemies will be in the exact same spot and thus unlikely that players will get the same path from A*.

IX. FUTURE WORK

The most unexpected significant result found in section VII is the NavMesh visualisation decreasing the percent of the level explored. Future research on this subject could research that in more detail to find a more definite reason for why that happened.

Also, as section VIII mentions, there were issues with the game used in this study, as future research would require a different or more complete game it could also give interesting data to look at pathfinding in more complex environments and other game genres such as stealth games.

Another area that could be explored in future work the RRT visualisation and variations on it. As the use of RRT in this study had numerous small RRTs with less than 500 nodes another area to research could be comparing having a RRT per room to a RRT per level. Another area would be to try varying the number of nodes in the RRT and for larger RRT variations clustering methods such as the one mentioned in section III-C that Bauer and Popovic used to make their use of RRT more legible.

X. CONCLUSION

In conclusion, while the use of RRT is more frequent in robotics than digital games its use appears feasible in this project. Its past use in game design tools shows that clustering can make the output understandable to the user. However, the need of optimisations such as RRT* or the use of A* may arise to produce a shorter path or to find any path.

Visualisation and foregrounding of AI have been successfully used before suggesting that it can be used here. Finally, previous studies have looked at way-finding and player exploration. These suggest that environmental factors in digital environments do have some effect on player exploration.

The results found that a number of significant results which means that to some extent the pathfinding method and visualisation effects the player's exploration in a level. Like many of the papers reviewed in section III this could be applied in game design. Level designers could take it into account what type of pathfinding will give the result they want as different results may be wanted for different genres or even different sections of the game. In this study visualising the pathfinding to the player often resulted in the player being unsure of what the visualisation was so more research may be required to use the visualisations in video games rather than just designing them.

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APPENDIX A
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APPENDIX B
FIRST APPENDIX: REFLECTIVE REPORT

While I am pleased with the final paper I produced there are many parts to this paper and the software that I could have improved on.

SMART

A. Play Testing

The first issue was play-testing I vastly underestimated how long this would take and left it too late. This lead to me struggling to get enough participants and resorting to getting more online. One way to address this in the future would be to run a larger pilot study. In this paper the pilot study consisted of 4 players, one for each variation. These all took around 20 minutes however in the actual study player took up to an hour.

B. Data Collection

Another area that I would improve on in the future would be how the data is collected and what data is collected. One issue I had with the data collected in this experiment is that the data from the game and the data from the questionnaire were both separate

* Play testing takes a long time * Data logging needs to be better

C. Time Management