



IIT ROORKEE



NPTEL ONLINE  
CERTIFICATION COURSE

# Charging Infrastructure

## Lecture-6

### Revisiting Diode Bridge rectifier-II

Dr. Apurv Kumar Yadav  
Department of Electrical Engineering

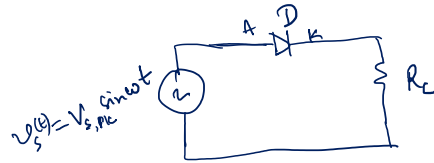


1- $\phi$  input, 1- $\phi$  AC-DC Converter  
3- $\phi$  input, 3- $\phi$  AC-DC Converter

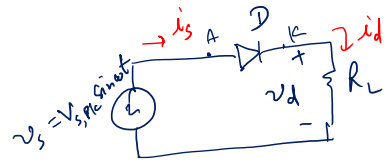
1- $\phi$  Diode Bridge Rectifier (uncontrolled Rectifier)

(i) Half-bridge Rectifier (ii) full-bridge Rectifier

1- $\phi$  Half-bridge rectifier with Resistive load



'D' turns on when the ' $v_s$ ' is in the positive half; it is reverse biased when ' $v_s$ ' is in the negative half cycle.



$$v_d = \begin{cases} v_s, & v_s > 0 \\ 0, & v_s < 0 \end{cases}$$

average value of  $v_d$ ,  $V_{d,avg} = \frac{1}{T} \int_0^{T/2} (V_{s,pk} \sin \omega t) \cdot dt$

$$= \frac{V_{s,pk}}{\omega T} \left[ -\cos \omega t \right]_0^{T/2}$$

$$= \frac{V_{s,pk}}{\omega T} \left( -\left( \cos \frac{\omega T}{2} - \cos 0 \right) \right)$$

$$= \frac{V_{s,pk}}{2\pi} \left( -(\cos \pi - \cos 0) \right)$$

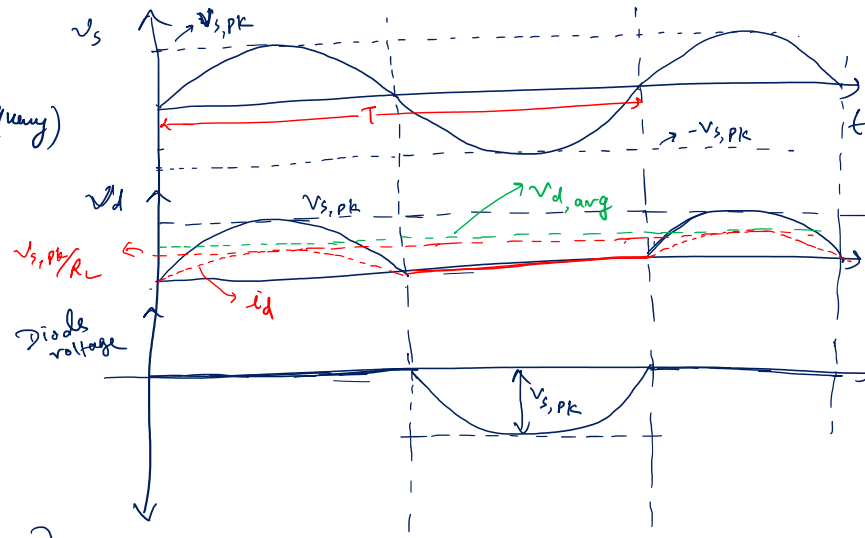
$$= \frac{V_{s,pk}}{2\pi} \left[ -(-1 - 1) \right]$$

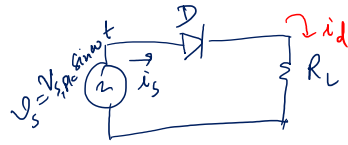
$$V_{d,avg} = \frac{V_{s,pk}}{\pi}$$

$$\omega = 2\pi b_s \quad (b_s = \text{supply frequency})$$

$$\Rightarrow T = \frac{1}{b_s}$$

$$\Rightarrow \omega T = 2\pi$$



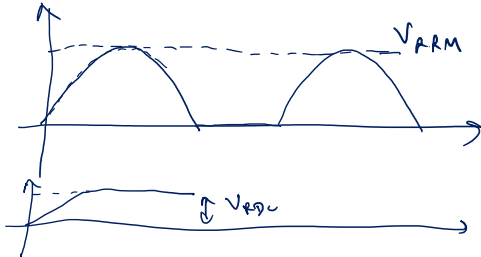


$$i_s = \begin{cases} i_d & ; v_s > 0 \\ 0 & ; v_s < 0 \end{cases}$$

## Diode selection

### v/g ratings

- Peak repetitive reverse voltage ( $V_{RRM}$ )
- Peak reverse voltage
- Reverse voltage or DC blocking voltage



### Current ratings

- Average forward current,  $I_{F(av)}$
- Average rectified forward current
- Repetitive peak forward current,  $I_{FRM}$
- Non-Repetitive Peak forward current,  $I_{FSM}$
- $I^2t$  rating

$I \rightarrow$  RMS value of forward current  
 $t \rightarrow$  the time period of the pulse

## Diode selection

### voltage rating

$$\rightarrow \text{Peak repetitive reverse voltage } (V_{RRM}) = V_{s,pk}$$

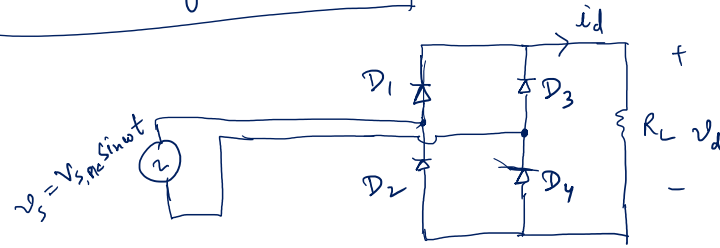
$$\rightarrow I_{F,avg} = \frac{V_{s,pk}}{\pi R_L}$$

$$\rightarrow I_{F,rms} = \sqrt{\frac{1}{T} \int_0^{T/2} \left( \frac{V_{s,pk} \sin \omega t}{R_L} \right)^2 dt}$$

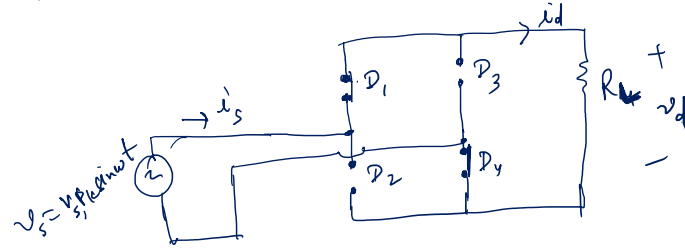
$$I_{F,rms} = \frac{V_{s,pk}}{2 R_L}$$

- The power is being delivered to the resistive load only in positive half cycle
- The output is pulsating in nature
- Average output voltage is proportional to  $V_{s, pk}$  (which is peak of the Applied voltage)
- The current drawn is not continuous

### 1- $\phi$ full-bridge Rectifier



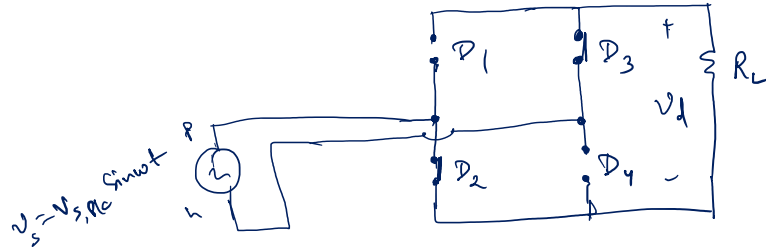
When  $v_s$  is in positive half cycle ( $v_s > 0$ ),  $D_1$  &  $D_4$  gets forward biased,  $D_2$  &  $D_3$  get reverse biased



$$\Rightarrow i_s = i_d$$

$$\Rightarrow v_d = v_s$$

When  $v_s$  is in negative half cycle ( $v_s < 0$ ),  $D_2$  &  $D_3$  is forward biased,  $D_1$  &  $D_4$  is reverse biased



$$v_d = -v_s ; i_s = -i_d$$

$v_s$  is +ve,

$$v_d = v_s$$

$$i_s = i_d$$

$v_s$  is -ve,

$$v_d = -v_s$$

$$i_s = -i_d$$

$$f_s = 50 \text{ Hz}$$

$$\Rightarrow T = \frac{1}{f_s} = 20 \text{ ms}$$

$$\omega = 2\pi f_s$$

$$\Rightarrow \omega T = 2\pi$$

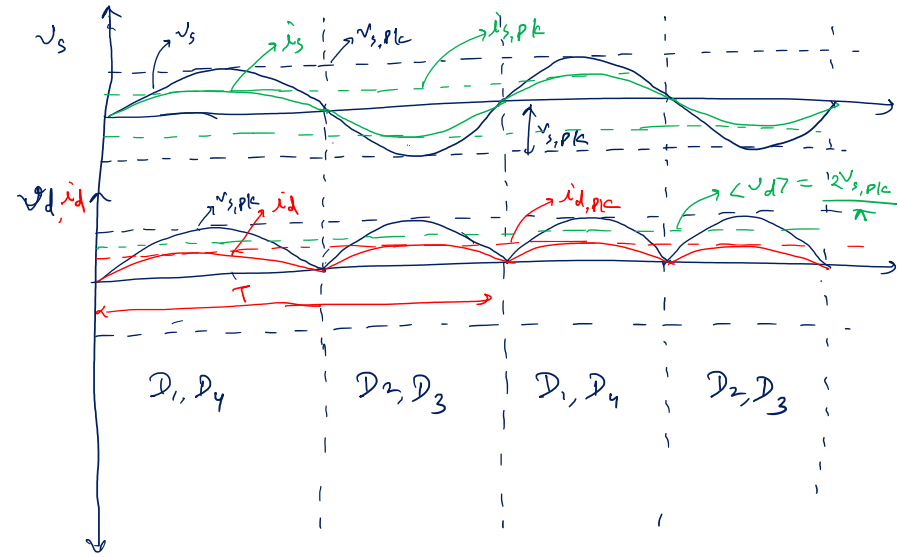
average voltage of  $v_d$ ,  $\langle v_d \rangle = \frac{1}{T/2} \int_0^{T/2} v_{s,pk} \sin \omega t \cdot dt$

$$= \frac{2}{\omega T} \left[ -v_{s,pk} \cos \omega t \right]_0^{T/2}$$

$$= \frac{2v_{s,pk}}{\omega T} \left[ - \left( \cos \frac{\omega T}{2} - \cos 0 \right) \right]$$

$$= \frac{2v_{s,pk}}{2\pi} \left[ - \left[ -1 - 1 \right] \right]$$

$$\langle v_d \rangle = \frac{2v_{s,pk}}{\pi}$$



## Diode Selection

$$V_{RRM} = V_{d,PK} = V_{s,PK}$$

$$\text{Average current, } I_{F(avg)} \quad (D_1, D_4) = \frac{1}{T} \int_0^{\tau/2} \frac{V_{s,PK} \sin \omega t}{R_L} \cdot dt$$

$$= \frac{V_{s,PK}}{\pi R_L} \tau$$

$$I_{F(avg)} \quad (D_2, D_3) = \frac{1}{T} \int_{\tau/2}^{\tau} -\frac{V_{s,PK} \sin \omega t}{R_L} \cdot dt$$

$$= \frac{V_{s,PK}}{\pi R_L}$$

$$I_F (avg) = \frac{V_{s,PK}}{\pi R_L} \quad (D_1, D_2, D_3, D_4)$$





$$I_{rms} = \sqrt{\frac{1}{T} \int_0^{T/2} \left( \frac{V_{s, pk} \sin t}{R_L} \right)^2 dt}$$

$$I_{rms} = \frac{V_{s, pk}}{2R_L}$$

⇒  $I^2t$  rating using  $I_{rms}$  value  
 $t = 10ms$

### Inference

- The output voltage is uncontrolled, it only depends on input AC voltage ( $V_{s, pk}$ )
- The input current is sinusoidal in nature
- Power is delivered in both the cycle (+ve & -ve) to  $R_L$ .
- The output voltage is not constant, it is rectified DC voltage  
 ⇒  $v_d(t) = |v_s(t)|$

it is continuously varying

# Thank You

