Assignment-2

https://github.com/Madhav-Kanda/MadhavKanda ES215 Assignment2

1. Assumptions:

- The inputs are such that the average is always an integer as the div operation used will always give value in terms of integer.
- The size of the array has been directly stored in the variable value (\$t8) as 100.
- The given array is pre-filled with the values.

MIPS Code

main:

addi \$t0, \$0, 200	# putting the base address of the array in \$t0
lw \$t1, 0(\$t0)	# Highest value of the array = \$t1= array[0]
lw \$t2, 0(\$t0)	#Lowest value of the array = \$t2 = array[0]
addi \$t3,\$0,0	#Highest value Index = \$t3 =0
addi \$t4,\$0,0	# Lowest value Index = \$t4 =0
addi \$t6,\$0,0	#\$t6=sum=0
addi \$t7,\$0,0	#\$t7=index=0
addi \$t8,\$0,100	#t8= value=100

while:

beq \$t7,\$t8,average	
lw \$s2,0(\$t0)	#load the value in \$s2
slt \$s1,\$t1,\$s2	# if \$t1 less than \$s2 then \$s1 will become 1
bne \$s1,\$0, Highest	#if the value of \$s1 not equals 0 then move to Highest
slt \$s1,\$s2,\$t1	# if \$s2 less than \$t1 then \$s1 will become 1
bne \$s1,\$0, Lowest	#if the value of \$s1 not equals 0 then move to Lowest
addi \$t7,\$t7,1	#index+=1
addi \$t0,\$t0,4	#incrementing the index value of the pointer
add \$t6,\$t6,\$s2	#increment sum
j while	

Highest:

add \$t1,\$0,\$s2 # Highest = array[0]

add \$t3,\$0,\$t7	#Highest Index= current index
addi \$t7,\$t7,1	#index+=1
add \$t6,\$t6,\$s2	#increment sum

addi \$t0,\$t0,4 #incrementing index value of the pointer

j while

Lowest:

add \$t2,\$0,\$s2	# Lowest = array[0]
add \$t4,\$0,\$t7	#LowestInd= current index
addi \$t7,\$t7,1	#index+=1
add \$t6,\$t6,\$s2	#increment sum
addi \$t0,\$t0,4	#incrementing the index value
j while	

average:

div \$t6,\$t6,100 #Dividing by 100

jr \$ra

2. Throughput = (Total number of instructions/Time taken to complete the instructions)

Total time = (CPI)*(Instruction Count)/(Clock Rate)

Therefore,

Instruction Count of Program A = (Total time) * (Clock Rate)/(CPI) = $6*(10^9)/6 = 10^9$ Instruction Count of Program B = (Total time) * (Clock Rate)/(CPI) = $5*(10^9)/5 = 10^9$

Total Instruction count = Instruction count of Program A + Instruction count of Program B = 2*(10^9)

Total time taken to complete the instruction count = maximum of (time taken by A, time taken by B) {This is because the processes are being done in different cores and therefore parallel operation} = 6 seconds

Thus, Throughput = (Total number of instructions/Time taken to complete the instructions) = $2*(10^9)/6 = 10^9/3 = 3.33*10^8$ Instructions per second

3. Total time taken = (CPI* Instruction count)/ (Clock Rate)

Given Instruction count of processor X for program $A = 10*(10^9)$ Given Clock Rate of processor X for program $A = 2*(10^9)$ Hz Given avg. CPI of processor X for program A = 3Total time taken by processor $X = 10*(10^9)*3/(2*(10^9)) = 15$ seconds

Given CPI of processor Y for program $A = 7*(10^9)$ Given Clock Rate of processor Y for program $A = 4*(10^9)$ Hz Given avg. CPI of processor Y for program A = 5Total time taken by processor $Y = 7*(10^9)*5/(4*(10^9)) = 8.75$ seconds

Speed up of Program A on processor Y over the processor X = total time taken by processor X = total time taken by processor Y = (15/8.75) = 1.71428

Therefore, Processor Y is 1.71428 times faster than Processor X for program A

4. Total time taken = (CPI* Instruction count)/ (Clock Rate)

Given Instruction count for program $A = 9*(10^9)$ Given Clock Rate for program $A = 1*(10^9)$ Hz Given avg. CPI for program A = 1.5Total time taken by program A on the processor = $9*(10^9)*1.5/(1*(10^9)) = 13.5$ seconds

Total time taken by program A on the newly designed processor = total time taken by program A on the previous processor/4 = 13.5/4 = 3.375 seconds

Assuming that the ISA remains the same and thus the Instruction count for the program remains the same on the new processor design

Thus, 3.375 seconds = (CPI of program A on new design* Instruction count)/(Clock rate of the new processor)

Thus the CPI of the program for the new processor = (3.375* clock rate of the new processor)/ Instruction count = $3.375*(2*10^9)/(9*10^9) = 0.75$

Therefore, the CPI of the program on the new processor design is 0.75 counts per instructions

5. Here to solve the question I have assumed that the dynamic power constitutes 60% and thus the static power constitutes 40% of the total power. This has been taken according to what has been mentioned in the book

Dynamic power is given by the formula = $0.5*C(V^2)*f$ Here C represents the Capacitance, V represents the voltage and f represents the frequency

Static power is given by the formula = VI Given total power = 80W Therefore, according to the assumption, Static power will be 0.4*80 = 32W Dynamic Power will be 0.6*80 = 48W

- a) Now if the frequency gets increased to 5GHz then the Dynamic Power will become 5/2 times the current dynamic power as the dynamic power is directly proportional to the frequency. Since the earlier frequency was 2 GHz thus the new value will be 5/2 times the current value as it has increased to 5 GHz thus the value of the dynamic power is: 48*2.5 W = 120 W
- b) Now the operating value of the voltage drops to 2V.
 Static power = VI = 32*(2/5) = 12.8W
 Dynamic power = 0.5*C(V^2)*f = (48*(2/5)^2) = 7.84W
 Overall power consumption = static power + dynamic power = 12.8W +7.84W = 20.64W

Fraction of static power in the total power = static power/total power = (12.8/20.64) = 0.6201

Grace Question

1. The pre-processor, compiler, and assembler generated files of each of mips and x_86 have been stored in the folders named mips and x_86 respectively.

Observations:

- .i file for mips (51 kb) is greater than that for the x86 files(48 kb) (Pre-processor)
- .o file for mips(2.32 kb) is less than that for the x86 files(2.72 kb) (assembler)
- .s files for mips(3.73 kb) is greater than that for x86 files(2.69 kb) (compiler)
- .out file for mips(255 kb) is significantly greater than x86 files(49 kb) (Binary)

Github link: https://github.com/Madhav-Kanda/MadhavKanda_ES215_Assignment2