

to Detect Objects

## Exp No: 15:- Implement a YOLO Model

### Aim:-

To implement and understand the YOLO (You only look once) model for real time object detection in images.

### Objectives:-

1. To understand the working of YOLO architecture for object detection
2. To detect & localize multiple objects in an image simultaneously
3. To apply pre-trained YOLO weights on a sample dataset or image
4. To visualize bounding boxes & confidence scores.

### Algorithm:-

1. Import YOLO pre-trained model (YOLOv3)
2. Load test images for detection
3. preprocess image (resize, normalize)
4. perform object detection using YOLO model
5. Draw bounding boxes & labels on detected objects.
6. Display and analyze output.

## Pseudo Code:

Load YOLO pre-trained model

Load class labels

For each image:

    preprocess (resize, normalize)

    pass through YOLO model

    Get bounding boxes, confidence, class ids

    Draw boxes & labels.

Display detected image

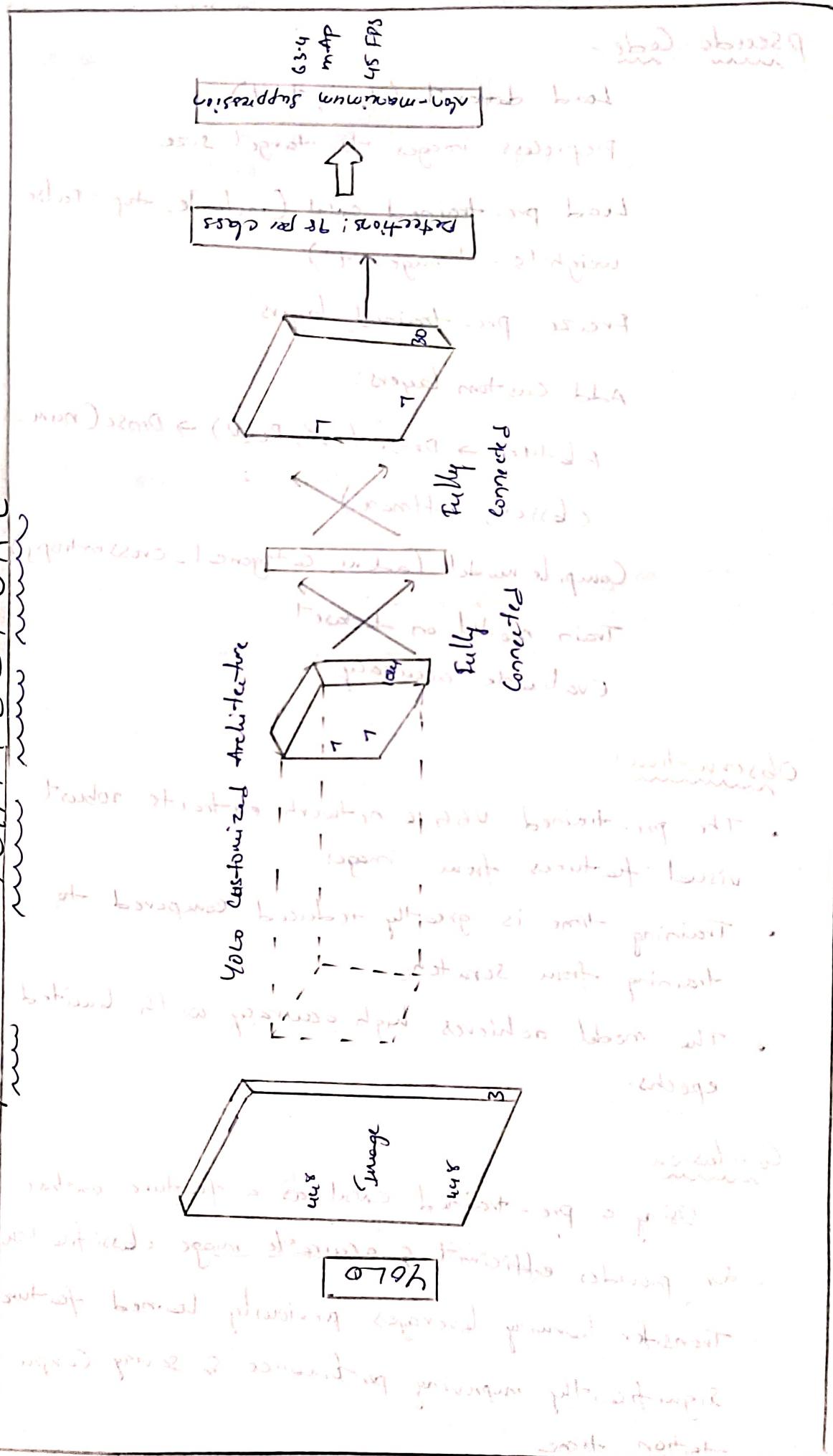
## Observations:

- YOLO detects multiple objects with bounding boxes and confidence scores.
- Inference is fast and efficient, suitable for real-time applications.
- Model accurately detects objects even in cluttered scenes.

## Conclusion:

The YOLO model demonstrates powerful real-time objects detection capabilities by simultaneously predicting class labels & bounding boxes. Its speed and accuracy make it widely used in autonomous systems, surveillance, & robotics.

# YOLO ARCHITECTURE



object detection

TensorRT 7.0.1 + CUDA 10.2 + PyTorch 1.7.0

Output

→ 1000 objects bounding boxes from TensorRT at  
448x640 (no detections), 68.1ms (N/A)  
→ 1000 objects bounding boxes from TensorRT at  
Speed : 10.7ms preprocess, 68.1ms inference, 0.8ms  
0.8ms postprocess per image at shape (1,3,448,640)

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(CPU) 1000 bounding boxes from TensorRT at  
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TensorRT inference speed is

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