

Subjective Question

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Gradient Descent optimizes an objective or a loss function with the help of an iterative step.

where

$$\omega^{k+1} \leftarrow \omega^k - \eta \Delta J$$

↓
new ω^n

If update was more generic: $\omega^{k+1} \leftarrow \omega^k + \delta$

$$\boxed{\delta = -\eta \Delta J} \text{ for GD}$$

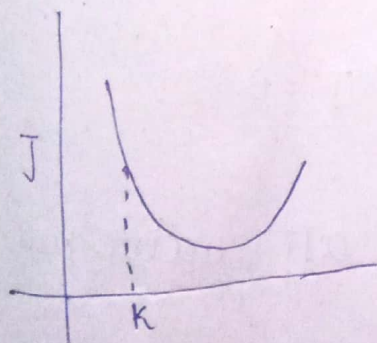
i.e. $\omega^{k+1} - \omega^k = \delta$

Using Taylor's series; which is given by

$$f(y) = f(x) + (y-x) f'(x) + \frac{(y-x)^2}{2} f''(x) + \dots$$

Assuming y is a vector we can write

$$f(y) = f(x) + [y-x]^T \nabla f + \frac{1}{2} [y-x]^T \underset{\substack{\uparrow \\ \text{Hessian matrix}}}{M} [y-x]$$



Given any time 'k', we would like to complete the objective J^n at $k+1$ th instant;

This is given by

$$J(\omega^{k+1}) \approx J(\omega^k) + [\omega^{k+1} - \omega^k]^T \nabla J(\omega^k) + \frac{1}{2} [\omega^{k+1} - \omega^k]^T M [\omega^{k+1} - \omega^k]$$

or

$$\boxed{J(\omega^{k+1}) = J + s^T \nabla J + \frac{1}{2} s^T H s}$$

Now to check if the error reduces, let us start with a further truncated expression

$$J(\omega^{k+1}) = J(\omega^k) + s \nabla J$$

$$J(\omega^{k+1}) = J(\omega^k) - \eta \nabla J^T \nabla J$$

$$J(\omega^{k+1}) = J(\omega^k) - \eta (\text{1st term})$$

Thus, this new objective is smaller than the previous objective.

Improvement of objective further depends on η

$$\begin{aligned} J(\omega^{k+1}) &= J(\omega^k) + s^T \nabla J + \frac{1}{2} s^T H s \\ &= J - \eta \nabla J^T \nabla J + \frac{\eta^2}{2} \nabla J^T H \nabla J \quad (\text{quadratic in } \eta) \end{aligned}$$

To optimize this, we differentiate w.r.t. η & equate to zero

$$\text{This gives } -\|\nabla J\|^2 + \eta \nabla J^T H \nabla J = 0$$

$$\text{or } \boxed{\eta = \frac{\|\nabla J\|^2}{\nabla J^T H \nabla J}} \quad \text{This is the best update rule.}$$

A function $f(x)$ is convex if $f''(x) \geq 0$ for all x .
i.e. $f'(x)$ is an increasing function of x .

The minimum is attained when $f(x) = 0$ since $f(x)$ keeps increasing to the left & right of that.

Thus there exists a global minimum which is unique.

For multivariate functions $\nabla^2 f(x)$ or the second derivate is the Hessian matrix M .

We have already established that $\nabla J^T \nabla J$ is positive and if M is positive semidefinite, the convex.

Given a function $f(x) = x^T A x$, where A is positive semidefinite, Hessian of $f(x)$ is A .

$\therefore M$ in $\nabla J^T H \nabla J$ is positive semidefinite.