

Signal & Systems
Set-D

YASH GUPTA
S20000010034

Q-1 $(n+2) (1/2)^n u(n) \rightarrow \left(\frac{1}{4}\right)^n u(n)$
 $x(n) \quad y(n)$

$$X(\omega) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n} = \frac{1}{1 - \frac{1}{2} e^{-j\omega}} \left(2 + \frac{e^{-j\omega}}{2} \right)$$

$$= \frac{2 - \frac{e^{-j\omega}}{2}}{\left(1 - \frac{e^{-j\omega}}{2} \right)^2}$$

$$Y(\omega) = \sum_{n=-\infty}^{\infty} y(n) e^{-j\omega n} = \frac{1}{1 - \frac{1}{4} e^{-j\omega}}$$

$$Y(n) = u(n) * u(n)$$

$$Y(\omega) = X(\omega) \times h(\omega)$$

$$h(\omega) = \frac{Y(\omega)}{X(\omega)} = \left(\frac{1}{1 - \frac{1}{4} e^{-j\omega}} \right) \left(\frac{\left(1 - \frac{e^{-j\omega}}{2} \right)^2}{1 - \frac{e^{-j\omega}}{2}} \right)$$

$$y_2(t) = ?$$

$$y_2(t) = \delta(n) - \left(\frac{1}{2} \right)^n u(n)$$

$$y_2(\omega) = 1 - \frac{1}{1 - \frac{e^{-j\omega}}{2}} = \frac{-e^{-j\omega}}{1 - \frac{e^{-j\omega}}{2}}$$

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Semester 10234

$$y_2(n) = x_2(n) * h(n)$$

$$Y_2(\omega) = X_2(\omega) H(\omega)$$

$$H_2(\omega) = \frac{Y_2(\omega)}{X_2(\omega)}$$

$$= \frac{-\frac{e^{-j\omega}}{2}}{1 - \frac{e^{-j\omega}}{2}} \times \frac{\left(1 - \frac{e^{-j\omega}}{4}\right) \left(2 - \frac{e^{-j\omega}}{2}\right)}{\left(1 - \frac{e^{-j\omega}}{2}\right)^2}$$

After ~~inverting~~ ^{inverting} $H_2(\omega)$ we will
get $h_2(t)$

Q-2

YASH GUPTA
SR020016239

$$u(t) = e^{-at} u(t)$$

$$X(\omega) = \int_{-\infty}^{\infty} e^{-at} u(t) e^{-j\omega t} dt$$

$$= \int_0^{\infty} e^{-(a+j\omega)t} dt$$

$$= \left[\frac{e^{-(a+j\omega)t}}{-(a+j\omega)} \right]_0^{\infty}$$

$$= -\frac{1}{a+j\omega} \left[-1 \right]$$

$$= \frac{1}{a+j\omega}$$

$$e^{-at} u(t) = \frac{1}{\pi} \int_0^{\omega\tau_0} |X(\omega)|^2 d\omega = 0.7 E_u$$

$$= \frac{1}{\pi} \int_0^{\omega\tau_0} \left| \frac{1}{a+j\omega} \right|^2 d\omega$$

$$= \frac{1}{\pi} \int_0^{\omega\tau_0} \frac{1}{a^2 + \omega^2} d\omega$$

$$= \frac{1}{a\pi} \left[\tan^{-1}\left(\frac{\omega}{a}\right) \right]_0^{\omega\tau_0} = 0.7 E_u$$

$$\frac{1}{a\pi} \tan^{-1}\left(\frac{\omega\tau_0}{a}\right) = 0.7 E_x$$

$$\boxed{\omega\tau_0 = a \tan(0.7 E_x \times a\pi)}$$

Q-3

TASH GUPTA
Snoooooo1234

$$x(n) = \{4, 2, 1, -1, 1, 2, 4\}$$

↑

$$\sum_{n=-\infty}^{\infty} [x(n)]^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} [X(\omega)]^2 d\omega$$

~~$$x(n) = x(n) e^{-jn\omega}$$~~

$$X(\omega) = \sum_{n=-3}^3 x(n) e^{-jn\omega}$$

$$\begin{aligned} &= 4e^{-3j\omega} + 2e^{-2j\omega} + 1e^{-j\omega} - 1e^{j\omega} + e^{j\omega} + 2e^{2j\omega} + 4e^{3j\omega} \\ &= 4(\cos 3\omega) + 2(\cos 2\omega) + 2\cos \omega - 1 \\ &= 8\cos 3\omega + 4\cos 2\omega + 2\cos \omega - 1 \end{aligned}$$

Q. 5

$$\begin{aligned} \sum_{n=-\infty}^{\infty} [x(n)]^2 &= 4^2 + 2^2 + 1^2 + (-1)^2 + 1^2 + 2^2 + 4^2 \\ &= 16 + 4 + 1 + 1 + 1 + 4 + 16 \\ &= 43 \end{aligned}$$

R.H.S

$$= \frac{1}{2\pi} \int_0^{2\pi} f(x(\omega))^2 d\omega$$

$$= \frac{1}{2\pi} \int_0^{2\pi} (8\cos 3\omega + 4\cos \omega + 2\cos \omega - 1)^2 d\omega$$

\therefore

after Solving

$$R.H.S = 43$$

$$R.H.S = L.H.S$$

Hence proved

YASH GUPTA
S202000010234