## Assignment 2

5 October, 2022

Due date: 25 October, by 13:20 in class

## Instructions

- If you write your solutions by hand, please ensure your handwriting is legible. We may subtract marks for hard-to-read solutions.
- Submit a hardcopy of your assignment in class.
- After 13:20, an assignment will be accepted only with an MSAF.
- Name your Matlab files **exactly** as specified.
- Do not submit zipped files to Avenue. We will **ignore any compressed file** containing your files.
- Submit only what is required.

Problem 1 [4 points] Write the body of the MATLAB function

```
function B = inverse(A)
```

For an  $n \times n$  nonsingular matrix A, it should compute the inverse  $A^{-1}$  of A. You can use only the lu function of MATLAB. Your inverse function must compute  $A^{-1}$  in  $O(n^3)$  operations. Then run the script

```
clear all;
n = 700;
m = 4;
for i = 1:m
   A = rand(n,n);
    tic;
    B = inverse(A);
    time(i) = toc;
    Ainv = inv(A);
    error(i) = norm(B-Ainv,inf)/norm(Ainv,inf);
   N(i) = n;
    n = 2*n;
    if (i==1)
        fprintf('n= %4d time=% .1e
                                                    error=%.2e\n', ...
            N(i), time(i), error(i));
    else
        fprintf('n= %4d time=% .1e ratio=%5.1f
                                                  error=%.2e\n', ...
            N(i), time(i), time(i)/time(i-1),error(i));
    end
end
```

Submit

- hardcopy: inverse.m and the output of this script
- Avenue: inverse.m

**Problem 2** [6 points] Consider the system Ax = b, where

$$A = \begin{bmatrix} 0.1 & 0.3 & 0.7 \\ 0.3 & 0.6 & 0.9 \\ 0.6 & 1.5 & 3 \end{bmatrix}$$

and  $b = [1.4, 1.8, 6]^T$ .

- a. [2 points] Show that A is singular.
- b. [2 points] If we were to use Gaussian elimination with partial pivoting to solve this system using exact arithmetic, show where the process fails.

- c. [1 point] Although A is singular, cond(A) does not return Inf. Why?
- d. [1 point] If we solve Ax = b in Matlab using  $A \setminus b$ , how accurate is the computed x?

**Problem 3** [4 points] The gamma function has the following values:  $\Gamma(0.5) = \sqrt{\pi}$ ,  $\Gamma(0.75) = \sqrt{\pi/2}$ ,  $\Gamma(1) = 1$ .

- a. [2 points] Derive the quadratic interpolation polynomial interpolating these values.
- b. [2 points] From this polynomial, determine the value of x for which  $\Gamma(x) = 1.5$ .

**Problem 4** [4 points] Given the three data points (-1,1), (0,0), (1,1), determine the interpolating polynomial of degree two using:

- a. [1 point] monomial basis
- b. [1 point] Lagrange basis
- c. [1 point] Newton basis

[1 point] Show that the three representations give the same polynomial.

**Problem 5** [8 points] Consider  $f(x) = \sqrt{x}$  on [0, 2].

- a. [3 points] Interpolate f(x) at 15 evenly spaced points  $x_0 = 0 < x_1 < \cdots < 2 = x_{14}$  in [0,2]. You can use the **polyfit** function; see also **linspace**. Denote the resulting interpolation polynomial by p(x).
  - Plot on the same plot f(x) and p(x) versus x at 100 evenly spaced points in [0,2].
  - Plot |f(x) p(x)| versus x at these points; use semilogy.
  - Why is the error largest when x is close to 0?
- b. [2 points] Instead of polyfit use spline and produce the plots in a.
- c. [2 points] Repeat a. with 15 Chebyshev points.
- d. [1 point] Explain the differences in the error plots in a. and c.

Submit the 6 plots in your hardcopy.

**Problem 6** [2 points] Suppose you interpolate  $e^{x^2}$  at x = 0, 0.5, 1 by a polynomial of degree 2. Derive a bound for the error of this interpolation.