## Fluid Motion Analysis

Using OpenCV and Python

### Introduction

In fluid mechanics, understanding velocity distribution and shear stress is crucial for predicting flow behavior, especially in industrial processes, environmental studies, and engineering applications.

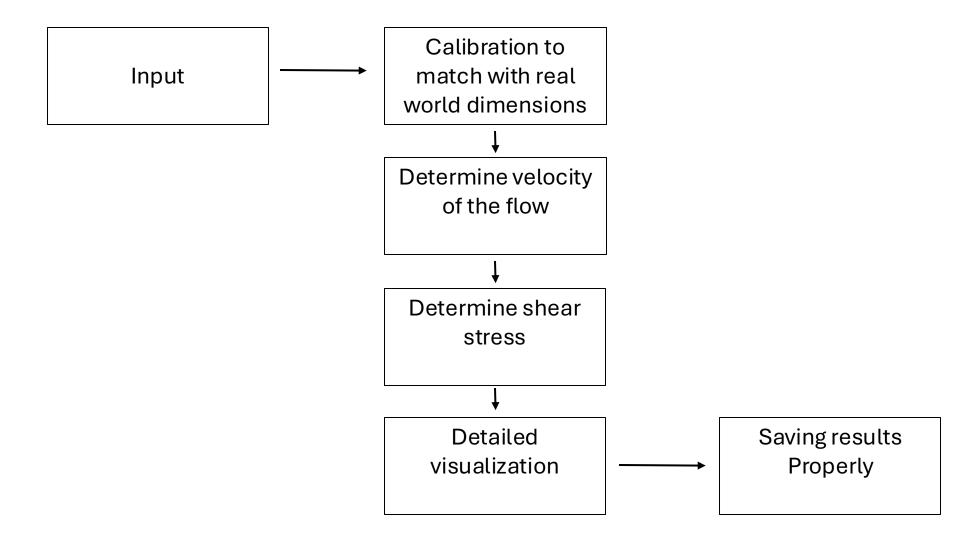
#### Addresses two main problems

- Velocity Calculation
- Shear Stress Calculation

#### **Objectives**

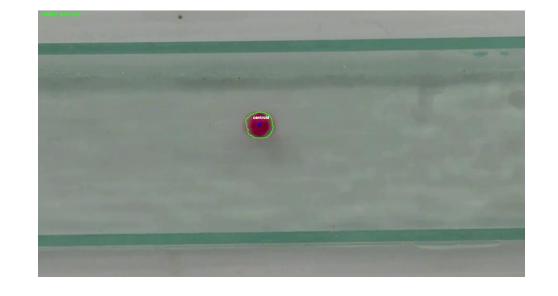
- tracking particle velocity
- calculating shear stress
- visualizing turbulent flows

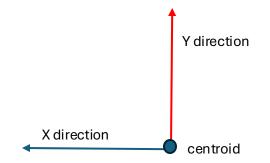
## System Workflow



## How to determine the Velocity?

Take the floating particle position by using contour centroids at each frame.





## How to determine the shear stress?

```
T = \mu (\Delta y / \Delta v)
```

#### Where:

- T = Shear stress (Pa)
- μ\muμ = Dynamic viscosity of the fluid (Pa·s)
- $\Delta v \triangle v = Change in velocity between fluid layers (m/s)$
- $\Delta y \Delta y = Distance between layers (m)$

```
du_dy = (velocity_magnitude[i] - velocity_magnitude[i - 1]) / (1 / pixels_per_cm_y)
shear = viscosity * du_dy
```

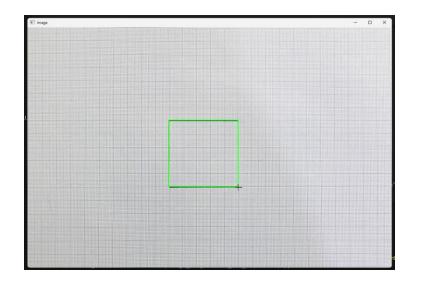
## How to relate to real-world dimensions?

#### **Purpose of Calibration:**

Convert pixel measurements from video frames into real-world units.

#### **Calibration Method:**

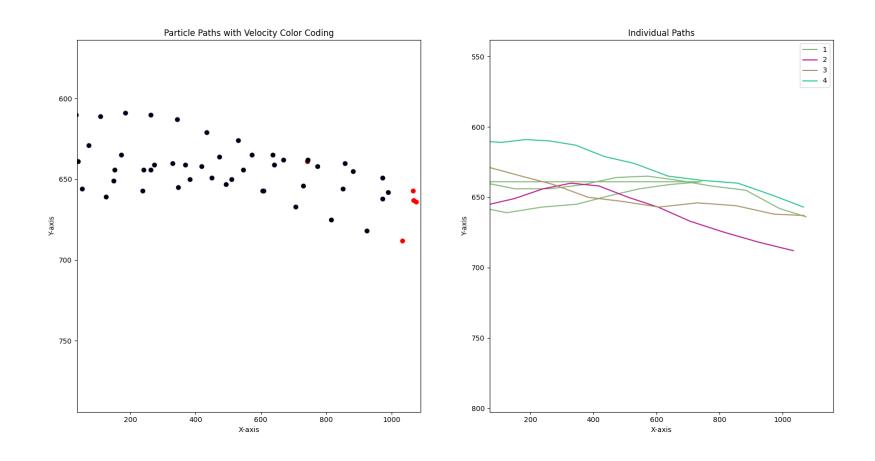
- Load Calibration Image:
  - A known reference object of a specific size is used (e.g., a square with known dimensions).
- Manual Selection:
  - User selects two points on the calibration image to define the known object's size.



```
def calculate_conversion_factor(ix, iy, x, y):
    width_pixels = abs(x - ix)
    height_pixels = abs(y - iy)
    return width_pixels / KNOWN_WIDTH_CM, height_pixels / KNOWN_HEIGHT_CM
```

```
Pixels per cm (Width): 22.6
Pixels per cm (Height): 20.6
```

## Results Analysis and Visualization



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```
Fluid ID | Date-Time | Avg Velocity (m/s) | Avg Shear Stress (Pa)

fluid_20240915_190601 | 2024-09-15 19:06:26 | 2.96 | -0.07

fluid_20240915_190647 | 2024-09-15 19:07:28 | 1.40 | -1.72
```

Watch a sample video demonstrating how the program works.

## Potential further improvements

#### **Challenges with Current Implementation:**

- The program may struggle to track multiple moving particles accurately.
- Particle overlap or occlusion leads to errors in velocity and shear stress calculations.

#### **Potential Solutions:**

- Implement blob detection
- Use Kalman filters for tracking particles
- Machine learning approaches for robust object detection and tracking.

# Thank you!