# Scheduling algorithm to avoid contention in meshed networks

## Dominique Barth<sup>1</sup>, Maël Guiraud<sup>1,2</sup>, Brice Leclerc<sup>2</sup>, Olivier Marcé<sup>2</sup>, and Yann Strozecki<sup>1</sup>

<sup>1</sup>David Laboratory, UVSQ <sup>2</sup>Nokia Bell Labs France

20 avril 2020

#### Introduction

#### 1 Model & Problems

#### 1.1 Model

Presenter le model : A rajouter par rapport a l'ancien

- la notion de buffers intermédiaires
- la métrique, on compte le temps différemment

### 2 General model and Problems

We use the notation [n] to denote the interval of n integers  $\{0, \ldots, n-1\}$ .

#### 2.1 Discrete time model

In the model presented here, the time is discrete. The unit of time is called a **tic**. This is the time needed to transmit an atomic data of size Q over the fastest link of the network. We consider that the speed of the links is the same over all the links of the network.

#### 2.2 Network modeling

The network is modeled as a directed graph G = (V, A). The **sending tic** of a message in a vertex u is the tic at which the beginning of this message is sent from u. Also, the **reception tic** of a message in a vertex v is the tic at which the beginning of the message arrives in v. Each arc

(u, v) in A is labeled by an integer weight  $\Omega(u, v)$  which represents the number of tics elapsed between the sending tic of the message in u and the reception tic of this message in v using this arc. A **route** r in G is a directed path, that is, a sequence of adjacent vertices  $u_0, \ldots, u_l$ , with  $(u_i, u_{i+1}) \in A$ . The **weight of a vertex**  $u_i$  in a route  $r = (u_0, \ldots, u_l)$  is defined by  $\lambda(u_i, r) = \sum_{0 \le j < i} \Omega(u_j, u_{j+1})$ . It is the number of tics needed

between the sending tic of a message in the first vertex of the route and the reception tic of this message at  $u_i$ . We also define  $\lambda(u_0, r) = 0$ . The weight of the route r is defined by  $\lambda(r) = \lambda(u_l, r)$ . We denote by  $\mathcal{R}$  a set of routes, the pair  $(G, \mathcal{R})$  is called a **routed network** and represents our telecommunication network. The first vertex of a route models an antenna (RRH) and the last one a data-center (BBU) which computes an answer to the messages sent by the antenna.

#### A simplifier

- Le debit sur les flux, qu'on considère tous les mêmes.
- La notion de jitter, on ne s'y intéresse pas vraiment, mais c'est un point important pour justifier, peut être à remonter dans l'intro en le redéfinissant pour un réseau déterministe?

#### 2.3 Problems

Je propose de ne parler que de SPALL, nos résultats sur PALL conflict depth 2 sont très peu interessants

## 3 Topologies

Je propose de parler rapidement des deux topologies. On peut peut être faire une sous section parlant de l'étoile en expliquant pourquoi on à un bon algo fpt(en renvoyant sur l'autre papier) vu que ce n'est pas très long.

## 4 Algorithms

#### 4.1 Greedy

Presenter les différents algo greedy, expliquer pourquoi on les essaye

#### 4.2 Local Search

Differentes techniques de voisinages utilisées Notion de voisinage n1

#### 4.3 FPT

Definir le voisinage, expliquer pour quoi ca nous donne un algo  ${\rm fpt},$  et le decrire

- 5 Results
- 6 Conclusion