

Greedy algorithms for scheduling periodic message

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Abstract—A recent trend in mobile networks is to centralize in distant data-centers processing units which were attached to antennas until now. The main challenge is to guarantee that the latency of the periodic messages sent from the antennas to their processing units and back, fulfills protocol time constraints. The problem is then to propose a sending scheme from the antennas to their processing units and back without contention and buffer.

We study a star shaped topology, where all contentions are on a single arc shared by all antennas. We present several greedy heuristic to solve PAZL. We study their experimental efficiency and we use them to prove that when the load of the network is less than 44%, there is always a solution to PAZL. We also prove that for random lengths of the arcs, most of the instances have a solution when the load is less than 45%.

I. INTRODUCTION

II. MODEL

Describe the general model + the simplified version for the star with a picture + a set of number d_1, \dots, d_n and two values P, τ . [?]

Explain the notion of shadow ? Give the compacity criteria.

III. BASIC ALGORITHMS

A. General graph

Algorithm with meta intervals with load $n/4$ Specialization to the result of the article for the star with $n/3$.

Copy the results of the previous article and propose heuristics to chose among several positions/candidates (compacity heuristic).

B. First position

Describes how it builds compact assignments + heuristic to build super compact assignment (among the compact assignments possible, chose the one which maximize the gain on the second bloc)

IV. TOWARDS $n/2$

Simple result with $\tau = 1$: $n/2$. Two questions:

- can we do better with a greedy alg ? + add the results with the heuristic which reduce collisions with the last elements by choosing properly the first $n/2$ elements which are placed to gain \sqrt{n} elements.

- can we get the same bound for any τ ? Answer: Yes by paying a waiting time of at most τ (all blocs aligned on meta interval, degenerate to the case $\tau = 1$).

A. Pairs of elements in order of shifts

Precise description of the algorithm.

B. Tuples of elements in order of shifts

Bit more sketchy description + value derived from the programm computing the value with many different size of groups.

V. ABOVE $1/2$

TODO: properly define the potential of a position, of a route. Relates both through a lemma showing that the sum of both is equal. Also a lemma which relates potential to the number of conflicts.

We assume that all distances are different (if at least a constant fraction are, it is ok). The greedy algorithm is as follows, for $(1/2 + \epsilon)P$ routes:

Let S be the set of routes of potential $2\epsilon n$, initialized to \emptyset . When a route is added to S , it is removed from the routes used to compute the potential. When $|S| \geq \epsilon n$, the algorithm stops. For $k < P/4$ routes already placed, the potential of a position i on the backward windows is the number of yet unused routes of delay d such that $i - d \bmod P$ is used. This potential corresponds to the number of routes for which placing a route at this position remove only one possible offset instead of two. On the backward windows select the unused position of largest potential and find a route which can be placed at this position, not in the best $\epsilon n - |S|$ routes.

Proof it works:

Since all distances are different, there are at least $(1/2 + \epsilon)n - |S| - k$ positions in the forward windows which allows to place a route attaining a given position in the backward windows. Since there are k used offsets in the forward windows, there are at least $(1/2 + \epsilon)n - |S| - 2k$ free positions among them. Since $k < n/4$, there are at least $\epsilon n - |S|$ possible routes satisfying the constraint, hence one is not among the $\epsilon n - |S|$ routes having best potential (with the chosen variant, not useful to spare the best ones, simplifying the proof and the algorithm).

Assume that there is a free position, which increases the global potential by at least $2/3$ of the average which is $k(1/2 - k)/n$. Then the global potential is at least $(2/3) \sum_{i=1}^k i(1/2 - i)/n$. On the other hand, if no position of at least $2/3$ the average is available, then the global potential is at least $1/3 k(1/2 - k)$. (to clean that, prove by induction that the potential is always larger than some value at step k). If we can prove that when $k = P/4$, the potential is at least $2\epsilon n(1/2 + \epsilon)n$, then it implies that the algorithm has stopped before that point and it implies there is a solution. We solve the equation lower bound on the potential larger than $2\epsilon n(1/2 + \epsilon)n$ to obtain a correct value on ϵ .

The computation is not optimised at all. We win only on the backward windows but we should win as much on the forward windows. Several simplification in the bound (but of little impact). Lose too much when dealing with only positions of potential lower than the average (can do better than $1/3$ vs $2/3$).

VI. ALGORITHMS FOR RANDOM INSTANCES

a) $\tau > 1$: Compute a better bound working w.h.p. for some greedy algorithms (celui qui fait un ou plusieurs serpents).

b) $\tau = 1$: Greedy algorithm with constraints on the possible positions. At each step placing a new route take only one slot more and more often. Should give a $2 - \sqrt{2} = 0.585 \dots$ bound.

VII. GREEDY AND DELAY

Tradeoff between waiting time and load. Can we prove $0.5 + \epsilon$ load for $f(\epsilon, n, \tau)$ waiting time ? No idea yet.

VIII. NON GREEDY ALGORITHM

Greedy + swap one element if necessary. Can we guarantee a solution for a larger load ? Conjecture, yes for $\lambda = 2/3$. Seems hard for group theoretic reason (how to avoid subgroups of $\mathbb{Z}/p\mathbb{Z}$ which are a problem)

IX. LOWER BOUNDS

Example/family of examples for which some greedy alg fail. Example/family of examples with a given load such that there are no feasible solution.

X. NP-HARDNESS

Are we able to prove NP-hardness