Representation of auditory signals by neuronal spike trains

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1. Introduction

The neuronal representation of sound is the result of the encoding of acoustic signals by the peripheral auditory system. The spike trains resulting from this encoding are influenced, among other factors, by the refractory period of the auditory nerve fibers. In fact, for example we learn in [Avissar et al. 2013] that, for the encoding of pure tones, the spike timing precision depends on the ratio of the refractory period to the stimulus period, and the entrainment of nerve responses to the stimulus was better with the refractory period. We also know from [Berry and Meister 1998] that the refractoriness of neurons may make their signals more reliable.

This project aims to study the effects of refractoriness on sound encoding in the peripheral auditory system. First, we studied this effect based on an ad-hoc measure of response spike trains, the rate-modulation depth, for four kinds of stimuli. In [Deger et al. 2010], point processes with refractoriness were studied and mathematical predictions were made for the Fourier coefficients of their response. The second part of the project consisted on trying to see if the results on the model matches these predictions when the stimulus is a modulated pure tone.

For this aim, a model of the peripheral auditory system was used [Zilany and Bruce 2006, 2007; Zilany et al. 2009], in which the absolute refractory period has been be modified. Virtual experiments were run on the two versions of the model and the resulting spike trains were compared to see the influence of the refractory period.

Now, before going any deeper into the model, we should introduce the basic physiology of the peripheral auditory system.

2. The Auditory System

This introduction is based on the book "Auditory Neuroscience" [Schnupp et al. 2011], chapter two.

The peripheral auditory system has (generally air) pressure as input, and spike trains as output. We will go through the parts of the ear, with help of Figure 1.

Let us first consider the external ear. There the pressure signals enters through the ear canal and make the eardrum vibrate. This takes to the medium ear, through which the vibration is propagated by three ossicles : malleus, incus and stapes. The farthest part from the external ear of the stapes touches the boundary of the cochlea, on the oval window, in the inner ear, and causes vibration in its contained liquid. The cochlea forms an interface between this mechanical vibration and the neural signal of the auditory nerve (VII nerve on Figure 1).
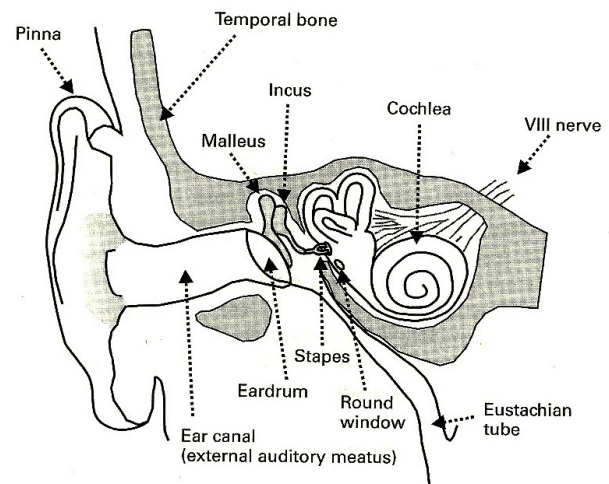

Figure 1. Peripheral auditory system ([Schnupp et al. 2011] p.52)
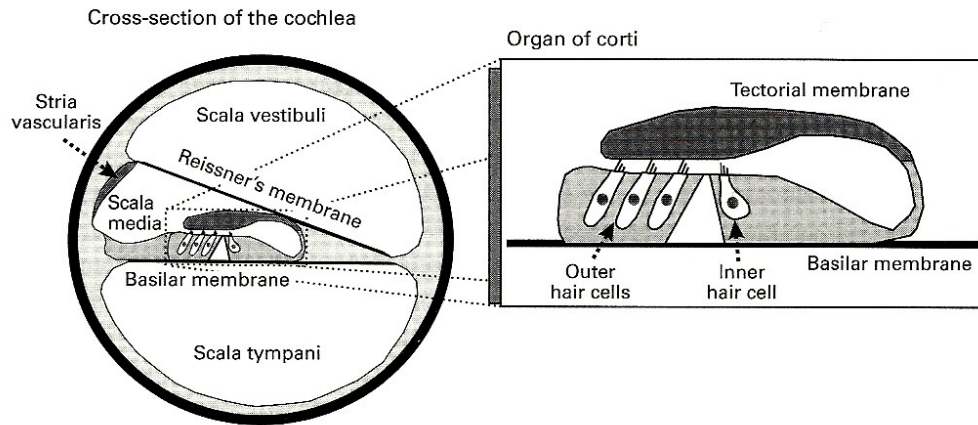
Figure 2. Organ of Corti ([Schnupp et al. 2011] p.65)

We will speak more about this interface below. But first we take a closer look at the vibration of the cochlea. The cochlea is a tube that has two main compartments which are placed on top of each other. These compartents are separated throughout the cochlear tube by the basilar membrane, except at the far end of it where they are joined, as can be seen on Figure 3.
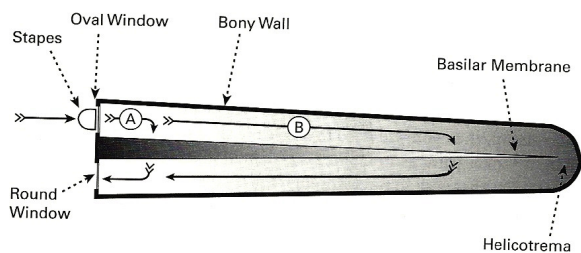

Figure 3. Unrolled cochlea ([Schnupp et al. 2011] p.55)

An incoming vibration will propagate through the basilar membrane from the upper compartment to the lower. In this process, it will not make all the parts of the basilar membrane vibrate at the same intensity. In fact, the cochlea is like a "biological Fourier analyzer", in the words of the book. The frequency content of vibrations is decomposed and each frequency has its "favorite" place in the cochlear coiled tube that it makes vibrate particularily. The part of the basilar membrane that is the first to vibrate, when we gradually put on the volume of a pure tone of frequency f, is said to be of "characteristic frequency" f. Near the oval window, the characteristic frequencies are high, and as we advance to the tip of the tube, the characteristic frequency decreases.

Throughout the cochlear tube spans the organ of Corti, which is the interface which was previously refered to above in the text. We will use Figure 2 to illustrate its purpose.
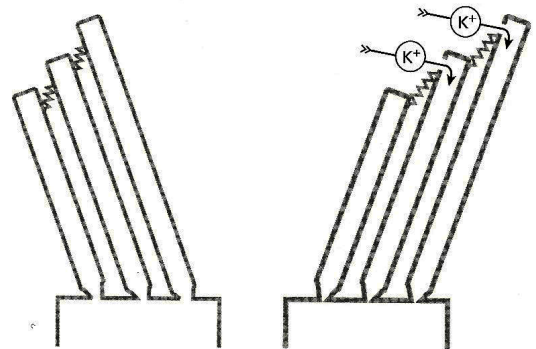

Figure 4. Transduction ([Schnupp et al. 2011] p.66)

The upper compartment of the cochlea is in fact in two parts separated by a membrane. The scala media, where we find the organ of Corti, has a higher concentration of potassium cations. A consequence, then is a polarization between the liquid of the scala media and the inner hair cells. When the basilar membrane vibrates, the tectorial membrane does that also, and that makes the liquid move. Outer hair cells then amplifies these movements, what is useful for low volume sounds. These movements cause the deflection of the stereocili of the inner hair cells, and when this happens, some potassium ions of the scala media go into the inner hair cells (IHC), where they lead to a depolarization. This is depicted in Figure 4. This depolarization causes glutamate to be released at the synapses
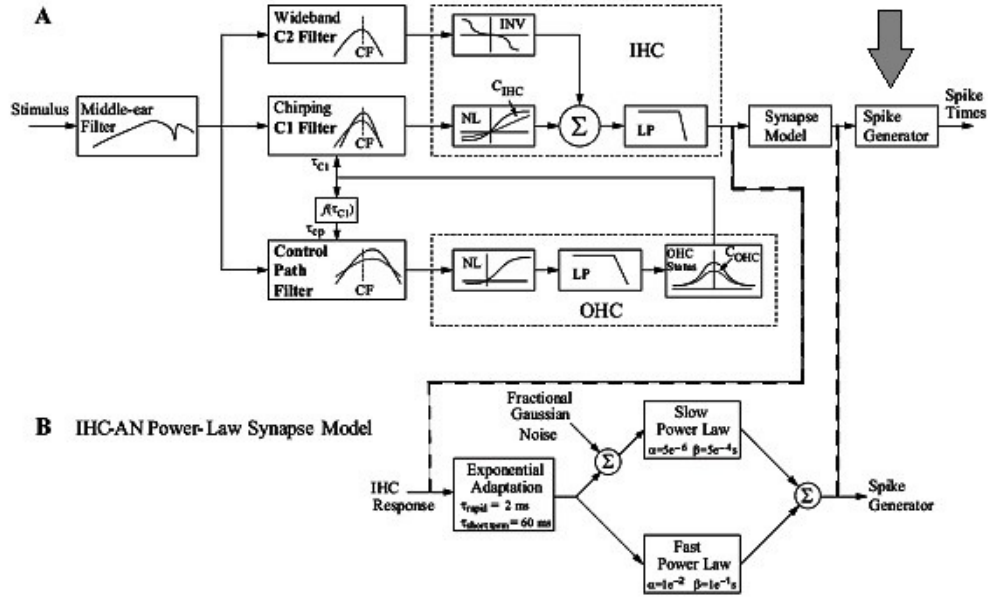
Figure 5. Schema of the model ([Zilany et al. 2009] their fig. 2). The spike generator (pointed to by an arrow) is the part where the modifications of the model were done

between the IHC and the auditory nerve fibers, what excites these fibers and make them emit action potentials (spikes).

3. Model

Let us now intriduce the model of the peripheral auditory system [Zilany and Bruce 2006, 2007; Zilany et al. 2009], which was used to run experiments in this project.

We will not go into the details of the model, but of the use of it. You can see in Figure 5 the schematic of the model. It is a complicated cascade of linear and non-linears filters.

From the user point of view, the model consists of two main functions that are called "catmodel_IHC" and "catmodel_Synapse". Their prototype, in MatLab language, are

vihc = catmodel_IHC(pin, CF, nrep, tdres, reptime, cohc, cihc);

and

[synout, psth] = catmodel_Synapse(vihc, CF, nrep, tdres, fibertype, implnt);

like specified in the "catmodel.m" file of the model. Let us go deeper into what each parameter and return value of these functions means.

The first function, `catmodel_IHC`, takes as parameters a sound pressure stimulus vector (`pin`, in Pa), sampled at some sampling rate that is the inverse of the bin size specified in `tdres`, and also the characteristic frequency (CF, in Hz) of the IHC for which we want to know the potential (`vihc`, in Volt) when stimulated. This latter (`vihc`) is what is returned by the function. `reptime` is the time for one repetition of the stimulus, and `nrep` is the number of repetitions we want to be run. The parameters `cohc` and `cihc` represents the damages on respectively the outer hair cells and inner hair cells in the simulation (not used in this project). `vihc` will contain the IHC potential for every repetition after the function has been run.

The second function, `catmodel_Synapse`, takes the IHC potential returned by `catmodel_IHC`, with the same sampling rate, so the same `tdres`, which is also here the bin size of the PSTH returned by the function (`psth`). The PSTH will be computed according to the specified number of repetitions (`nrep`). The synapse output of the IHC (`synout`) is also returned by the function. The `fibertype` parameter is used to tell the model which nerve fiber type we "test" with the stimulus, distinguished by their spontaneus rate (SR) : low, medium or high. Finally, `implnt` is used to indicate the precision we want in the simulation for the power-law functions in the model.

As an example of what kind of result the model can give, in Figure 6 you can see some graphs that represent

the steps of a simulation of a pure tone step stimulus. A nerve fiber with high SR with a 1 kHz characteristic frequency was chosen.
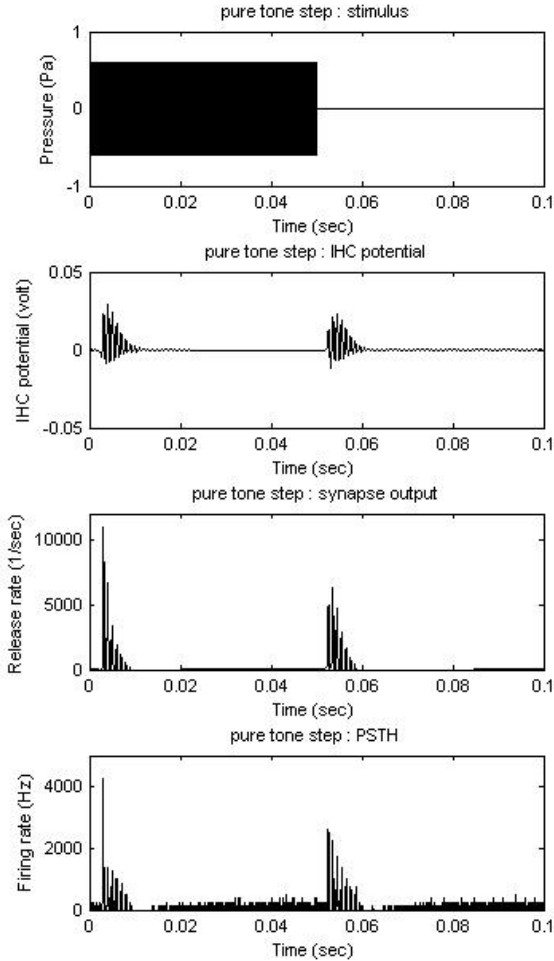

Figure 6. Example of model results ([Zilany et al. 2009])

The first graph is a representation of one period of the stimulus, sampled at 100'000 Hz (so with bins of 0.01 ms size), at 84 dB SPL. The stimulus, as given to the model as `pin`, was this period of 100 ms repeated 800 times : a pure tone step. The frequency of the pure tone is so high here (10 kHz) that we cannot see its sinusoid. On the second graph, you can see the IHC potential from the first function in response of the last repetition of the stimulus (with dependencies on the preceding periods included). The third graph shows a part of the synapse output given by `catmodel_Synapse`,

for the same period as for the potential of IHC. The fourth graph represents the peristimulus time histogram (PSTH).

For the project, the code of the model has been modified to put to zero the absolute refractory period (ARP) of nerve fibers. This transformation was done in the spike generator part of the model (see in Figure 5 the step pointed by the arrow). After that, the spike trains with and without this refractory period could be compared.

In Figure 7 you can see an example of a graph where are drawn two periodograms, calculated from the PSTH given by the model (either modified or not), for another stimulus as before, a pure tone which is not modulated.
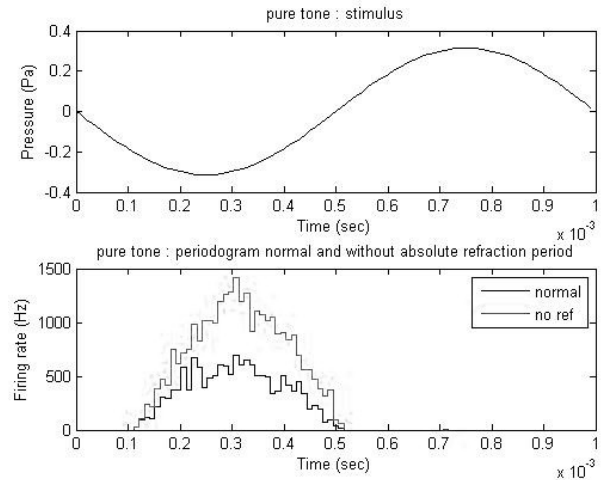

Figure 7. Periodogram with and without refractory period for the stimulus of period above

In Figure 7, first graph, you can see one period of the stimulus, a 1 kHz pure tone, at 84 dB SPL. The second graph shows the periodogram with and without absolute refractory period. We can see phase-locking for the two periodograms : spikes occur preferentially for a specific phase of the stimulus cycle. We see that here the phase caracteristics seems not to change when the refractory period changes. This simulation was done with a medium SR nerve fiber, with 1 kHz characteristic frequency and 0.01ms bin size. We will now describe the results of the project.

4. Results

4.1 Rate modulation depth

For the first part of the project, an ad-hoc measure called rate modulation depth (RMD) was used to quan-
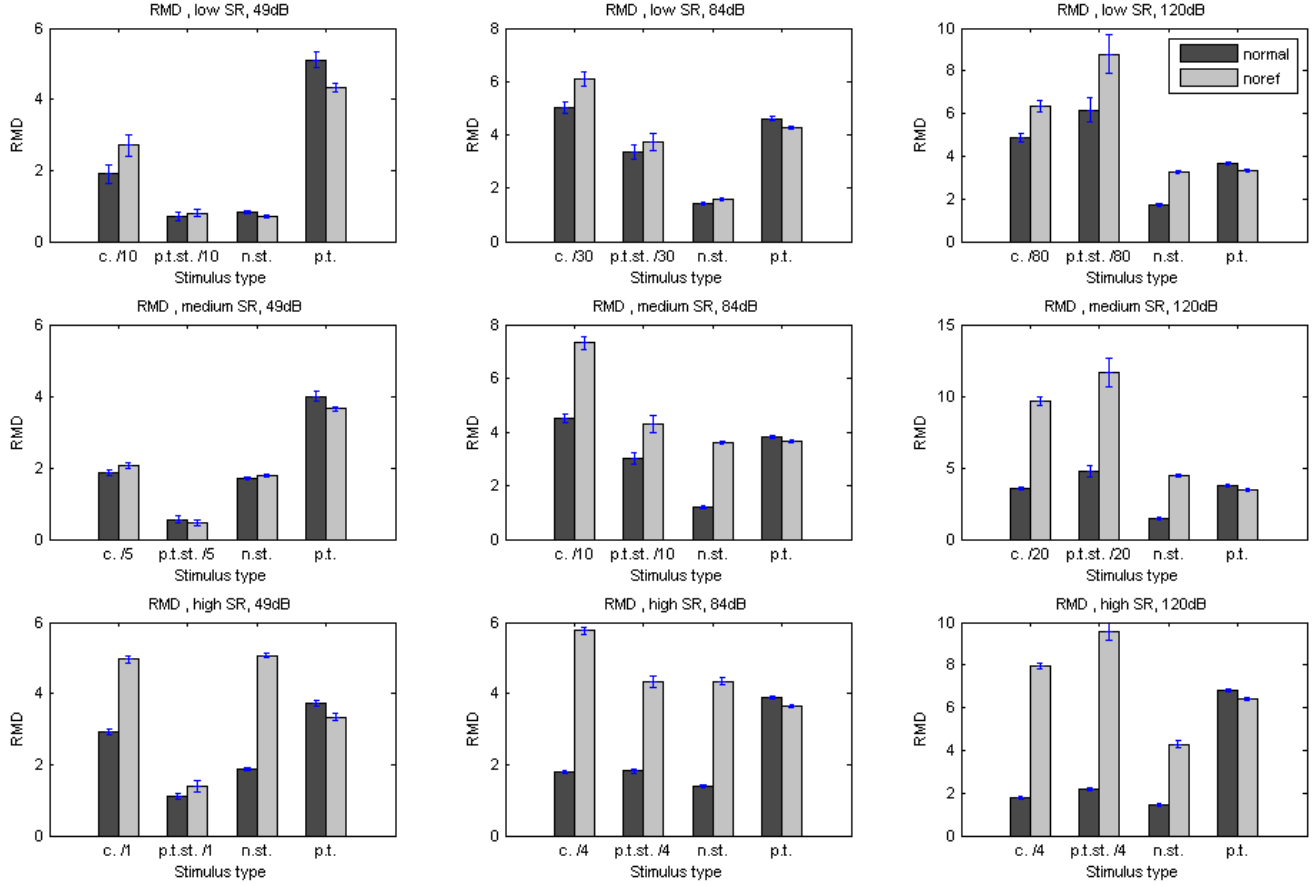
Figure 8. RMD values for different SR fibers and intensities. Experiment labels are abbreviated (c. for click, p. t. st. for pure tone step, n. st. for noise step, p. t. for pure tone). Some RMD results had to be scaled to fit properly in the graph and the scaling factor is written in the legend of the x-axis. From left to right, we have sound intensities : 49 dB, 84 dB, 120 dB, from top to bottom, we have fiber types : low SR, medium SR and high SR.

tify differences between encoding of acoustic signal with and without an absolute refractory period (ARP) of the auditory nerve.

Four kinds of experiments where run and the average RMD was calculated for each of them, with each type of nerve fiber, and three different sound intensities : 49 dB SPL, 84 dB SPL and 120 dB SPL (49 dB : average home, rainfall; 84 dB : busy road; 120 dB : threshold of discomfort, possible hearing loss) to have an overall view of the effects. For each virtual experiment, the bin size was 0.01 ms, the characteristic frequency was 1 kHz, there was no damage on IHC or OHC, and we told the model to use the built-in approximations for power-law function calculations.

The four experiments were clicks, pure tones, noise steps and pure tone steps. The clicks were rarefaction clicks (negative pressure excursion) of 0.1 ms and suf-

ficient time was waited between two of them to avoid influence from one to the other. The two step stimuli had a period of 100 ms and in the first half of the period there was noise or pure tone signal, and in the second half there was 0 Pa as pressure. The noise for the noise step was composed of random normal variables divided by the square root of the bin size (gaussian white noise). The pure tone of the pure tone step was of 10 kHz frequency.

The rate modulation depth (RMD) was defined as

$$RMD = \frac{m - b}{b} \qquad (1)$$

for clicks and pure tone steps, where m was the maximum of the periodogram of the encoded sounds when converted in 2 ms bins. The meaning of the b depended on the stimulus. For the clicks it corresponded to the mean response to a 0 Pa pressure signal, with same

number of repetitions than for the click stimulus. For the noise step, the baseline is the value of the periodogram just before the second half of the period, so just before the stimulus onset, in 10 ms bins. The baseline for the pure tone step was the mean of PSTH values of a response to a pure tone of the frequency used for the stimulus (10 kHz), after the IHC were saturated (as could be seen in the potential, which stays constant because it has not the time to be depolarized between two periods of the stimulus). The periodogram was computed from the same number of repetitions as for the pure tone step stimulus. For the pure tone, the baseline was chosen as the mean of the periodogram. For pure tones and noise steps, for each repetition the RMD was calculated and the final result is the mean, whereas for clicks and pure tone steps b and m where found separately and their means where then used for the RMD calculation.

Figure 8 displays RMD values as obtained in our virtual experiments, for several fiber types and sound intensities. Error bars for noise steps and pure tones are standard deviation of the mean of the RMDs calculated for each repetition of the stimulus. For clicks and pure tone step, the error bars are of value $\sigma_{<RMD>}$. To find this value, the standard deviation of the means of m and b were calculated and then propagated for the division with Equation 2.

$$\frac{\sigma_{<RMD>}}{|<RMD>|} = \sqrt{\left(\frac{\sigma_{<m>}}{<m>}\right)^2 + \left(\frac{\sigma_{<b>}}{<b>}\right)^2} \quad (2)$$

As displayed on Figure 8, overall effects are these: for clicks, pure tone steps and noise steps, the RMD without absolute refractory period is bigger than for the normal case, and it is the opposite for pure tones.

We may explain the first finding because, first, we are in presence of a highly non-linear system and, secondly, the three stimuli for which the RMD without ARP is bigger, are stimuli with very sudden changes. In fact, the click can be seen as an approximation of a delta function, which corresponds to a broad-band stimulus. Also, sudden steps excite a wide range of frequencies, which make many non-linearities of the system contribute to the response.

The second finding that RMD is lower for pure tones without ARP, may be explained by the fact that we have less interactions between frequencies in the non-linear system up to the spike generator, in the model, and the effects of ARP are strong enough to be seen.

4.2 Response according to frequencies of modulated pure tones

In [Deger et al. 2010], predictions are made for the absolute value (norm) and angle of the Fourier coefficients (harmonics 0, 1, 2 and 3) of response of stochastic point processes with refractory period, to sinusoidal stimuli, as a function of the frequency. This case roughly corresponds to a tone with a high frequency carrier function, modulated by a low frequency oscillation. In fact, the inner hair cells will not be able to follow the carrier frequency and they will excite the nerve with a synaptic release rate dominated by the modulation.

The product of the absolute refractory period d and the modulation frequency f, determines the response spectrum, as shown in Figure 9 (norm of Fourier coefficient) and Figure 10 (angle). Here d was 80 ms. In the graphs, the black ligns are for harmonic 0, dark gray for 1, mid gray for 2, light gray for 3. β_k is the k harmonic of the output.
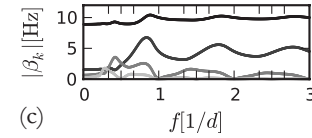

(c)

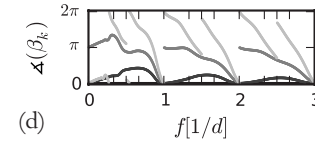**Figure 9.** Predictions for norm ([Deger et al. 2010] their fig. 3 (c))

(d)

Figure 10. Predictions for angle ([Deger et al. 2010] their fig. 3 (d))

To see if the predictions are coherent with the model of the peripheral auditory system, experiments with modulated pure tone were run. The carrier frequency used was 10 kHz, the modulation frequency varied from 50 Hz to 4000 Hz with steps of 50 Hz. We chose nerve fibers with medium SR, characteristic frequency 5 kHz and the stimuli were of intensity 84 dB. The stimulis $y(t)$ were calculated like that :

$$y(t) = A(1 + 0.5 sin(2\pi t f_m)) sin(2\pi t f_c) \quad (3)$$

where A is the amplitude, f_m is the modulation frequency, f_c is the carrier frequency.
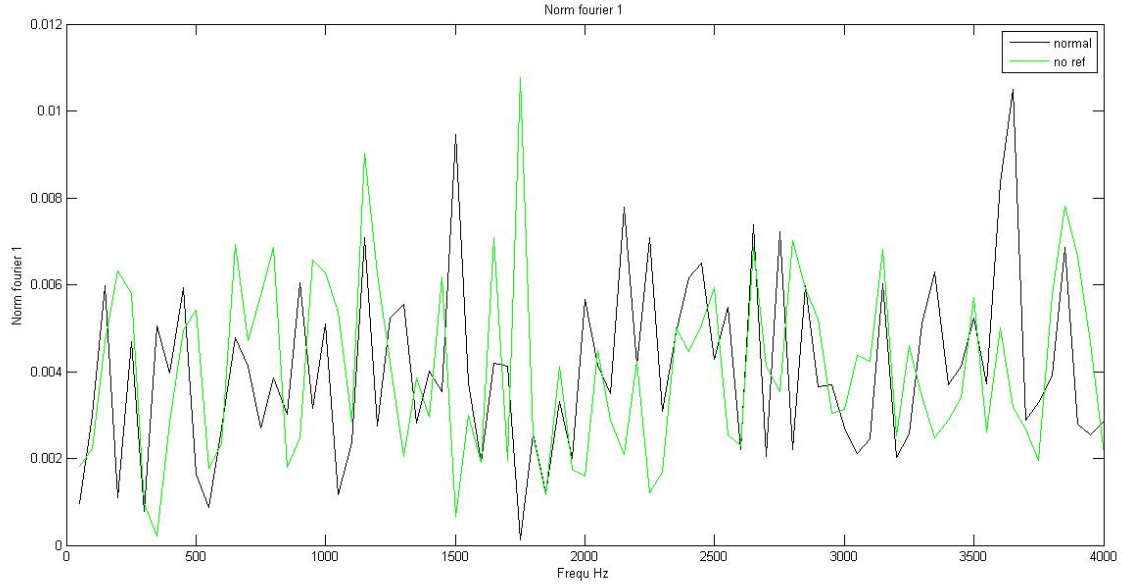
Figure 11. Norm of first harmonic of response to a modulated pure tone, in function of modulation frequency

Two seconds of each stimulus were run, then, the second half of the PSTH was kept and its β_k Fourier coefficients were calculated according the following formula.

$$\beta_k = \frac{1}{T} \sum_{j=0}^{\frac{T}{\Delta t}} e^{i\omega k j \Delta t} z (j\Delta t) \Delta t \qquad (4)$$

where T is the period (1 second here), ω is $\frac{2\pi}{T}$, Δt is the bin size (0.01ms), $z(t)$ is the PSTH, and k is the number of the caculated harmonic.

In the model, the absolute refractory period is of 0.75 ms, so mutiples of $1/d$ are near 1333 Hz and 2666 Hz in our experiments. Sadly, not enough data could be yet calculated to see if the results match the predictions of [Deger et al. 2010]. As you can see in Figure 11, after 10'400 repetitions, the results are too noisy to be able to conclude anything. The graph shows the norm of the first harmonic. The other norms and angles graphs are also chaotic, so we do not show them.

5. Conclusion

The rate modulation depth calculation gave interesting results. In fact, RMD is a measure of the precision of response, and we found that absolute refractory period increased it only for a specific stimulus (pure tone). This in line with [Avissar et al. 2013], where they found that for pure tones, refractory period uncreased

entrainment and may increase the precision. For the other stimuli, the non-linear effects triggered by the sudden changes seems to be stronger than the effects of the refractory period and hide them.

For the second part of the project, the results were too noisy to conclude anything.

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