

Міністерство освіти і науки України Національний технічний університет України «Київський політехнічний інститут імені Ігоря Сікорського» Інститут прикладного системного аналізу

Практична робота №1

з курсу «Технології та методи напівкерованого навчання» Варіант №3

Виконав:

студент 5 курсу групи КІ-31мп Шабо О.А. **Перевірив:** Кирило Лісогорський

Мета роботи: Налаштування інструментарію необхідного для виконання подальших лабораторних робіт, отримання базових навичок роботи з фреймворком машинного навчання Pytorch, ознайомитись з загальним принципом та вимогами до виконання лабораторних робіт протягом курсу.

Завдання:

- 1. Виконати налаштування робочої середи;
- 2. Встановити сід генератору псевдовипадкових чисел;
- 3. Завантажити обраний набір даних;
- 4. Відобразити декілька зображень з набору даних у блокноті;
- 5. Розділити обраний набір даних на три вибірки: тренувальну, валідаційну та тестову. Співвідношення розміру вибірок обрати на власний розсуд;
- 6. Завантажити та налаштувати нейронну мережу обраної архітектури;
- 7. Провести навчання нейронної мережі. Вибір гіперпараметрів на власний розсуд;
- 8. Зберегти ваги навченої нейронної мережі у файл.
- 9. Побудувати графіки точності та loss мережі під час навчання. Зробити висновки, оформити звіт;

№	Архітектура нейронної мережі	Набір даних
3	AlexNet	Cifar10

Хід роботи та висновки:

Variant: 3 (27) NN architecture: AlexNet Dataset: Cifar10 link to dataset: https://www.cs.toronto.edu/~kriz/cifar.html

The CIFAR-10 dataset

The CIFAR-10 dataset consists of 60000 32x32 colour images in 10 classes, with 6000 images per class. There are 50000 training images and 10000 test images.

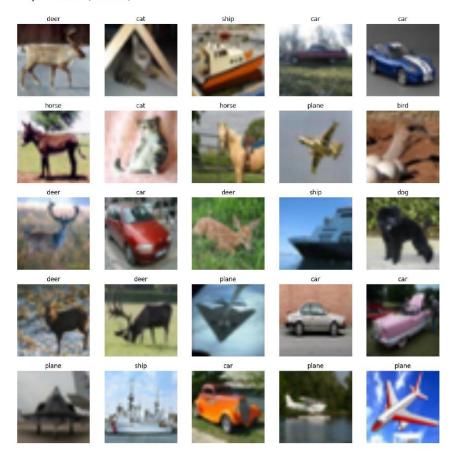
The dataset is divided into five training batches and one test batch, each with 10000 images. The test batch contains exactly 1000 randomly-selected images from each class. The training batches contain the remaining images in random order, but some training batches may contain more images from one class than another. Between them, the training batches contain exactly 5000 images from each class.

```
Imports
import torch
import torchvision
import torchvision.transforms as transforms
import torchvision.models as models
import torch.optim as optim
import torch.nn as nn
import torchmetrics
import random
import numpy as np
import matplotlib.pyplot as plt
/opt/conda/lib/python3.10/site-packages/scipy/__init__.py:146:
UserWarning: A NumPy version >=1.16.5 and <1.23.0 is required for this</pre>
version of SciPy (detected version 1.23.5
  warnings.warn(f"A NumPy version >={np_minversion} and
<{np_maxversion}"
# Make device agnostic code
device = "cuda" if torch.cuda.is available() else "cpu"
device
'cuda'
Setting random number seed
# Seed the RNG for all devices (both CPU and CUDA)
torch.manual seed(0)
# Set python seed
random.seed(0)
# Set numpy seed
np.random.seed(0)
# Force cuDNN to deterministically select an algorithm
# *possibly at the cost of reduced performance
torch.backends.cudnn.benchmark = False
# Configure PyTorch to use deterministic algorithms
```

```
# torch.use deterministic_algorithms(True) (involves env. variables,
so not used)
# Worker initialization function for data loaders (simplest approach)
def seed_worker(worker_id):
    worker seed = (torch.initial seed() + worker id) % 2**32
    np.random.seed(worker_seed)
    random seed (worker seed)
g train = torch.Generator()
g test = torch.Generator()
g_train.manual_seed(0)
g test.manual seed(1)
<torch. C.Generator at 0x790259c41e30>
# Calculate mean and std of test and train sets (255 - possible pixel
value range)
traindata = torchvision.datasets.CIFAR10(
\label{eq:root} root='./data', \; train=True, \; download=True).data \; / \; 255 \\ testdata = torchvision.datasets.CIFAR10(
    root='./data', train=False, download=True).data / 255
mean trn = traindata.mean(axis = (0,1,2))
std\_trn = traindata.std(axis = (0,1,2))
mean tst = testdata.mean(axis = (0,1,2))
std \overline{t}st = testdata.std(axis = (0,1,2))
# Create sequence of transformations: data -> resize to 256 x 256 ->
            -> (random horizontal flip for training data) -> tensor -
#
> (tensor - mean) / std
transform_train = transforms.Compose([
    transforms.Resize(256),
    transforms.RandomHorizontalFlip(),
    transforms.ToTensor(),
    transforms.Normalize(mean_trn, std_trn),
])
transform test = transforms.Compose([
    transforms.Resize(256),
    transforms.ToTensor(),
    transforms.Normalize(mean_tst, std_tst),
# Number of images in each batch, reccomended to == 2^n
batch size = 32
# Download CIFAR10 trainset
trainset = torchvision.datasets.CIFAR10(
```

```
root='./data', train=True, download=False,
transform=transform_train)
# Create a sampler, that provides an iterable over the trainset
trainloader = torch.utils.data.DataLoader(
    trainset, batch_size=batch_size, shuffle=True, num_workers=0,
worker init fn=seed worker, generator=g train)
# Download CIFAR10 testset
testset = torchvision.datasets.CIFAR10(
    root='./data', train=False, download=False,
transform=transform test)
# Create a sampler, for testset
testloader = torch.utils.data.DataLoader(
    testset, batch size=batch size, shuffle=False, num workers=0,
worker_init_fn=seed_worker, generator=g_test)
# 10 classes used in CIFAR10 dataset
classes = ('plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog',
'horse', 'ship', 'truck')
Downloading https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz to
./data/cifar-10-python.tar.gz
100%| 170498071/170498071 [00:03<00:00, 42899225.75it/s]
Extracting ./data/cifar-10-python.tar.gz to ./data
Files already downloaded and verified
In this lab work we don't perform hyperparameter tuning, as a result we split data only
into train/test sets and therefore don't use validation set (test set plays his role).
Data visualization
def imshow(imq):
    # Unnormalize image
    img = img * std trn[:, None, None] + mean trn[:, None, None]
    npimg = img.numpy()
    plt.imshow(np.transpose(npimg, (1, 2, 0)))
# Get some training images
dataiter = iter(trainloader)
images, labels = next(dataiter)
# Show images and labels in a grid 5x5
fig = plt.figure(figsize=(15, 15))
rows, cols = 5, 5
for i in range(0, rows * cols):
    img, label = images[i], labels[i]
    fig.add\_subplot(rows, cols, i + 1)
    imshow(img)
```

plt.title(classes[label]) plt.axis(False)



Neural network setup

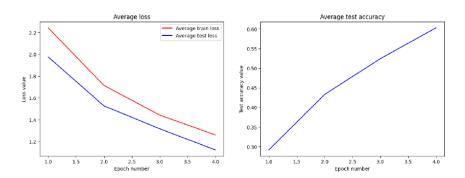
```
# Set up untrained AlexNet neural network with modified
# classification head to 10 classes, send this NN to GPU
alexnet = models.alexnet(num_classes=10).to(device)
```

```
# Set up loss criterion
criterion = nn.CrossEntropyLoss()
# Set up and send to GPU accuracy metric
accuracy = torchmetrics.Accuracy(task = 'multiclass',
num_classes=len(classes)).to(device)
# Set up stohastic gradient descent method of NN training with
# learning rate = 0.01
# momentum = 0.9
```

```
# (original values from scientific paper)
optimizer = optim.SGD(alexnet.parameters(), lr=0.001, momentum=0.9)
Network training
# Set the number of epochs
epochs = 4
# Set the number of batches, after which info will be displayed
cycle = 400
# Create required arrays to store loss and accuracy
train data len = len(trainloader)
train_loss_arr = np.zeros(epochs)
test_data_len = len(testloader)
test loss arr = np.zeros(epochs)
test_accuracy_arr = np.zeros(epochs)
# Create training and testing loop
for epoch in range(epochs):
    print(f"Current epoch: {epoch + 1}\n-----")
    ##### Training #####
    train_loss = test_acc = test_loss = 0
    # Set network to train mode
    alexnet.train()
    # Add a loop through training batches
    for batch_num, (tr_inputs, tr_labels) in enumerate(trainloader):
        # Send data to cuda (preferably)
tr_inputs = tr_inputs.to(device)
        tr labels = tr labels.to(device)
        # Zero the parameter gradients
        optimizer.zero_grad()
        # Forward, backward pass + optimization
        outputs = alexnet(tr_inputs).to(device)
        loss = criterion(outputs, tr labels)
        loss.backward()
        optimizer.step()
        # Accumulatively add up the loss per epoch
        train loss += loss
        # Print out how many samples have been seen
        # Save loss each cycle batches (cycle*batch samples)
        if batch num % cycle == 0 and batch num != 0:
            print(f"Looked at {batch_num * batch_size} samples")
            print(f"Current train loss for batch: {loss}")
    ##### Training end #####
```

```
##### Testing #####
    # Set network to evaluation mode
    alexnet.eval()
    # Turn on inference mode (no autograd)
    with torch.inference mode():
        for tst_inputs, tst_labels in testloader:
             # Send data to cuda (preferably)
             tst_inputs = tst_inputs.to(device)
             tst labels = tst labels.to(device)
             predictions = alexnet(tst inputs).to(device)
             # Test loss and accuracy calculation
            test_loss += criterion(predictions, tst_labels)
             test_acc += accuracy(predictions.argmax(dim=1),
tst_labels)
    ##### Testing end #####
        # Save average (throughout the epoch) loss and accuracy
        train_loss_arr[epoch] = train_loss / train_data_len
test_loss_arr[epoch] = test_loss / test_data_len
        test_accuracy_arr[epoch] = Test_acc / test_data_len
    # Print out average loss and accuracy of this epoch
print(f"\nAverage train loss: {train_loss_arr[epoch]:.5f}")
    print(f"Average test loss: {test_loss_arr[epoch]:.5f}, Average
test acc: {test_accuracy_arr[epoch]:.2f}%\n")
Current epoch: 1
Looked at 12800 samples
Current train loss for batch: 2.2986178398132324
Looked at 25600 samples
Current train loss for batch: 2.3025524616241455
Looked at 38400 samples
Current train loss for batch: 2.214437961578369
Average train loss: 2.24261
Average test loss: 1.97583, Average test acc: 0.29%
Current epoch: 2
Looked at 12800 samples
Current train loss for batch: 1.8430495262145996
Looked at 25600 samples
Current train loss for batch: 1.8827046155929565
Looked at 38400 samples
Current train loss for batch: 1.7750179767608643
Average train loss: 1.71503
Average test loss: 1.52774, Average test acc: 0.43%
```

```
Current epoch: 3
Looked at 12800 samples
Current train loss for batch: 1.2983227968215942
Looked at 25600 samples
Current train loss for batch: 1.4208163022994995
Looked at 38400 samples
Current train loss for batch: 1.4184082746505737
Average train loss: 1.44337
Average test loss: 1.31813, Average test acc: 0.52%
Current epoch: 4
Looked at 12800 samples
Current train loss for batch: 1.4427822828292847
Looked at 25600 samples
Current train loss for batch: 1.1974681615829468
Looked at 38400 samples
Current train loss for batch: 1.339410424232483
Average train loss: 1.26154
Average test loss: 1.12364, Average test acc: 0.60%
Weights saving
# Save weights to file 'AlexNet CIFAR10 weights.pth'
torch.save(alexnet.state dict(), 'AlexNet CIFAR10 weights.pth')
# To load weigths:
# alexnet.load state dict(torch.load('AlexNet CIFAR10 weights.pth'))
# alexnet.eval()
Accuracy and loss plots
plt.figure(figsize = (15, 5))
epoch_arr = np.arange(1, epochs + 1)
plt.subplot(121)
plt.plot(epoch_arr, train_loss_arr, 'r', label='Average train loss')
plt.plot(epoch_arr, test_loss_arr, 'b', label='Average test loss')
plt.title("Average loss")
plt.legend()
plt.tegend()
plt.xlabel("Epoch number")
plt.ylabel("Loss value")
plt.subplot(122)
plt.plot(epoch_arr, test_accuracy_arr, 'b')
plt.title("Average test accuracy")
plt.xlabel("Epoch number")
plt.ylabel("Test accuracy value")
plt.show()
```



Conclusions

As we see train and test loss were declining throughout the 4 epochs (as well as accuracy), this means that we stil haven't reached the optimum point (point, where train loss continue to decline, but test loss starts to rise). As a result it is advisable to continue training of the model, although, in this lab work, we will stop straining after epoch 4, due to limited computational resources. In the final run we got accuracy 60%, which is much better then accuracy of random classifier - 10%. In real situation we would also use validation test instead of test set, to tune hyperparameters of the model, and the test set would only be used to evaluate the performance of model after the training.

In this work to ensure reproducibility we set numpy, random and pytorch seed, as well as forced cuDNN to deterministically select an algorithm. We also saved the weights of the final model, so it's possible to reproduce latest results.

```
# OPTIONAL SECTION - WEIGHTS LOADING
alexnet.load_state_dict(torch.load('AlexNet_CIFARIO_weights.pth'))
alexnet.veul()

with torch.inference_mode():

test_loss = test_acc = 0
for tst_inputs, tst_labels in testloader:

# Send data to cuda (preferably)
tst_inputs = tst_inputs.to(device)
tst_labels = tst_labels.to(device)
predictions = alexnet(tst_inputs).to(device)

# Test loss and accuracy calculation
test_loss += criterion(predictions, tst_labels)
test_acc += accuracy(predictions, argmax(dim=1), tst_labels)

# Print out average loss and accuracy
print(f*Average test loss: {test_loss / len(testloader):.5f}, Average test acc: {test_acc / len(testloader):.2f}%\n*')

Python

As we see the results are the same as in the 4-th epoch
```