

1.1. Since $A \in \mathbb{R}^{n \times n}$ as a real $n \times n$ matrix.

To prove that the eigenvalues of AA^T and $A^T A$ are real and non-negative, we need to prove that AA^T and $A^T A$ are positive semidefinite

- The product of any matrix and its transpose is symmetric, so both AA^T and $A^T A$ are symmetric matrix. By properties of symmetric matrix that it has real eigenvalues, we know that

- Let λ be an eigenvalue of AA^T and q be the eigenvector associated with λ . Then, $(AA^T)q = \lambda q$

$$q^T (AA^T) q = \lambda q^T q$$

$$\lambda = \frac{q^T (AA^T) q}{q^T q} = \frac{z^T z}{q^T q} \quad \text{where } z = A^T q$$

Since $z^T z \geq 0$ and $q^T q \geq 0$, $\lambda \geq 0$, which implies that all eigenvalues of AA^T are nonnegative.

- Similar process can be done for $A^T A$.

Let λ' be an eigenvalue of $A^T A$ and q' be the eigenvector associated with λ' . Then, $(A^T A)q' = \lambda' q'$

$$q'^T (A^T A) q' = \lambda' q'^T q'$$

$$\lambda' = \frac{(Aq')^T Aq'}{q'^T q'} = \frac{z'^T z'}{q'^T q'} \quad \text{where } z' = Aq'$$

Since $z'^T z' \geq 0$ and $q'^T q' \geq 0$, $\lambda' \geq 0$, which implies that all eigenvalues of $A^T A$ are nonnegative.

Therefore, overall, the eigenvalues of AA^T and $A^T A$ are real and non-negative.

1.2. Claim: If $A \in \mathbb{R}^{m \times n}$ as a real $m \times n$ matrix, then $A^T A$ and $A A^T$ have the same nonzero eigenvalues.

Proof: Suppose A is an $m \times n$ matrix, and suppose that λ is a nonzero eigenvalue of $A^T A$. Then there exists a nonzero vector $x \in \mathbb{R}^n$ such that $(A^T A)x = \lambda x$ (1)

Multiplying both sides of the equation by A :

$$A(A^T A)x = A\lambda x$$

$$(A A^T)(Ax) = \lambda(Ax)$$

Since $\lambda \neq 0$ and $x \neq \vec{0}$, $\lambda x \neq \vec{0}$, and thus, by equation (1), $(A^T A)x \neq \vec{0}$; thus $A^T(Ax) \neq \vec{0}$, which implies $Ax \neq \vec{0}$.

Therefore, Ax is an eigenvector of $A A^T$ corresponding to eigenvalue λ .

An analogous argument can be used to show that every nonzero eigenvalue of $A A^T$ is an eigenvalue of $A^T A$, and thus completing the proof.

1.3. $A \in \mathbb{R}^{m \times n}$ as a real $m \times n$ matrix.

$$\underline{A} = \begin{bmatrix} \underline{a}_1 & \underline{a}_2 & \dots & \underline{a}_n \\ | & | & & | \\ \hline \end{bmatrix} = \begin{bmatrix} -x_1^T \\ -x_2^T \\ \vdots \\ -x_m^T \end{bmatrix} = \overset{m \times m}{U} \overset{m \times n}{\Sigma} \overset{n \times n}{V^T}$$

1) let $\underline{B} = A A^T = \sum_{i=1}^n \underline{a}_i \underline{a}_i^T$ as a symmetric matrix

$$\underline{B} = \underline{U} \overset{\underset{1}{\downarrow}}{\Sigma} \underline{V^T} \underline{V} \Sigma^T \underline{U^T} = \underline{U} \Sigma \Sigma^T \underline{U^T} = \underline{U} \begin{bmatrix} \sigma_1^2 & & 0 \\ & \ddots & \\ 0 & & \sigma_n^2 & \\ & & 0 & \ddots & 0 \end{bmatrix} \underline{U^T},$$

the form of eigendecomposition of B

Therefore, the left singular vector of $A \iff$ eigenvectors of $B = A A^T$,

and $\lambda_i = \begin{cases} \sigma_i^2 & i = 1, 2, \dots, n \\ 0 & i = n+1, \dots, m \end{cases}$, which means the

eigenvalues correspond to the square of singular values.

2) Let $B' = A^T A = \sum_{i=1}^m \underline{x}_i \underline{x}_i^T$ as a symmetric matrix

$$\underline{B}' = V \underline{\Sigma}^T \underbrace{U^T U}_{\underline{I}} \underline{\Sigma} V^T = V \underline{\Sigma}^T \underline{\Sigma} V^T = \underline{V} \begin{bmatrix} \sigma_1^2 & & 0 \\ & \ddots & \\ 0 & & \sigma_n^2 \end{bmatrix} \underline{V}^T$$

Therefore, right singular value of $A \Leftrightarrow$ eigenvectors of $B' = A^T A$, and $\lambda_i = \sigma_i^2$, $i = 1, 2, \dots, n$, which means the eigenvalues are given by the square of singular values.

In all, this set of eigenvalues are correspond to the square of singular values.

2.1 Let $A^{n \times n}$, a real square matrix.

If rows of A are orthonormal, $AA^T = I$

To prove that columns of A are also orthonormal, we need to show that $A^T A = I$.

Started by $AA^T = I$, multiply each side by A^{-1}

$$\underline{A^{-1} A A^T} = A^{-1} I$$

$$A^T = A^{-1} I$$

$$A^T = A^{-1}$$

By the properties of inverse matrix that

$$AA^T = I = A^T A, \text{ we can substitute } A^{-1} \text{ by } A^T.$$

Therefore, $AA^T = I = \underline{A^T A}$.

$A^T A = I$ implies that the columns of the matrix are orthonormal.

2.2. • $Ax=b$ is consistent $\Rightarrow \text{rank}(A) = \text{rank}(A|b)$

The system $Ax=b$ is consistent means that

$b \in$ column space of A , so the dimension of the column space of $A =$ the dimension of column space of $A|b$.

Since $\dim(\text{column space of } A) = \text{rank}(A|b)$,
 $\text{rank}(A) = \text{rank}(A|b)$

• $\text{rank}(A) = \text{rank}(A|b) \Rightarrow Ax=b$ is consistent

$\text{rank}(A) = \text{rank}(A|b)$

$\Rightarrow \dim(\text{column space of } A) = \dim(\text{column space of } A|b)$.

\Rightarrow a basis in column space of A is a basis in column space of $A|b$.

therefore, b is in the span of the columns of A , which means that $Ax=b$ is consistent.

• Geometrically $\text{Rank}(A) = \text{Rank}(A|b)$ means that adding the vector b as a column to A does not increase the dimension of the vector space spanned by the columns of A .

2.3. $M = [0, 1, 2]^{1 \times 3}$

$$u \Sigma^2 u^T$$

$$a) M M^T = [0, 1, 2] \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = 0+1+4=5. = [1] [5] [1]$$

Singular value $\Sigma = \sqrt{5}$

$$M^T M = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} [0, 1, 2] = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 2 & 4 \end{bmatrix}$$

$$\det(M^T M - \lambda I) = \det \begin{bmatrix} -\lambda & 0 & 0 \\ 0 & 1-\lambda & 2 \\ 0 & 2 & 4-\lambda \end{bmatrix} = \lambda^3 - 5\lambda^2$$

$$\lambda_1 = \lambda_2 = 0 \quad \lambda_3 = 5$$

$$M^T M - 5I = \begin{pmatrix} -5 & 0 & 0 \\ 0 & -4 & 2 \\ 0 & 2 & -1 \end{pmatrix} \quad v_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad v_2 = \begin{pmatrix} 0 \\ -2/\sqrt{5} \\ 1/\sqrt{5} \end{pmatrix} \quad v_3 = \begin{pmatrix} 0 \\ 1/\sqrt{5} \\ 2/\sqrt{5} \end{pmatrix}$$

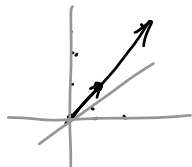
$$M^T M - 0I = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 2 & 4 \end{pmatrix} \Rightarrow V = \begin{pmatrix} 0 & 1/\sqrt{5} & 2/\sqrt{5} \\ 1 & 0 & 0 \\ 0 & -2/\sqrt{5} & 1/\sqrt{5} \end{pmatrix}$$

$$\Sigma = (\sqrt{5}, 0, 0)$$

Therefore, by SVD,

$$M = [0, 1, 2]^{1 \times 3} = [1]^{1 \times 1} \cdot [\sqrt{5}, 0, 0]^{1 \times 3} \begin{bmatrix} 0 & 1/\sqrt{5} & 2/\sqrt{5} \\ 1 & 0 & 0 \\ 0 & -2/\sqrt{5} & 1/\sqrt{5} \end{bmatrix}^{3 \times 3}$$

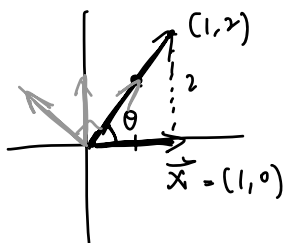
b).



Since the column space of M is a one dimensional subspace spanned by row vector $[0, 1, 2]$, we can view M as a transformation of unit vector $(0, 1)$ to $(1, 2)$. Instead of applying $(1, 2)$ to

the unit vector, instead, we do rotation, stretching,

and then different rotation. In \mathbb{R}^2 , to transform



$(1, 0)$ to $(1, 2)$ we need to apply

$$\begin{pmatrix} \cos(\tan^{-1} 2) & -\sin(\tan^{-1} 2) \\ \sin(\tan^{-1} 2) & \cos(\tan^{-1} 2) \end{pmatrix}$$

which is $\begin{pmatrix} 1/\sqrt{5} & -2/\sqrt{5} \\ 2/\sqrt{5} & 1/\sqrt{5} \end{pmatrix}$ by rotation.

Then, to stretch \mathbb{R}^2 to what we want as $(1, 2)$ we need to multiply the vectors by $\sqrt{5}$ as $\|(1, 2)\| = \sqrt{5} \|(1, 0)\|$.

Therefore, the stretching determines the singular value of $\sqrt{5}$.

Since we do not need an extra rotation, the

transformation is done, so just set U as I .

Finally, map the 2D space back to 3D where $M = [0, 1, 2]$, we just need to expand the column and row by one for rotation, and column by one for stretching.

Therefore, $U = (I)$, $\Sigma = (\sqrt{5}, 0, 0)$, and $V = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1/\sqrt{5} & -2/\sqrt{5} \\ 0 & 2/\sqrt{5} & 1/\sqrt{5} \end{pmatrix}$

Since the row of matrix can change,

V^T can be written as $\begin{pmatrix} 0 & 1/\sqrt{5} & 2/\sqrt{5} \\ 1 & 0 & 0 \\ 0 & -2/\sqrt{5} & 1/\sqrt{5} \end{pmatrix}$

$$V^T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1/\sqrt{5} & 2/\sqrt{5} \\ 0 & -2/\sqrt{5} & 1/\sqrt{5} \end{pmatrix}$$

to match A .

Therefore, $A = (I) (\sqrt{5}, 0, 0) \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1/\sqrt{5} & 2/\sqrt{5} \\ 0 & -2/\sqrt{5} & 1/\sqrt{5} \end{pmatrix}$.

$$3. | \quad A^{m \times n} x^{n \times 1} = b^{m \times 1}, \quad m > n$$

$${}^m \begin{bmatrix} \\ \\ \end{bmatrix} {}^n \begin{bmatrix} \\ \\ \end{bmatrix} = \begin{bmatrix} \\ \\ \end{bmatrix} {}^m$$

To minimize the error $\|Ax^* - b\|_2$, we can minimize $\|Ax^* - b\|_2^2$.

$$\|Ax^* - b\|_2^2 = \|b - Ax^*\|_2^2 = (b - Ax^*)^T (b - Ax^*)$$

$$= (b^T - x^{*T} A^T) (b - Ax^*)$$

$$= b^T b - b^T A x^* - x^{*T} A^T b + x^{*T} A^T A x^*$$

To find the local minimum, we apply derivative to $\|Ax^* - b\|_2^2$

$$\frac{d\|Ax^* - b\|_2^2}{dx^*} = 0 - b^T A - (A^T b)^T + 2x^{*T} A^T A$$

The local minimum/maximum exist when derivative equals zero

$$\Rightarrow x^{*T} A^T A = x^{*T} b^T A$$

Since A is full rank, $A^T A$ is invertible

$$x^* = b^T A (A^T A)^{-1}$$

$$x^* = (A^T A)^{-1} A^T b$$

To check it's local minimum we need to check second derivative is greater than 0 $\frac{d^2 \|Ax^* - b\|_2^2}{dx^{*2}} = 2A^T A$

Since $A^T A$ is non-negative, so $\frac{d^2 \|Ax^* - b\|_2^2}{dx^{*2}} \geq 0$, which means $x^* = (A^T A)^{-1} A^T b$ is a local minimum.

3.2 Least Square via SVD.

\Rightarrow Find $\min_x \|Ax - b\|_2^2$

$$AV = \Sigma U$$

$$\|Ax - b\|_2^2 = \|(U \Sigma V^T)x - b\|_2^2$$

Since U is orthogonal matrix, $\|U^T\| = 1$. we can add a U^T in the front and since $AV = \Sigma U \Rightarrow U = AV \Sigma^T$, so

$$= \|U^T (AV \Sigma^T \Sigma V^T)x - b\|_2^2$$

$$= \|U^T (AV V^T x - b)\|_2^2$$

$$= \|\Sigma (\underbrace{V^T x}_z) - U^T b\|_2^2$$

$$= \|\Sigma z - U^T b\|_2^2$$

$$\text{let } V^T x = z$$

$$\text{let Rank}(A) = r.$$

$$= \sum_{i=1}^r (\sigma_i z_i - u_i^T b)^2 + \sum_{i=r+1}^m (u_i^T b)^2$$

The optimal solution is given by $z_i = \frac{u_i^T b}{\sigma_i}$, for $i = 1, \dots, r$

and the object becomes $\sum_{i=r+1}^m (u_i^T b)^2 = \min_x (\|Ax - b\|_2^2)$

Therefore, the actual x^* :

$$x^* = V z^*$$

$$x^* = \sum_{i=1}^r \left(\frac{u_i^T b}{\sigma_i} \right) v_i$$