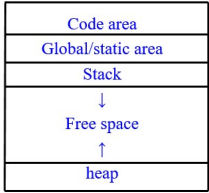


and make delete operation difficult.
2) Separate chaining
Each bucket is a linear list , collisions are resolved by inserting the new item into the bucket list.
It is the best scheme for compiler construction.
The Size of the hash table
The actual size of the bucket array should be chosen to be a **prime number**
The algorithm of the Hash function
Repeatedly use a constant number α as a multiplying factor when adding in the value of the next character
$$h_{i+1} = \alpha h_i + \alpha_i, h_0 = 0$$
$$h = (\text{Sigma}(i=1 \rightarrow n) \alpha_i \alpha^{-i} (n-i)) \bmod \text{size}$$
The choice of α has a significant effect on the outcome, a reasonable choice for α is a power of 2, such as 16 or 128, 因为这样乘法可以用移位来完成
Sequential declaration:
Each declaration is added to the symbol table as it is processed.
Collateral declaration:
Declarations not to be added immediately to the existing symbol table.
Accumulated in a new table (or temporary structure).
Added to the existing table after all declarations have been processed.
Recursive declaration:
Declaration may refer to themselves or each other.
Runtime Environments
General organization of runtime storage



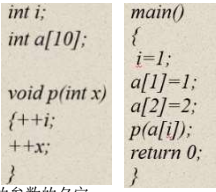
Fully Static Runtime Environment
All data are static, remaining fixed in memory for the duration of program execution.
Used for a language, such as FORTRAN77.
no pointer or dynamic allocation.
no recursive procedure calling.
The global variables and all variables are allocated statically.
Each procedure has only a single activation record.
All variables (local or global) can be accessed directly via fixed address.
No extra information about the environment needs to be kept in an activation record.
The calling sequence (simple)
Each argument is computed and stored into its appropriate parameter location in the activation of the procedure being called.
1) The return address in the code of the caller is saved.
2) A jump is made to the beginning of the code of the called procedure.
3) On return, a simple jump is made to the return address.
In FORTRAN77:
1) an extra reference is required to access parameter values.
2) array parameters do not need to be reallocated and copied.
3) constant arguments must be stored to a memory location and this location used during the call.
The unnamed location is used to store temporary value during the computation of arithmetic expression.
Stack-based runtime environment
1) Recursive calls are allowed
2) Local variables are newly allocated at each call
3) Activation records cannot be allocated statically. Instead, activation records must be allocated in a stack-based fashion.
4) The stack of activation records grows and shrinks with the main of calls in the executing program.
5) Each procedure may have several different activation records on the call stack at one time.
6) More complex strategy for bookkeeping and variable access
The calling sequence:
1) Compute the arguments and store them in their correct positions in the new activation record of the procedure.
2) Store the fp as the control link in the new activation record;
3) Change the fp so that it points to the beginning of the new activation record;
4) Store the return address in the new activation record;
5) Perform a jump to the code of the procedure to be called.
access link represents the defining environment of the procedure; access link is sometimes also called the static link.
control link represents the calling environment of the procedure.
可以通过 Control Link 来找到每个函数中的局部变量, 但是必须在执行时保存用于每个过程的局部符号表, 这样才可能允许在每个活动记录中查询标识符, 以及若它退出的话也可以看到, 并且可以判定

出它的偏移。这是运行时环境的最主要额外复杂性。解决这个问题方法也实现静态作用域, 是将一个 **access link** 额外信息添加到每个活动记录中, 除了可以指向代表过程的定义环境而不是调用环境之外, 访问链与控制链相似, 正是由于这个原因, 即使它不是编译时决定的量, 访问链有时也被成为静态链(static link)
Heap Management:
A standard method for maintaining the heap and implementing these functions:
(1) A circular linked list of free blocks.
(2) Memory is taken by malloc.
(3) Memory is return by free.
Drawbacks:
(1) The free operation can not tell if the pointer is legal or not.
(2) Care must be taken to coalesce blocks, otherwise, the heap can quickly become fragmented.
A different implementation of malloc and free.
Use a circular linked list data structure that keep track of both allocated and free block.
Automatic Management of the heap:
Mark and sweep garbage collection
No memory is freed until a call to malloc fails, which does this in two passes.
(1) Follows all pointers recursively, starting with all currently accessible pointer values and marks each block of storage reached.
(2) Sweeps linearly through memory.
returning unmarked blocks to free memory.
perform memory compaction to leave only one large block of contiguous free space at the other end.
Drawbacks:1. Require extra storage 2. The double pass through memory cause a significant delay in processing
这种方法中, 直到一个对 malloc 的调用失败之前都不会释放存储器, 在这是将垃圾回收程序激活, 寻找可被引用的所有存储器并释放所有未引用的存储器。这是通过两遍来完成的。第一遍递归的访问所有的指针前进, 从所有当前的可访问指向值开始, 并标出到达的每个存储块。这个过程要求额外的位存储标识, 另一个则线性地扫描存储器, 并将未标出的块反馈到自由存储器中。虽然这个过程通常要寻找足够的相邻自由存储器以满足一系列的新要求, 但存储器有可能非常破碎, 故尽管是在垃圾回收之后, 大的存储请求仍会失败, 因此, 垃圾回收经常也会通过将所有的内存空间移到堆的末尾, 以及在另一端留下相邻的自由空间的唯一一个大块儿执行存储器压缩(memory compaction)。这个过程还必须在存储器中更新对那些在执行程序时被移除的区域的所有引用。标识和扫描垃圾回收有若干缺点: 它要求额外的存储 (用于标识), 在存在气中的两个遍历导致了过程中很大的延迟, 有时需要几秒钟, 而每一次的调用垃圾回收程序又都需要几分钟时间。这对于那些许多设计到了交互和即时相应的应用程序显然是不合适的。
Stop-and-copy or two-space garbage collection
(1) During the marking pass, all reached blocks are immediately copied to the second half of storage not in use;
(2) No extra mark bit is required and only one pass is required;
(3) It also performs compaction automatically.
(4) It does little to improve processing delays during storage reclamation.
可以通过将可用的存储器分为两个部分并每次只从一个部分中分配存储来对这个过程进行改进。在标识遍历时, 将所有的块都复制到未被使用的另一半存储器中, 这就意味着在存储式不在要求额外的标志位而且只需要一遍就够了。它还自动地进行压缩。一旦位于使用的区域中的所有可达到的块都复制好时, 就将使用的和未使用的存储器部分相互交换, 而过程依然继续进行。对存储回收过程中的过程延迟改进不大。
General garbage collection:
Allocated objects that survive long enough are simply copied into permanent space and are never deallocated during subsequent storage reclamations.
这就意味着垃圾回收程序在更新的存储分配时只需要搜索存储器中很小的一部分, 当然永久存储器也有可能由于不可达到的过程而用尽, 但这相对于前面的问题就不那么严重了, 这是因为临时存储会很快消失, 而可被分配的存储则总会有的。人们已经证明了这个存储方法很好, 在虚拟存储系统中尤为如此。
Parameter Passing Mechanisms:
Pass by value
The arguments are expressions that are evaluated at the time of the call.
Their values becomes the values of the parameter during the execution of the procedure.
The only parameter passing mechanism available in C; C 常用的方式
The default in Pascal and Ada
Pass by reference
Pass by reference passes the location of the variable.
The parameter becomes an alias for the argument.
The only parameter passing mechanism in Fortran77
In Pascal, pass by reference achieved with the use of var keyword
In C++, by the use of special symbol & in the

parameter declaration
在引用传递中, 自变量必须与分配的地址一起变化。并非传递变量的值; 引用传递的是变量的地址, 因此参数就成为了自变量的别名(alias), 而且在参数上发生的任何变化都会出现在自变量上
Fortran 这样只可用引用传递的语言中, 要为了不带地址的值的自变量提供一个位置
如 P(2+3) 是非合法的, 编译程序必须为 2+3 创造一个地址并把 2+3 传进去在进行引用
Pass by value-result
The mechanism achieves a similar result to pass by reference, except that no actual alias is established.
Known as copy-in, copy-out, or copy- restore.
The value of the argument is copied into the procedure.
The final value of the parameter is copied back out to the location of the argument.
This is the mechanism of Ada in out parameter.
在过程中复制和使用自变量的值, 当过程退出时, 再将参数的最终值复制回自变量的地址。

```
void p(int x, int y)
{
    ++x;
    ++y;
}
main()
{
    int a=1;
    p(a, a);
    return 0;
}
```


If pass by reference, a is 3, if pass by value-result, a is 2
Pass by name
This is the most complex of the parameter passing mechanisms. (delayed evaluation)
Idea:
The argument is not evaluated until its actual use in the called program.
思想是知道在被调用的程序真正使用了自变量 (作为一个参数) 之后才对这个自变量赋值, 所以它还被称为延迟赋值(delayed evaluation)因此, 自变量的名称或是它在调用点上的结构表示取代了它对



应的参数的名字。
对 p 的调用的结果是让 a[2] 设置为 3 并保持 a[1] 不变
在调用点上的自变量的文本被看成是它自己右边的函数, 每当在被调用的过程的代码中到达相应的参数名时, 就要计算它。
Code Generation
Three-Address Code:
The most basic instruction of three address code is designed to represent the evaluation of arithmetic expressions and has the following general form:
$$x = y \text{ op } z$$

其中 x 的地址必须不同于 y, z 的地址, y, z 可以代表常量, 但是 x 不行
$$2^*a + (b-3) \text{ 转换为 } T1 = 2^*a$$
$$T2 = b - 3$$
$$T3 = T1 + T2$$

其中 T1, T2, T3 均为临时变量
Data Structures for the Implementation of Three-Address Code:
1) Four fields are necessary: one for the operation and three for the addresses. Such a representation of three-address code is called a quadruple.
2) Those instructions that need fewer than three addresses, one or more of the address fields is given a null or "empty" value.
3) The entire sequence of three-address instructions is implemented as an array or linked list.
4) We allow an address to be only an integer constant or a string (representing the name of a temporary or a variable).
5) Since names are used, these names must be entered into a symbol table, and lookups will need to be performed during further processing.
6) An alternative to keeping names in the quadruples is to keep pointers to symbol table entries. This avoids the need for additional lookups and is particularly advantageous in a language with nested scopes.
7) A different implementation of three-address code is use the instructions themselves to represent the temporaries. Such an implementation of three-address code is called a triple.
P-Code:
P-code began as a standard target assembly code produced by a number of Pascal compilers of the 1970s and early 1980s.
It was designed to be the actual code for a hypothetical stack machine, called the P-machine, for which an interpreter was written on various actual machines.
The P-machine consists of a code memory, an unspecified data memory for named variables, and a stack for temporary data, together with whatever registers are needed to maintain the

stack and support execution.
Example:
 $2^*a + (b-3)$:
ldc 2 ;load constant 2 (pushes 2 onto the temporary)
lod a ;load value of variable a(pushes a onto the temporary)
mpi ;integer multiplication (pops these two values from the stack, multiplies them (in reverse order), and pushes the result onto the stack.)
lod b ;load value of variable b
ldc 3 ;load constant 3
sbi ;integer subtraction(subtracts the first from the second)
adi ;integer addition
x:=y+1;
lda x ;load address of x
lod y ;load value of y
ldc 1 ;load constant 1
adi ;add
sto ;store top to address below top & pop both
other:
stn : stores the value to the address but leaves the value at the top of the stack, while discarding the address.
1) P-code is in many respects closer to actual machine code than three-address code. P-code instructions also require fewer addresses:
2) P-code is less compact than three-address code in terms of numbers of instructions, and P-code is not "self-contained" in that the instructions operate implicitly on a stack.
3) Historically, P-code has largely been generated as a text file, but the previous descriptions of internal data structure implementations for three-address code will also work with appropriate modification for P-code.
Code Generation
Intermediate code generation can be viewed as an attribute computation. This code becomes a synthesized attribute that can be defined using an attribute grammar and generated either directly during parsing or by a postorder traversal of the syntax tree.


```
Begin
If T is not nil then
    Generate code to prepare for code of left child of T;
    Genscode(left child of T);
    Generate code to prepare for code of right child of T;
    Genscode(right child of T);
    Generate code to implement the action of T;
End;
```


Data Structure References
Three-Address Code:
$$t1 = \&x + 10$$
$$*t1 = 2$$
P-Code:
ind ("indirect load") ind i
ixa ("indexed address")
Each address must be computed from the base address of a (its starting address in memory) and an offset that depends linearly on the value of the subscript.
The offset is computed from the subscript value as follows.
1) An adjustment must be made to the subscript value if the subscript range does not begin at 0.
2) The adjusted subscript value must be multiplied by a scale factor that is equal to the size of each array element in memory. Finally, the resulting scaled subscript is added to the base address to get the final address of the array element.
Example:
$$a[i+1] = a[j*2] + 3$$
Three-Address Code:
$$t1 = j * 2 \quad t2 = a[t1] \quad t3 = t2 + 3$$
$$t4 = i + 1 \quad a[t4] = t3$$
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<code for S>
up L1
lab L2
Logical Expressions
$$(x \neq 0) \&\& (y == x)$$

lod x ldc 0 neq fip L1 lod y lod x equ fip L1 up L2 lab L1 lod FALSE lab L2
Procedure and Function Calls
int f(x, int y)
{ return x + y + 1; }
Three-Address Code:
entry f t1 = x + y t2 = t1 + 1 return r2
P-Code:
ent f lod x lod y adi ldc 1 adi ret
The call f(2+3, 4)
Three-Address Code:
begin args t1 = 2 + 3 arg t1 arg 4 call f
P-Code:
mst: mark stack, the same as begin_args in Three-Address Code
cup: call user procedure
mst ldc 2 ldc 3 adi ldc 4 cup f
Example:
fn f(x) = 2+x;
fn g(x,y) = f(x)+y;
g(3,4)
P-Code:
ent f ldc 2 lod x adi ret
ent g mst lod x cup f lod y adi ret
mst ldc 3 ldc 4 cup g
More Examples
LL(1):
S \rightarrow ES'
S' $\rightarrow \epsilon \mid +S$
E $\rightarrow \text{num} \mid (S)$

	num	+	()	S
S	$S \rightarrow \text{ES}'$		$S \rightarrow \text{ES}'$		
S'		$S' \rightarrow +S$		$S' \rightarrow \epsilon$	$S' \rightarrow \epsilon$
E	$E \rightarrow \text{num}$		$E \rightarrow (S)$		

LR(0):
A $\rightarrow (A) \mid a$

State	(a)	A	Goto
0	s3	s2			1
1	r2	r1	r1		
2	r1	r2	r2		
3	s3	s2			4
4			s5		
5	r3	r3	r3		

Parsing stack	Input	Action
1 \$0	((a))\$	(a)\$ Shift
2 \$0 (3	((a))\$	(a)\$ Shift
3 \$0 (3 (3	((a))\$	(a)\$ Shift
4 \$0 (3 (3 a2	((a))\$	j\$ Reduce A -> a
5 \$0 (3 (3 A4	j\$	j\$ Shift
6 \$0 (3 (3 A4 j5	j\$	Reduce A -> (A)
7 \$0 (A4	j\$	j\$ Shift
8 \$0 (3 A4 j5	j\$	Reduce A -> (A)
9 \$0 A1	j\$	\$ Accept

SLR(1):
Not LR(0), but SLR(1)

LR(1):
A $\rightarrow (A) \mid a$

State	(a)	\$	Goto
0	s2	s3			1
1			accept		
2	s5	s6			4
3			r2		
4			s7		
5	s5	s6			8
6			r2		
7			r1		
8			s9		
9			r1		

LALR(1):
A $\rightarrow (A) \mid a$