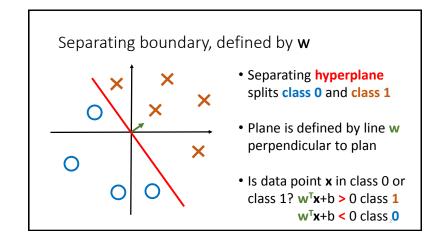
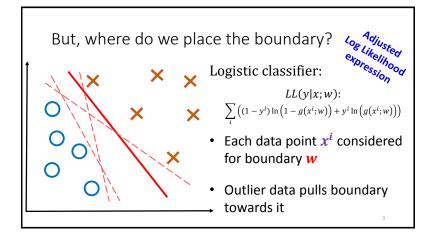
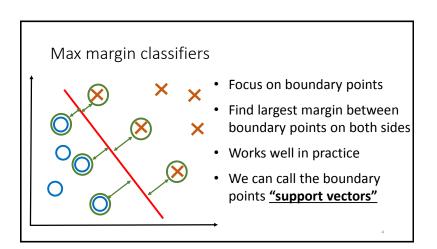
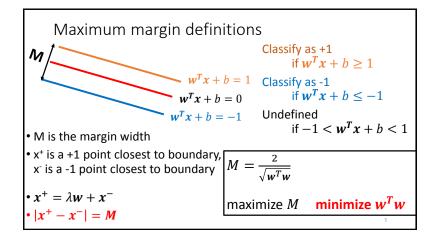
Support Vector Machines

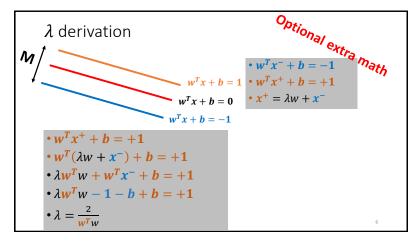
CISC 5800 Professor Daniel Leeds

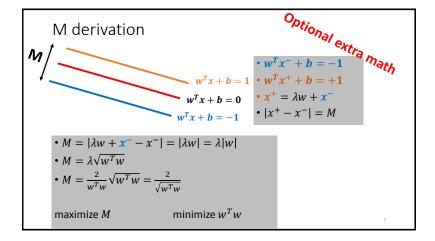


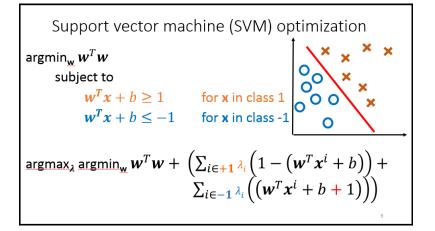












Support vector machine (SVM) optimization

$$\begin{array}{l} \operatorname{argmin}_{\mathbf{w}} \mathbf{w}^T \mathbf{w} + \left(\sum_{i \in +1} \lambda_i \left(1 - \left(\mathbf{w}^T \mathbf{x}^i + b \right) \right) + \\ \sum_{i \in -1} \lambda_i \left(\left(\mathbf{w}^T \mathbf{x}^i + b + 1 \right) \right) \end{array} \right) \end{array}$$

Find λ that causes highest error

Find **w** that causes lowest error given hardest λ

Gradient ascent:
$$\lambda_i \leftarrow \lambda_i + \varepsilon \frac{\partial}{\partial \lambda_i} \mathcal{L}(x, y; w, \lambda)$$

Gradient descent:
$$w_j \leftarrow w_j - \varepsilon \frac{\partial}{\partial w_j} \mathcal{L}(\mathbf{x}, y; \mathbf{w}, \lambda)$$

Support vector machine (SVM) optimization

$$\begin{vmatrix} \operatorname{argmax}_{\lambda} \operatorname{argmin}_{\mathbf{w}} \mathbf{w}^T \mathbf{w} + \left(\sum_{i \in +1} \lambda_i \left(1 - \left(\mathbf{w}^T \mathbf{x}^i + b \right) \right) + \sum_{i \in -1} \lambda_i \left(\left(\mathbf{w}^T \mathbf{x}^i + b + 1 \right) \right) \end{vmatrix}$$

$$\mathcal{L}(\mathbf{x}, \mathbf{y}; \mathbf{w}, \lambda) = \mathbf{w}^T \mathbf{w} + \left(\sum_{i \in +1} \lambda_i \left(1 - \left(\mathbf{w}^T \mathbf{x}^i + b \right) \right) + \sum_{i \in -1} \lambda_i \left(\left(\mathbf{w}^T \mathbf{x}^i + b + 1 \right) \right) \right)$$

Gradient ascent: $\lambda_i \leftarrow \lambda_i + \varepsilon \frac{\partial}{\partial \lambda_i} \mathcal{L}(x,y;w,\lambda)$ Require $\lambda \geq 0$ If λ drops below 0,
Gradient descent: $w_j \leftarrow w_j - \varepsilon \frac{\partial}{\partial w_j} \mathcal{L}(x,y;w,\lambda)$ reset to $\lambda = 0$

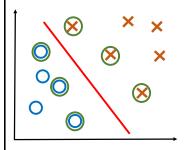
Support vector machine (SVM) optimization

$$\begin{aligned} \operatorname{argmax}_{\lambda} \operatorname{argmin}_{\mathbf{w}} \mathbf{w}^T \mathbf{w} + \left(\sum_{i \in \mathbf{+1}} \lambda_i \left(1 - \left(\mathbf{w}^T \mathbf{x}^i + b \right) \right) + \\ \sum_{i \in \mathbf{-1}} \lambda_i \left(\left(\mathbf{w}^T \mathbf{x}^i + b + 1 \right) \right) \end{aligned} \end{aligned}$$

Gradient descent:
$$w_j \leftarrow w_j - \varepsilon \frac{\partial}{\partial w_i} \mathcal{L}(\mathbf{x}, \mathbf{y}; \mathbf{w}, \boldsymbol{\lambda})$$

$$\frac{\partial}{\partial w_i} \mathcal{L}(\mathbf{x}, y; \mathbf{w}, \lambda) : \ \mathbf{2}w_j + \left(\sum_{i \in +\mathbf{1}} -\lambda_i x_j^i + \sum_{i \in -\mathbf{1}} \lambda_i x_j^i\right)$$

Alternate SVM formulation

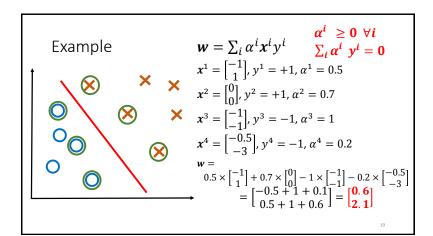


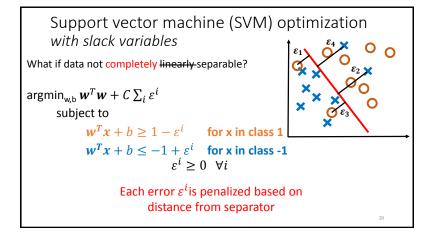
$$\mathbf{w} = \sum_{i} \alpha^{i} \mathbf{x}^{i} \mathbf{y}^{i}$$

Support vectors x_i have $\alpha_i > 0$

 y_i are the data labels +1 or -1

$$\alpha^i \geq 0 \ \forall i \qquad \sum_i \alpha^i \ y^i = 0$$





Support vector machine (SVM) optimization with slack variables

Example: Linearly separable but with narrow margins $argmin_{w,b} \mathbf{w}^T \mathbf{w} + C \sum_i \varepsilon^i$ subject to $\mathbf{w}^T x + b \ge 1 - \varepsilon^i \qquad \text{for x in class 1}$ $\mathbf{w}^T x + b \le -1 + \varepsilon^i \qquad \text{for x in class -1}$ $\varepsilon_i \ge 0 \quad \forall i$

Hyper-parameters for learning

 $\operatorname{argmin}_{wh} \mathbf{w}^T \mathbf{w} + C \sum_i \varepsilon_i$

Optimization constraints: **C** influences tolerance for label errors versus narrow margins

$$w_j \leftarrow w_j + \varepsilon \mathbf{x}_j^i (y^i - g(\mathbf{w}^T \mathbf{x}^i)) - \frac{w_j}{\lambda}$$

Gradient ascent:

- E influences effect of individual data points in learning
- T number of training examples, L number of loops through data balance learning and over-fitting

Regularization: *↑* influences the strength of your prior belief

Parameter counts

Each data point x^i has N features (presuming classify with w^Tx^i+b)

Separator: w and b

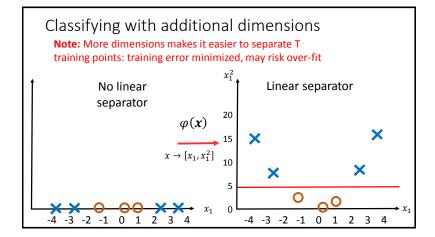
- N elements of w, 1 value for b: N+1 parameters OR
- t support vectors -> t non-zero α^i , 1 value for b: t+1 parameters

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Binary -> M-class classification

- Learn boundary for class m vs all other classes
 - Only need M-1 separators for M classes Mth class is for data outside of classes 1, 2, 3, ..., M-1
- Find boundary that gives highest margin for data points xi

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Quadratic mapping function (math) $\sum_{i=1}^{w^{T}} x^{k} + b = \sum_{i=1}^{s} a^{i} y^{i} (x^{i})^{T} x^{k} + b$

$$X_1, X_2, X_3, X_4 \rightarrow X_1, X_2, X_3, X_4, X_1^2, X_2^2, ..., X_1X_2, X_1X_3, ..., X_2X_4, X_3X_4$$

N features ->
$$N + N + \frac{N \times (N-1)}{2} \approx N^2$$
 features

space

N² values to learn for w in higher-dimensional space

Or, observe:
$$(\boldsymbol{v}^T\boldsymbol{x}+1)^2 = \boldsymbol{v}_1^2x_1^2 + \cdots + \boldsymbol{v}_N^2x_N^2 + \boldsymbol{v}_1\boldsymbol{v}_2x_1x_2 + \cdots + \boldsymbol{v}_{N-1}\boldsymbol{v}_Nx_{N-1}x_N + \boldsymbol{v}_1x_1 + \cdots + \boldsymbol{v}_Nx_N$$
v with N elements operating in quadratic

Quadratic mapping function **Simplified**

$$\mathbf{x} = [\mathbf{x}_1, \mathbf{x}_2] \rightarrow [\sqrt{2}\mathbf{x}_1, \sqrt{2}\mathbf{x}_2, \mathbf{x}_1^2, \mathbf{x}_2^2, \sqrt{2}\mathbf{x}_1\mathbf{x}_2, 1]$$

$$\mathbf{x}^i = [5, -2] \rightarrow [10, -4, 25, 4, -20, 1] \quad \mathbf{x}^k = [3, -1] \rightarrow [6, -2, 9, 1, -6, 1]$$

$$\varphi(\mathbf{x}^i)^T \varphi(\mathbf{x}^k) = 30 + 4 + 225 + 4 + 60 + 1 = 324$$
Or, observe:
$$\left(\mathbf{x}^{i^T} \mathbf{x}^k + 1\right)^2 = \left((15 + 2) + 1\right)^2 = (18)^2 = 324$$

Mapping function(s)

- Map from low-dimensional space $x = (x_1, x_2)$ to higher dimensional space $\varphi(x) = (\sqrt{2}x_1, \sqrt{2}x_2, x_1^2, x_2^2, \sqrt{2}x_1x_2, 1)$
- N data points guaranteed to be separable in space of N-1 dimensions or more

$$\mathbf{w} = \sum_{i} \alpha_{i} \varphi(\mathbf{x}^{i}) y^{i}$$
$$\sum_{i} \alpha_{i} y^{i} \varphi(\mathbf{x}^{i})^{T} \varphi(\mathbf{x}^{k}) + b$$

Classifying x^k :

$$\sum_{i} \alpha_{i} y^{i} \varphi(x^{i})^{T} \varphi(x^{k}) + b$$

Kernels

Classifying x^k :

$$\sum_{i} \alpha_{i} y^{i} \varphi(\mathbf{x}^{i})^{T} \varphi(\mathbf{x}^{k}) + b$$

Kernel trick:

• Estimate high-dimensional dot product with function

•
$$K(x^i, x^k) = \varphi(x^i)^T \varphi(x^k)$$

Now classifying \mathbf{x}^k

$$\sum_{i} \alpha_{i} y^{i} K(\boldsymbol{x}^{i}, \boldsymbol{x}^{k}) + b$$

Radial Basis Kernel

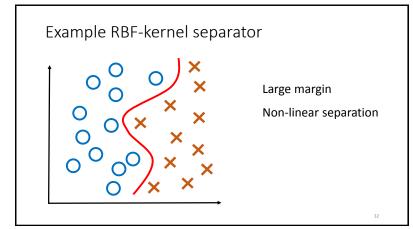
Try projection to infinite dimensions

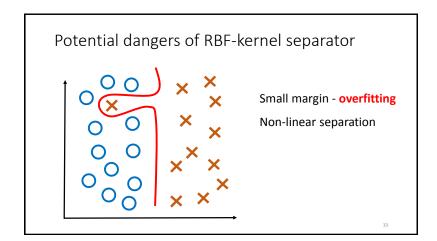
$$\varphi(\mathbf{x}) = \left[x_1, \dots, x_n, x_1^2, \dots, x_n^2, \dots, x_1^{\infty}, \dots, x_n^{\infty}\right]$$

Taylor expansion: $e^x = \frac{x^0}{0!} + \frac{x^1}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots + \frac{x^{\infty}}{\infty!}$

$$K(x^{i}, x^{k}) = \exp\left(-\frac{(x^{i} - x^{k})^{2}}{2\sigma^{2}}\right)$$
Note: $(x^{i} - x^{k})^{2} = (x^{i} - x^{k})^{T}(x^{i} - x^{k})$

Draw separating plane to curve around all support vectors





The power of SVM (+kernels)

Boundary defined by a few support vectors

- Caused by: maximizing margin
- Causes: less overfitting
- Similar to: regularization

 $\label{lem:condition} \textit{Kernels keep number of learned parameters in check}$

Benefits of generative methods

- $P(\boldsymbol{D}|\boldsymbol{\theta})$ and $P(\boldsymbol{\theta}|\boldsymbol{D})$ can generate non-linear boundary
- E.g.: Gaussians with multiple variances

