

Implementation of Kirchhoff acoustic solver

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1 Mathematical formulation

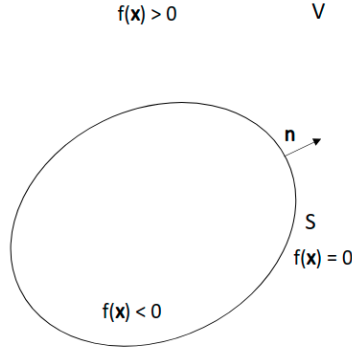


Figure 1: Stationary Kirchhoff surface S encloses sound source

In this section, we derive the Kirchhoff formula for a stationary control surface (Farassat et al. 1988). We chose a control surface S that encloses all the acoustic sources (1), and the pressure perturbations p satisfies the homogeneous wave equation

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) p = 0 \quad \text{in } V. \quad (1)$$

The control surface S is defined by $f(\mathbf{x}) = 0$, $f(\mathbf{x}) > 0$ for \mathbf{x} in V and $f(\mathbf{x}) < 0$ for \mathbf{x} inside surface S . We scale the function f such that $\nabla f = \mathbf{n}$. Then the Heaviside function of $f(\mathbf{x})$ is

$$H(f) = \begin{cases} 1, & \text{for } \mathbf{x} \text{ in } V. \\ 0, & \text{for } \mathbf{x} \text{ inside } S. \end{cases} \quad (2)$$

The gradient of the Heaviside function is given by

$$\nabla H(f) = \delta(f) \mathbf{n}. \quad (3)$$

We define the pressure p as a generalized function $pH(f)$ (Ffowcs Williams et al. 1969) where

$$pH(f) = \begin{cases} p, & \text{for } \mathbf{x} \text{ in } V. \\ 0, & \text{for } \mathbf{x} \text{ inside } S. \end{cases} \quad (4)$$

The generalized pressure $pH(f)$ is defined everywhere in space, unlike p defined only in V . We will derive the acoustic wave equation for the generalised pressure. Using (3), the gradient of pH is

$$\nabla(pH) = \nabla pH + p\delta(f)\mathbf{n}. \quad (5)$$

Therefor the Laplacian is given by

$$\nabla^2(pH) = \nabla^2 pH + \frac{\partial p}{\partial n}\delta(f) + \nabla \cdot (p\delta(f)\mathbf{n}). \quad (6)$$

The partial derivative in time is

$$\frac{\partial^2}{\partial t^2}(pH) = \frac{\partial^2 p}{\partial t^2}H. \quad (7)$$

We premultiply (7) with $1/c_0^2$ and subtract (6) to obtain the acoustic wave equation in generalised pressure

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2\right)pH = H\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2\right)p - \frac{\partial p}{\partial n}\delta(f) - \nabla \cdot (p\delta(f)\mathbf{n}), \quad (8)$$

or

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2\right)pH = -\frac{\partial p}{\partial n}\delta(f) - \nabla \cdot (p\mathbf{n}\delta(f)). \quad (9)$$

The right side of the equation (9) is non-zero only at surface S , as it contains $\delta(f)$. The acoustic wave equation (9) in generalized variables is valid in the entire unbounded space. Therefore we can use free-space Green's function to solve the equation. The Green's function is the solution of wave equation for an impulsive point source $\delta(\mathbf{x} - \mathbf{y})\delta(t - \tau)$ placed at point \mathbf{y} and time τ

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2\right)G(\mathbf{x}, t; \mathbf{y}, \tau) = \delta(\mathbf{x} - \mathbf{y})\delta(t - \tau). \quad (10)$$

The Green's function for the acoustic wave operator (Howe 2003) in three dimensions is

$$G(\mathbf{x}, t; \mathbf{y}, \tau) = \frac{\delta\left(t - \tau - \frac{|\mathbf{x} - \mathbf{y}|}{c_0}\right)}{4\pi|\mathbf{x} - \mathbf{y}|}. \quad (11)$$

The solution for arbitrary source can be obtained by multiplying $s(\mathbf{y}, \tau)$ in (10)

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2\right)s(\mathbf{y}, \tau)G(\mathbf{x}, t; \mathbf{y}, \tau) = s(\mathbf{y}, \tau)\delta(\mathbf{x} - \mathbf{y})\delta(t - \tau), \quad (12)$$

Integrating both sides

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2\right) \int s(\mathbf{y}, \tau)G(\mathbf{x}, t; \mathbf{y}, \tau)d\mathbf{y}d\tau = \int s(\mathbf{y}, \tau)\delta(\mathbf{x} - \mathbf{y})\delta(t - \tau)d\mathbf{y}d\tau, \quad (13)$$

and using the properties of delta function, we get the solution for the acoustic wave equation with source $s(\mathbf{x}, t)$

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) p(\mathbf{x}, t) = s(\mathbf{x}, t), \quad (14)$$

where,

$$p(\mathbf{x}, t) = \int s(\mathbf{y}, \tau) G(\mathbf{x}, t; \mathbf{y}, \tau) d\mathbf{y} d\tau. \quad (15)$$

We can use the above relation to solve the acoustic wave equation (9)

$$\begin{aligned} (pH)(\mathbf{x}, t) = & -\frac{1}{4\pi} \int \frac{\partial p}{\partial n} \delta(f) \frac{\delta\left(t - \tau - \frac{|\mathbf{x}-\mathbf{y}|}{c_0}\right)}{|\mathbf{x}-\mathbf{y}|} d\mathbf{y} d\tau \\ & -\frac{1}{4\pi} \int \nabla_{\mathbf{y}} \cdot (p \mathbf{n} \delta(f)) \frac{\delta\left(t - \tau - \frac{|\mathbf{x}-\mathbf{y}|}{c_0}\right)}{|\mathbf{x}-\mathbf{y}|} d\mathbf{y} d\tau. \end{aligned} \quad (16)$$

Incomplete step!

$$\begin{aligned} (pH)(\mathbf{x}, t) = & -\frac{1}{4\pi} \int \frac{\partial p}{\partial n} \delta(f) \frac{\delta\left(t - \tau - \frac{|\mathbf{x}-\mathbf{y}|}{c_0}\right)}{|\mathbf{x}-\mathbf{y}|} d\mathbf{y} d\tau \\ & -\frac{1}{4\pi} \nabla_{\mathbf{x}} \cdot \int (p \mathbf{n} \delta(f)) \frac{\delta\left(t - \tau - \frac{|\mathbf{x}-\mathbf{y}|}{c_0}\right)}{|\mathbf{x}-\mathbf{y}|} d\mathbf{y} d\tau. \end{aligned} \quad (17)$$

We use the following property to convert volume integral to surface integral (Farassat et al. 1988). Incomplete step !

$$\int \phi(\mathbf{y}) \delta(f) \mathbf{n} d\mathbf{y} = \int_S \phi(\mathbf{y}) \mathbf{n} dS \quad (18)$$

We use the above property to convert volume integral to surface integral on S

$$\begin{aligned} (pH)(\mathbf{x}, t) = & -\frac{1}{4\pi} \int \frac{\partial p}{\partial n} \frac{\delta\left(t - \tau - \frac{|\mathbf{x}-\mathbf{y}|}{c_0}\right)}{|\mathbf{x}-\mathbf{y}|} dS d\tau \\ & -\frac{1}{4\pi} \nabla_{\mathbf{x}} \cdot \int (p \mathbf{n}) \frac{\delta\left(t - \tau - \frac{|\mathbf{x}-\mathbf{y}|}{c_0}\right)}{|\mathbf{x}-\mathbf{y}|} dS d\tau. \end{aligned} \quad (19)$$

Using the property of delta function we obtain

$$\begin{aligned} (pH)(\mathbf{x}, t) = & -\frac{1}{4\pi} \int_S \left[\frac{\partial p}{\partial n} \right] \frac{dS}{|\mathbf{x}-\mathbf{y}|} \\ & -\frac{1}{4\pi} \nabla_{\mathbf{x}} \cdot \int_S [p] \mathbf{n} \frac{dS}{|\mathbf{x}-\mathbf{y}|}. \end{aligned} \quad (20)$$

The square bracket implies the functions are computed at the retarded time i.e, $[p] = p(\mathbf{y}, t - \frac{|\mathbf{x}-\mathbf{y}|}{c})$. Simplifying the equation further, we obtain the **Kirchhoff formula** for a stationary control surface (Farassat et al. 1988, Jamaluddin et al. 2011).

$$(pH)(\mathbf{x}, t) = -\frac{1}{4\pi} \int_S \left[\frac{p}{r^2} \frac{\partial r}{\partial n} - \frac{1}{r} \frac{\partial p}{\partial n} + \frac{1}{cr} \frac{\partial r}{\partial n} \frac{\partial p}{\partial \tau} \right]_{\tau} dS. \quad (21)$$

Where, $r = |\mathbf{x}-\mathbf{y}|$, the square bracket again implies the functions are computed at the retarded time $\tau = t - r/c$.

2 Results

We compute the sound waves emitted by a monopole source using the Kirchhoff solver. The acoustic wave equation for a monopole source placed at a point $\mathbf{x} = 0$ is

$$\left(\frac{1}{c_0^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) p(\mathbf{x}, t) = -q(t)\delta(\mathbf{x}), \quad (22)$$

where $q(t)$ is the time dependent source function. The solution can be obtained by substituting the free space Green's function (11) in (15)

$$p(\mathbf{x}, t) = \int s(\mathbf{y}, \tau) \frac{1}{4\pi|\mathbf{x} - \mathbf{y}|} \delta\left(t - \tau - \frac{|\mathbf{x} - \mathbf{y}|}{c_0}\right) d\mathbf{y} d\tau, \quad (23)$$

and using the property of delta function we obtain,

$$p(\mathbf{x}, t) = \frac{1}{4\pi} \int \frac{s\left(\mathbf{y}, t - \frac{|\mathbf{x} - \mathbf{y}|}{c_0}\right)}{|\mathbf{x} - \mathbf{y}|} d\mathbf{y}. \quad (24)$$

The pressure at any point \mathbf{x} and time t is a linear superposition of contributions from all the sources located at \mathbf{y} , which radiated at the earliest times $t - \frac{|\mathbf{x} - \mathbf{y}|}{c_0}$. The integral formula (24) is called the retarded potential. Substituting $s(\mathbf{y}, \tau) = -q(t)\delta(\mathbf{x})$ in the above equation we obtain

$$p(\mathbf{x}, t) = -\frac{1}{4\pi} \int \frac{\delta(\mathbf{y})q\left(t - \frac{|\mathbf{x} - \mathbf{y}|}{c_0}\right)}{|\mathbf{x} - \mathbf{y}|} d\mathbf{y}, \quad (25)$$

using the property of delta function, the pressure radiated by a monopole source is given by

$$p(\mathbf{x}, t) = -\frac{1}{4\pi} \frac{q\left(t - \frac{r}{c_0}\right)}{r}. \quad (26)$$

where $r = |\mathbf{x}|$.

2.1 Monopole test case

We chose the monopole of strength

$$q(t) = 2(t - t_0)f_0^2 \exp(-f_0^2(t - t_0)^2). \quad (27)$$

where $f_0 = 100$ is the dominant frequency and $t_0 = \frac{4}{f_0}$. We enclose the monopole source using a cuboidal Kirchhoff surface whose diagonally opposite points are $p_1 = (-1.0, -1.0, -1.0)$ and $p_2 = (1.0, 1.0, 1.0)$. The surface is embedded in a cuboidal domain of size $[-5.0, 5.0] \times [-5.0, 5.0] \times [-5.0, 5.0]$. The domain is discretized into structured grid of size $h = 0.1$ and the Kirchhoff surface is discretized into square cells of size $h = 0.1$. The pressure and its derivatives are interpolated from cell centers to quadrature points on Kirchhoff surface using fourth-order WENO polynomial. The Kirchhoff Integral (21) is computed using the two-point Gauss quadrature formula. The exact and numerical pressure are evaluated at observer point $xo = (3.0, 3.0, 3.0)$ and plotted against the function of time.

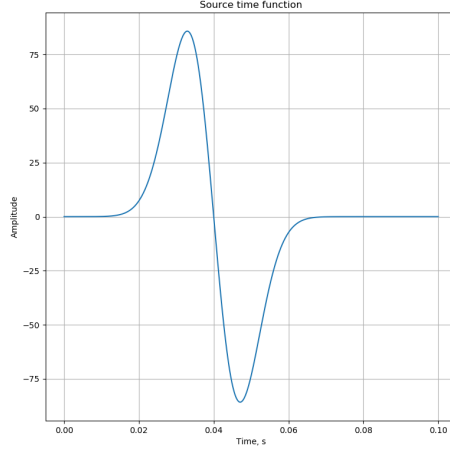


Figure 2: Monopole source as a function of time

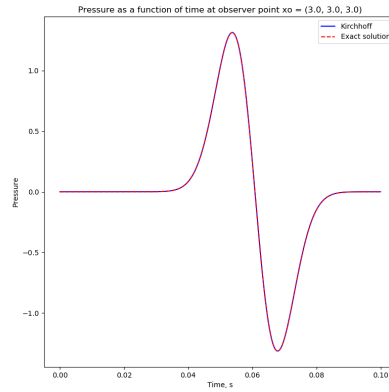


Figure 3: The exact and numerical pressure as a function of time at observer point $x_o = (3.0, 3.0, 3.0)$. The L_∞ error is $3.11\text{e-}4$.

References

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