Project Development Part 2 Traffic Management



Team Details

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Problem	We will start to
Description	build the IOT
	simulation of
	another part for
	traffic management

Simulation Steps

STEP 1: Access Wokwi

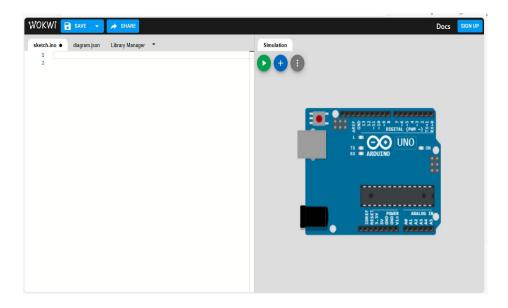
• Go to the websites(https://wokwi.com)

STEP 2: Create a Project

• Click on the new project

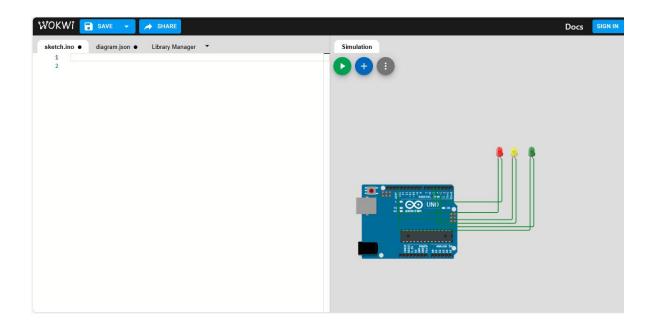
STEP 3: Add component

• In the component panel search for a "Arduino UNO" and drag it onto the virtual breadboard



STEP 4: Add a LED

- Find and drag an LED
- Drag the 3 LED with different kind of colours(red,yellow and green)

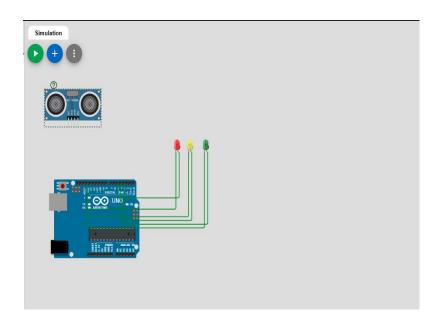


SIMULATION CONNECTION:

- LED 1 Cathode connected in the "Arduino" at GND 1.
- LED 1 Anode connected in the "Arduino" at uno 5.
- LED 2 Cathode connected in the "Arduino" at GND 1.
- LED 2 Anode connected in the "Arduino" at uno 4.
- LED 3 Cathode connected in the "Arduino" at GND 1.
- LED 3 Anode connected in the "Arduino" at uno 3.

STEP 5: Add a Ultrasonic sensor.

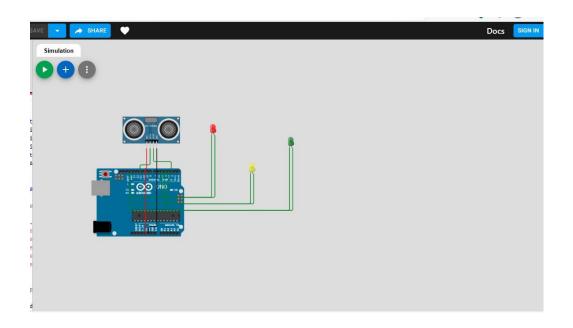
• Find and drag a ultrasonic sensor.



Simulation steps:

- Ultrasonic 1:GND is connected to the "Arduino" at uno GND 2.
- Ultrasonic 1. Echo is connected to the "Arduino" at uno 2.
- Ultrasonic 1.TRIG is connected to the "Arduino" at Uno 11.
- Ultrasonic 1.VCC is connected to the "Arduino" at Uno 5V.

ULTRASONIC CONNECTIO TO THE "ARDUINO"



STEP 6: CODE

```
#include <WiFi.h>
#include <ThingSpeak.h>
#include <stdio.h>
const int echoPin=2;
int ledPin1=3;
int ledPin2=4;
int ledPin3=5;
const int trigPin=11;
bool ledActivated=false;
unsigned long ledActivationTime=0;
unsigned long myChannelNumber = 2126746;
const char * myWriteAPIKey = "LZNGZ5F5XFUQXL07";
void setup()
  Serial.begin(9600);
  pinMode(echoPin,INPUT);
  pinMode(trigPin,OUTPUT);
  pinMode(ledPin1,OUTPUT);
  pinMode(ledPin2,OUTPUT);
  pinMode(ledPin3,OUTPUT);
```

```
}
void loop()
  if(!ledActivated)
    digitalWrite(trigPin,LOW);
    delayMicroseconds(2);
    digitalWrite(trigPin,HIGH);
    delayMicroseconds(10);
    digitalWrite(trigPin,LOW);
    unsigned long duration=pulseIn(echoPin,HIGH);
    unsigned long distance=duration/58;
    Serial.print("Distance:");
    Serial.print(distance);
    Serial.println("cm");
    if(distance<50)</pre>
    {
      digitalWrite(ledPin3,HIGH);
      Serial.println("Heavily Crowded");
      ledActivated=true;
      ledActivationTime=millis();
    }
    else if(distance<100)</pre>
      digitalWrite(ledPin2,HIGH);
      Serial.println("Moderately Crowded");
      ledActivated=true;
      ledActivationTime=millis();
    }
    else
      digitalWrite(ledPin1,HIGH);
      Serial.println("Less Crowded");
      ledActivated=true;
      ledActivationTime=millis();
    }
  }
  else
  {
    if(millis()-ledActivationTime>=2000)
    {
```

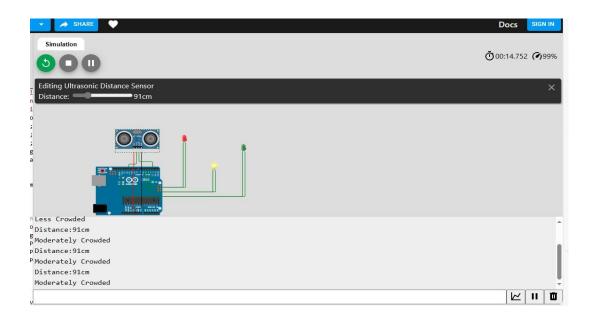
```
digitalWrite(ledPin1,LOW);
    digitalWrite(ledPin2,LOW);
    digitalWrite(ledPin3,LOW);
    ledActivated=false;
    }
}
delay(1000);
```

STEP 7: Simulation

- Click on the simulate button to start the simulation.
- The LED should start to blinking the according to the ultrasonic sensor distance.
- The green light will be blink when the ultrasonic distanc sensor has high volume then it will display that the less crowed.



• The Yellow light will be blink when the ultrasonic distanc sensor has medium volume then it will display that the moderately crowed.



• The Green light will be blink when the ultrasonic distanc sensor has less volume then it will display that the heavy crowed.



WEB APPLICATIO FOR TRAFFIC MANAGEMENT

CODE:

```
<!DOCTYPE html>
<html lang="en">
<head>
 <meta charset="UTF-8">
 <meta http-equiv="X-UA-Compatible"</pre>
content="IE=edge">
 <meta name="viewport" content="width=device-width,</pre>
initial-scale=1.0">
 <title>WEB APPLICATION </title>
 <style>
  @import
url('https://fonts.googleapis.com/css2?family=Nunito:wg
ht@400;700&display=swap');
  * {
   margin: 0;
   padding: 0;
   box-sizing: border-box;
  }
  body {
   color: #000;
   font-family: 'Nunito', sans-serif;
```

```
.testimonial {
 height: 100%;
 display: flex;
 flex-direction: column;
 justify-content: center;
 align-items: center;
 padding-bottom: 5rem;
h1 {
 margin: 20px 0;
.line {
 height: 2px;
 width: 6rem;
 background-color: #e26c4f;
 margin-bottom: calc(3rem + 2vmin);
}
.arrow-wrapper {
 position: relative;
 width: 70%;
 border-radius: 2rem;
 box-shadow: rgba(99, 99, 99, 0.2) 0px 2px 8px 0px;
 overflow: hidden;
 place-items: center;
```

```
.review-wrap {
 display: flex;
 flex-direction: column;
 justify-content: center;
 align-items: center;
 padding-top: calc(2rem + 1vmin);
 width: 100%;
#imgBox {
 border-radius: 50%;
 width: calc(10rem + 4vmin);
 height: calc(10rem + 4vmin);
 position: relative;
 box-shadow: 5px -3px #e26c4f;
 background-size: cover;
 margin-bottom: calc(0.7rem + 0.5vmin);
#name {
 margin-bottom: calc(0.7rem + 0.5vmin);
 font-size: calc(1rem + 0.5vmin);
 letter-spacing: calc(0.1rem + 0.1vmin);
 font-weight: bold;
#profession {
 font-size: calc(0.8rem + 0.3vmin);
```

```
margin-bottom: calc(0.7rem + 0.5vmin);
   color: #e26c4f;
  #description {
   font-size: calc(0.8rem + 0.3vmin);
   width: 70%;
   max-width: 40rem;
   text-align: center;
   margin-bottom: calc(2.4rem + 1vmin);
   color: rgb(92, 92, 92);
   line-height: 2rem;
  .arrow {
   width: calc(1.4rem + 0.6vmin);
   height: calc(1.4rem + 0.6vmin);
   border: solid #e26c4f;
   border-width: 0 calc(0.5rem + 0.2vmin) calc(0.5rem
+ 0.2 \text{vmin}) 0;
   cursor: pointer;
   transition: transform 0.3s;
  }
  .arrow:hover {
   transition: 0.3s;
   transform: scale(1.15);
```

```
.left-arrow-wrap {
   position: absolute;
   top: 50%;
   left: 5%;
   transform: rotate(135deg);
  .right-arrow-wrap {
   position: absolute;
   top: 50%;
   right: 5%;
   transform: rotate(-45deg);
  @media screen and (max-width: 900px) {
   .testimonial {
    width: 100%;
 </style>
</head>
<body>
 <div class="testimonial">
  <h1>TRAFFIC MANAGEMENT USING IOT</h1>
  <div class="line"></div>
  <!-- arrow wrapper contains the review and the arrows
-->
  <div class="arrow-wrapper">
```

```
<!-- review section -->
   <div id="reviewWrap" class="review-wrap">
    <div id="imgBox"></div>
    <div id="name"></div>
    <div id="profession"></div>
    <div id="description"></div>
   </div>
   <!-- left arrow -->
   <div class="left-arrow-wrap">
    <div class="arrow"></div>
   </div>
   <!-- right arrow -->
   <div class="right-arrow-wrap">
    <div class="arrow"></div>
   </div>
  </div>
 </div>
 <script>
  const reviewWrap =
document.getElementById("reviewWrap");
  const leftArrow = document.querySelector(".left-
arrow-wrap .arrow");
  const rightArrow = document.querySelector(".right-
arrow-wrap .arrow");
  const imgBox =
document.getElementById("imgBox");
  const name = document.getElementById("name");
```

```
const profession =
document.getElementById("profession");
  const description =
document.getElementById("description");
  let people = [{
    photo:
'url("https://th.bing.com/th/id/OIP.tBrw_mxy9n2uhuUj1f
9hzwHaF8?pid=ImgDet&rs=1.jpg")',
    name: "Traffic management",
    profession: "Monitor traffic flow",
    description: "Traffic management using iot devices
to mointor the traffic flow and congestion:"
   },
    photo:
"url('https://ae01.alicdn.com/kf/HTB1F4S5RXXXXXXaC
XpXXq6xXFXXXR/High-quality-New-design-single-
light-300mm-red-color-LED-traffic-signal-light.jpg')",
    name: "RED SIGNAL",
    profession: "BASED ON ULTRASONIC
SENSOR",
    description: "The ultrasonic sensor has a low
distance radiation then the red light will be blink. Then
there is HEAVY CROWED"
   },
```

```
photo:
"url('https://th.bing.com/th/id/OIP.FmKR6MebmOgh0m
WDcQCbqwHaKH?pid=ImgDet&rs=1.jpg')",
    name: "YELLOW SIGNAL",
    profession: "BASED ON ULTRASONIC
SENSOR",
    description: "The ultrasonic sensor has A MEDIUM
distance radiation then the green light will be blink. Then
there is MODERATE CROWED"
   },
    photo:
"url('https://th.bing.com/th/id/R.8cf589bfa8b98fdc6f82d4
48d040e37e?rik=Ex5W1RM1pf07Eg&riu=http%3a%2f
%2fwww.kbrhorse.net%2fsigpics%2fmarb 6540f.jpg&e
hk=RVOnFsrGfoLz2j7rJNmVEsHuZ7lir%2b7JQI0yI7G
JOU0%3d&risl=&pid=ImgRaw&r=0.jpg')",
    name: "GREEN LIGHT",
    profession: "BASED ON ULTRASONIC
SENSOR",
    description: "The ultrasonic sensor has a High
distance radiation then the green light will be blink. Then
there is LESS CROWED"
   }
  ];
  // set the first person
  imgBox.style.backgroundImage = people[0].photo;
  name.innerText = people[0].name;
```

```
profession.innerText = people[0].profession;
  description.innerText = people[0].description;
  let currentPerson = 0;
  //Select the side where you want to slide
  function slide(side, personNumber) {
   let reviewWrapWidth = reviewWrap.offsetWidth +
"px";
   let descriptionHeight = description.offsetHeight +
"px";
   //(+ or -)
   let side1symbol = side === "left" ? "" : "-";
   let side2symbol = side === "left" ? "-" : "";
   setTimeout(() => {
    imgBox.style.backgroundImage =
people[personNumber].photo;
   \}, 0);
   setTimeout(() => {
    description.style.height = descriptionHeight;
   }, 100);
   setTimeout(() => {
    name.innerText = people[personNumber].name;
   }, 200);
   setTimeout(() => {
    profession.innerText =
people[personNumber].profession;
   }, 300);
   setTimeout(() => {
```

```
description.innerText =
people[personNumber].description;
   }, 400);
  function setNextCardLeft() {
   if (currentPerson === 3) {
     currentPerson = 0;
     slide("left", currentPerson);
   } else {
     currentPerson++;
   slide("left", currentPerson);
  function setNextCardRight() {
   if (currentPerson === 0) {
     currentPerson = 3;
     slide("right", currentPerson);
   } else {
     currentPerson--;
    }
   slide("right", currentPerson);
  leftArrow.addEventListener("click", setNextCardLeft);
```

rightArrow.addEventListener("click",
setNextCardRight);
 </script>
 </body></html>

OUTPUT:

♦ THE HOME PAGE OF APPLICATION



♦ THE NEXT PAGES OF APPLICATION

TRAFFIC MANAGEMENT USING IOT



TRAFFIC MANAGEMENT USING IOT



