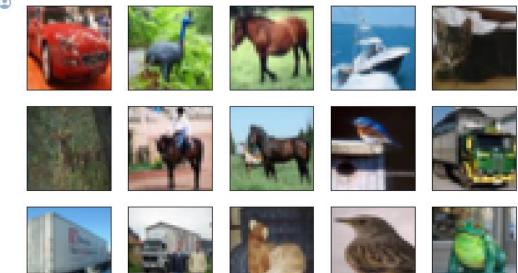
Program

```
import tensorflow as tf
from tensorflow.keras import datasets, layers, models
import matplotlib.pyplot as plt
(train_images, train_labels), (test_images, test_labels) = datasets.cifar10.load_data()
# Normalize pixel values to be between 0 and 1
train_images, test_images = train_images / 255.0, test_images / 255.0
class_names = ['airplane', 'automobile', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck']
plt.figure(figsize=(10,10))
for i in range(25):
  plt.subplot(5,5,i+1)
  plt.xticks([])
  plt.yticks([])
  plt.grid(False)
  plt.imshow(train_images[i])
# The CIFAR labels happen to be arrays, which is why you need the extra index
plt.xlabel(class_names[train_labels[i][0]])
plt.show()
model = models.Sequential()
model.add(layers.Conv2D(32, (3, 3), activation='relu', input_shape=(32, 32, 3)))
model.add(layers.MaxPooling2D((2, 2)))
model.add(layers.Conv2D(64, (3, 3), activation='relu'))
model.add(layers.MaxPooling2D((2, 2)))
model.add(layers.Conv2D(64, (3, 3), activation='relu'))
model.summary()
model.add(layers.Flatten())
model.add(layers.Dense(64, activation='relu'))
model.add(layers.Dense(10))
model.summary()
model.compile(optimizer='adam',loss=tf.keras.losses.SparseCategoricalCrossentropy(from_logits=
True), metrics=['accuracy'])
```

```
history = model.fit(train_images, train_labels, epochs=10, validation_data=(test_images, test_labels))
plt.plot(history.history['accuracy'], label='accuracy')
plt.plot(history.history['val_accuracy'], label = 'val_accuracy')
plt.xlabel('Epoch')
plt.ylabel('Accuracy')
plt.ylim([0.5, 1])
plt.legend(loc='lower right')
test_loss, test_acc = model.evaluate(test_images, test_labels, verbose=2)
print(test_acc)
```

Output







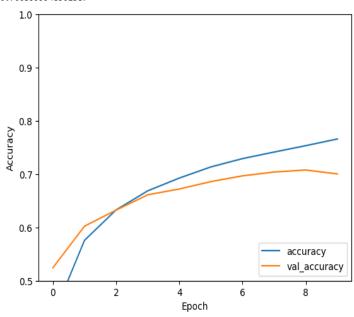
| \supseteq | Layer (type) | Output Shape | Param # |
|-------------|--|--------------------|---------|
| | conv2d_3 (Conv2D) | (None, 30, 30, 32) | 896 |
| | <pre>max_pooling2d_2 (MaxPoolin g2D)</pre> | (None, 15, 15, 32) | 0 |
| | conv2d_4 (Conv2D) | (None, 13, 13, 64) | 18496 |
| | <pre>max_pooling2d_3 (MaxPoolin g2D)</pre> | (None, 6, 6, 64) | 0 |
| | conv2d_5 (Conv2D) | (None, 4, 4, 64) | 36928 |

Total params: 56320 (220.00 KB)
Trainable params: 56320 (220.00 KB)
Non-trainable params: 0 (0.00 Byte)

| Layer (type) | Output Shape | Param # |
|--------------------------------|--------------------|---------|
| conv2d_3 (Conv2D) | (None, 30, 30, 32) | 896 |
| max_pooling2d_2 (MaxPooling2D) | (None, 15, 15, 32) | 0 |
| conv2d_4 (Conv2D) | (None, 13, 13, 64) | 18496 |
| max_pooling2d_3 (MaxPooling2D) | n (None, 6, 6, 64) | 0 |
| conv2d_5 (Conv2D) | (None, 4, 4, 64) | 36928 |
| flatten_1 (Flatten) | (None, 1024) | 0 |
| dense_2 (Dense) | (None, 64) | 65600 |
| dense_3 (Dense) | (None, 10) | 650 |

Non-trainable params: 0 (0.00 Byte)

```
Epoch 1/10
\rightarrow
   1563/1563 [=
                       =======] - 79s 49ms/step - loss: 1.5548 - accuracy: 0.4323 - val_loss: 1.3287 - val_accuracy: 0.5243
   Epoch 2/10
   1563/1563 [
                               - 67s 43ms/step - loss: 1.1896 - accuracy: 0.5758 - val_loss: 1.1114 - val_accuracy: 0.6023
   Epoch 3/10
   1563/1563 F
                     =========] - 64s 41ms/step - loss: 1.0427 - accuracy: 0.6329 - val_loss: 1.0360 - val_accuracy: 0.6325
   Epoch 4/10
   1563/1563 [
                            ===] - 64s 41ms/step - loss: 0.9469 - accuracy: 0.6687 - val_loss: 0.9580 - val_accuracy: 0.6612
   Epoch 5/10
              1563/1563 [
   Epoch 6/10
   1563/1563 [=
                Epoch 7/10
               1563/1563 [
   Epoch 8/10
   1563/1563 [=
              Epoch 9/10
   1563/1563 [
                   =========] - 62s 40ms/step - loss: 0.6952 - accuracy: 0.7535 - val_loss: 0.8652 - val_accuracy: 0.7078
   Epoch 10/10
   1563/1563 [=
                   :========] - 63s 41ms/step - loss: 0.6633 - accuracy: 0.7660 - val_loss: 0.8976 - val_accuracy: 0.7004
   313/313 - 3s - loss: 0.8976 - accuracy: 0.7004 - 3s/epoch - 10ms/step
   0.7003999948501587
```



Advantages of Convolutional Neural Networks (CNNs)

- Good at detecting patterns and features in images, videos, and audio signals.
- Robust to translation, rotation, and scaling invariance.
- End-to-end training, no need for manual feature extraction.
- Can handle large amounts of data and achieve high accuracy.

Disadvantages of Convolutional Neural Networks (CNNs)

- Computationally expensive to train and require a lot of memory.
- Can be prone to overfitting if not enough data or proper regularization is used.
- Requires large amounts of labeled data.
- Interpretability is limited, it's hard to understand what the network has learned.