

Homework #1

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1 The experiments

Kindly find the results/logs in directories with names related to the experiments, e.g. `BC-Ant-v2` or `Dagger-Walker2d-v2`. In each directory there is a `config.yaml` corresponding to the specific experiment. Moreover, `log.txt` contains all the outputs written to `stdout`.

2 Question 1.2

Table 1: Behavior Cloning **results** for `Ant-v2`.

<code>Ant-v2</code>	Behavior Cloning	Expert
<code>AverageReturn</code>	4704.03	4713.66
<code>StdReturn</code>	105.96	12.20

Table 2: Behavior Cloning **results** for `Walker2d-v2`.

<code>Walker2d-v2</code>	Behavior Cloning	Expert
<code>AverageReturn</code>	3168.86	5566.85
<code>StdReturn</code>	1872.78	9.24

Table 3: Behavior Cloning **results** for `Humanoid-v2`.

<code>Humanoid-v2</code>	Behavior Cloning	Expert
<code>AverageReturn</code>	298.61	10344.52
<code>StdReturn</code>	70.61	20.99

Table 4: Behavior Cloning **hyper-parameters**.

*	max_episode_length	train_steps_per_iter	n_layers
Ant-v2	1000	5000	3
Walker2d-v2	1000	5000	3
Humanoid-v2	1000	5000	3

Behavior Cloning fails to capture the true behavior of the expert in some environments, take **Humanoid-v2** as a case in point. It barely manages to get to 50% of average return in **Walker2d-v2**, but it has huge variance.

3 Question 1.3

I chose the amount of data provided to BC for ablations, namely `max_episode_length`, and I expect better performance with more data.

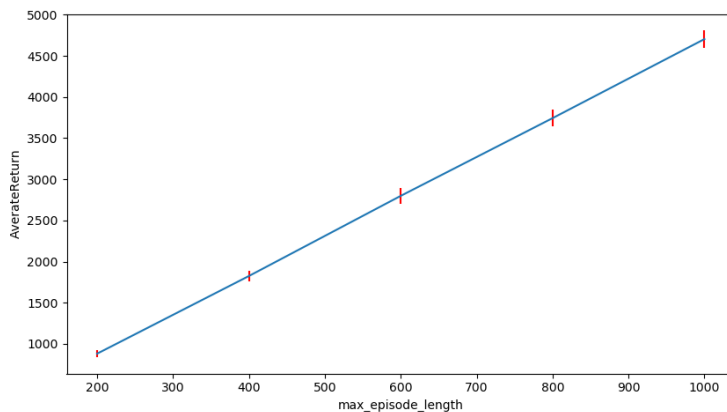


Figure 1: Ablation on the amount of data provided to BC, for **Ant-v2**.

We observe that the performance of the BC agent improves linearly wrt the amount of data provided.

4 Question 2.2

Table 5: DAgger **best results** for Ant-v2.

Ant-v2	DAgger	Expert
AverageReturn	4764.02	4713.66
StdReturn	116.59	12.20

Table 6: DAgger **best results** for Walker2d-v2.

Walker2d-v2	DAgger	Expert
AverageReturn	5588.88	5566.85
StdReturn	29.49	9.24

Table 7: DAgger **best results** for Humanoid-v2.

Humanoid-v2	DAgger	Expert
AverageReturn	324.12	10344.52
StdReturn	69.96	20.99

- Observation: DAgger significantly helps in the case of **Walker2d-v2**, and actually cracks the task. Moreover, the performance variance is reduced significantly via DAgger.
- Observation: DAgger fails to improve the performance in the case of **Humanoid-v2**.
- Note: The variance, i.e. error bars, seem to be large for some data points, and that is because we are using 5 trajectories during evaluation which is a small number. It was prescribed in the assignment, but I am now realizing we could benefit from a larger sample size.

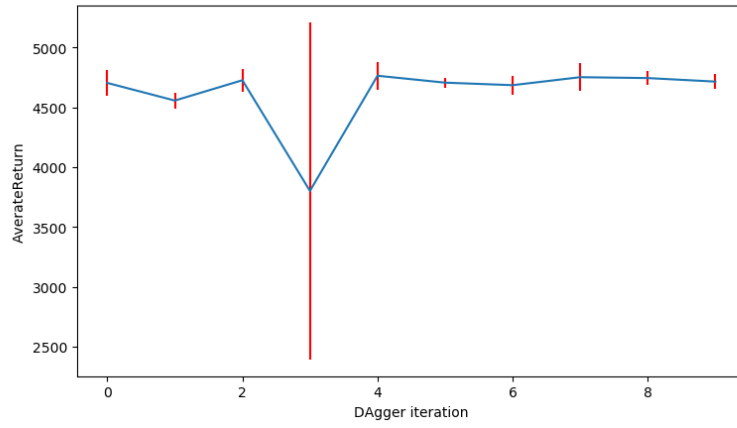


Figure 2: DAGger performance for Ant-v2.

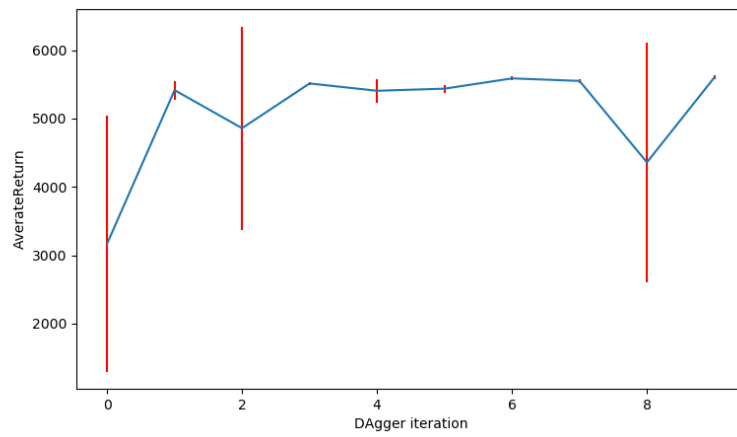


Figure 3: DAGger performance for Walker2d-v2.