MAHAN FATHI

+1 (514) 213-9373 ⋄ mahanf@google.com ⋄ github.com/MahanFathi ⋄ 🔗 mahanfathi

HIGHLIGHTS

· **3+ years** of academic experience in development of research infrastructure and doing actual research in **Reinforcement Learning** and **Optimal Control of Dynamical/Robotic Systems**, on massive accelerators at scale
· **3+ years** of work experience as **Software Engineer**, **Data Scientist**, and **Team Leader** (e.g., user-centric ML, high-throughput streaming microservices, gigantic image datasets)
· **Proud of switching gears** – pun intended: coming from a Mechanical Engineering background, I decided to not settle for anything less than following my true passion, robotics. RL just happened to be a recently popularized means to this end.

SELECTED EXPERIENCES

Google Brain ❖ *Student Researcher (SR) – Deep RL*   *Montréal, QC* ◆ Aug. 2022 – Present
· Member of MonRL team, led by **Marc G. Bellemare**
· Supervised by **Ross Goroshin**
· Working on the intersection of Sequence Modeling and Reinforcement Learning, in both online and offline settings

Mila: MTL. Inst. for Learning Algs. ❖ *MSc Student*   *Montréal, QC* ◆ Jan. 2021 – Present
· Advised by **Pierre-Luc Bacon** at Université de Montréal
· Research Areas: Sample-efficient Reinforcement Learning, Energy-based Policy/Imitation Networks, Continuous Sequence Models (HiPPO-inspired) in RL and Control

Polytechnique Montréal ❖ *Teaching Assistant*   *Montréal, QC* ◆ Sep. 2021 – Jan. 2022
· Teaching Assistant for INF8953DE – Reinforcement Learning, by **Sarath Chandar**
· Responsible for designing the majority of the assignments

Aalto University ❖ *Research Assistant*   *Espoo, Finland* ◆ Jun. – Sep. 2019
· Supervised by **Perttu Hämäläinen**
· Developed a framework that offered *MuJoCo* dynamics step functions as differentiable *PyTorch* operations
· Controlled systems as complicated as `Humanoid` using analytic policy gradients

CafeBazaar ❖ *Senior SWE/DS and TL*   *Tehran, Iran* ◆ Oct. 2018 – Jan. 2021
· Worked at **Balad**, which is now the biggest domestic map and navigation application of Iran (joined at userbase of 100k and left when ∼6M)
· Technical Leadership and Product Management of Data Infrastructure, a team of 7 Data Scientists, and ETA&Traffic, a team of 4 Software Engineers and 3 Data Scientists
· As a Computer Vision Scientist I was concerned with information extraction from street and aerial imagery
· As a Software Engineer I single-handedly developed the first traffic logging&predicting service of Balad

TAPSI ❖ *Backend Developer*   *Tehran, Iran* ◆ Feb. – Oct. 2018
· Among the biggest Iranian tech companies, TAPSI is a ride-hailing platform with millions of monthly active users.
· Improved finished rides rate by 3% in a self-directed project, and rewrote many legacy services including Location and Dispatch from scratch

HONORS & AWARDS

Bourse D'excellence DIRO & MSc Tuition Exemption Scholarship (Bourse C)   2022

Fully Funded Admission to Mila/UdeM, ETH, UBC, McGill, Aalto   2019

Awarded membership to the *National Elites Foundation*   2013

Silver Medalist at 25th National Physics Olympiad   2012

---

* I am a strong believer in the one-page resume. Full experience summary is available in LinkedIn

EDUCATION

M.Sc. in Computer Science   Jan'21 – Present
Université de Montréal & Mila

B.Sc. in Mechanical Engineering   Sep'13 – Jul'17
Sharif University of Technology

NODET: High School   Sep'09 – Jun'13
National Organization for Development of Exceptional Talents, Mathematics and Physics

TECHNOLOGIES

Auto-diff & RL Frameworks
• JAX, TensorFlow, PyTorch
• Flax, Haiku, RLax, trajax, JAXopt, etc
• BRAX, Dopamine, Acme
• XM, Google Infrastructure

Everything Data
• Apache Spark, SparkSQL, Apache Kafka
• Apache Flink, Apache Beam
• HDFS, YARN
• Redis, MongoDB
• PostgreSQL, MySQL

Main Programming Languages
• C/C++ • Python • JS • Java • Lua • SQL

Miscellaneous
• 10+ years experience with Linux systems
• Emacs, Arch Linux
• 🗣 English, Farsi

RESEARCH INTERESTS

• Deep Reinforcement & Representation Learning
• Reinforcement Learning as Supervised Learning
• Sequence Modeling, Eligibility Traces, And Credit Assignment
• Energy-based Models & Behavior/Option Mixing

SELECTED PROJECTS

HJxB   iLQR-MuJoCo   NxDP

Sample-based Motion Planning for Ballbot

TrajOpt of Passive Walker   LQR-RRT*

Points of Interest Collection   OBJET

Model-based Policy Gradients

Unsupervised Object Detection

Learning to Drive in 2 Days