Microcontroller 1BM19EE025 1) Drive a Steffer Motor interfore to notate the motor in anti-clockwise by N-steps. Introduce suitable delay 6/w successive steps stindude « stdio. h? #include < reg 51.h. char xdata fort -at- 0xe803; der xolata poèta _at_ 0xe800; char idata acc _at_ 0x30; olelay () for (j=0; j < 800; j++); void main () Lost = 0x80; while (1) $f = 0 \times 11$ porta = acc; delay (); acc = 0 x 22; porta = acc; 0 x44; forta = ace; delay(); delay (); acc acc = 0 x 8 8; porta = acc; y delay ();

3) Derign the steffer motor to rotate the motor in clocking direction. Hindude coldio. h? # include < reg 51. h? char xdata post_at_0xe803; xdela forta-at- 0xe800; idata acc_at_0x300% char wid delay for (at I =0; i < 800; 1+1); Lost = 0x80; while (1) occ = 0x 88; poeta= acc; dolay (1); all = 0x 44) horta zou; dday (); ou = 0x22; forta = ou; delay (); occ = 0 x11', porta = ace; delay(1)