

### 1.LED Blinking

```
int led = 13;
void setup() {
  pinMode(led, OUTPUT);
}
void loop() {
  digitalWrite(led, HIGH);
  delay(1000);
  digitalWrite(led, LOW);
  delay(1000);
}
```

### 2. Gas Sensor

```
int ledPin_1 = 2;
int ledPin_2 = 3;
int ledPin_3 = 13;
int ledPin_4 = 12;
int ledPin_5 = 6;
int ledPin_6 = 7;
int mq8Pin = A0;
int sensorValue = 0;
int threshold = 350;
void setup() {
  pinMode(ledPin_1, OUTPUT);
  pinMode(ledPin_2, OUTPUT);
  pinMode(ledPin_3, OUTPUT);
  pinMode(ledPin_4, OUTPUT);
```

```
  pinMode(ledPin_5, OUTPUT);
  pinMode(ledPin_6, OUTPUT);
  Serial.begin(9600);
}
void loop() {
  sensorValue =
  analogRead(mq8Pin);
  Serial.print(" Gas Sensor Value:
  ");
  Serial.println(sensorValue);
  if (sensorValue > threshold) {
    digitalWrite(ledPin_2, LOW);
    digitalWrite(ledPin_1, HIGH);
    digitalWrite(ledPin_5, LOW);
    digitalWrite(ledPin_6, HIGH);
    digitalWrite(ledPin_4, LOW);
  } else {
    delay(1000);
    digitalWrite(ledPin_1, LOW);
    digitalWrite(ledPin_4, LOW);
    digitalWrite(ledPin_6, LOW);
    digitalWrite(ledPin_4, HIGH);
  }
}
```

### 3. Ultrasonic

```
const int trigPin = 2;
const int echoPin = 3;
const int buzzerPin = 8;
```

```
float length = 0;
const float thresholdDistance =
30.0;
void setup() {
  Serial.begin(9600);
  pinMode(trigPin, OUTPUT);
  pinMode(echoPin, INPUT);
  pinMode(buzzerPin, OUTPUT);
}
void loop() {
  digitalWrite(trigPin, LOW);
  delayMicroseconds(2);
  digitalWrite(trigPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin, LOW);
  long duration = pulseIn(echoPin,
HIGH);
  length = duration * 0.0343 / 2;
  Serial.print("Distance: ");
  Serial.print(length);
  Serial.println(" cm");
  if (length < thresholdDistance) {
    tone(buzzerPin, 1000); // Play a
tone at 1000 Hz
    delay(200); // Sound duration
    noTone(buzzerPin); // Stop the
tone
  }
}
```

```
delay(500); // Delay between
measurements
}
```

### 4. Water Sensor

```
int sensorPin = A3;
int sensorValue = 0;
int value;
void setup() {
  Serial.begin(9600);
  pinMode(sensorPin, INPUT);
}
void loop() {
  value = analogRead(sensorPin);
  if (value<=480){
    Serial.println("Water level: 0mm
- Empty!");
  }
  else if (value>480 &&
value<=530){
    Serial.println("Water level: 0mm
to 5mm");
  }
  else if (value>530 &&
value<=615){
    Serial.println("Water level: 5mm
to 10mm");
  }
  else if (value>615 &&
value<=660){
```

```
    Serial.println("Water level: 10mm
to 15mm");
  }
  else if (value>660 &&
value<=680){
    Serial.println("Water level: 15mm
to 20mm");
  }
  else if (value>680 &&
value<=690){
    Serial.println("Water level: 20mm
to 25mm");
  }
  else if (value>690 &&
value<=700){
    Serial.println("Water level: 25mm
to 30mm");
  }
  else if (value>700 &&
value<=705){
    Serial.println("Water level: 30mm
to 35mm");
  }
  else if (value>705){
    Serial.println("Water level: 35mm
to 40mm");
  }
  delay(2000);
}
```

### 5. LED Fade in Fade Out

```
int led = 9;
int brightness = 0;
int fadeAmount = 5;
void setup() {
  pinMode(led, OUTPUT);
}
void loop() {
  analogWrite(led, brightness);
  brightness = brightness +
fadeAmount;
  if (brightness <= 0 || brightness >=
255) {
    fadeAmount = -fadeAmount;
  }
  delay(30);
}
```