

# ACCELERATE DEEP LEARNING INFERENCE USING INTEL® TECHNOLOGIES

### INTRODUCTION: SMART VIDEO

INTEL® DISTRIBUTION OF OPENVINO™ TOOLKIT 2020.R4 VERSION

July 2020

### **AGENDA**

- Intel® Smart Video/Computer vision Tools Overview
- Model Optimizer
- Inference Engine
- 15 Minute Break
- Accelerators based on Intel® Movidius™
   Vision Processing Unit
- Accelerators based on Intel<sup>®</sup> Arria<sup>®</sup> FPGA
- Multiple Models in One Application
- DL Workbench + Demo

- DL Streamer
- Register for access to Intel<sup>®</sup> DevCloud for the Edge
- Lab1 DevCloud Sample Application:
   Accelerated Object Detection
- Lab2 DevCloud Advanced Tutorials: DL Streamer Benchmark





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### AI CHANGING AND ENABLING EVERY INDUSTRY



Al software market is projected to reach USD 126.0 billion in annual worldwide revenue by 2025<sup>3</sup>



Deep learning software revenue is estimated to grow to USD 67.2 billion by 2025<sup>4</sup>

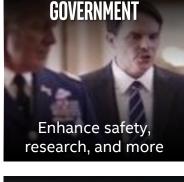


Global deep learning chip market is expected to reach USD 29.4 billion by 2025<sup>5</sup>











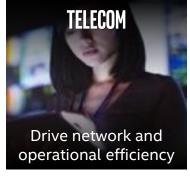
















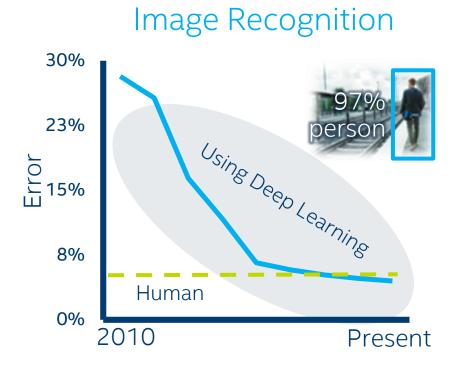


5. AlliedMarketResearch, Deep Learning Chip Market, 2018

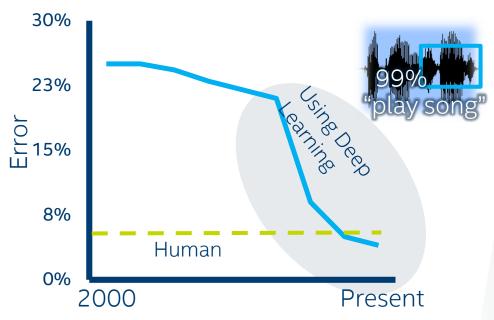


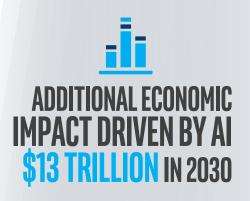
### DEEP LEARNING BREAKTHROUGHS AND OPPORTUNITIES

Machines able to meet or exceed human image and speech recognition







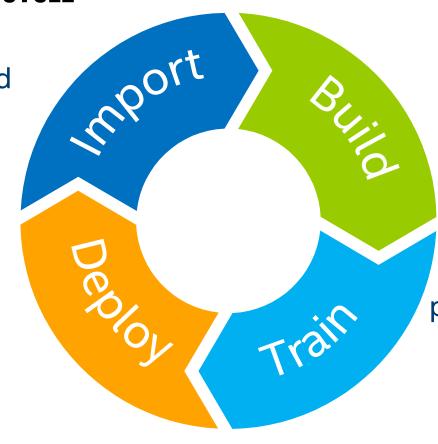




### DEEP LEARNING DEVELOPMENT CYCLE

Data acquisition and organization

Integrate trained models with application code



Create models

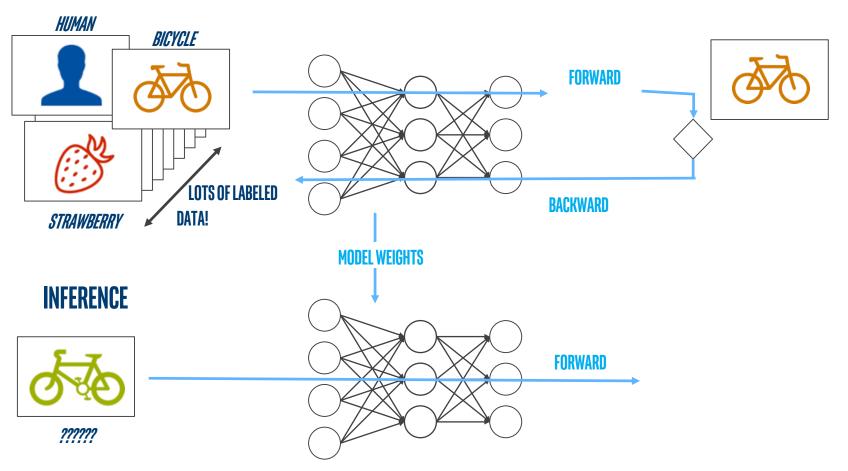
Adjust models to meet performance and accuracy objectives

Intel® Distribution OpenVINO™ Toolkit Provides Deployment from Intel® Edge to Cloud



### **DEEP LEARNING: TRAINING VS. INFERENCE**

#### **TRAINING**





#### **DID YOU KNOW?**

Training requires a very large data set and deep neural network (many layers) to achieve the highest accuracy in most





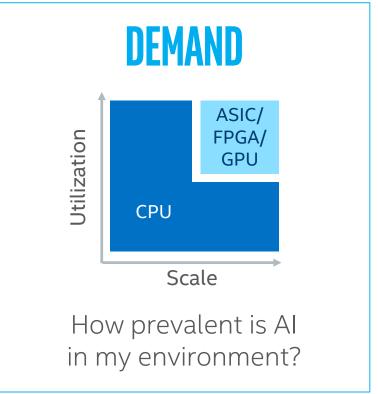


### AI COMPUTE CONSIDERATIONS

How do you determine the right computing for your AI needs?

## **WORKLOADS** What is my workload profile?

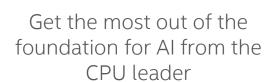




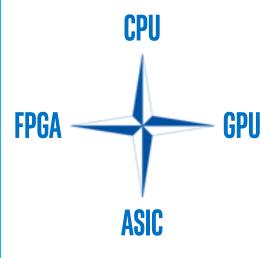


### WHY INTEL AI COMPUTE?

# MAXIMIZE

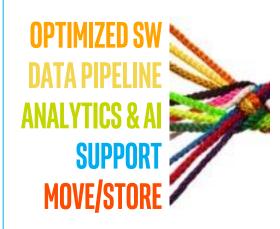


### **OPTIMIZE**



Choose the right compute for you from the one with all the options

### **SIMPLIFY**



Reduce "moving parts" by building on an optimized AI platform

### **LEAD**



Lead your industry by aligning with the builder of next-gen Al solutions





### INTEL® DISTRIBUTION OF OPENVINO™ TOOLKIT

#### **Tool Suite for High-Performance, Deep Learning Inference**

Fast, accurate real-world results using high-performance, AI and computer vision inference deployed into production across Intel® architecture from edge to cloud



High-Performance, Deep Learning Inference



Streamlined Development, Ease of Use



Write Once, Deploy Anywhere



### USING THE INTEL® DISTRIBUTION OF OPENVINO™ TOOLKIT

Advanced capabilities to streamline deep learning deployments

### 1. BUILD







ONNX

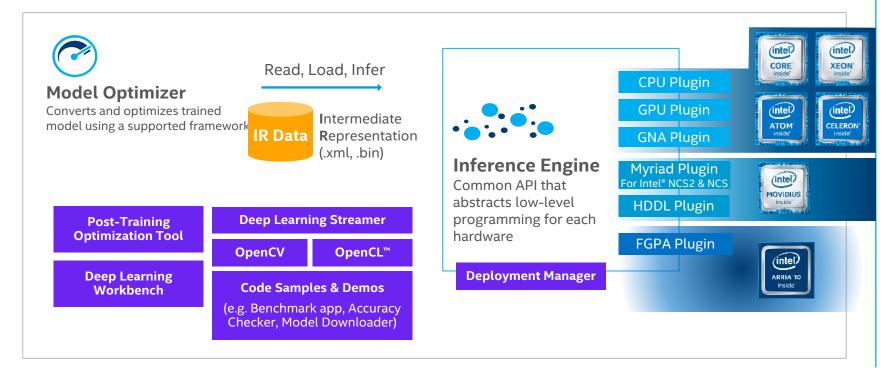


#### **Open Model Zoo**

100+ open sourced and optimized pre-trained models; 80+ supported public models

#### 2. OPTIMIZE

3. DEPLOY



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### MODEL OPTIMIZER

#### INTEL® DEEP LEARNING DEPLOYMENT TOOLKIT

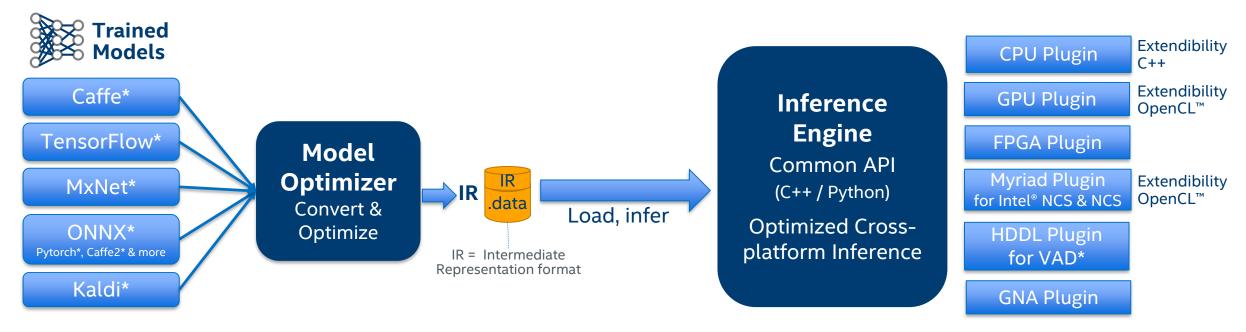
#### FOR DEEP LEARNING INFERENCE

#### **Model Optimizer**

- A Python\* based tool to import trained models and convert them to Intermediate Representation
- Optimizes for performance or space with conservative topology transformations
- Hardware-agnostic optimizations

#### **Inference Engine**

- High-level, C/C++ and Python, inference runtime API
- Interface is implemented as dynamically loaded plugins for each hardware type
- Delivers advanced performance for each type without requiring users to implement and maintain multiple code pathways



GPU = Intel® CPU with integrated GPU/Intel® Processor Graphics, Intel® NCS = Intel® Neural Compute Stick (VPU) \*VAD = Intel® Vision Accelerator Design Products (HDDL-R)



### **MODEL OPTIMIZER: GENERIC OPTIMIZATION**

### Model optimizer performs generic optimization

- Node merging
- Horizontal fusion
- Batch normalization to scale shift

- Fold scale shift with convolution
- Drop unused layers (dropout)

#### The simplest way to convert a model is to run mo.py with a path to the input model file

By default, generic optimization will be automatically applied, unless manually set disable

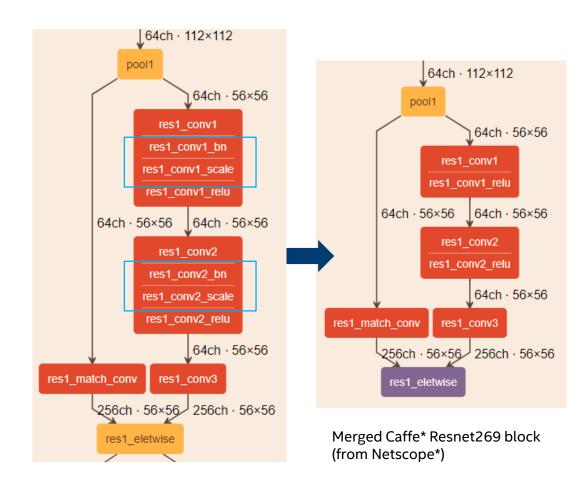
```
python3 /opt/intel/openvino/deployment_tools/model_optimizer/mo.py \
    --input_model models/public/resnet-50/resnet-50.caffemodel \
```



### MODEL OPTIMIZATION TECHNIQUES

#### Linear Operation Fusing: 3 stages

- **1. BatchNorm and ScaleShift decomposition:** *BN* layers decomposes to *Mul->Add->Mul->Add* sequence; ScaleShift layers decomposes to *Mul->Add* sequence.
- **2. Linear operations merge:** Merges sequences of Mul and Add operations to the **single** Mul->Add instance.
- **3. Linear operations fusion:** Fuses Mul and Add operations to Convolution or FullybConnected layers.



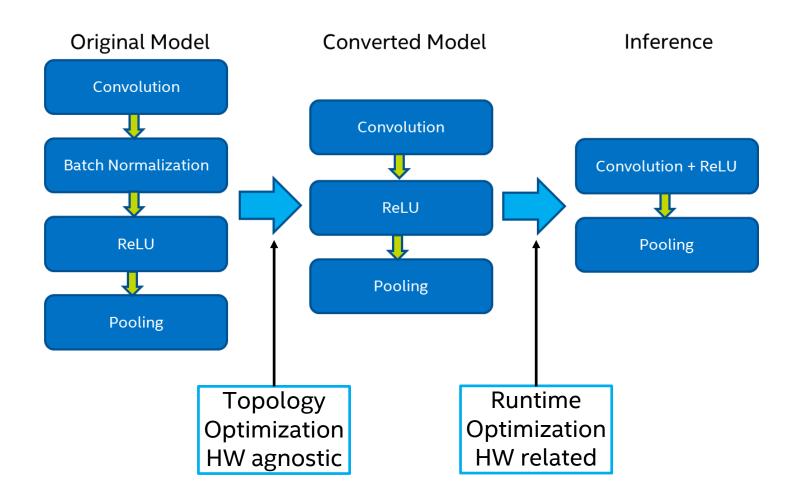
Caffe\* Resnet269 block (from Netscope)



### **MODEL OPTIMIZER: LINEAR OPERATION FUSING**

#### Example

- Remove Batch normalization stage.
- 2. Recalculate the weights to 'include' the operation.
- Merge Convolution and ReLU into one optimized kernel.





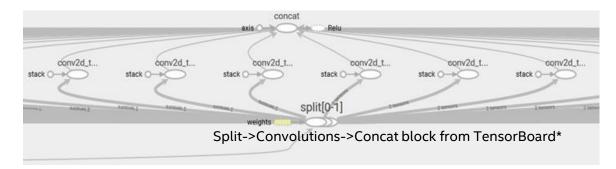
### MODEL OPTIMIZER: FRAMEWORK OR TOPOLOGY SPECIFIC OPTIMIZATION

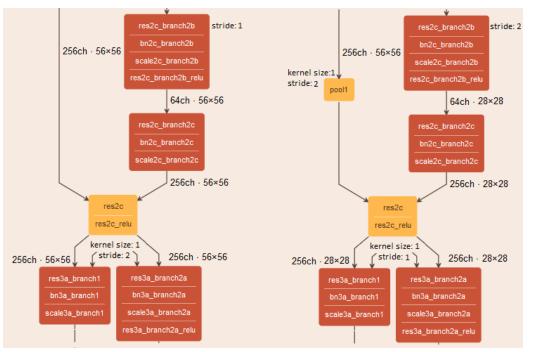
#### **Grouped Convolutions Fusing**

• Grouped convolution fusing is a specific optimization that applies for TensorFlow\* topologies. The main idea of this optimization is to combine convolutions results for the Split outputs and then recombine them using **Concat** operation in the same order as they were out from **Split**.

#### **ResNet\* optimization (stride optimization)**

This optimization is to move the stride that is greater than 1 from Convolution layers with the kernel size = 1 to upper Convolution layers. In addition, the Model Optimizer adds a Pooling layer to align the input shape for a Eltwise layer, if it was changed during the optimization.







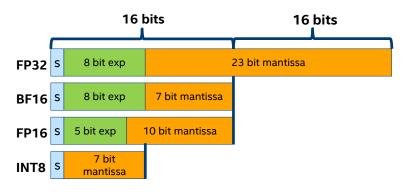
### MODEL OPTIMIZER: QUANTIZATION

#### --data\_type {FP16,FP32,half,float}

- Data type for all intermediate tensors and weights.
- If original model is in FP32 and --data\_type=FP16 is specified, all model weights and biases are quantized to FP16.

```
python3 /opt/intel/openvino/deployment_tools/model_optimizer/mo.py \
    --input_model models/public/resnet-50/resnet-50.caffemodel \
    --data_type FP16 \
    --model_name resnet-50-fp16 \
    --output_dir irfiles/
```

PLUGIN	FP32	FP16	INT8
CPU plugin	Supported and preferred	Supported	Supported
GPU plugin	Supported	Supported and preferred	Supported*
VPU plugins	Not supported	Supported	Not supported
GNA plugin	Supported	Supported	Not supported
FPGA plugin	Supported	Supported	Not supported



#### Note:

1. To create INT8 models, you will need DL Workbench or Post Training Optimization Tool

2. FPGA also support FP11, convert happens on FPGA





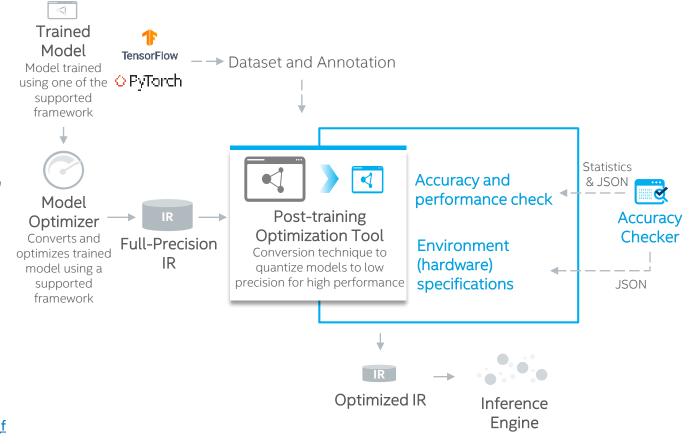
### Post-Training Optimization Tool



- Using the Python API, the Post-training Optimization Tool integrates with the Model Optimizer, DL Workbench and accuracy checker tools to streamline the development process
- Enables a conversion technique of deep learning model that reduces model size into low precision data types, such as INT8, without re-training
- Reduces model size while also improving latency, with little degradation in model accuracy and without model re-training.
- Different optimization approaches are supported: quantization algorithms, sparsity, etc.

#### Performance Benchmarks ▶

https://docs.openvinotoolkit.org/latest/\_docs\_performance\_int8\_vs\_fp32.html



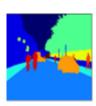


### SPEED UP DEVELOPMENT WITH OPEN SOURCE RESOURCES

#### Open source resources with pre-trained models, samples and demos













#### **Computer Vision**

Object detection

Object recognition

Reidentification

Volumetric segmentation

**Human pose estimation** 

**Image processing** 

**Action recognition** 

Image super resolution

#### Audio, Speech, Language

Language processing

Speech to text

**Text detection** 

**Text recognition** 

Natural Language Processing

#### Other

(Data Generation, Reinforcement Learning)

Compressed models

**Image retrieval** 

Semantic segmentation

**Instance segmentation** 

3D reconstruction





 Provides an easy way of accessing a number of public models as well as a set of pre-trained Intel models

 Check for accuracy of the model (original and after conversion) to IR file using a known data set And more...

### **PRE-TRAINED MODELS**

https://github.com/opencv/open model zoo

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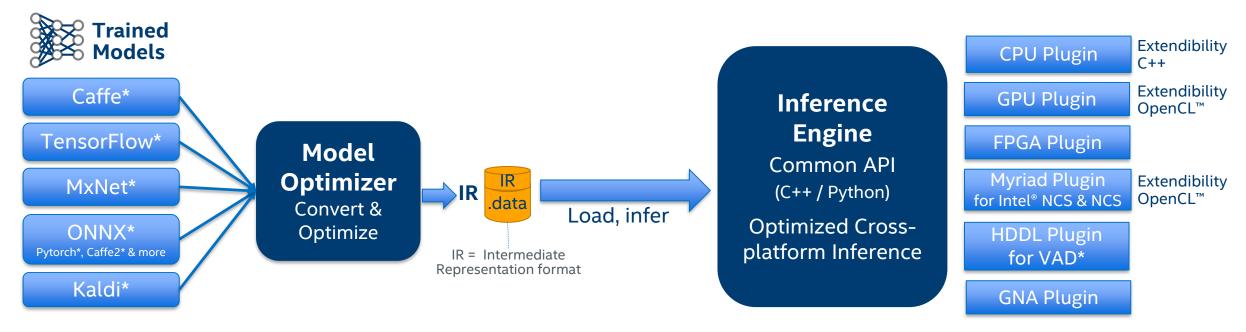
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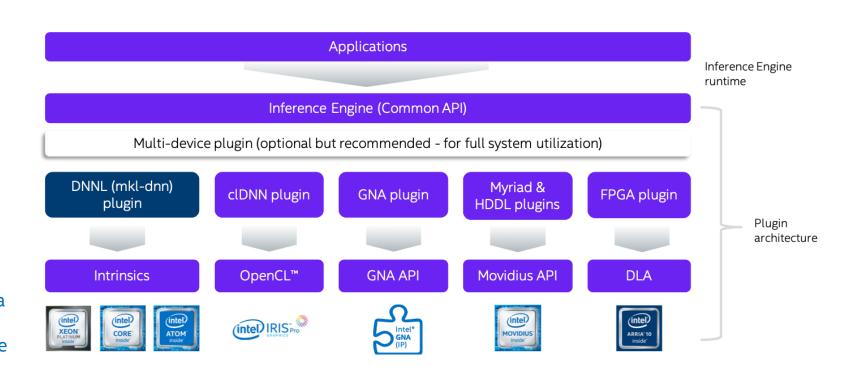
### OPTIMAL MODEL PERFORMANCE USING THE INFERENCE ENGINE

#### **Core Inference Engine Libraries**

- Create Inference Engine Core object to work with devices
- Read the network
- Manipulate network information
- Execute and pass inputs and outputs

#### **Device-specific Plugin Libraries**

 For each supported target device, Inference Engine provides a plugin — a DLL/shared library that contains complete implementation for inference on this device.

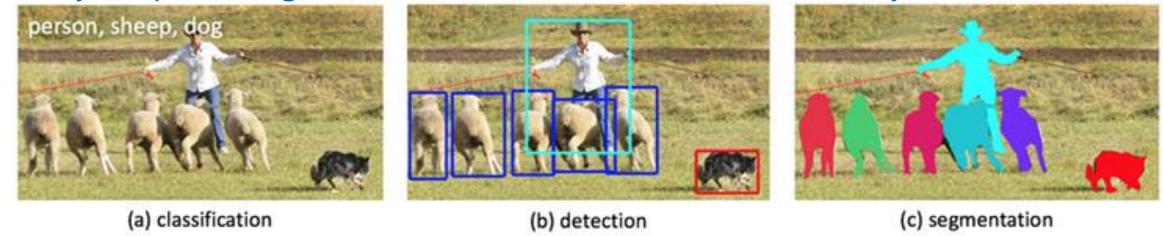


#### COMMON WORKFLOW FOR USING THE INFERENCE ENGINE API exec net = ie.load network(network=net, device name=device, num requests=request number) Create Read the **Prepare inputs Load Network to** Inference **Intermediate** device & Create and outputs **Engine Core** Representation format infer request object input blob = next(iter(net.inputs)) net = ie = IECore() ie.read network(model=model xml, output blob = next(iter(net.outputs)) weights=model bin) res = **exec net.infer**(inputs={input blob: in frame}) **Prepare input Process the Run Inference** results frame n, c, h, w = net.inputs[input blob].shape in\_frame = cv2.resize(image, (w, h)) Inference loop in frame = in frame.transpose((2, 0, 1)) in frame = in frame.reshape((n, c, h, w))



### INFERENCE ON AN INTEL® EDGE SYSTEM

Many deep learning networks are available—choose the one you need.



The complexity of the problem (data set) dictates the network structure. The more complex the problem, the more 'features' required, the deeper the network.



### PROCESS THE RESULTS

#### OBJECT DETECTION SSD EXAMPLE

Process the results (Post-processing)

The array of detection summary info, name - detection out, shape - 1, 1, N, 7, where N is the number of detected bounding boxes. For each detection, the description has the format: [ image id , label , conf , x min , y min , x max , y max ], where:

- image id ID of the image in the batch
- label predicted class ID
- conf confidence for the predicted class
- (x\_min, y\_min) coordinates of the top left bounding box corner (coordinates are in normalized format, in range [0, 1])
- (x max, y max) coordinates of the bottom right bounding box corner (coordinates are in normalized format, in range [0, 1])

```
boxes, classes = \{\}, \{\}
data = res[0][0]
for number, proposal in enumerate(data):
    if proposal[2] > 0:
        imid = np.int(proposal[0])
        ih, iw = images hw[imid]
        label = np.int(proposal[1])
        confidence = proposal[2]
        xmin = np.int(iw * proposal[3])
        ymin = np.int(ih * proposal[4])
        xmax = np.int(iw * proposal[5])
        ymax = np.int(ih * proposal[6])
        print("[{},{}] element, prob = {:.6}
                                                 ({},{})-({},{}) batch
        id : {}".format(number, label, confidence, xmin, ymin, xmax,
        ymax, imid), end="")
        if proposal[2] > 0.5:
            print(" WILL BE PRINTED!")
            if not imid in boxes.keys():
                boxes[imid] = []
            boxes[imid].append([xmin, ymin, xmax, ymax])
            if not imid in classes.keys():
                classes[imid] = []
            classes[imid].append(label)
    else:
        print()
for imid in classes:
    tmp image = cv2.imread(args.input[imid])
    for box in boxes[imid]:
        cv2.rectangle(tmp image, (box[0], box[1]), (box[2], box[3]), (
        232, 35, 244), 2)
    cv2.imwrite("out.bmp", tmp image)
    log.info("Image out.bmp created!")
```

res = res[out blob]



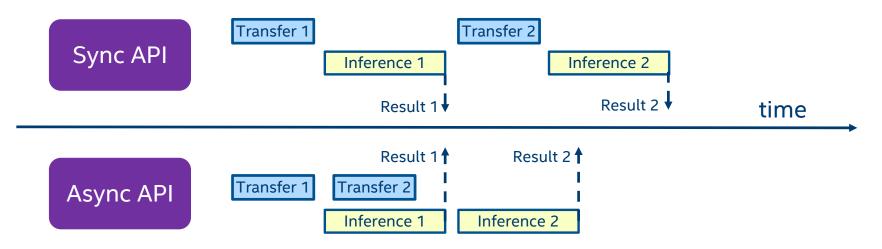


#### **Synchronous vs Asynchronous Execution**

In IE API model can be executed by **Infer Request** which can be:

- Synchronous blocks until inference is completed.
  - exec\_net.infer(inputs = {input\_blob: in\_frame})

- Asynchronous checks the execution status with the wait, or specify a completion callback (recommended way).
  - exec\_net.start\_async(request\_id = id, inputs={input\_blob: in frame})
  - If exec\_net.requests[id].wait() != 0 do something







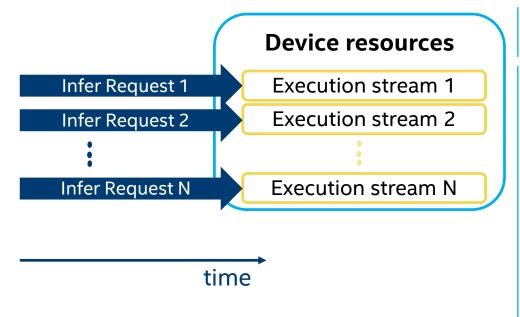
Throughput Mode for CPU, iGPU and VPU

**Latency** – inference time of 1 frame (ms).

**Throughput** – overall amount of frames inferred per 1 second (FPS)

"Throughput" mode allows the Inference Engine to efficiently run multiple infer requests simultaneously, greatly improving the overall throughput.

Device resources are divided into execution "streams" – parts which runs infer requests in parallel



#### **CPU Example:**

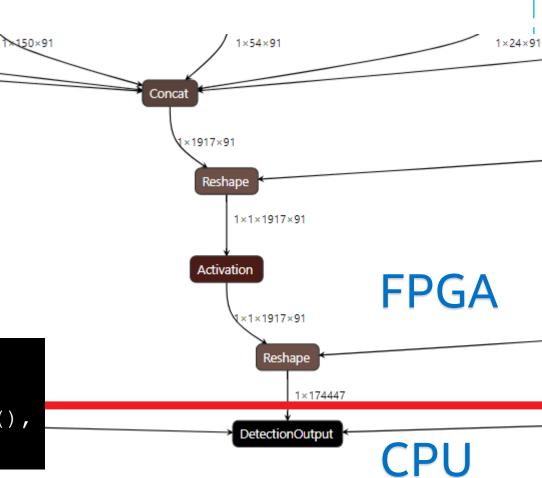
ie = IECore()
ie.GetConfig(CPU, KEY CPU THROUGHPUT STREAMS)



#### **Heterogeneous Support**

- You can execute different layers on different HW units
- Offload unsupported layers on fallback devices:
  - Default affinity policy
  - Setting affinity manually (CNNLayer::affinity)
- All device combinations are supported (CPU, GPU, FPGA, MYRIAD, HDDL)
- Samples/demos usage "-d HETERO: FPGA, CPU"

```
InferenceEngine::Core core;
    auto executable_network =
    core.LoadNetwork(reader.getNetwork(),
    "HETERO:FPGA,CPU");
```







Infer requests

### **INFERENCE ENGINE**

#### **Multi-device Support**

Automatic load-balancing between devices (inference requests level) for full system utilization

- Any combinations of the following devices are supported (CPU, iGPU, VPU, HDDL)
- As easy as "-d MULTI:CPU,GPU" for cmd-line option of your favorite sample/demo
- C++ example (Python is similar)

```
CPU
                       VPU
            GPU
queue
           queue
                       queue
 CPU
            GPU
                       VPU
           Plugin
Plugin
                       Plugin
CPU
           GPU
                       VPU
                                   etc
```

**Application** 

**Queue Manager** 

Device priority

Inference

**Engine** 

```
Core ie;
ExecutableNetwork exec =
ie.LoadNetwork(network, { "DEVICE_PRIORITIES", "CPU, GPU"} }, "MULTI")
```

### SPEED UP DEVELOPMENT WITH OPEN SOURCE RESOURCES

#### Open source resources with pre-trained models, demos, and tools

The Open Model Zoo demo applications are console applications that demonstrate how you can use your applications to solve specific use-cases.



#### **Smart Classroom**

Recognition and action detection demo for classroom settings



#### **Weld Porosity Detection**

Demonstrates how to find defects in welding



#### Multi-Camera, Multi-Person

Tracking multiple people on multiple cameras for public safety use cases



#### **Person Inpainting**

Removes unwanted people in images or videos



#### **Gaze Estimation**

Face detection followed by gaze estimation, head pose estimation and facial landmarks regression.

And more...

### **DEMO APPLICATIONS**

https://github.com/opencv/open\_model\_zoo

### **15 MINS BREAK**

**Survey:** <a href="https://bit.ly/VINOsurvey">https://bit.ly/VINOsurvey</a>

Download the Intel® Distribution of OpenVINO(TM) toolkit

https://software.intel.com/content/www/us/en/develop/tools/openvino-toolkit/choose-download.html

Intel® Edge Software Hub – Edge Computing Software and Packages
<a href="https://www.intel.com/content/www/us/en/edge-computing/edge-software-hub.html">https://www.intel.com/content/www/us/en/edge-computing/edge-software-hub.html</a>

Schedule for the Intel® Distribution of OpenVINO™ Toolkit Virtual Workshops <a href="https://software.seek.intel.com/OpenVINOworkshops">https://software.seek.intel.com/OpenVINOworkshops</a>

Go to Market with the Intel® Distribution of OpenVINO™ Toolkit
<a href="https://software.intel.com/content/www/us/en/develop/topics/iot/training/go-to-market-with-openvino.html">https://software.intel.com/content/www/us/en/develop/topics/iot/training/go-to-market-with-openvino.html</a>



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# REDEFINING THE AI DEVELOPMENT KIT INTEL® NEURAL COMPUTE STICK 2





Vision Processing Unit (VPU)

Software Development Kit

Operating Software Support

**Supported Framework** 

Connectivity

**Dimensions** 

**Operating Temperature** 

**Material Master Number** 

MSRP

Intel® Movidius™ Myriad™ X VPU

Intel® Distribution of OpenVINO™ toolkit

Ubuntu\* 16.04 or 18.04 LTS (64 bit), Windows® 10 (64 bit), CentOS\* 7.4 (64 bit), macOS\* 10.4.4, Raspbian\*, and other via the open-source

distribution of OpenVINO™ toolkit

TensorFlow\*, Caffe\*, MXNet\*, ONNX\*, and

PyTorch\* / PaddlePaddle\* via ONNX\* conversion

USB 3.1 Type-A

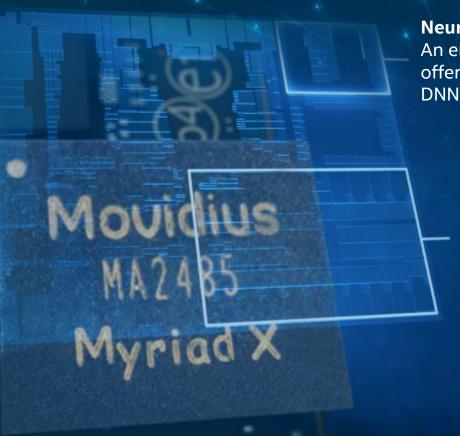
72.5mm X 27mm X 14mm

0° - 40° C

964486

\$69 as of July 14<sup>th</sup> 2019

# NEXT GENERATION AI INFERENCE INTEL® MOVIDIUS™ MYRIAD™ X VPU



#### **Neural Compute Engine**

An entirely new deep neural network (DNN) inferencing engine that offers flexible interconnect and ease of configuration for on-device DNNs and computer vision applications

#### **16 SHAVE Cores**

VLIW (DSP) programmable processors are optimized for complex vision & imaging workloads

### **EXAMPLES OF INTEL® VISION ACCELERATOR DESIGN PRODUCTS**Accelerators based on Intel® Movidius™ VPU

**EXAMPLE CARD BASED ON VISION ACCELERATOR DESIGNS** 



1 Intel<sup>®</sup> Movidius™ **VPU** 

M.2, Key E



2 Intel<sup>®</sup> Movidius™ **VPUs** 

miniPCle\*\*



PCle x4

**INTERFACE** 

**CURRENTLY MANUFACTURED** BY\*













**SOFTWARE TOOLS** 

#### INTEL® DISTRIBUTION OF OPENVINO™ TOOLKIT

Develop NN Model; Deploy across Intel® CPU, GPU, VPU, FPGA; Leverage common algorithms

\*Please contact Intel representative for complete list of ODM manufacturers. Other names and brands may be claimed as the property of others. **Optimization Notice** 

> Click here for Latest Publicly Posted Benchmarks Click here for Programing Guide for Use with Intel® Distribution of OpenVINO toolkit

### **AGENDA**

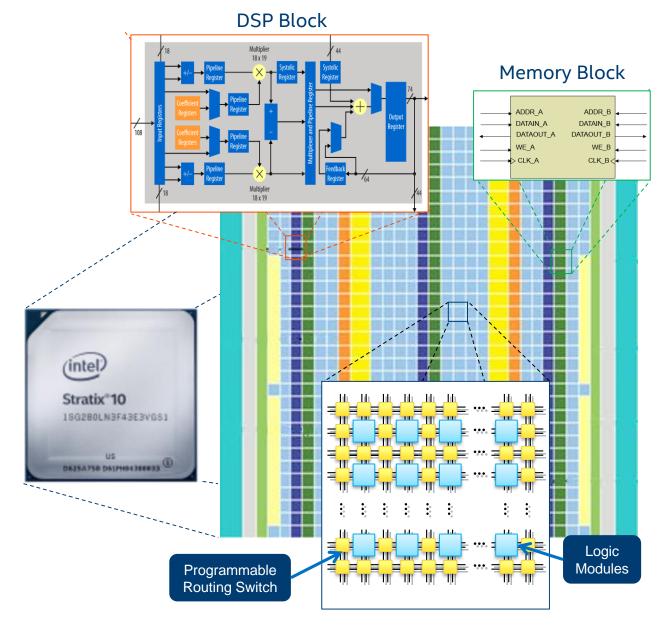
- Intel® Smart Video/Computer vision Tools Overview
- Model Optimizer
- Inference Engine
- 15 Minute Break
- Accelerators based on Intel<sup>®</sup> Movidius<sup>™</sup>
   Vision Processing Unit
- Accelerators based on Intel® Arria® FPGA
- Multiple Models in One Application
- DL Workbench + Demo

- DL Streamer
- Register for access to Intel<sup>®</sup> DevCloud for the Edge
- Lab1 DevCloud Sample Application:
   Accelerated Object Detection
- Lab2 DevCloud Advanced Tutorials: DL Streamer Benchmark



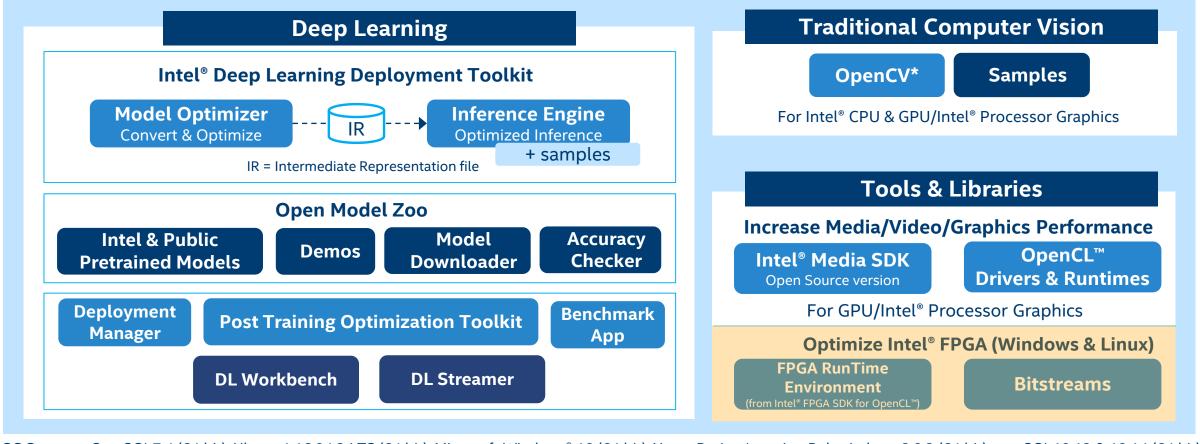
### **FPGA OVERVIEW**

- Field Programmable Gate Array (FPGA)
  - Millions of logic elements
  - Thousands of embedded memory blocks
  - Thousands of DSP blocks
  - Programmable routing
  - High speed transceivers
  - Various built-in hardened IP
- Used to create Custom Hardware!





### INSIDE INTEL® DISTRIBUTION OF OPENVINO™ TOOLKIT



OS Support: CentOS\* 7.4 (64 bit), Ubuntu\* 16.04.3 LTS (64 bit), Microsoft Windows® 10 (64 bit), Yocto Project\* version Poky Jethro v2.0.3 (64 bit), macOS\* 10.13 & 10.14 (64 bit)

Intel® Architecture-Based Platforms Support















Intel® Vision Accelerator Design Products & AI in Production/ Developer Kits

An open source version is available at <a href="https://openvinotoolkit">o1.org/openvinotoolkit</a> (some deep learning functions support Intel CPU/GPU only).



### INTEL® DISTRIBUTION OF OPENVINO™ TOOLKIT WITH DLA USER FLOWS







Intel<sup>®</sup> Distribution of OpenVINO™ toolkit

















FPGA Architecture Development Flow







Custom create FPGA bitstream

Or







User Customization of **DLA Suite** Source Code



**Intel® FPGA SDK** for OpenCL™

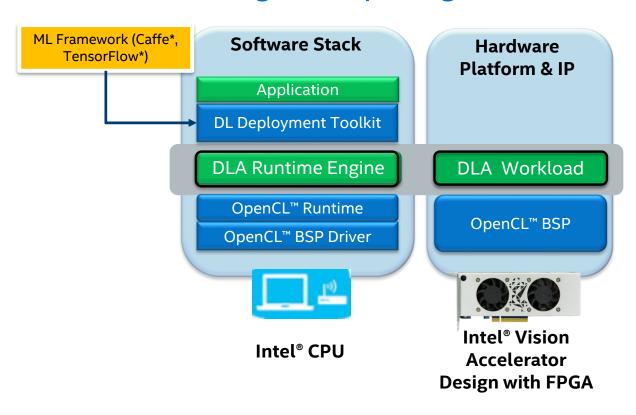


### MACHINE LEARNING ON INTEL® FPGA PLATFORM

**Acceleration Stack Platform Solution** 

#### ML Framework (Caffe\*, **Software Stack** Hardware TensorFlow\*) **Platform & IP Application DL Deployment Toolkit DLA Workload DLA Runtime Engine** OpenCL™ Runtime **FPGA** Interface Manager **Acceleration Stack** Intel<sup>®</sup> Programmable Intel® Xeon® **Acceleration Card CPU**

#### **Edge Computing Solution**



Intel® FPGA Acceleration Hub

Intel® Vision Accelerator Design Products



### INTEL® VISION ACCELERATION DESIGN WITH INTEL® ARRIA® 10 FPGA key differentiators

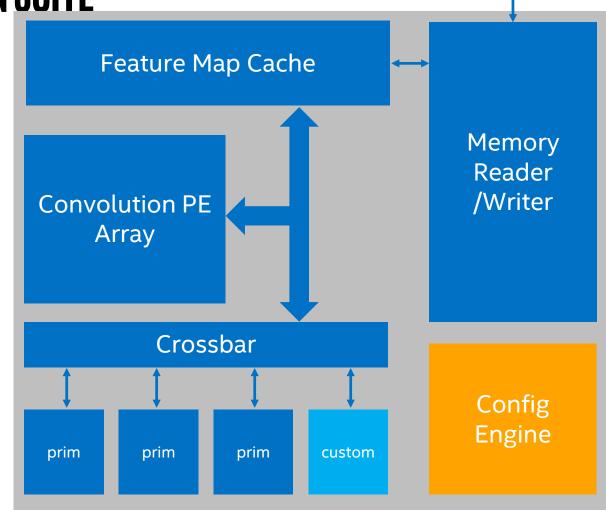


- High performance, low latency
- Flexibility to adapt to new, evolving, and custom networks
- Supports large image sizes (e.g., 4K)
- Large networks (up to 4 billion parameters)
- Wide ambient temperature range (0° C to 65° C)
- 24/7/365 operation
- Long lifespan (8–10 years)



INTEL® FPGA DEEP LEARNING ACCELERATION SUITE

- CNN inference acceleration engine for topologies executed in a graph loop architecture
  - AlexNet, GoogleNet, SqueezeNet, VGG, ResNet\*,
     MobileNet\*, Yolo, SSD, ...
- Software Deployment
  - No FPGA compile required
  - Run-time reconfigurable
- Customized Hardware Development
  - Custom architecture creation w/ parameters
  - Custom primitives using OpenCL<sup>™</sup> flow

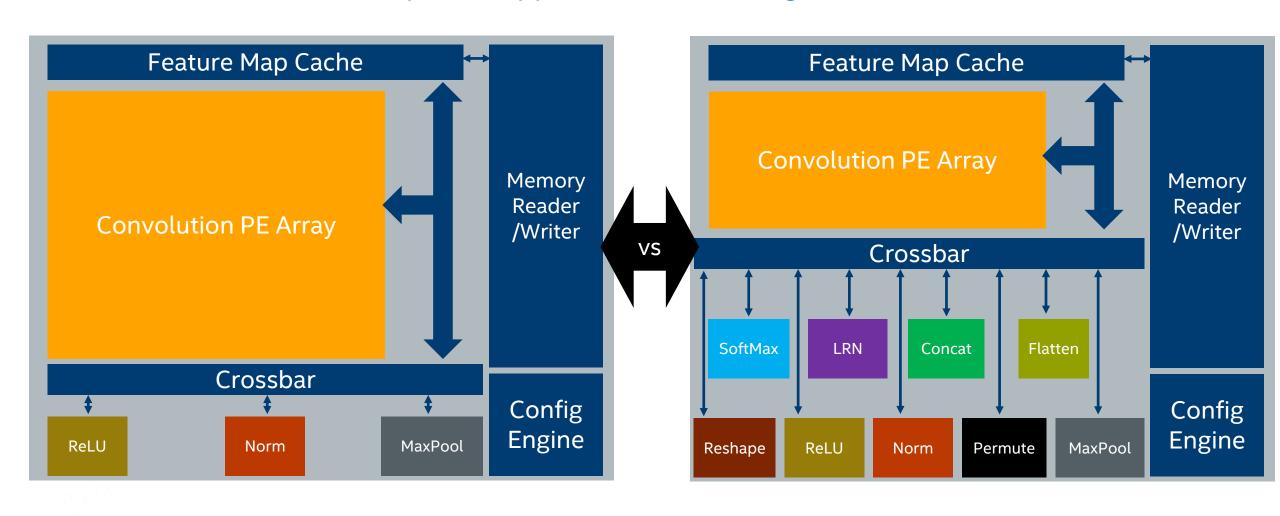




DDR

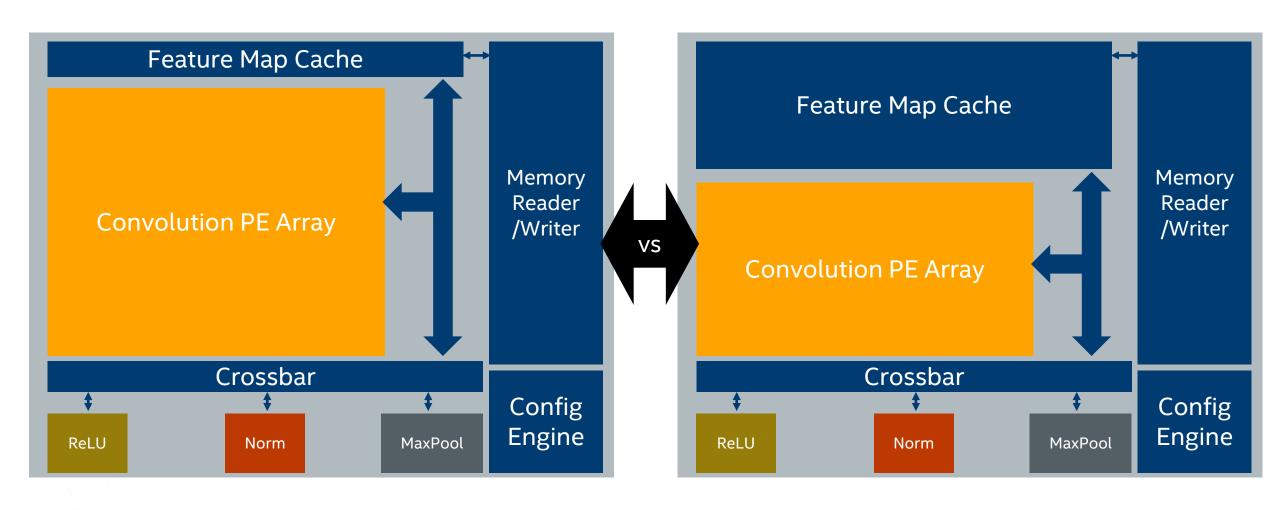
### SUPPORT FOR DIFFERENT TOPOLOGIES

Adapts to support new or evolving networks



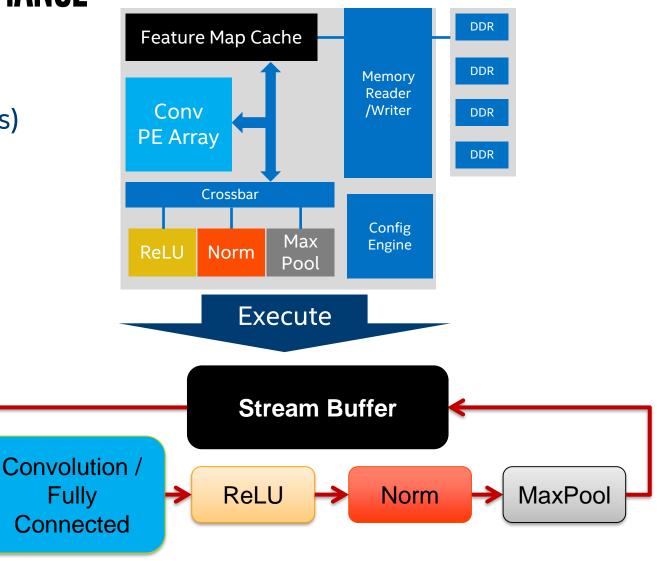
### OPTIMIZE FOR BEST PERFORMANCE

Tradeoff between size of Feature Map cache and convolutional PE array



### DLA ARCHITECTURE: BUILT FOR PERFORMANCE

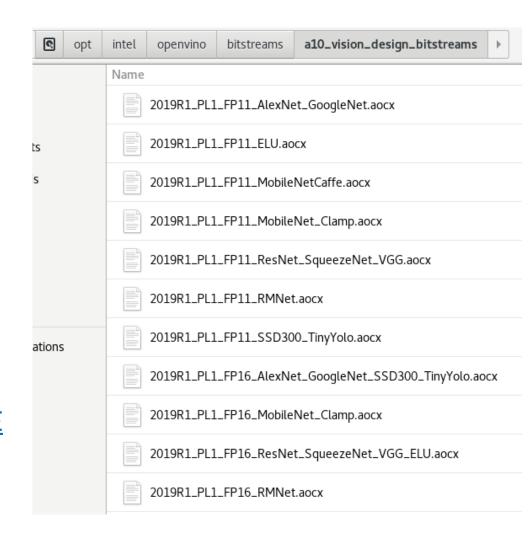
- Maximize Parallelism on the FPGA
  - Filter Parallelism (Processing Elements)
  - Input-Depth Parallelism
  - Winograd Transformation
  - Batching
  - Feature Stream Buffer
  - Filter Cache
- Choosing FPGA Bitstream
  - Data Type / Design Exploration
  - Primitive Support





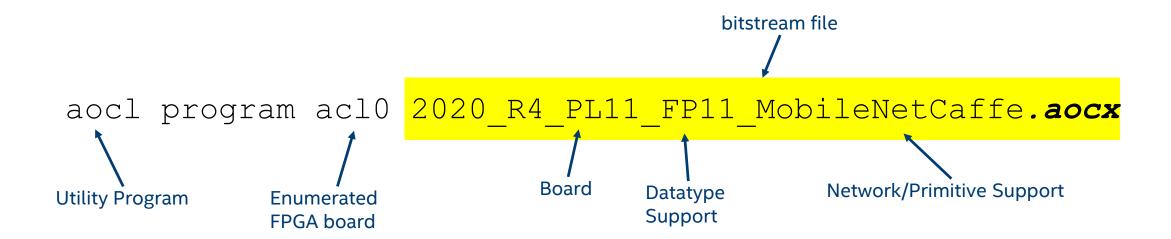
### **DLA ARCHITECTURE SELECTION**

- Intel® Distribution of OpenVINO™ toolkit ships with many FPGA images for various boards/data types/topologies
  - <version>\_<board>\_<data
    type>\_<Topologies/Feature>.aocx
- Find ideal FPGA image that meets your needs
- Check documentation for list of FPGA images and supported topologies
  - https://docs.openvinotoolkit.org/latest/\_docs\_IEDG\_supported\_plugins\_FPGA.html
- Example: ResNet\* focused image does not have Norm (better performance)



### LOAD SELECTED BITSTEAM PRIOR TO EXECUTION

Program the FPGA with the selected FPGA bitstream





# INTEL® DISTRIBUTION OF OPENVINO™ TOOLKIT FOR INTEL® VISION ACCELERATOR DESIGN WITH AN INTEL® ARRIA® 10 FPGA AND THE INTEL® PROGRAMMABLE ACCELERATION CARD WITH INTEL® ARRIA® 10 GX FPGA SUPPORT CHANGE

Intel will be transitioning to the next-generation programmable deep-learning solution based on FPGAs in order to increase the level of customization possible in FPGA deep-learning.

As part of this transition, future standard releases (i.e., non-LTS releases) of Intel® Distribution of OpenVINO™ toolkit will no longer include the Intel® Vision Accelerator Design with an Intel® Arria® 10 FPGA and the Intel® Programmable Acceleration Card with Intel® Arria® 10 GX FPGA.

Intel® Distribution of OpenVINO™ toolkit 2020.3.X LTS release will continue to support Intel® Vision Accelerator Design with an Intel® Arria® 10 FPGA and the Intel® Programmable Acceleration Card with Intel® Arria® 10 GX FPGA.



### **AGENDA**

- Intel® Smart Video/Computer vision Tools Overview
- Model Optimizer
- Inference Engine
- 15 Minute Break
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   Vision Processing Unit
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# MULTIPLE MODELS IN ONE APPLICATION SECURITY BARRIER DEMO

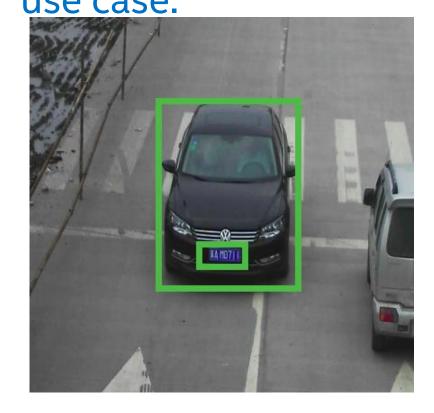
### VIDEO ANALYTICS IN INTEL® DISTRIBUTION OF OPENVINO™ TOOLKIT

Topology	Туре	Description
vehicle-license-plate- detection-barrier-0007	detection	Multiclass (vehicle, license plates) detector based on RESNET* 10 plus SSD.
vehicle-attributes- recognition-barrier- 0010	object_attributes	Vehicle attributes recognition with modified RESNET 10 backbone.
license-plate- recognition-barrier- 0001	ocr	Chinese license plate recognition.



# VEHICLE-LICENSE-PLATE-DETECTION-BARRIER-007 USE CASE/HIGH-LEVEL DESCRIPTION

RESNET\* 10 plus SSD-based vehicle and (Chinese) license plate detector for "Barrier" use case.



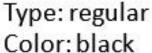


## VEHICLE-ATTRIBUTES-RECOGNITION-BARRIER-0010 USE CASE/HIGH-LEVEL DESCRIPTION

Vehicle attributes classification algorithm for a traffic analysis

scenario.







# LICENSE-PLATE-RECOGNITION-BARRIER-0001 USE CASE/HIGH-LEVEL DESCRIPTION

Small-footprint network trained E2E to recognize Chinese license plates in traffic scenarios.

Note: The license plates in the image are modified from the originals.





### **SECURITY BARRIER DEMO**









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### DEEP LEARNING WORKBENCH

#### Deep Learning Workbench



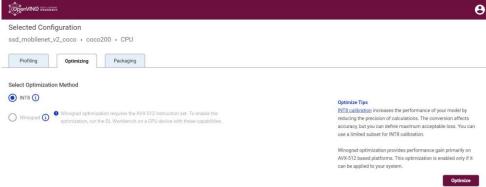
- Web-based, UI extension tool of the Intel® Distribution of OpenVINO™ toolkit
- Visualizes performance data for topologies and layers to aid in model analysis
- Automates analysis for optimal performance configuration (streams, batches, latency)
- Experiment with INT8 or Winograd calibration for optimal tuning using the Post Training Optimization Tool
- Provide accuracy information through accuracy checker
- Direct access to models from public set of Open Model Zoo
- Enables remote profiling, allowing the collection of performance data from multiple different machines without any additional set-up.

#### **Development Guide**

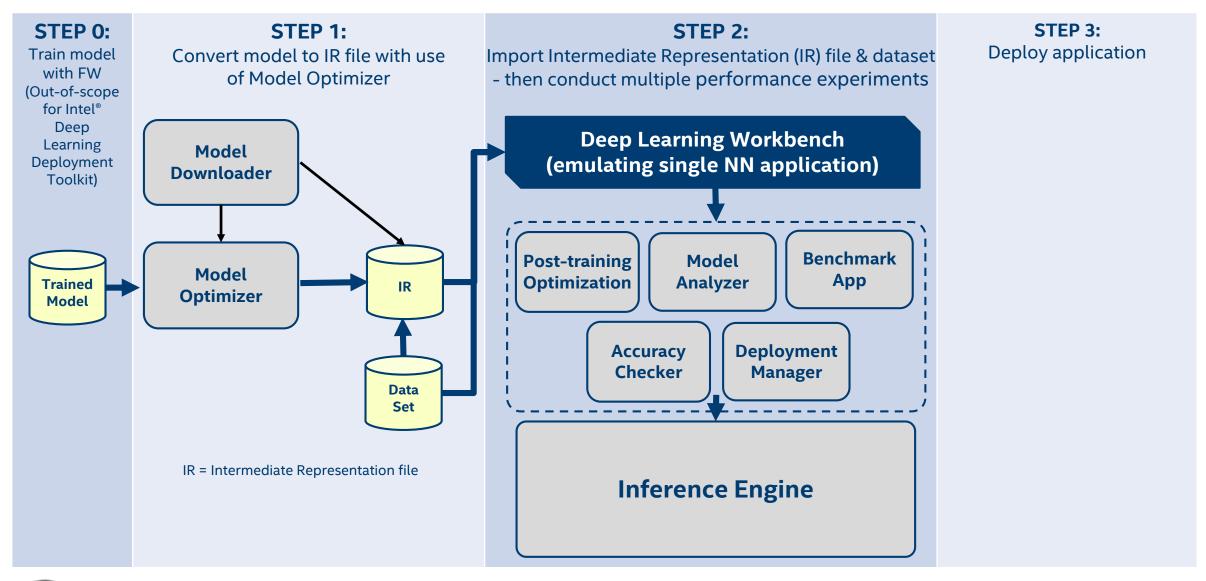
https://docs.openvinotoolkit.org/latest/ docs Workbench DG Introduction.html







### DEEP LEARNING WORKBENCH DATA FLOW





#### **DEEP LEARNING WORKBENCH: FEATURES**

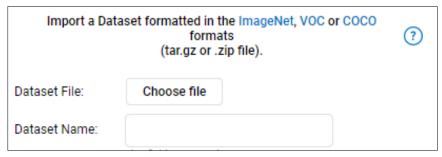
## CONVERT MODEL TO INT8 USING 2 NEW CALIBRATION ALGORITHMS

## IMPORT DATASET IN COCO FORMAT TO USE WITH MODEL

# IMPROVED PER-LAYER DATA VISUALIZATION AND COMPARISON MODE.



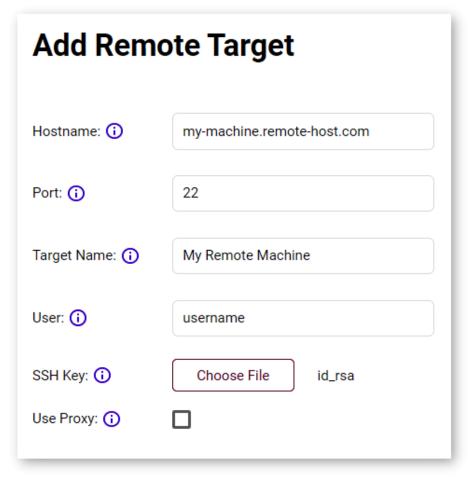




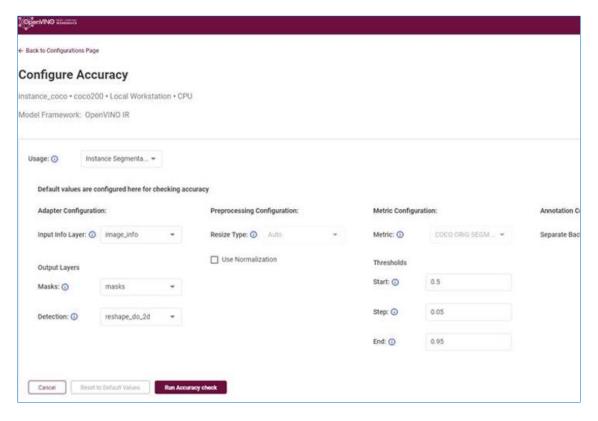
ld1_22832/Fused_Add This is calle	d layer fusion and	ansformed on device to single layer the diagram below demonstrates the fusior
heme and information on each layer f	om ongmank.	
Add1_22832/Fused_Add_	]	
	$\rightarrow$	Add1_22832/Fused_Add_

### **DEEP LEARNING WORKBENCH: NEW FEATURES**

### REMOTE PROFILING SUPPORT



## SUPPORT FOR SEGMENTATION USE CASES





### **DEMO - DL WORKBENCH WALKTHROUGH**



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### DEEP LEARNING STREAMER



### INTRODUCING.. DL STREAMER

- Intel® Distribution of OpenVINO™ toolkit Deep Learning (DL) Streamer, now part of the default installation package
- Enables developers to create and deploy optimized streaming media analytics pipelines across Intel® architecture from edge to cloud
- Optimal pipeline interoperability with a familiar developer experience built using the GStreamer multimedia framework



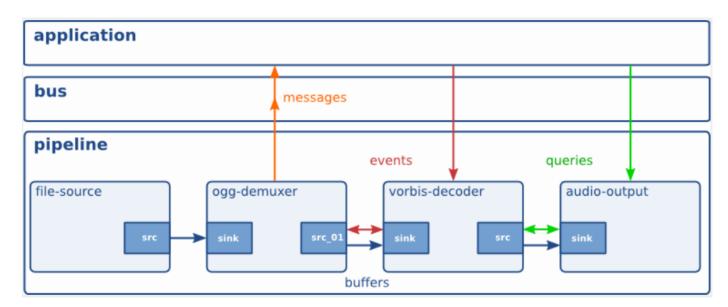






### WHAT IS GSTREAMER?

- A pipeline consists of connected processing elements
- Each element is provided by a plug-in and can be grouped into bins
- Elements communicate by means of pads source pad and sink pad
- Data buffers flow from Source element to Sink element & from source pad to sink pad



Ref:

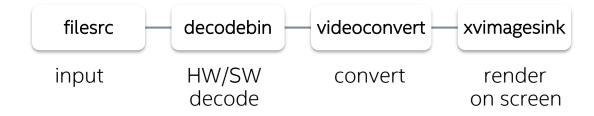
https://gstreamer.freedesktop.org/data/do c/gstreamer/head/manual/manual.pdf





### MEDIA PROCESSING PIPELINE

Video Pipeline – decode, convert, render

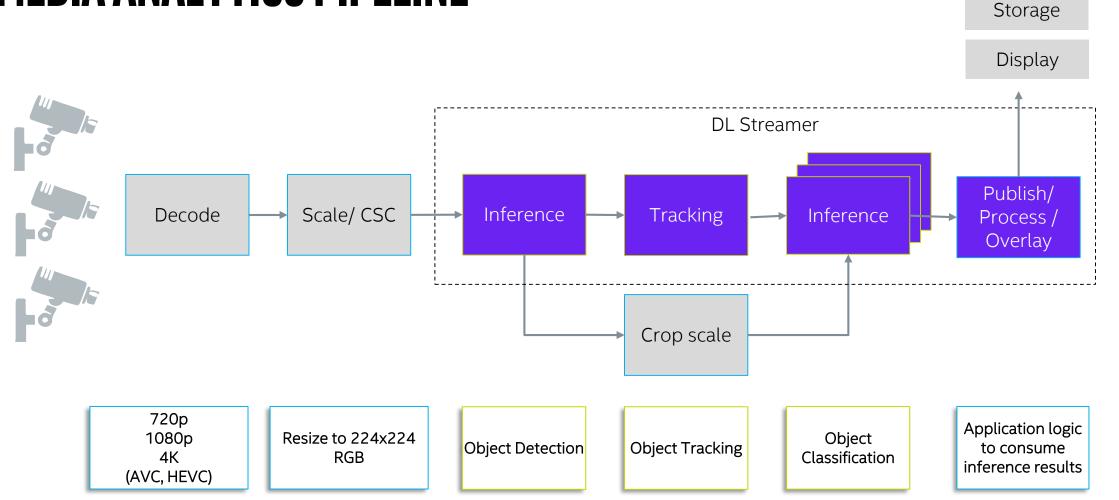




gst-launch-1.0 filesrc location=/path/to/video.mp4 ! decodebin ! videoconvert ! xvimagesink

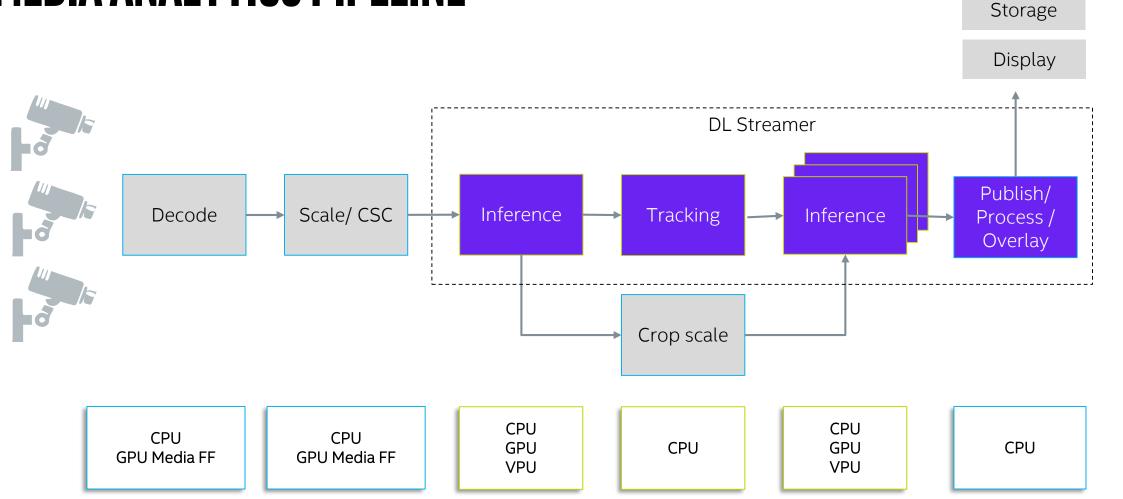


### MEDIA ANALYTICS PIPELINE





# MEDIA ANALYTICS PIPELINE

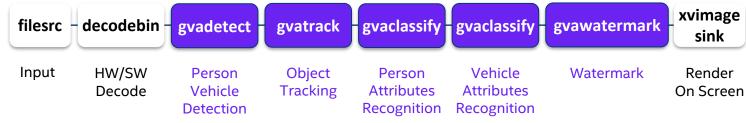






# **USING THE DL STREAMER**

Video Analytics pipeline – person and vehicle detection, person, vehicle attributes classification





```
gst-launch-1.0 filesrc location=/path/to/video.mp4 !
decodebin ! videoconvert ! video/x-raw,format=BGRx ! \
gvadetect model=person-vehicle-bike-detection-crossroad-0078.xml model-proc=person-vehicle-bike-detection-
crossroad-0078.json inference-interval=10 threshold=0.6 device=CPU ! queue ! \
gvatrack tracking-type="short-term" ! queue ! \
gvaclassify model= person-attributes-recognition-crossroad-0230.xml model-proc= person-attributes-recognition-
crossroad-0230.json reclassify-interval=10 device=CPU object-class=person ! queue ! \
gvaclassify model= vehicle-attributes-recognition-barrier-0039.xml model-proc= vehicle-attributes-recognition-
barrier-0039.json reclassify-interval=10 device=CPU object-class=vehicle ! queue ! \
gvawatermark ! videoconvert ! fpsdisplaysink video-sink=xvimagesink sync=true
```



# **UNDER THE HOOD: DL STREAMER**

Application

GStreamer framework

GStreamer Media Plugins (Standard)

Plugin

Decode

VPP

Encode

Detect

Classify

Track

Publish

Runtime Libraries

VAAPI

Libav

Intel® Distribution of OpenVINO™ toolkit Deep Learning Inference Engine

OpenCV

MQTT/ Kafka

Hardware











#### f want to know more: Check out the Webinar

HTTPS://SOFTWARE.SEEK.INTEL.COM/OPENVINO-WEBINAR-SERIES



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# INTEL® DEVCLOUD FOR THE EDGE

Sign Up Here: <a href="https://devcloud.intel.com/edge">https://devcloud.intel.com/edge</a>



## TEST HARDWARE WITH THE INTEL® DEVCLOUD FOR THE EDGE

Powered by Intel® Distribution of OpenVINO™ toolkit



#### Trained Model

Model trained using one of the supported frameworks

-or-

Using a pre-trained model available from the Open Model Zoo

### **OpenVINO**

Intel® Distribution of OpenVINO™ toolkit

Model Optimizer

Model Optimizer Inference Engine



#### Intel® DevCloud for the Edge

A development sandbox to try AI and vision workloads remotely before purchasing Intel® platforms

- Prototype on the latest hardware and software to future proof your solution
- Benchmark your customized Al application
- Run Al applications from anywhere in the world
- Help to reduce development time and cost

https://devcloud.intel.com/edge/















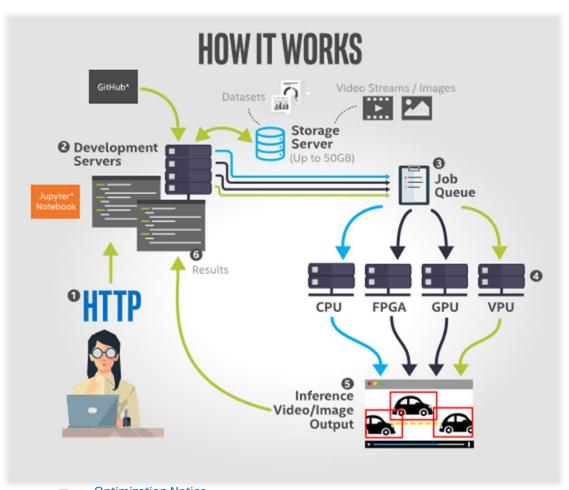






### ACCELERATE TIME TO PRODUCTION WITH INTEL® DEVCLOUD FOR THE EDGE

### SEE IMMEDIATE AI APPLICATION PERFORMANCE ACROSS INTEL'S VAST ARRAY OF EDGE SOLUTIONS



- Instant, Global AccessRun AI applications from anywhere in the world
- Prototype on the Latest Hardware and Software
   Develop knowing you're using the latest Intel technology
- Benchmark your Customized AI Application
   Immediate feedback frames per second, performance
- Reduce Development Time and Cost
   Quickly find the right compute for your edge solution

Sign up now for access

79

### Signup for Access to the Intel® DevCloud for Edge

Sign Up Here: https://devcloud.intel.com/edge/		
Intel's Registration Passcode:		
Code Valid From:		
Code Valid To:		
Account Activation:		
Account Deactivation:	Valid for 30 days	



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# LAB1 - DEVCLOUD SAMPLE APPLICATIONS



### **Accelerated Object Detection**

**BASICS** 

Learn how to accelerate your object detection applications with Asynchronous inference and offloading to multiple types of processing units.



# LAB2 - DEVCLOUD ADVANCED TUTORIALS



### **DL Streamer**

These tutorials walk you through the workflow of building a modular GStreamer pipeline to perform object detection, tracking, and classification using the DL Streamer component of OpenVINO Toolkit.



### **AGENDA**

- Register for access to Intel® DevCloud for the Edge
- Intel® Smart Video/Computer vision Tools Overview
- Model Optimizer + Demo
- Inference Engine
- Lab1 DevCloud Tutorial: Classification
- 15 Minute Break

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# GETTING STARTED WITH INTEL® DISTRIBUTION OF OPENVINO™ TOOLKIT

### Recommendations to the customer or developer

#### **QUALIFY**

#### Use a trained model and <u>check</u> if framework is supported

- or -

 Take advantage of a pre-trained model from the <u>Open Model</u> Zoo

### INSTALLATION

- Download the Intel®
   OpenVINO™ toolkit
   package from Intel®
   Developer Zone, or by YUM or APT repositories
- Utilize the <u>Getting</u>
   Started Guide

#### PREPARE

- Understand sample <u>demos</u> and <u>tools</u> included
- Understand performance
- Choose hardware option with <u>Performance</u> Benchmarks
- Build, test and remotely run workloads on the <u>Intel® DevCloud for</u> <u>the Edge</u> before buying hardware

#### HANDS ON

- Visualize metrics with the <u>Deep Learning</u>
   Workbench
- Utilize prebuilt, <u>Reference</u> <u>Implementations</u> to become familiar with capabilities
- Optimize workloads with these performance best practices
- Use the <u>Deployment</u> <u>Manager</u> to minimize deployment package

### SUPPORT

- Ask questions and share information with others through the <u>Community Forum</u>
- Engage using #OpenVINO on Stack Overflow
- Visit <u>documentation</u>
   <u>site</u> for guides, how to's, and resources
- Attend training and <u>get</u> certified
- Ready to go to market?
  Tell us how we can help





https://bit.ly/VINOsurvey