Forums > Digital Design and Embedde... → Microcontrollers → CAN application with CANbus vs CANopen Soliverlin09 · Aug 2, 2011 A Not open for further replies. Aug 2, 2011 ≪ #1 oliverlin09 Member level 1 Hi All, I am new to CAN and CANbus. If I want to build a system to connect to a CANbus, do I need CANopen protocol?? (The system may have a microcontroller/FPGA chip, CAN transceiver and motor......I don't know if I need to add more components.) Aug 2, 2011 #2 ckshivaram Advanced Member level 5 when you use a microcontroller, which supports CAN protocol, then the controller will have inbuilt registers for complete communication through CAN.. you have to set these registers and use it to send and receive the data appropriately... if the system has everything you said then you dont need anything more... ramina and oliverlin09 oliverlin09 This site uses cookies to help personalise content, tailor your experience and to keep you logged in if you register. By continuing to use this site, you are consenting to our use of cookies. ramin ✓ Accept Learn more... points



Helpful Answer Positive Rating

Aug 17, 2011 ·

Aug 2, 2011

% #3



frankee

Newbie level 3



Hi Oliver,

You only need the CANopen protocol if you intend to communicate with devices which provide it as the means for controlling or monitoring them. If you are building a custom network you can come-up with your own controlling scheme using the inherent capabilities of CANbus: for example, you can send and receive packets of up to 8 bytes and encode/deocde them to suit your application.

CANopen's strength, like most protocols, is in its error recovery mechanism. and in functions like transmitting information that wont fit into a standard 8 byte CAN packet and which requires multiple packets, and if a huge set of standardized parameters to for almost every kind of device under the sun (motor controls, I/O, encoders, analog devices etc.) Even if you were to communicate with an off-the-shelf CANopen device you could do it quite simply since CANopen is a bit of a buffet protocol where you can pick and choose which functions you need to implement.

Frank

ramina and oliverlin09



oliverlin09

points: 2

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Aug 3, 2011 ·

R

ramina

points: 2

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Aug 17, 2011 ·

Aug 2, 2011

#4



lokesh88

Member level 1



refer the link below it will help you.

CAN Bus Interface Description CANbus Pin Out, and Signal Names. Controller Area Network

oliverlin09

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oliver

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% #5



bigdogguru Administrator



The Microchip website has an entire section on CAN Design:

Microchip's CAN Design Solutions

There are plenty of training videos, appnotes, etc on the various aspects of CAN Design, including the use of CANopen.

lokesh88 and oliverlin09



oliverlin09

points: 2

Helpful Answer Positive Rating

Aug 3, 2011 ·



lokesh88

points: 2

Helpful Answer Positive Rating

Aug 3, 2011 ·

Aug 5, 2011

\$ #6



oliverlin09

Member level 1



Those links are useful.

Now I have another question.

If I wanna build a PCB to control a motor and 2 different sensors, do I need 3 CAN transceivers and 3 CAN controllers to control these three things in my PCB??

Aug 5, 2011

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#7

ckshi

Accept







yes you need 3 different pcb's for each sensor with 3 transceivers for each board.....

paavithra

P

paavithra

points: 2 Helpful Answer Positive Rating Aug 21, 2011 ·



bigdogguru Administrator



oliverlin09 said: ①

Those links are useful.

Now I have another question.

If I wanna build a PCB to control a motor and 2 different sensors, do I need 3 CAN transceivers and 3 CAN controllers to control these three things in my PCB??

No, not necessarily. The screenshot below shows three nodes of a CANbus, each node has exactly one CAN interface and one MCU. Notice for instance, Node 0 can control a PWM output channel, the state of 8 LEDs, LCD display and store values into an EEPROM, while at the same time monitor/read a potentiometer and two buttons.

The controlling and monitoring various motors and sensors is only limited by the node's MCU or other controller type. The CANbus only provides a path for data I/O and command flow to the various nodes on that particular CANbus.

Hope this example helps answer your question.

BigDog



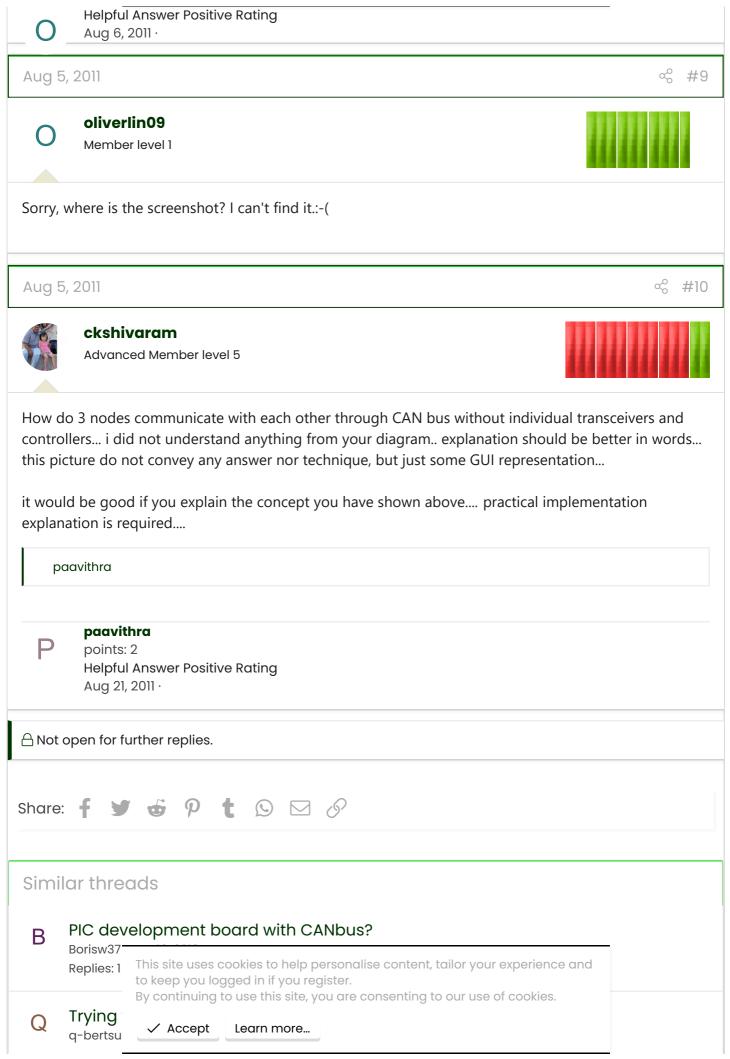
oliverlin09

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