

$X \cdot Y \rightsquigarrow$ Dot product \rightsquigarrow It is a linear operation

$X \cdot Y > 0 \Rightarrow$ They are positively correlated

$X \cdot Y < 0 \Rightarrow$ They are negatively correlated

$X \cdot Y = 0 \Rightarrow$ They are uncorrelated \rightsquigarrow They are orthogonal

If two vectors are linearly independent, can I say, they are uncorrelated. \rightarrow

$$A = \begin{bmatrix} \overset{A_1}{1} & \overset{A_2}{3} & 13 \\ 3 & 7 & 17 \\ 2 & 11 & 19 \end{bmatrix} \quad \text{Rank} = 3 \quad \text{full rank} \quad \begin{array}{l} A_1 \text{ \& } A_2 \text{ are linearly independent} \\ A_1 \cdot A_2 \neq 0 \end{array}$$

$$AX = X\Lambda \rightsquigarrow \text{Eigen decomposition}$$

$$Ax = \lambda x \rightsquigarrow \text{eigen value \& eigen vector}$$

$$|A| = \prod_{i=1}^d \lambda_i$$

what if one of the eigen values is equal to zero?

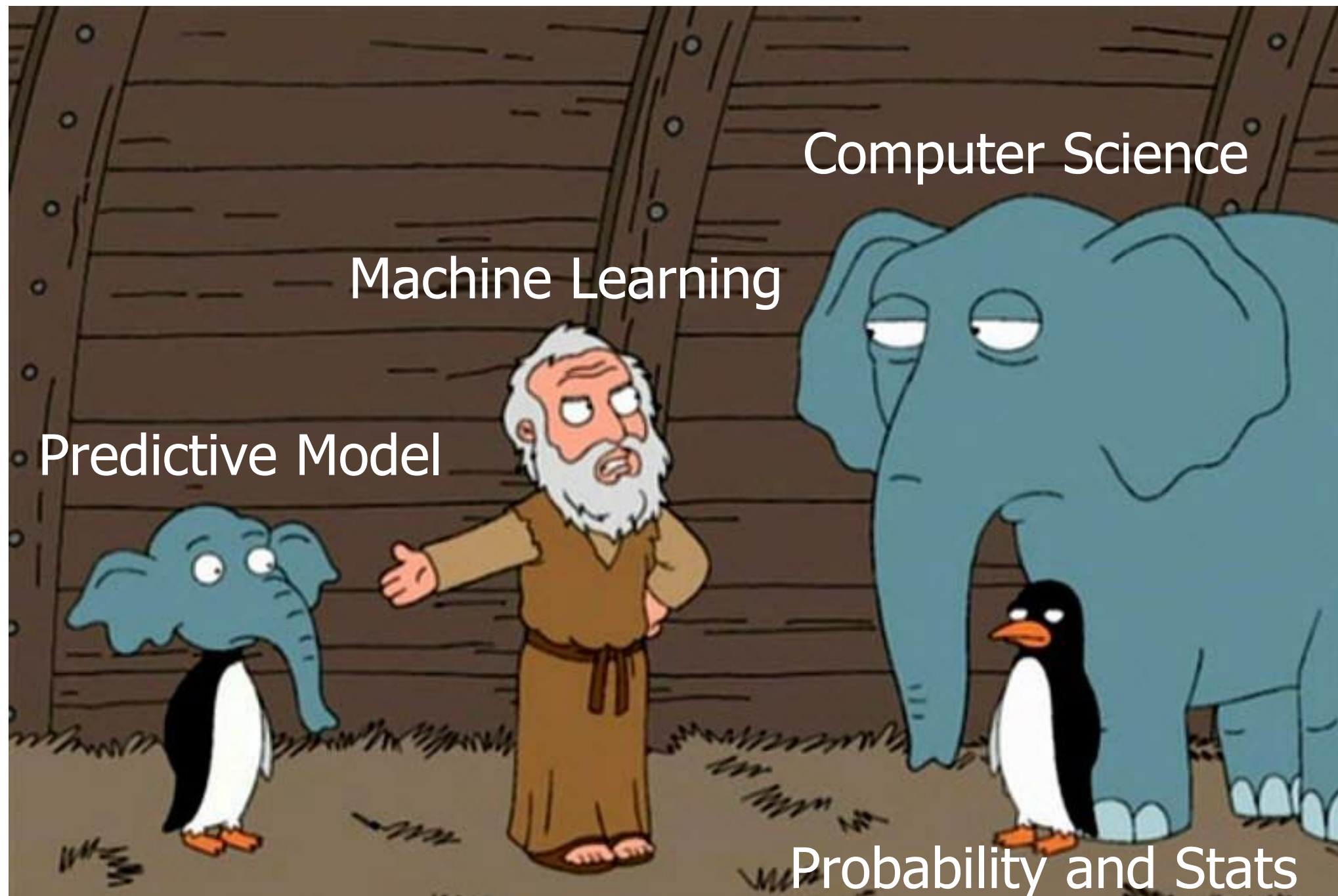
\Downarrow

$|A| = 0 \rightsquigarrow$ Singular matrix \rightarrow Not invertible

\rightarrow non-full rank \rightarrow some of columns

or row are linearly dependent


$$A = \begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix}$$



Probability and Statistics

Mahdi Roozbahani
Georgia Tech

Outline

- Probability Distributions 
- Joint and Conditional Probability Distributions
- Bayes' Rule
- Mean and Variance
- Properties of Gaussian Distribution
- Maximum Likelihood Estimation

Probability

- A **sample space S** is the set of all possible outcomes of a conceptual or physical, repeatable experiment. (S can be finite or infinite.)
 - E.g., S may be the set of all possible outcomes of a dice roll: S
(1 2 3 4 5 6)
 - E.g., S may be the set of all possible nucleotides of a DNA site: S
(A C G T)
- E.g., S may be the set of all possible time-space positions of an aircraft on a radar screen.
- An **Event A** is any subset of S
 - Seeing "1" or "6" in a dice roll; observing a "G" at a site; UA007 in space-time interval



Three Key Ingredients in Probability Theory

A **sample space** is a collection of all possible outcomes

RV

Random variables **X** represents **outcomes** in sample space

$$P(X=1) = \frac{1}{6}$$

Probability of a random variable to happen

$$p(x) = p(X = x)$$

$$p(x) \geq 0$$

density = Likelihood = $P(x) = f(x)$



Continuous variable

Continuous probability distribution

pdf

← Probability density function
Density or likelihood value
Temperature (real number)
Gaussian Distribution

$$\int_x p(x) dx = 1$$

$$\int_x f(x) dx = 1$$

Discrete variable

Discrete probability distribution

pmf

Probability mass function

Probability value

Coin flip (integer)

Bernoulli distribution

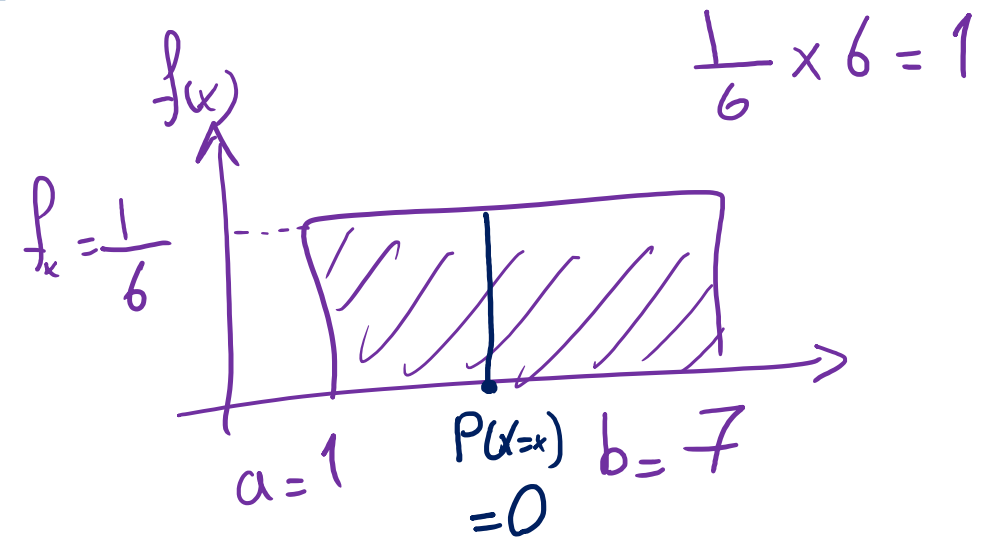
$$\sum_{x \in A} p(x) = 1$$

Continuous Probability Functions

- Examples:

- Uniform Density Function:

$$f_x(x) = \begin{cases} \frac{1}{b-a} & \text{for } a \leq x \leq b \\ 0 & \text{otherwise} \end{cases}$$



- Exponential Density Function:

$$f_x(x) = \frac{1}{\mu} e^{-\frac{x}{\mu}} \quad \text{for } x \geq 0$$

$$F_x(x) = 1 - e^{-\frac{x}{\mu}} \quad \text{for } x \geq 0$$

μ as a parameter

- Gaussian(Normal) Density Function

$$f_x(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

μ
 σ we have two parameters

Discrete Probability Functions

- Examples:

- Bernoulli Distribution:

- $$\begin{cases} 1 - p & \text{for } x = 0 \\ p & \text{for } x = 1 \end{cases}$$

In Bernoulli, just a **single** trial is conducted

- Binomial Distribution:


- $$P(X = k) = \binom{n}{k} p^k (1 - p)^{n-k}$$

k is number of successes

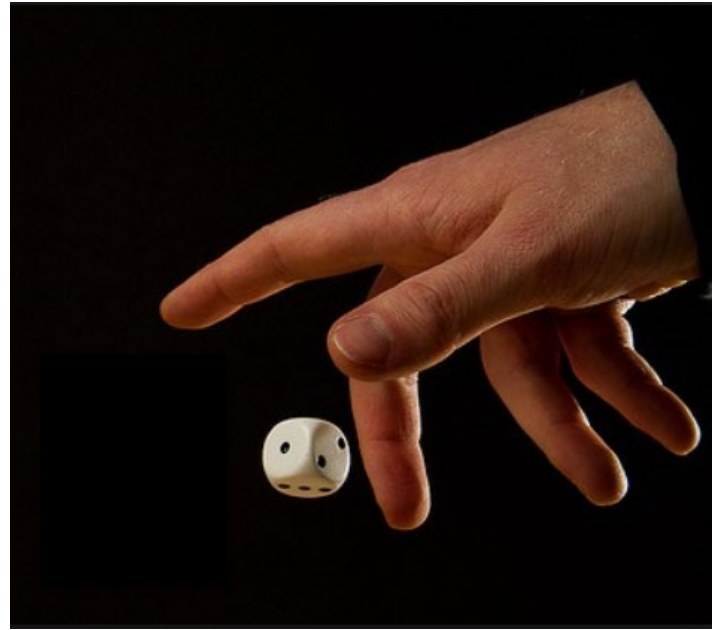
n-k is number of failures

$\binom{n}{k}$ The total number of ways of selection **k** distinct combinations of **n** trials, **irrespective of order**.

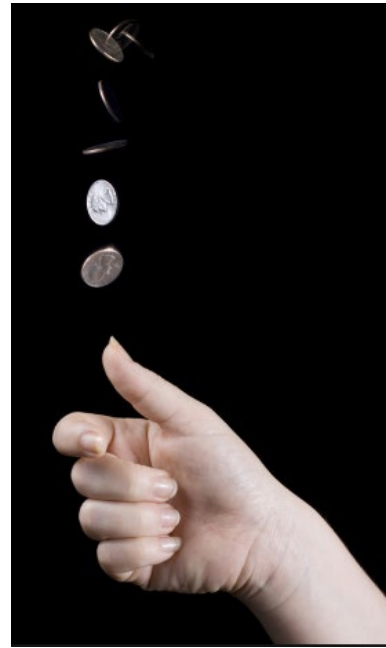
Outline

- Probability Distributions
- Joint and Conditional Probability Distributions ← 
- Bayes' Rule
- Mean and Variance
- Properties of Gaussian Distribution
- Maximum Likelihood Estimation

Example



X = Throw a
dice



Y = Flip a coin

\mathbf{X} and \mathbf{Y} are random variables

\mathbf{N} = total number of trials

n_{ij} = Number of occurrence

		\mathbf{X}						C_j
		$x_{i=1} = 1$	$x_{i=2} = 2$	$x_{i=3} = 3$	$x_{i=4} = 4$	$x_{i=5} = 5$	$x_{i=6} = 6$	
\mathbf{Y}	$y_{j=2} = tail$	$n_{ij} = 3$	$n_{ij} = 4$	$n_{ij} = 2$	$n_{ij} = 5$	$n_{ij} = 1$	$n_{ij} = 5$	20
	$y_{j=1} = head$	$n_{ij} = 2$	$n_{ij} = 2$	$n_{ij} = 4$	$n_{ij} = 2$	$n_{ij} = 4$	$n_{ij} = 1$	15
	C_i	5	6	6	7	5	6	N=35

X**C_j**
 $x_{i=1} = 1 \quad x_{i=2} = 2 \quad x_{i=3} = 3 \quad x_{i=4} = 4 \quad x_{i=5} = 5 \quad x_{i=6} = 6$
Y $y_{j=2} = \text{tail}$
 $y_{j=1} = \text{head}$
C_i

$n_{ij} = 3$	$n_{ij} = 4$	$n_{ij} = 2$	$n_{ij} = 5$	$n_{ij} = 1$	$n_{ij} = 5$	20
$n_{ij} = 2$	$n_{ij} = 2$	$n_{ij} = 4$	$n_{ij} = 2$	$n_{ij} = 4$	$n_{ij} = 1$	15
5	6	6	7	5	6	N=35

$$P(Y=h, X=2) = \frac{2}{35} = \frac{n_{ij}}{N}$$

$$P(Y=t) = \frac{20}{35} = \frac{C_j}{N}$$

$$P(X=5) = \frac{5}{35} = \frac{C_i}{N}$$

$$P(Y=t | X=1) = \frac{3}{5} = \frac{n_{ij}}{C_i}$$

$$P(X=1 | Y=t) = \frac{3}{20} = \frac{n_{ij}}{C_j}$$

$$P(Y=y, X=x) = \frac{n_{ij}}{N} = \frac{n_{ij}}{C_i} \frac{C_i}{N} = P(Y=y | X=x) P(X=x)$$

$$= \frac{n_{ij}}{C_j} \frac{C_j}{N} = P(X=x | Y=y) P(Y=y)$$

Probability:

$$p(X = x_i) = \frac{c_i}{N}$$

Joint probability:

$$p(X = x_i, Y = y_j) = \frac{n_{ij}}{N}$$

Conditional probability:

$$p(Y = y_j | X = x_i) = \frac{n_{ij}}{c_i}$$

Sum rule

$$p(X = x_i) = \sum_{j=1}^L p(X = x_i, Y = y_j) \Rightarrow p(X) = \sum_Y P(X, Y)$$

Product rule

$$p(X = x_i, Y = y_j) = \frac{n_{ij}}{N} = \frac{n_{ij}}{c_i} \frac{c_i}{N} = p(Y = y_j | X = x_i) p(X = x_i)$$

$$p(X, Y) = p(Y|X)p(X)$$

Conditional Independence

- Examples:

$$P(\text{Virus} \mid \text{Drink Beer}) = P(\text{Virus})$$

iff **Virus** is independent of **Drink Beer**

$$P(\text{Flu} \mid \text{Virus}, \text{Drink Beer}) = P(\text{Flu} \mid \text{Virus})$$

iff **Flu** is independent of **Drink Beer**, given **Virus**

$$P(\text{Headache} \mid \text{Flu}, \text{Virus}, \text{Drink Beer}) =$$

$$P(\text{Headache} \mid \text{Flu}, \text{Drink Beer})$$

iff **Headache** is independent of **Virus**, given **Flu** and **Drink Beer**

$$P(H, F, V, D) = P(H \mid \underline{F, V, D}) P(F, V, D)$$

$$= P(H \mid F, D) P(F \mid V, D) P(V, D)$$

$$= P(H \mid F, D) P(F \mid V) \underbrace{P(V \mid D) P(D)}_{P(V)}$$

Assume the above independence, we obtain:


$$P(\text{Headache}, \text{Flu}, \text{Virus}, \text{Drink Beer})$$

$$= P(\text{Headache} \mid \text{Flu}, \text{Virus}, \text{Drink Beer}) P(\text{Flu} \mid \text{Virus}, \text{Drink Beer})$$

$$P(\text{Virus} \mid \text{Drink Beer}) P(\text{Drink Beer})$$

$$= P(\text{Headache} \mid \text{Flu}, \text{Drink Beer}) P(\text{Flu} \mid \text{Virus}) P(\text{Virus}) P(\text{Drink Beer})$$

Outline

- Probability Distributions
- Joint and Conditional Probability Distributions
- Bayes' Rule 
- Mean and Variance
- Properties of Gaussian Distribution
- Maximum Likelihood Estimation

Bayes' Rule

- $P(X|Y)$ = Fraction of the worlds in which X is true given that Y is also true.
- For example:
 - H = "Having a headache"
 - F = "Coming down with flu"
 - $P(\text{Headache}|\text{Flu})$ = fraction of flu-inflicted worlds in which you have a headache. How to calculate?

- Definition:

$$P(X|Y) = \frac{P(X, Y)}{P(Y)} = \frac{P(Y|X)P(X)}{P(Y)}$$

Corollary:

$$P(X, Y) = P(Y|X)P(X)$$

This is called **Bayes Rule**


Bayes' Rule

- $$P(\text{Headache}|\text{Flu}) = \frac{P(\text{Headache},\text{Flu})}{P(\text{Flu})}$$
$$= \frac{P(\text{Flu}|\text{Headache})P(\text{Headache})}{P(\text{Flu})}$$

Other cases:

- $$P(Y|X) = \frac{P(X|Y)P(Y)}{P(X|Y)P(Y)+P(X|\neg Y)P(\neg Y)}$$
- $$P(Y = y_i|X) = \frac{P(X|Y)P(Y)}{\sum_{i \in S} P(X|Y = y_i)P(Y=y_i)}$$
- $$P(Y|X, Z) = \frac{P(X|Y, Z)P(Y, Z)}{P(X, Z)} =$$
$$\frac{P(X|Y, Z)P(Y, Z)}{P(X|Y, Z)P(Y, Z)+P(X|\neg Y, Z)P(\neg Y, Z)}$$

Outline

- Probability Distributions
- Joint and Conditional Probability Distributions
- Bayes' Rule
- Mean and Variance 
- Properties of Gaussian Distribution
- Maximum Likelihood Estimation

Mean and Variance

- Expectation: The mean value, center of mass, first moment:

$$E_X[g(X)] = \int_{-\infty}^{\infty} g(x)p_X(x)dx = \mu$$

- N-th moment: $g(x) = x^n$
- N-th central moment: $g(x) = (x - \mu)^n$
- Mean: $E_X[X] = \int_{-\infty}^{\infty} xp_X(x)dx$
 - $E[\alpha X] = \alpha E[X]$
 - $E[\alpha + X] = \alpha + E[X]$
- Variance(Second central moment): $Var(x) = E_X[(X - E_X[X])^2] = E_X[X^2] - E_X[X]^2$
 - $Var(\alpha X) = \alpha^2 Var(X)$
 - $Var(\alpha + X) = Var(X)$

For Joint Distributions


- Expectation and Covariance:

- $E[X + Y] = E[X] + E[Y]$

- $cov(X, Y) = E[(X - E_X[X])(Y - E_Y(Y))] = E[XY] - E[X]E[Y]$

- $Var(X + Y) = Var(X) + 2cov(X, Y) + Var(Y)$

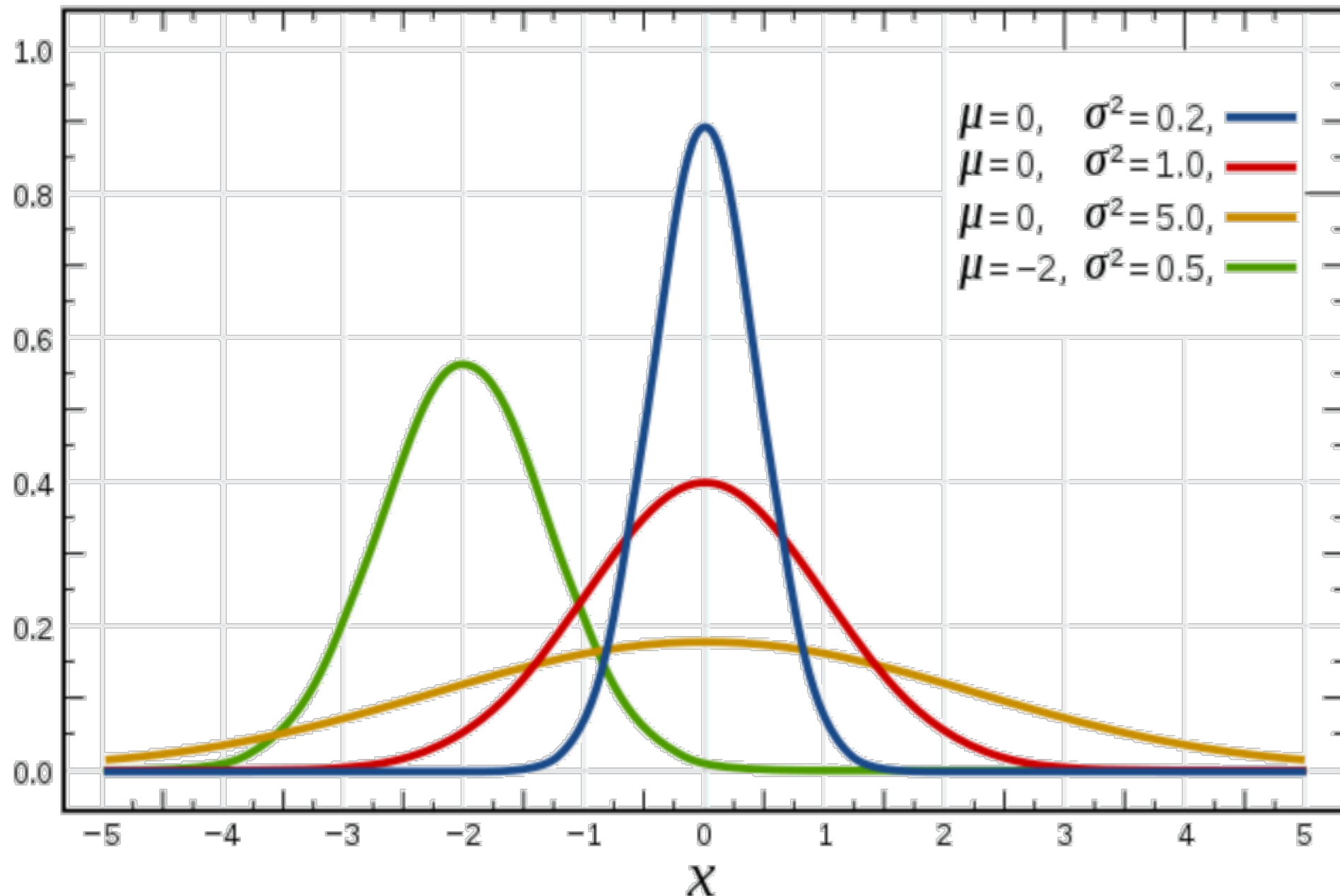
Outline

- Probability Distributions
- Joint and Conditional Probability Distributions
- Bayes' Rule
- Mean and Variance
- Properties of Gaussian Distribution ← 
- Maximum Likelihood Estimation

Gaussian Distribution

- Gaussian Distribution:
$$f(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Probability density function



Probability versus likelihood

Multivariate Gaussian Distribution

$$p(x|\mu, \Sigma) = \frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} (x - \mu)^\top \Sigma^{-1} (x - \mu)\right\}$$

- Moment Parameterization $\mu = E(X)$

$$\Sigma = \text{Cov}(X) = E[(X - \mu)(X - \mu)^\top]$$

- Mahalanobis Distance $\Delta^2 = (x - \mu)^\top \Sigma^{-1} (x - \mu)$
- Tons of applications (MoG, FA, PPCA, Kalman filter,...)

Properties of Gaussian Distribution

- The **linear transform** of a Gaussian r.v. is a Gaussian. Remember that no matter how x is distributed

$$E(AX + b) = AE(X) + b$$

$$\text{Cov}(AX + b) = A\text{Cov}(X)A^T$$

this means that for Gaussian distributed quantities:

$$X \sim N(\mu, \Sigma) \rightarrow AX + b \sim N(A\mu + b, A\Sigma A^T)$$

- The **sum** of two independent Gaussian r.v. is a Gaussian

$$Y = X_1 + X_2, X_1 \perp X_2 \rightarrow \mu_y = \mu_1 + \mu_2, \Sigma_y = \Sigma_1 + \Sigma_2$$

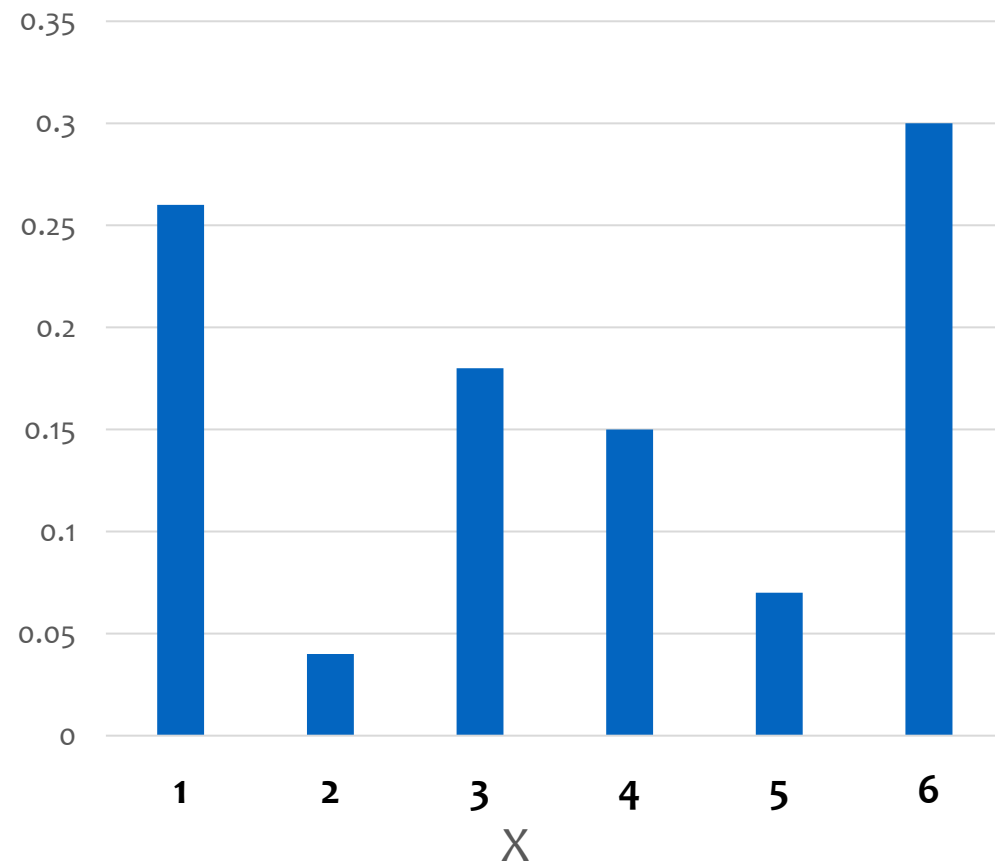
- The **multiplication** of two Gaussian functions is another Gaussian function (although no longer normalized)

$$N(a, A)N(b, B) \propto N(c, C),$$

$$\text{where } C = (A^{-1} + B^{-1})^{-1}, c = CA^{-1}a + CB^{-1}b$$

Central Limit Theorem

Probability mass function of a **biased** dice



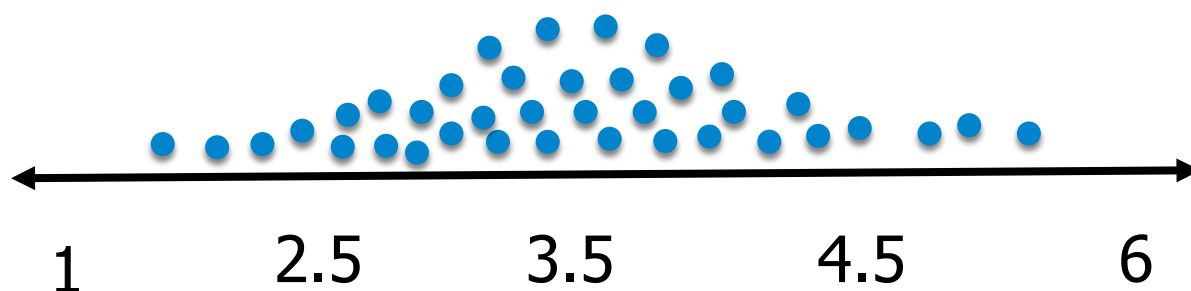
Let's say, I am going to get a sample from this pmf having a size of **$n = 4$**

$$S_1 = \{1,1,1,6\} \Rightarrow E(S_1) = 2.25$$

$$S_2 = \{1,1,3,6\} \Rightarrow E(S_2) = 2.75$$


\vdots

$$S_m = \{1,4,6,6\} \Rightarrow E(S_m) = 4.25$$



According to CLT, it will follow a bell curve distribution (normal distribution)

Outline

- Probability Distributions
- Joint and Conditional Probability Distributions
- Bayes' Rule
- Mean and Variance
- Properties of Gaussian Distribution
- Maximum Likelihood Estimation 

Maximum Likelihood Estimation

- Probability: inferring probabilistic quantities for data given fixed models (e.g. prob. of events, marginals, conditionals, etc).
- Statistics: inferring a model given fixed data observations (e.g. clustering, classification, regression).

Main assumption:

Independent and identically distributed random variables
i.i.d

Maximum Likelihood Estimation

For Bernoulli (i.e. flip a coin):

Objective function: $P(x_i|\theta) = \theta^{x_i}(1 - \theta)^{1-x_i}$ $x_i \in \{0,1\}$ or $\{head, tail\}$

$$L(\theta|X) = L(\theta|X = x_1, X = x_2, X = x_3, \dots, X = x_n)$$

i.i.d assumption

$$L(\theta|X) = \prod_{i=1}^n P(x_i|\theta)$$

$$L(\theta|X) = \prod_{i=1}^n P(x_i|\theta) = \prod_{i=1}^n \theta^{x_i}(1 - \theta)^{1-x_i}$$

$$\begin{aligned} L(\theta|X) &= \theta^{x_1}(1 - \theta)^{1-x_1} \times \theta^{x_2}(1 - \theta)^{1-x_2} \dots \times \theta^{x_n}(1 - \theta)^{1-x_n} = \\ &= \theta^{\sum x_i} (1 - \theta)^{\sum (1-x_i)} \end{aligned}$$

We don't like multiplication, let's convert it into summation

What's the trick?

Take the log

$$L(\theta|X) = \theta^{\sum x_i} (1 - \theta)^{\sum (1 - x_i)}$$

$$\log L(\theta|X) = l(\theta|X) = \log(\theta) \sum_{i=1}^n x_i + \log(1 - \theta) \sum_{i=1}^n (1 - x_i)$$

How to optimize θ ?

$$\frac{\partial l(\theta|X)}{\partial \theta} = 0 \quad \frac{\sum_{i=1}^n x_i}{\theta} - \frac{\sum_{i=1}^n (1 - x_i)}{1 - \theta} = 0$$

$$\theta = \frac{1}{n} \sum_{i=1}^n x_i$$