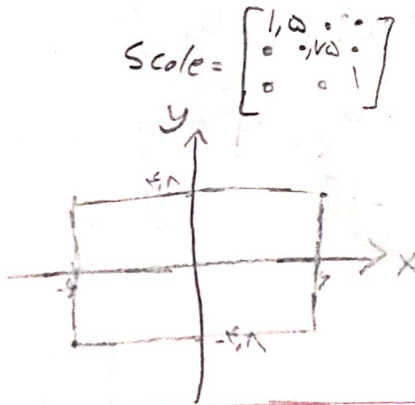
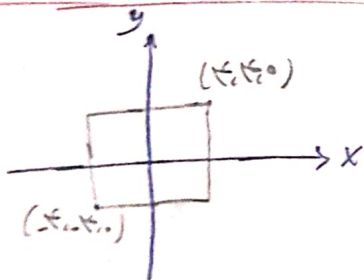


$T(x, y, z) = (x, y, x - 2z)$ $T(KU) = KT(U)$
 $T(1, 2, 3) = (3, 2, 3)$ $\Rightarrow T(KU) = (2, 4, 4) = (4, -1, 4)$ $KT(U) = 2(3, 2, 3) = (6, 4, 6)$
 T تبدیل خطی نیست $(4, -1, 4) \neq (6, 4, 6)$

$R_x = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \theta & \sin \theta & 0 \\ 0 & -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$, $R_y = \begin{bmatrix} \cos \theta & 0 & -\sin \theta & 0 \\ 0 & 1 & 0 & 0 \\ \sin \theta & 0 & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$, $R_z = \begin{bmatrix} \cos \theta & \sin \theta & 0 & 0 \\ -\sin \theta & \cos \theta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$
 $R_x(30^\circ) \times R_y(30^\circ) \times R_z(30^\circ) = \begin{bmatrix} \dots \\ \dots \\ \dots \\ \dots \end{bmatrix}_{4 \times 4}$

$T = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ b_x & b_y & b_z & 1 \end{bmatrix}$, $S = \begin{bmatrix} s_x & 0 & 0 & 0 \\ 0 & s_y & 0 & 0 \\ 0 & 0 & s_z & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \Rightarrow T_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 40 & -9 & 1 & 1 \end{bmatrix}$, $S_1 = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$
 $result = S_1 \times T_1 \Rightarrow \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 40 & -9 & 1 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 40 & -9 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 40 & -9 & 1 & 1 \end{bmatrix}$



$S_{cale} = \begin{bmatrix} 1,5 & 0 & 0 & 0 \\ 0 & 0,75 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$
 $\begin{bmatrix} 4 & 4 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 1,5 & 0 & 0 & 0 \\ 0 & 0,75 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 6 & 3 & 0 & 0 \end{bmatrix}$
 $\begin{bmatrix} -4 & -4 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 1,5 & 0 & 0 & 0 \\ 0 & 0,75 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -6 & -3 & 0 & 0 \end{bmatrix}$

$T_1 = [x, y, z, 0] \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ b_x & b_y & b_z & 1 \end{bmatrix}$, $T_2 = [x, y, z, 1] \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ b_x & b_y & b_z & 1 \end{bmatrix}$

T_1 نقاط را منتقل می کند چون بر اثر آن z است
 T_2 برای بردارها استفاده می شود، چون با z بر اثر آن صورت
 انتقال مختصات یک بردار سه بعدی نیست چون بردار در واقع دارای مختصات مشخصی نیست و می توان آن را جابجا کرد و مقدار
 اندازه و جهت دارد

(1) $\begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 3 \end{pmatrix} - 2I = \begin{pmatrix} -1 & 2 & 0 \\ 0 & -1 & 3 \end{pmatrix}$

$\begin{pmatrix} -1 & 2 & 0 \\ 0 & -1 & 3 \end{pmatrix} - 2I = \begin{pmatrix} -3 & 2 & 0 \\ 0 & -3 & 3 \end{pmatrix} \Rightarrow 3X = \begin{pmatrix} -3 & 2 & 0 \\ 0 & -3 & 3 \end{pmatrix}$

(a) $\begin{pmatrix} -1 & 2 & 0 \\ 0 & -1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 0 & 0 \end{pmatrix}$

(b) $\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 2 \\ -2 & 1 \end{pmatrix}$

(c) $\begin{pmatrix} 1 & 0 & 1 \\ 0 & -1 & 2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}$

(a) $[1, 2, 3] = \frac{T}{[1, 2, 3]^T} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$

(b) $\begin{bmatrix} x & y \\ z & w \end{bmatrix} = \frac{T}{[x & y]^T} = \begin{bmatrix} x & z \\ y & w \end{bmatrix}$

(c) $\begin{pmatrix} 1 & 2 \\ 2 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 0 \\ 2 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}$

$U \times V = \begin{pmatrix} U_x & U_y & U_z \\ V_x & V_y & V_z \end{pmatrix} \begin{pmatrix} 0 & U_z & -U_y \\ -U_z & 0 & U_x \\ U_y & -U_x & 0 \end{pmatrix} = \begin{pmatrix} -U_y U_z + U_z U_y & U_x U_z - U_z U_x \\ -U_x U_y + U_y U_x & 0 \end{pmatrix} = U \times V$

(1) $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & V \end{pmatrix} \xrightarrow{\text{Solve}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & V \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & V \end{pmatrix}$

$\begin{pmatrix} 1 & -1 \\ 0 & V \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 0 & V \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 0 & V \end{pmatrix}$

(11) $A = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} = \frac{1}{\det A} \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} = \frac{1}{1} \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} = A^{-1}$

$B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & V \end{pmatrix} = B^{-1} = \frac{B^*}{\det B} \Rightarrow B^* = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & V \end{pmatrix} \Rightarrow B^* = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & V \end{pmatrix}$

$$P_1(0,0,0,0) \cdot P_2(0,0,1,0) \cdot P_3(0,0,0,0)$$

$$(a) \frac{1}{F} P_1 + \frac{1}{F} P_2 + \frac{1}{F} P_3 \Rightarrow P_1(0,0,0,0) \cdot P_2(0,0,\frac{1}{F},0) \cdot P_3(\frac{1}{F},0,0,0)$$

$$(b) 0.1 P_1 + 0.1 P_2 + 0.1 P_3 \Rightarrow P_1(0,0,0,0) \cdot P_2(0,0,0.1,0) \cdot P_3(0.1,0,0,0)$$

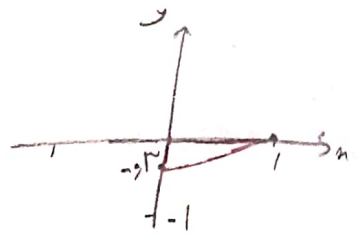
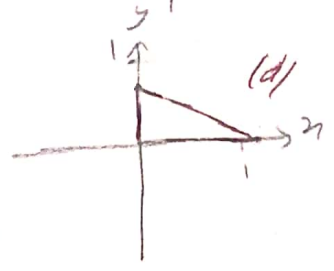
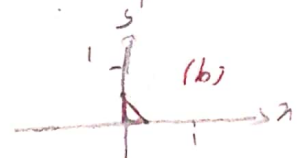
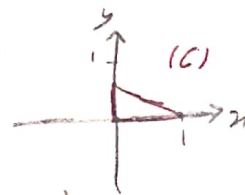
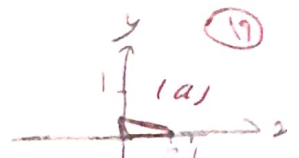
$$(c) 0.0 P_1 + 0.0 P_2 + 0.1 P_3 \Rightarrow P_1(0,0,0,0) \cdot P_2(0,0,0,0) \cdot P_3(0.1,0,0,0)$$

(d)

$$(d) -0.1 P_1 + 0.1 P_2 + 0.1 P_3 \Rightarrow P_1(0,0,0,0) \cdot P_2(0,0,0.1,0) \cdot P_3(0.1,0,0,0)$$

$$(e) 0.1 P_1 + 0.1 P_2 - 0.1 P_3 \Rightarrow P_1(0,0,0,0) \cdot P_2(0,0,0.1,0) \cdot P_3(-0.1,0,0,0)$$

$$(f) 0.1 P_1 - 0.1 P_2 + 0.1 P_3 \Rightarrow P_1(0,0,0,0) \cdot P_2(0,0,-0.1,0) \cdot P_3(0.1,0,0,0)$$



$$S = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\cdot R_{xyz}(\pi/2) \Rightarrow$$

$$R_x(\pi/2) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \pi/2 & \sin \pi/2 & 0 \\ 0 & -\sin \pi/2 & \cos \pi/2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$R_y(\pi/2) = \begin{bmatrix} \cos \pi/2 & 0 & \sin \pi/2 & 0 \\ 0 & 1 & 0 & 0 \\ \sin \pi/2 & 0 & \cos \pi/2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$R_z(\pi/2) = \begin{bmatrix} \cos \pi/2 & \sin \pi/2 & 0 & 0 \\ -\sin \pi/2 & \cos \pi/2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$S \cdot R_{xyz}(\pi/2) \cdot T = \text{result}$$

$$P \times \text{result}$$

$$Q \times \text{result}$$