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Summary

Machine Intelligence enthusiast, experienced in algorithm development for perception and communication for robots and vehicles.

Research Experience

University of Central Florida | Graduate Research Assistant

08/2018 - present

Ford Motor Company | Research Intern

06/2020 - 08/2020

Education

University of Central Florida | PhD, Computer Engineering

08/2024

University of Central Florida | MS, Computer Engineering

04/2022

Bangladesh University of Engineering and Technology | BS, Electrical and Electronic Engineering

02/2017

Projects

Multi-scale Local Attention for Semantic Segmentation (ongoing)

- · formulating novel attention mechanism for small object segmentation
- · exploring efficient fusion of multi-scale attentional features

Automated Vehicle Marshaling System (ongoing)

- developing system architecture to support remote driving under infrastructural supervision
- · extending message types beyond safety to enable advanced tele-operated driving

Learning-based communication module for Realistic Driving Simulator (ongoing)

· developing attention-based model to emulate vehicular communication in CARLA under diverse condition

Cooperative Steering Control for Autonomous Driving

- enabled look-ahead for V2X-equipped transport
- developed end-to-end learning with LSTM-based deep network

Infrastructure-assisted Tolling

- prototyped a V2I-based tolling service for tele-operated driving support
- developed multi-priority aperiodic packet handling feature in medium access layer of LTE D2D

Scalability in Cellular-V2X

- · enhanced transmission rate control algorithm with increased adaptability to congested traffic
- generated traffic scenarios with synthetic mobility traces to test scalability in I-405 highway
- co-authored a congestion control algorithm that accommodates advanced safety services
- · applied for patent and submitted as technical document for 3GPP standardization jointly with Ford Motor Company

Dynamic-Object-Map-based Architecture for Cooperative Vehicle Safety Systems

- · enabled centralized in-vehicle map to enhance autonomous navigation
- · laid out platform to build advanced vehicular safety protocols

Point-to-Point Driver Messenger System

- · enabled arbitration in critical driving maneuver via local object map sharing
- defined scenario detection and target recognition module to notify driver intent

Publications &

- On Batching Acknowledgements in C-V2X Services; IEEE VTC 2023
- · Addressing Rare Outages in CV2X with Time-controlled One-shot Resource Scheduling; TechRxiv 2023
- · Performance Analysis of V2I Zone Activation and Scalability for C-V2X Transactional Services; IEEE VTC 2022
- · Performance Analysis of Cellular-V2X with Adaptive and Selective Power Control; IEEE CAVS 2020

- · Controlling Steering Angle for Cooperative Self-driving Vehicles utilizing CNN and LSTM; IEEE IV Symposium 2019
- · Connected and Autonomous Vehicles in the Deep Learning Era:; IEEE IV Symposium 2019
- · Dynamic Object Map based Architecture for Robust CVS Systems; SAE Technical Paper
- · Finite State Markov Modeling of C-V2X Erasure Links for Stability Analysis of Platooning Applications, IEEE Syscon 2022
- · A Maneuver-based Urban Driving Dataset and Model for Cooperative Vehicle Applications; IEEE CAVS 2020, Canada
- · Connected Autonomous Vehicles in the Deep Learning Era: A case study on Computer-guided Steering; *Handbook of Pattern Recognition and Computer Vision*, 6th ed. p365-384; 2020

Patents

• One-shot transmission for v2x messaging 69

Teaching Experience

Algorithms for Machine Learning | Instructor, UCF &

- · designed course curriculum and evaluation strategies
- · lectured core-to-advanced ML topics to 200+ students for
- · guided in writing NLP/CV models and mentored in MLOps

Digital Systems and Computer Organization | Graduate Teaching Assistant, UCF

· instructed courses and projects on FPGA using Verilog and low-level assembly language

Skills

- · Python, PyTorch, OpenCV, Scikit-learn
- · C++, NS3, MATLAB
- · Git, Bash Scripting, Linux

References

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