

Divide and Conquer Algorithms

Introduction

- Solves computational problem by
 - Dividing it into subproblems of smaller size
 - Solve each problem recursively
 - Merging solutions to sub-problems to produce solution
- e.g.,
 - Merge Sort
 - Quick Sort
- Complexity analyzed using recurrence relations

Divide and Conquer

- Divide Step:
 - If input size smaller than certain threshold solve by straightforward method
 - Divide input data into two or more disjoint subsets
- Recur:
 - Recursively solve subproblems associated with the subsets
- Conquer
 - Take the solutions to the subproblems and merge them into a solution to the original problem

Sorting

- Merge Sort

- Divide: Trivial
- Conquer: Recursively Sort each sub-array
- Combine: Linear-time merge

- Quick Sort

- Divide: Split array based on pivot
- Conquer: Recursively split
- Combine: Trivial

Powering a Number

- Compute a^n
- Naive algorithm: $\Theta(n)$
- Divide and Conquer Algorithm
 - $$a^n = \begin{cases} a^{n/2} \cdot a^{n/2} & \text{if } n \text{ is even} \\ a^{(n-1)/2} \cdot a^{n/2} & \text{if } n \text{ is odd} \end{cases}$$
 - $T(n) = T(n/2) + \Theta(1) \Rightarrow T(n) = \mathcal{O}(\lg n)$

Matrix Multiplication

■ Input: $X = [x_{ij}]$, $Y = [y_{ij}]$, $i, j = 1, 2, 3, \dots, n$

■ Output: $Z = [z_{ij}] = XY$

■
$$z_{ij} = \sum_{k=1}^n x_{ik} \cdot y_{kj}$$

■ $O(n^3)$

■ *Divide and conquer can reduce cost*

Divide and Conquer Strategy

■ Idea

■ $n \times n$ matrix = 2×2 matrix of $(n/2) \times (n/2)$ submatrices

■ Rewrite $Z = X \times Y$ as

■
$$\begin{pmatrix} i & j \\ k & l \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \times \begin{pmatrix} e & f \\ g & h \end{pmatrix}$$

■ $i = ae + bg$

■ $j = af + bh$

■ $k = ce + dg$

■ $l = cf + dh$

Divide and Conquer Strategy

■ Analysis

- 8 multiplications of $(n/2) \times (n/2)$ submatrices

- 4 additions of $(n/2) \times (n/2)$ submatrices

- $T(n) = 8T(n/2) + \Theta(n^2)$

- This is $\Theta(n^3)$ – not better than brute force

Strassen's Method

- Multiply 2×2 matrices with 7 recursive multiplications

- $P_1 = a \cdot (f - h)$

- $P_2 = (a + b) \cdot h$

- $P_3 = (c + d) \cdot e$

- $P_4 = d \cdot (g - e)$

- $P_5 = (a + d) \cdot (e + h)$

- $P_6 = (b - d) \cdot (g + h)$

- $P_7 = (a - c) \cdot (e + f)$

- $r = P_5 + P_4 - P_2 + P_6$

- $s = P_1 + P_2$

- $t = P_3 + P_4$

- $u = P_5 + P_1 - P_3 - P_7$

- 7 multiplications, 18 adds/subs

- No reliance on commutativity of multiplication

Strassen's Algorithm

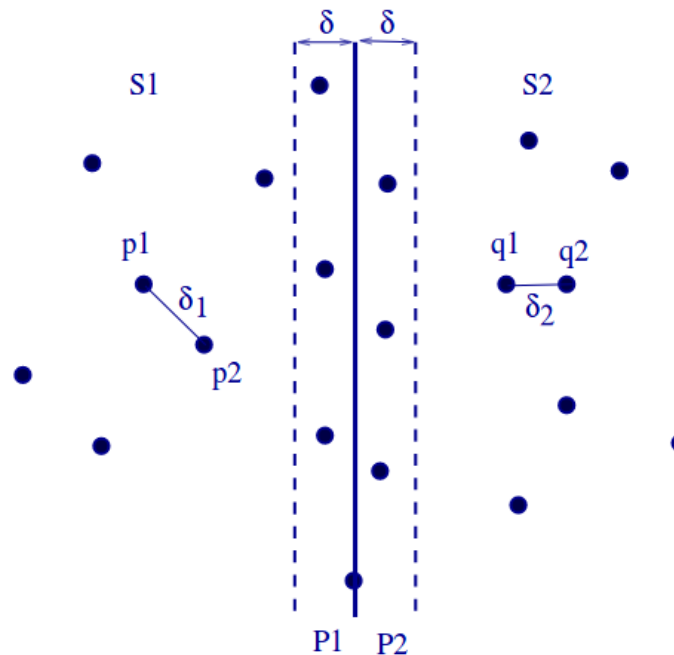
- Partition: A and B into $(n/2) \times (n/2)$ submatrices.
 - Form terms to be multiplied using + and −.
- Conquer: Perform 7 multiplications of $(n/2) \times (n/2)$ submatrices recursively
- Combine: Form C using + and − on $(n/2) \times (n/2)$ submatrices.
- $T(n) = 7T(n/2) + O(n^2)$
- This is $O(n^{2.81})$

Closest Pair Problem

- Input: n points in a plane, each given by a pair of real numbers
- Output: Pair of points with shortest distance between them
- Brute Force
 - Compute distance between every pair and find the minimum distance pair
 - $\Theta(n^2)$
- Apply divide and conquer

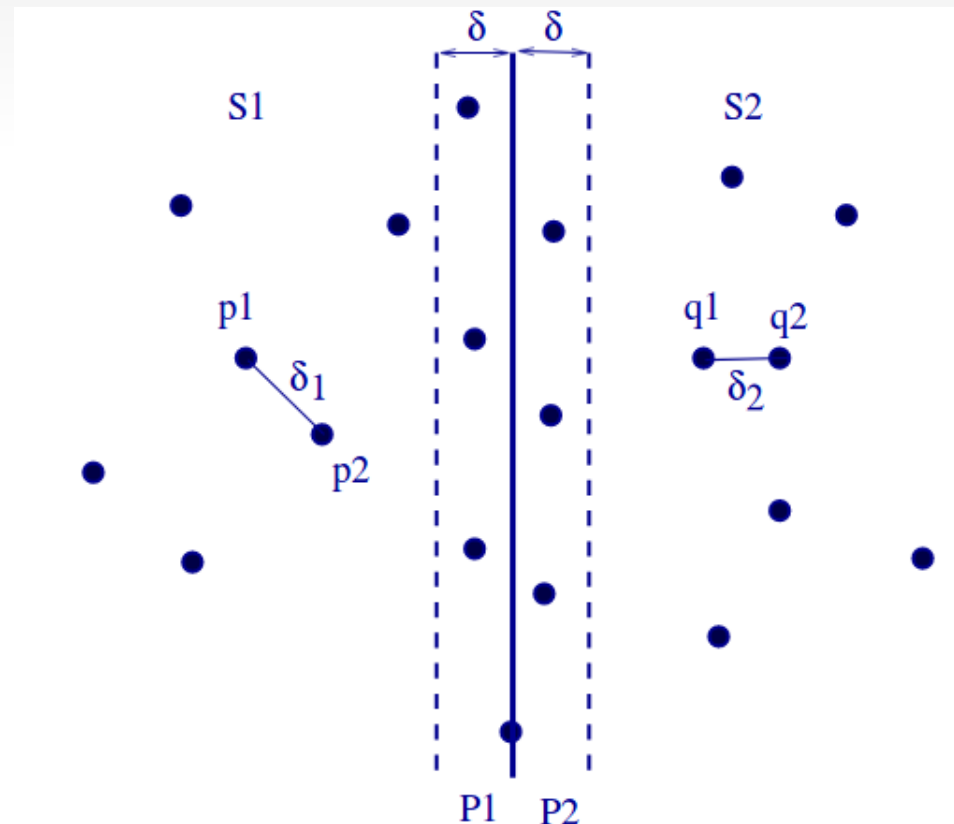
Strategy

- Partition S into S_1 , S_2 by vertical line l defined by median x -coordinate in S
- Recursively compute closest pair distances δ_1 and δ_2 . Set $d = \min(\delta_1, \delta_2)$.
- Now compute the closest pair with one point each in S_1 and S_2



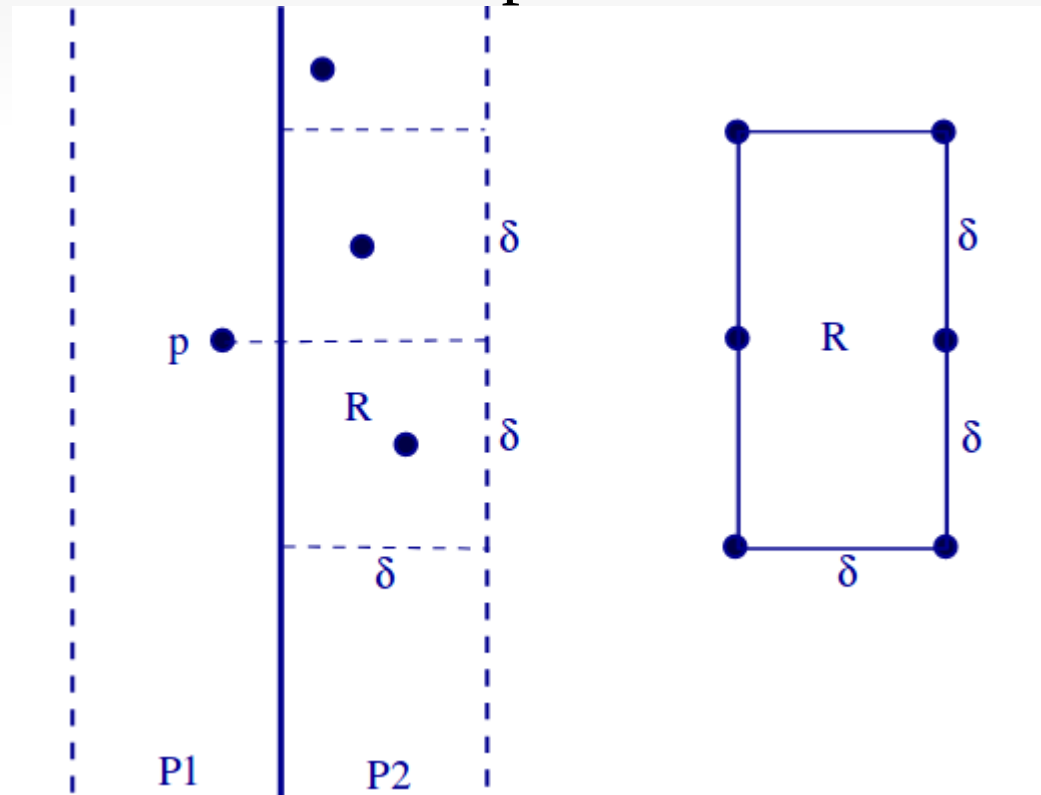
Divide and Conquer Strategy

- In each candidate pair (p, q) , where $p \in S_1$ and $q \in S_2$, the points p, q must both lie within δ of l
- It's possible that all $n/2$ points of S_1 (and S_2) lie within δ of l .



Conquer Step

- Points in P_1 , P_2 (δ strip around l) have a special structure, that helps solve the conquer step faster
- Consider a point $p \in S_1$.
 - All points of S_2 within distance δ of p must lie in a $\delta \times 2\delta$ rectangle R .



Conquer Step

- How many points can be inside R if each pair is at least δ apart?
 - In 2D, this number is at most 6! therefore $6 \times n/2$ distance comparisons
 - This is still costly
 - In order to determine at most 6 potential counterpoints of p , project p and all points of P_2 onto line l
 - Pick out points whose projection is within δ of p ; at most six.
 - Presorting by 'y' axis can help make this faster
- Complexity: $T(n) = 2T(n/2) + \Theta(n)$

Why does this work

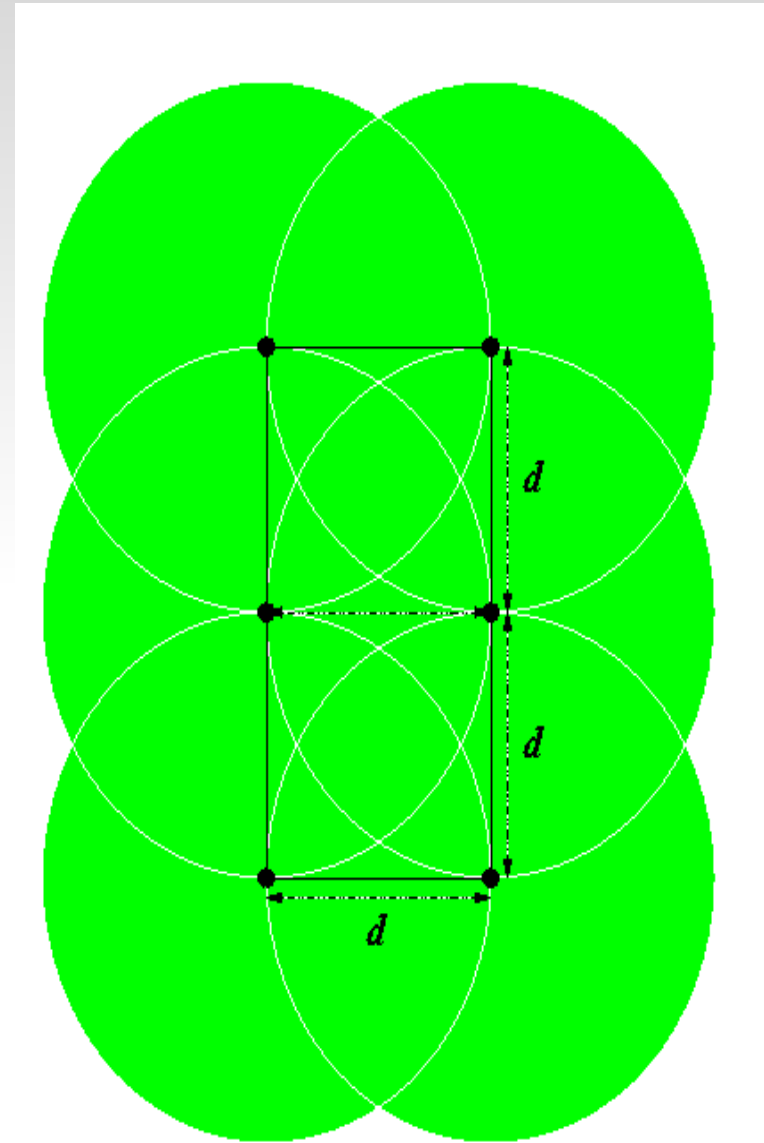
■ Idea:

- A rectangle of width d and height $2d$ can contain at most six points such that any two points are at distance at least d

■ Proof

- Place points into the box until it is impossible to add any more.
- Imagine a circle around each point of radius d , which cannot contain any other point inside it
- If you try to move any one of these points in any direction within the boundaries of the rectangle, then you would be moving two points too close together.

<https://www.cs.mcgill.ca/~cs251/ClosestPair/proofbox.html>



Problems

- Given an array having first n ints and next n chars

$A = i_1 i_2 i_3 \dots i_n, c_1 c_2 c_3 \dots c_n$

Write an in-place algorithm to rearrange the elements of the array as: $A = i_1 c_1 i_2 c_2 \dots i_n c_n$

- Give an algorithm to divide an integer array into 2 sub-arrays s.t their averages are equal i.e average of values of left array must be same as average of right array