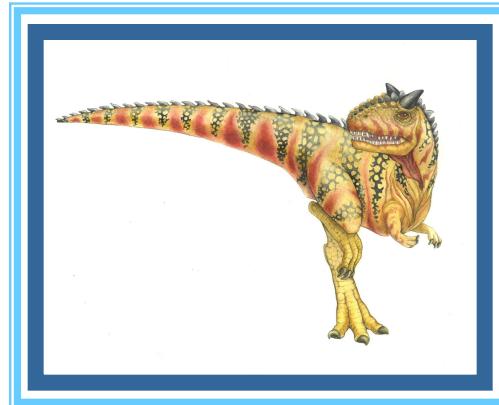


Chapter 4: Threads & Concurrency





Outline

- Overview
- Multicore Programming
- Multithreading Models
- Thread Libraries
- Implicit Threading
- Threading Issues
- Operating System Examples





Objectives

- Identify the basic components of a thread, and contrast threads and processes
- Describe the benefits and challenges of designing multithreaded applications
- Illustrate different approaches to implicit threading including thread pools, fork-join, and Grand Central Dispatch
- Describe how the Windows and Linux operating systems represent threads
- Designing multithreaded applications using the Pthreads, Java, and Windows threading APIs





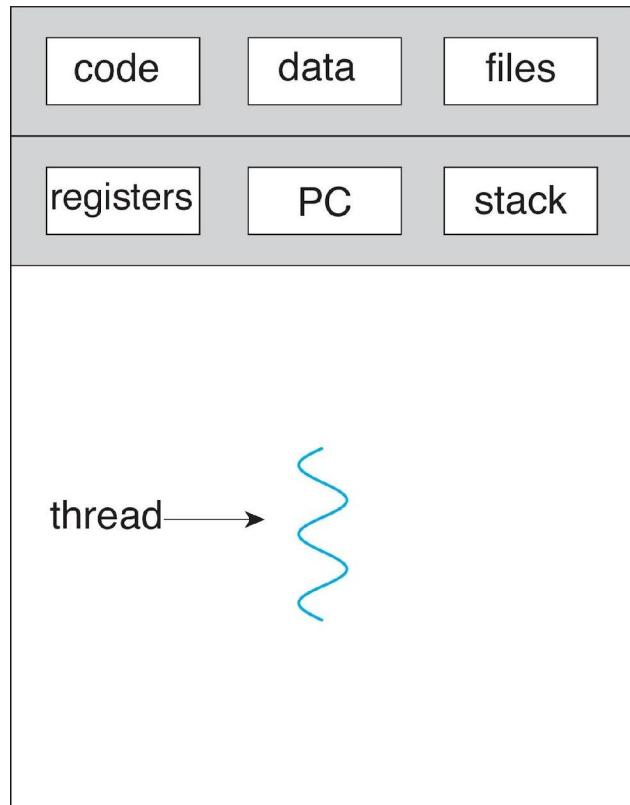
Motivation

- Most modern applications are multithreaded
- Threads run within application
- Multiple tasks within the application can be implemented by separate threads
 - Update display
 - Fetch data
 - Spell checking
 - Answer a network request
- Process creation is heavy-weight while thread creation is light-weight
- Can simplify code, increase efficiency
- Kernels are generally multithreaded

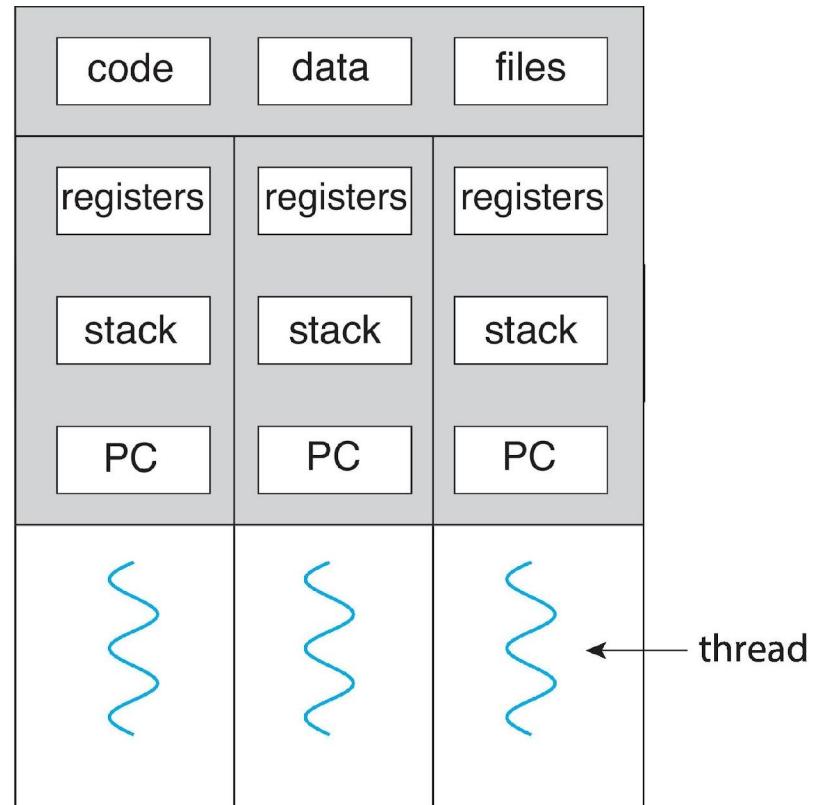




Single and Multithreaded Processes



single-threaded process

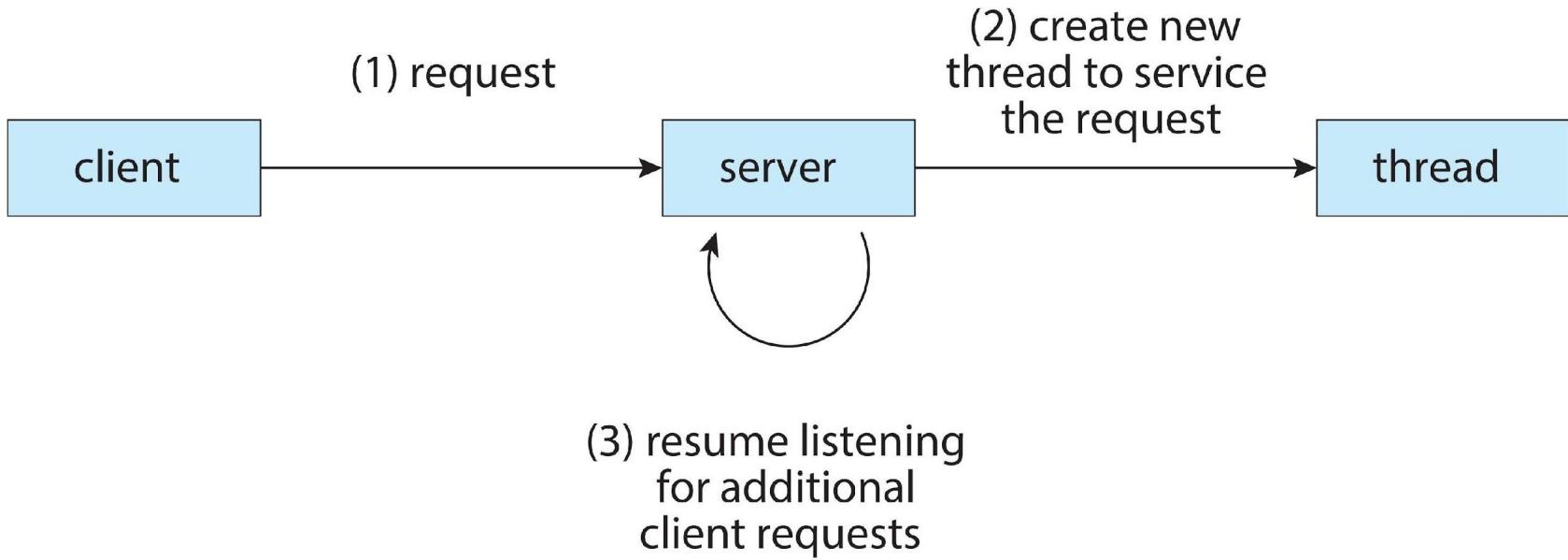


multithreaded process





Multithreaded Server Architecture





Benefits

- **Responsiveness** – may allow continued execution if part of process is blocked, especially important for user interfaces
- **Resource Sharing** – threads share resources of process, easier than shared memory or message passing
- **Economy** – cheaper than process creation, thread switching lower overhead than context switching
- **Scalability** – process can take advantage of multicore architectures





Multicore Programming

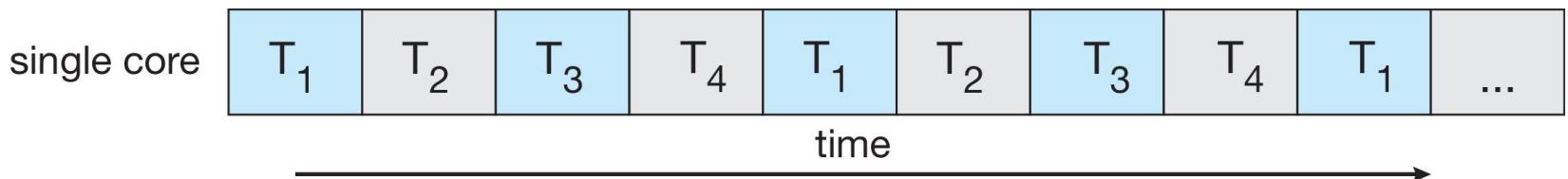
- **Multicore** or **multiprocessor** systems puts pressure on programmers, challenges include:
 - **Dividing activities**
 - **Balance**
 - **Data splitting**
 - **Data dependency**
 - **Testing and debugging**
- **Parallelism** implies a system can perform more than one task simultaneously
- **Concurrency** supports more than one task making progress
 - Single processor / core, scheduler providing concurrency



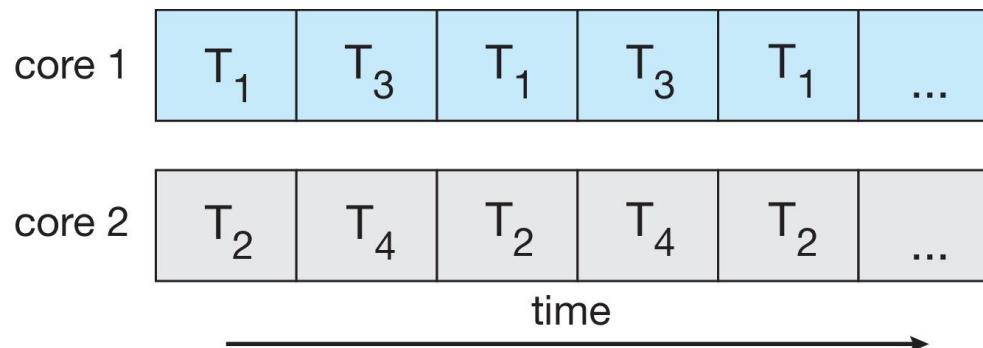


Concurrency vs. Parallelism

- Concurrent execution on single-core system:



- Parallelism on a multi-core system:





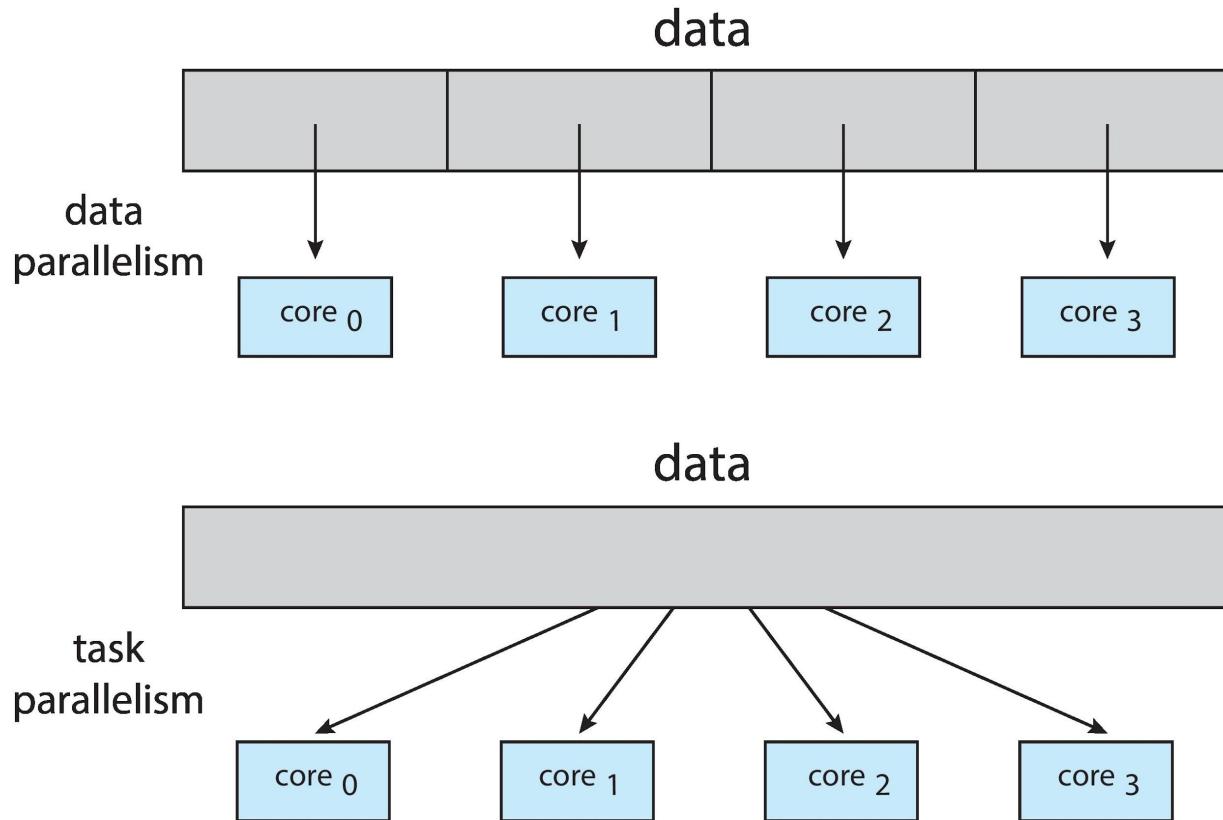
Multicore Programming

- Types of parallelism
 - **Data parallelism** – distributes subsets of the same data across multiple cores, same operation on each
 - **Task parallelism** – distributing threads across cores, each thread performing unique operation





Data and Task Parallelism





Amdahl's Law

- Identifies performance gains from adding additional cores to an application that has both serial and parallel components
- S is serial portion
- N processing cores

$$\text{speedup} \leq \frac{1}{S + \frac{(1-S)}{N}}$$

- That is, if application is 75% parallel / 25% serial, moving from 1 to 2 cores results in speedup of 1.6 times
- As N approaches infinity, speedup approaches $1 / S$

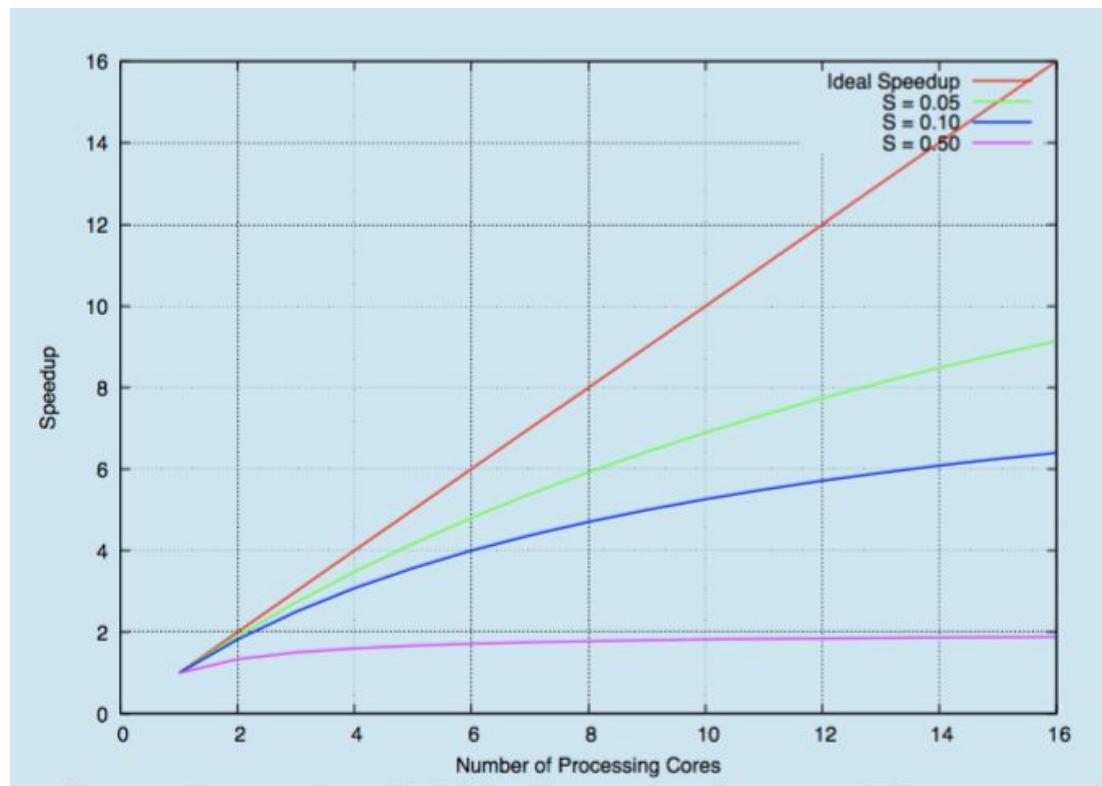
Serial portion of an application has disproportionate effect on performance gained by adding additional cores

- But does the law take into account contemporary multicore systems?





Amdahl's Law





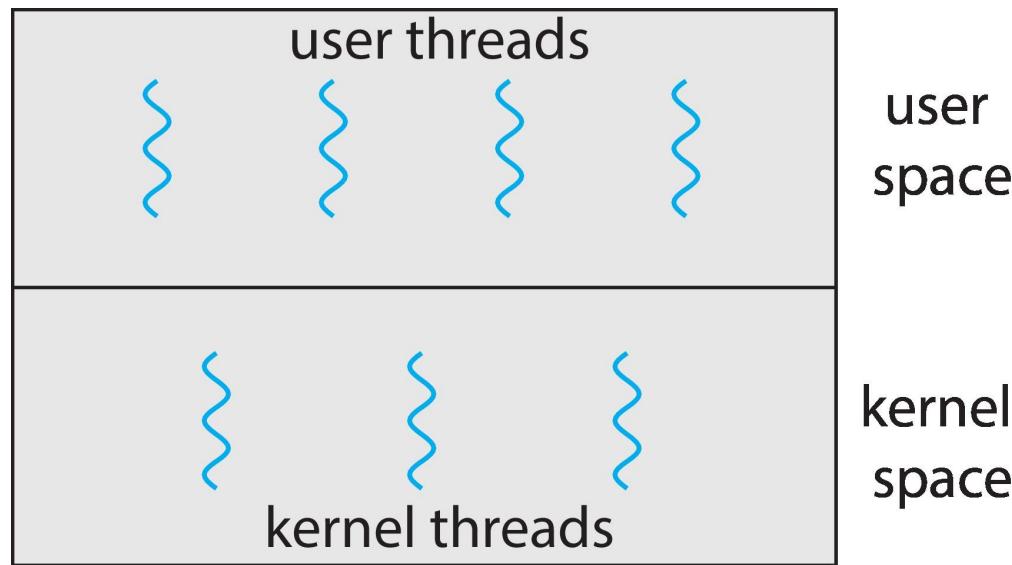
User Threads and Kernel Threads

- **User threads** - management done by user-level threads library
- Three primary thread libraries:
 - POSIX **Pthreads**
 - Windows threads
 - Java threads
- **Kernel threads** - Supported by the Kernel
- Examples – virtually all general-purpose operating systems, including:
 - Windows
 - Linux
 - Mac OS X
 - iOS
 - Android





User and Kernel Threads





Multithreading Models

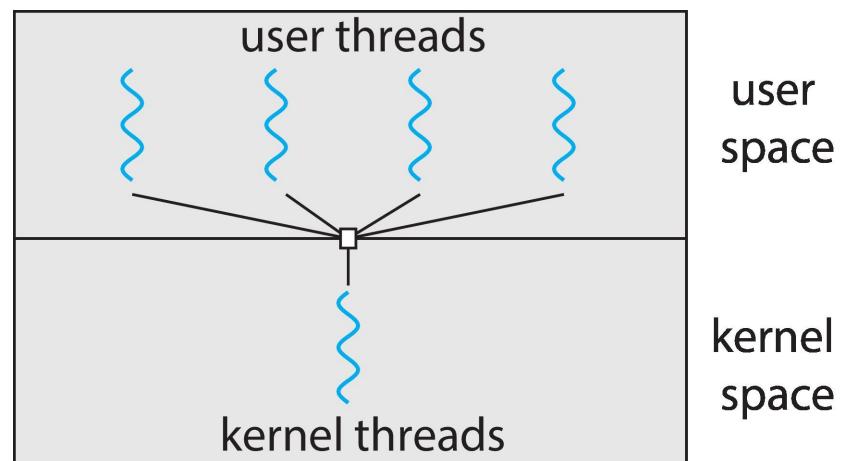
- Many-to-One
- One-to-One
- Many-to-Many





Many-to-One

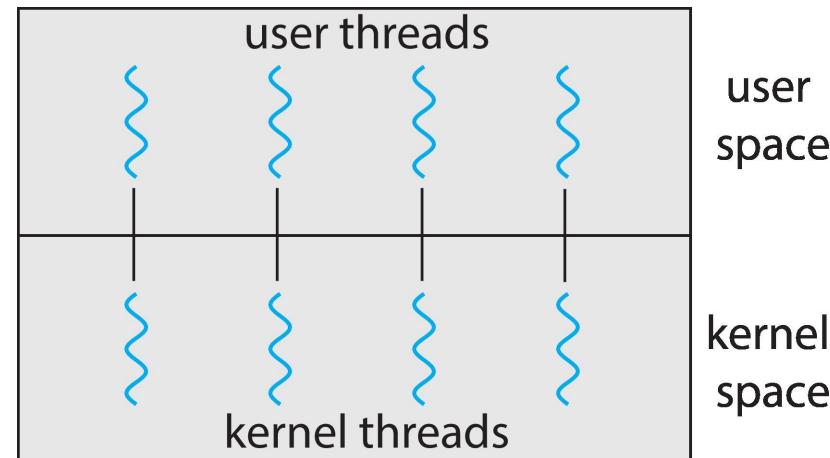
- Many user-level threads mapped to single kernel thread
- One thread blocking causes all to block
- Multiple threads may not run in parallel on multicore system because only one may be in kernel at a time
- Few systems currently use this model
- Examples:
 - **Solaris Green Threads**
 - **GNU Portable Threads**





One-to-One

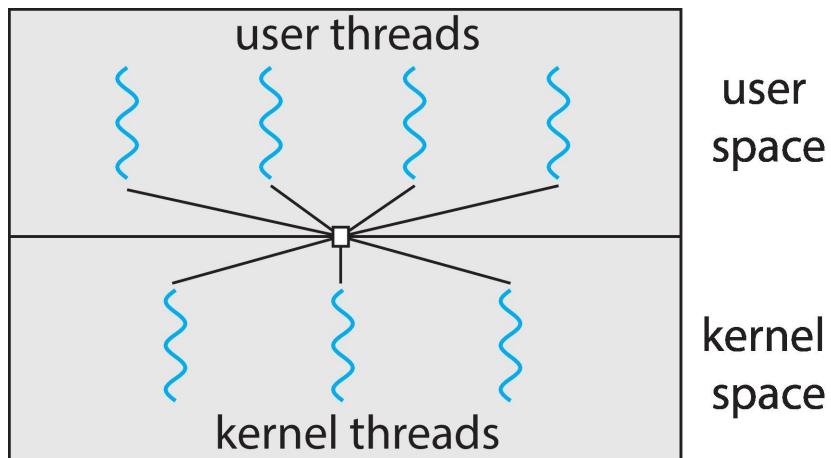
- Each user-level thread maps to kernel thread
- Creating a user-level thread creates a kernel thread
- More concurrency than many-to-one
- Number of threads per process sometimes restricted due to overhead
- Examples
 - Windows
 - Linux





Many-to-Many Model

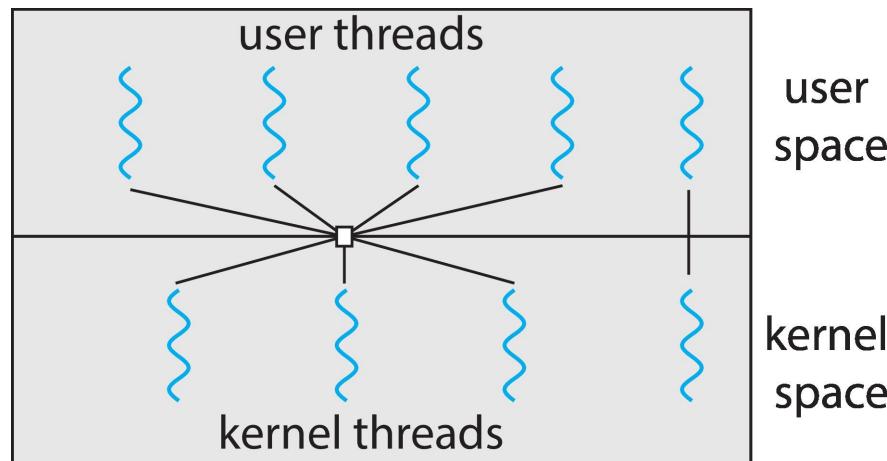
- Allows many user level threads to be mapped to many kernel threads
- Allows the operating system to create a sufficient number of kernel threads
- Windows with the *ThreadFiber* package
- Otherwise not very common





Two-level Model

- Similar to M:M, except that it allows a user thread to be **bound** to kernel thread





Thread Libraries

- **Thread library** provides programmer with API for creating and managing threads
- Two primary ways of implementing
 - Library entirely in user space
 - Kernel-level library supported by the OS





Pthreads

- May be provided either as user-level or kernel-level
- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization
- ***Specification***, not *implementation*
- API specifies behavior of the thread library, implementation is up to development of the library
- Common in UNIX operating systems (Linux & Mac OS X)





Pthreads Example

```
#include <pthread.h>
#include <stdio.h>

#include <stdlib.h>

int sum; /* this data is shared by the thread(s) */
void *runner(void *param); /* threads call this function */

int main(int argc, char *argv[])
{
    pthread_t tid; /* the thread identifier */
    pthread_attr_t attr; /* set of thread attributes */

    /* set the default attributes of the thread */
    pthread_attr_init(&attr);
    /* create the thread */
    pthread_create(&tid, &attr, runner, argv[1]);
    /* wait for the thread to exit */
    pthread_join(tid,NULL);

    printf("sum = %d\n",sum);
}
```





Pthreads Example (Cont.)

```
/* The thread will execute in this function */
void *runner(void *param)
{
    int i, upper = atoi(param);
    sum = 0;

    for (i = 1; i <= upper; i++)
        sum += i;

    pthread_exit(0);
}
```





Pthreads Code for Joining 10 Threads

```
#define NUM_THREADS 10

/* an array of threads to be joined upon */
pthread_t workers[NUM_THREADS];

for (int i = 0; i < NUM_THREADS; i++)
    pthread_join(workers[i], NULL);
```





Implicit Threading

- Growing in popularity as numbers of threads increase, program correctness more difficult with explicit threads
- Creation and management of threads done by compilers and run-time libraries rather than programmers
- Five methods explored
 - Thread Pools
 - Fork-Join
 - OpenMP
 - Grand Central Dispatch
 - Intel Threading Building Blocks





Thread Pools

- Create a number of threads in a pool where they await work
- Advantages:
 - Usually slightly faster to service a request with an existing thread than create a new thread
 - Allows the number of threads in the application(s) to be bound to the size of the pool
 - Separating task to be performed from mechanics of creating task allows different strategies for running task
 - 4 i.e., Tasks could be scheduled to run periodically
- Windows API supports thread pools:

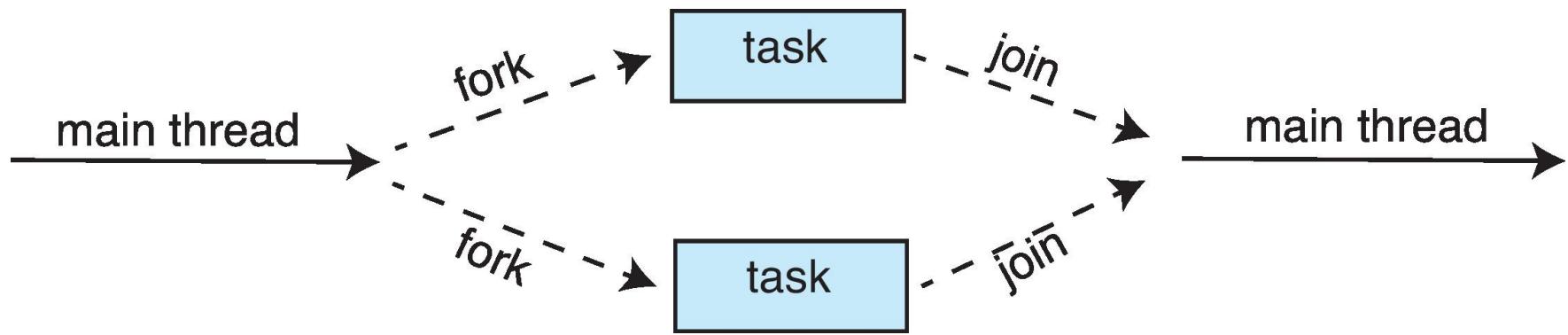
```
DWORD WINAPI PoolFunction(VOID Param) {  
    /*  
     * this function runs as a separate thread.  
     */  
}
```





Fork-Join Parallelism

- Multiple threads (tasks) are **forked**, and then **joined**.





Fork-Join Parallelism

- General algorithm for fork-join strategy:

```
Task(problem)
    if problem is small enough
        solve the problem directly
    else
        subtask1 = fork(new Task(subset of problem)
        subtask2 = fork(new Task(subset of problem)

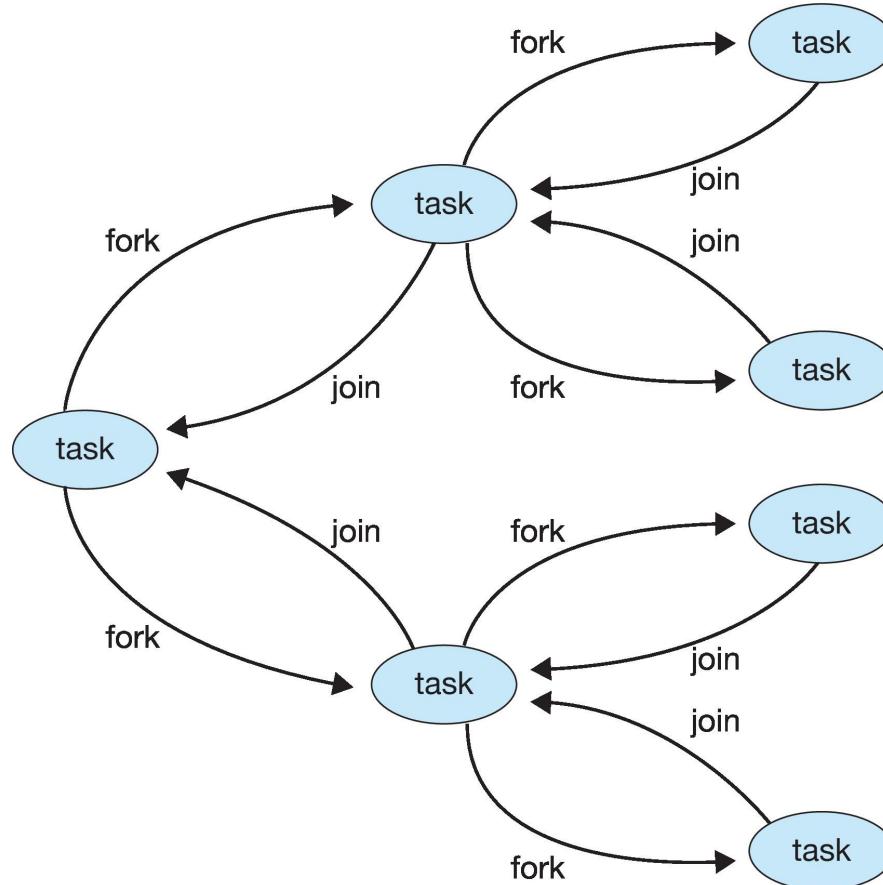
        result1 = join(subtask1)
        result2 = join(subtask2)

    return combined results
```





Fork-Join Parallelism





OpenMP

- Set of compiler directives and an API for C, C++, FORTRAN
- Provides support for parallel programming in shared-memory environments
- Identifies **parallel regions** – blocks of code that can run in parallel

#pragma omp parallel

Create as many threads as there are cores

```
#include <omp.h>
#include <stdio.h>

int main(int argc, char *argv[])
{
    /* sequential code */

    #pragma omp parallel
    {
        printf("I am a parallel region.");
    }

    /* sequential code */

    return 0;
}
```





- Run the for loop in parallel

```
#pragma omp parallel for
for (i = 0; i < N; i++) {
    c[i] = a[i] + b[i];
}
```





Grand Central Dispatch

- Apple technology for macOS and iOS operating systems
- Extensions to C, C++ and Objective-C languages, API, and run-time library
- Allows identification of parallel sections
- Manages most of the details of threading
- Block is in “^{ }” :

```
^{ printf("I am a block"); }
```
- Blocks placed in dispatch queue
 - Assigned to available thread in thread pool when removed from queue





Grand Central Dispatch

- Two types of dispatch queues:
 - **serial** – blocks removed in FIFO order, queue is per process, called **main queue**
 - 4 Programmers can create additional serial queues within program
 - **concurrent** – removed in FIFO order but several may be removed at a time
 - 4 Four system wide queues divided by quality of service:
 - QOS_CLASS_USER_INTERACTIVE
 - QOS_CLASS_USER_INITIATED
 - QOS_CLASS_USER.Utility
 - QOS_CLASS_USER_BACKGROUND





Grand Central Dispatch

- For the Swift language a task is defined as a closure – similar to a block, minus the caret
- Closures are submitted to the queue using the `dispatch_async()` function:

```
let queue = dispatch_get_global_queue  
    (QOS_CLASS_USER_INITIATED, 0)  
  
dispatch_async(queue, { print("I am a closure.") })
```





Intel Threading Building Blocks (TBB)

- Template library for designing parallel C++ programs
- A serial version of a simple for loop

```
for (int i = 0; i < n; i++) {  
    apply(v[i]);  
}
```

- The same for loop written using TBB with **parallel_for** statement:

```
parallel_for (size_t(0), n, [=](size_t i) {apply(v[i]);});
```





Threading Issues

- Semantics of **fork()** and **exec()** system calls
- Signal handling
 - Synchronous and asynchronous
- Thread cancellation of target thread
 - Asynchronous or deferred
- Thread-local storage
- Scheduler Activations





Semantics of fork() and exec()

- Does `fork()` duplicate only the calling thread or all threads?
 - Some UNIXes have two versions of fork
- `exec()` usually works as normal – replace the running process including all threads





Signal Handling

- **Signals** are used in UNIX systems to notify a process that a particular event has occurred.
- A **signal handler** is used to process signals
 1. Signal is generated by particular event
 2. Signal is delivered to a process
 3. Signal is handled by one of two signal handlers:
 1. default
 2. user-defined
- Every signal has **default handler** that kernel runs when handling signal
 - **User-defined signal handler** can override default
 - For single-threaded, signal delivered to process





Signal Handling (Cont.)

- Where should a signal be delivered for multi-threaded?
 - Deliver the signal to the thread to which the signal applies
 - Deliver the signal to every thread in the process
 - Deliver the signal to certain threads in the process
 - Assign a specific thread to receive all signals for the process





Thread Cancellation

- Terminating a thread before it has finished
- Thread to be canceled is **target thread**
- Two general approaches:
 - **Asynchronous cancellation** terminates the target thread immediately
 - **Deferred cancellation** allows the target thread to periodically check if it should be cancelled
- Pthread code to create and cancel a thread:

```
pthread_t tid;  
  
/* create the thread */  
pthread_create(&tid, 0, worker, NULL);  
  
.  
.  
.  
  
/* cancel the thread */  
pthread_cancel(tid);  
  
/* wait for the thread to terminate */  
pthread_join(tid,NULL);
```





Thread Cancellation (Cont.)

- Invoking thread cancellation requests cancellation, but actual cancellation depends on thread state

Mode	State	Type
Off	Disabled	—
Deferred	Enabled	Deferred
Asynchronous	Enabled	Asynchronous

- If thread has cancellation disabled, cancellation remains pending until thread enables it
- Default type is deferred
 - Cancellation only occurs when thread reaches **cancellation point**
 - 4 i.e., `pthread_testcancel()`
 - 4 Then **cleanup handler** is invoked
- On Linux systems, thread cancellation is handled through signals





Thread-Local Storage

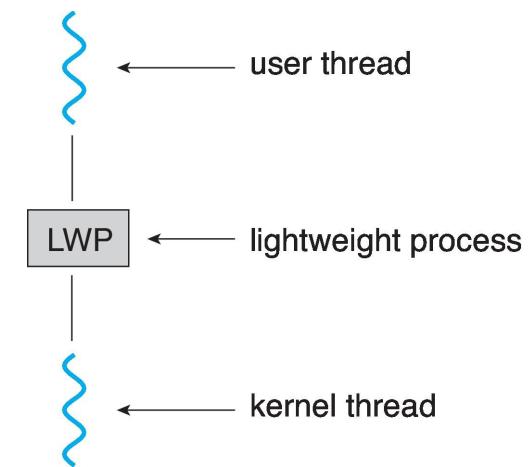
- **Thread-local storage (TLS)** allows each thread to have its own copy of data
- Useful when you do not have control over the thread creation process (i.e., when using a thread pool)
- Different from local variables
 - Local variables visible only during single function invocation
 - TLS visible across function invocations
- Similar to **static** data
 - TLS is unique to each thread





Scheduler Activations

- Both M:M and Two-level models require communication to maintain the appropriate number of kernel threads allocated to the application
- Typically use an intermediate data structure between user and kernel threads – **lightweight process (LWP)**
 - Appears to be a virtual processor on which process can schedule user thread to run
 - Each LWP attached to kernel thread
 - How many LWPs to create?
- Scheduler activations provide **upcalls** - a communication mechanism from the kernel to the **upcall handler** in the thread library
- This communication allows an application to maintain the correct number kernel threads





Linux Threads

- Linux refers to them as ***tasks*** rather than ***threads***
- Thread creation is done through **`clone()`** system call
- **`clone()`** allows a child task to share the address space of the parent task (process)
 - Flags control behavior

flag	meaning
<code>CLONE_FS</code>	File-system information is shared.
<code>CLONE_VM</code>	The same memory space is shared.
<code>CLONE_SIGHAND</code>	Signal handlers are shared.
<code>CLONE_FILES</code>	The set of open files is shared.

- **`struct task_struct`** points to process data structures (shared or unique)



End of Chapter 4

