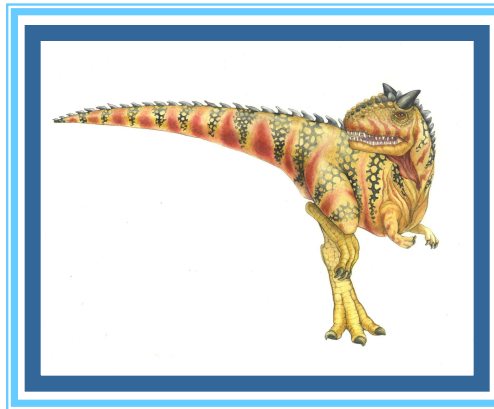


Chapter 8: Main Memory





Recap

- Background
- Address Binding
 - Base and Limit registers
 - Hardware Address Protection
- Logical and Physical addresses
- Dynamic Relocation (MMU)
- Dynamic Linking





Objectives

- Swapping
- Contiguous Memory Allocation
 - Fixed size partitioning
 - Variable size partitioning
- Dynamic Storage-Allocation Problem
 - First Fit
 - Best Fit
 - Worst Fit
- Fragmentation
 - Internal Fragmentation
 - External Fragmentation
- Compaction





Swapping

- A process can be **swapped** temporarily out of memory to a backing store, and then brought back into memory for continued execution
 - Total physical memory space of processes can exceed physical memory
- **Backing store** – fast disk large enough to accommodate copies of all memory images for all users; must provide direct access to these memory images
- **Roll out, roll in** – swapping variant used for priority-based scheduling algorithms; lower-priority process is swapped out so higher-priority process can be loaded and executed
- Major part of swap time is transfer time; total transfer time is directly proportional to the amount of memory swapped
- System maintains a **ready queue** of ready-to-run processes which have memory images on disk





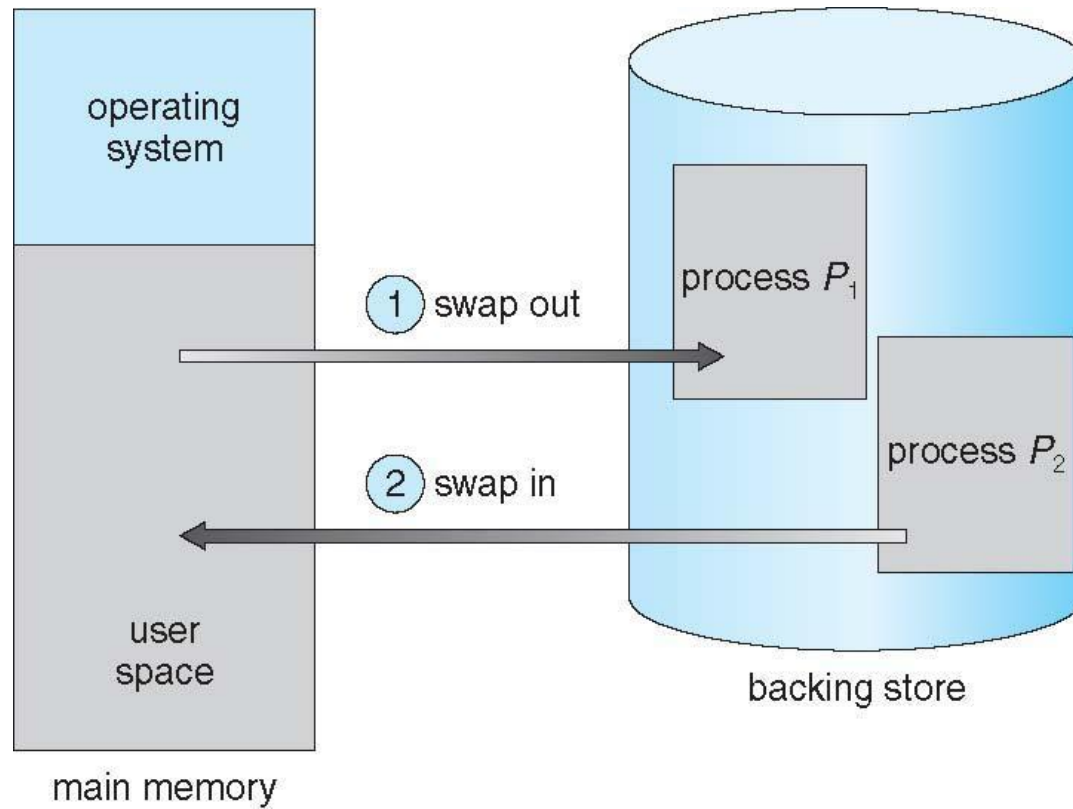
Swapping (Cont.)

- Does the swapped-out process need to swap back into same physical addresses?
- Depends on address binding method
 - Plus consider pending I/O to / from process memory space
- Modified versions of swapping are found on many systems (i.e., UNIX, Linux, and Windows)
 - Swapping normally disabled
 - Started if more than threshold amount of memory allocated
 - Disabled again once memory demand reduced below threshold



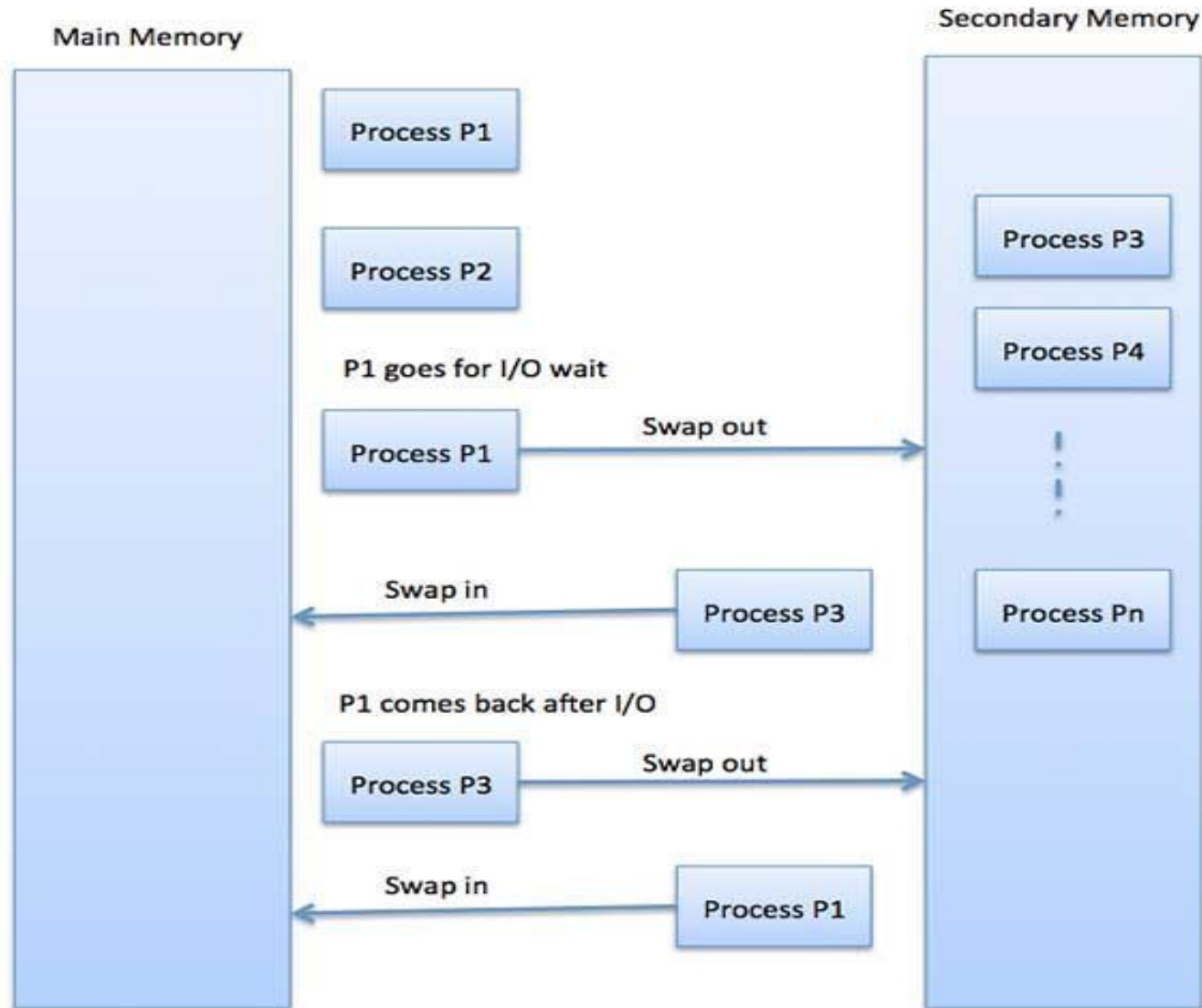


Schematic View of Swapping





Schematic View of Swapping





Context Switch Time including Swapping

- If next processes to be put on CPU is not in memory, need to swap out a process and swap in target process
- Context switch time can then be very high
- 100MB process swapping to hard disk with transfer rate of 50MB/sec
 - Swap out time of 2000 ms
 - Plus swap in of same sized process
 - Total context switch swapping component time of 4000ms (4 seconds)
- Can reduce if reduce size of memory swapped – by knowing how much memory really being used
 - System calls to inform OS of memory use via `request_memory()` and `release_memory()`





Context Switch Time and Swapping (Cont.)

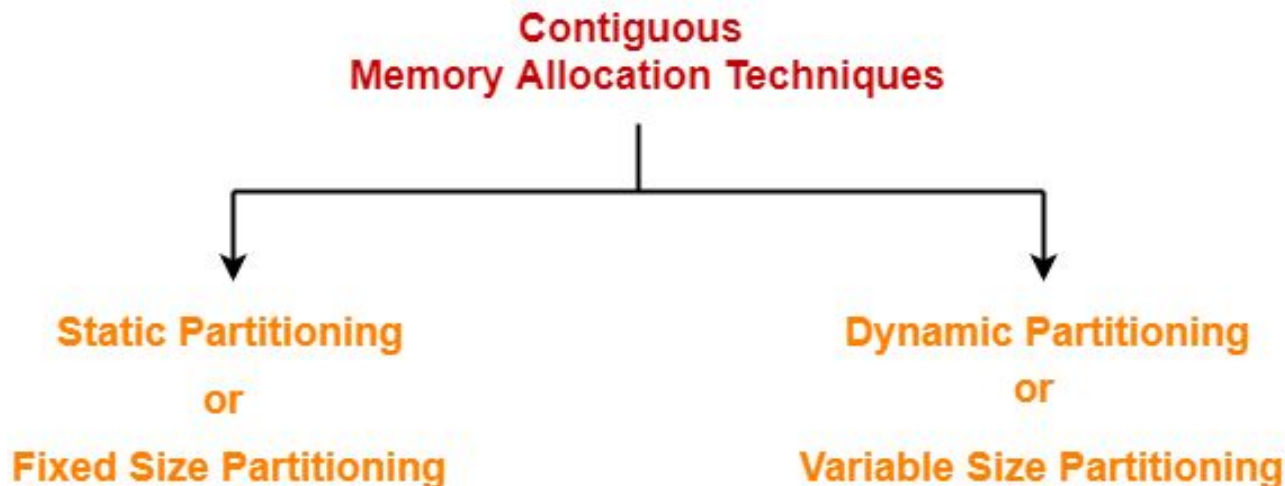
- Other constraints as well on swapping
 - Pending I/O – can't swap out as I/O would occur to wrong process
 - Or always transfer I/O to kernel space, then to I/O device
 - 4 Known as **double buffering**, adds overhead
- Standard swapping not used in modern operating systems
 - But modified version common
 - 4 Swap only when free memory extremely low





Contiguous Allocation

- Main memory must support both OS and user processes
- Limited resource, must allocate efficiently
- Contiguous allocation is one early method
- Main memory usually divided into two **partitions**:
 - Resident operating system, usually held in low memory with interrupt vector
 - User processes then held in high memory
 - Each process contained in single contiguous section of memory





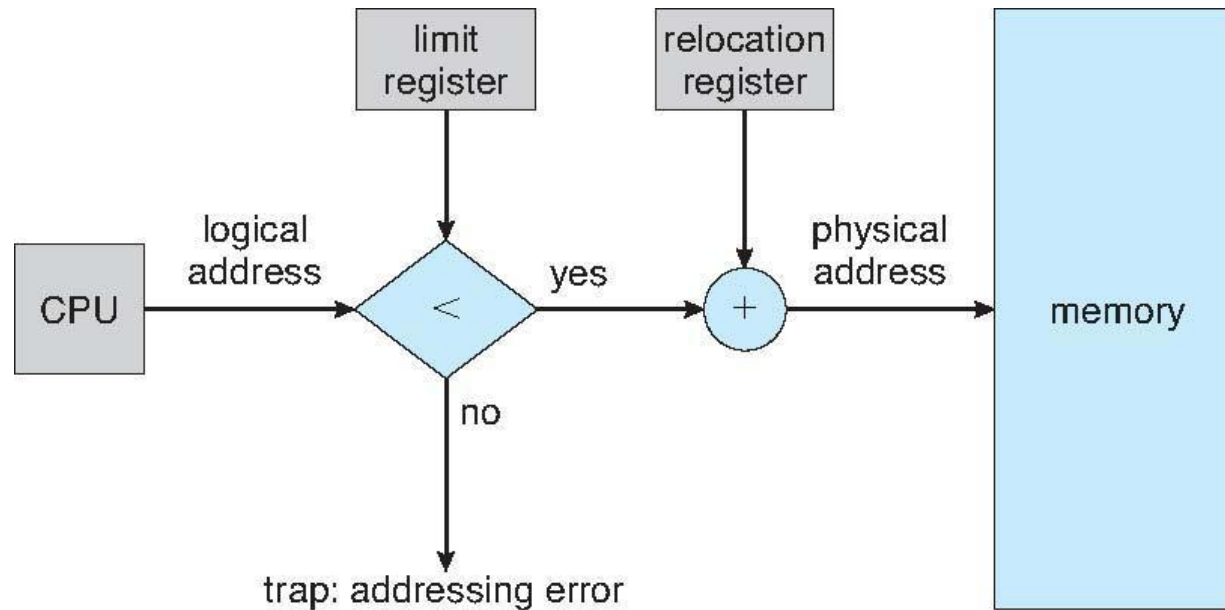
Contiguous Allocation (Cont.)

- Relocation registers used to protect user processes from each other, and from changing operating-system code and data
 - Base register contains value of smallest physical address
 - Limit register contains range of logical addresses – each logical address must be less than the limit register
 - MMU maps logical address *dynamically*
 - Can then allow actions such as kernel code being **transient** and kernel changing size





Hardware Support for Relocation and Limit Registers





Fixed Size Partitioning

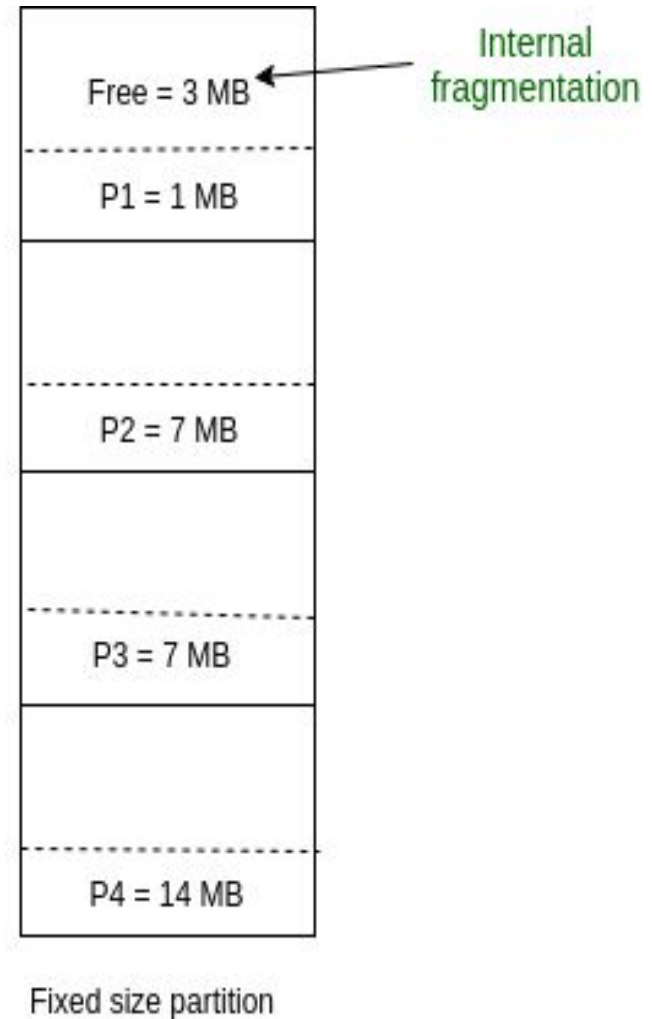
- This is the oldest and simplest technique used to put more than one processes in the main memory. In this partitioning, number of partitions (non-overlapping) in RAM are **fixed but size** of each partition may or **may not be same**.
- As it is **contiguous** allocation, hence no spanning is allowed. Here partition are made before execution or during system configure.+/

Block size = 4 MB

Block size = 8 MB

Block size = 8 MB

Block size = 16 MB





Variable Size Partitioning

- In contrast with fixed partitioning, partitions are not made before the execution or during system configure. Various **features** associated with variable Partitioning-
- Initially RAM is empty, and partitions are made during the run-time according to process's need instead of partitioning during system configure.
- The size of partition will be equal to incoming process.
- The partition size varies according to the need of the process so that the internal fragmentation can be avoided to ensure efficient utilization of RAM.
- Number of partitions in RAM is not fixed and depends on the number of incoming process and Main Memory's size.

Dynamic partitioning

Operating system
P1 = 2 MB
P2 = 7 MB
P3 = 1 MB
P4 = 5 MB
Empty space of RAM

Block size = 2 MB

Block size = 7 MB

Block size = 1 MB

Block size = 5 MB

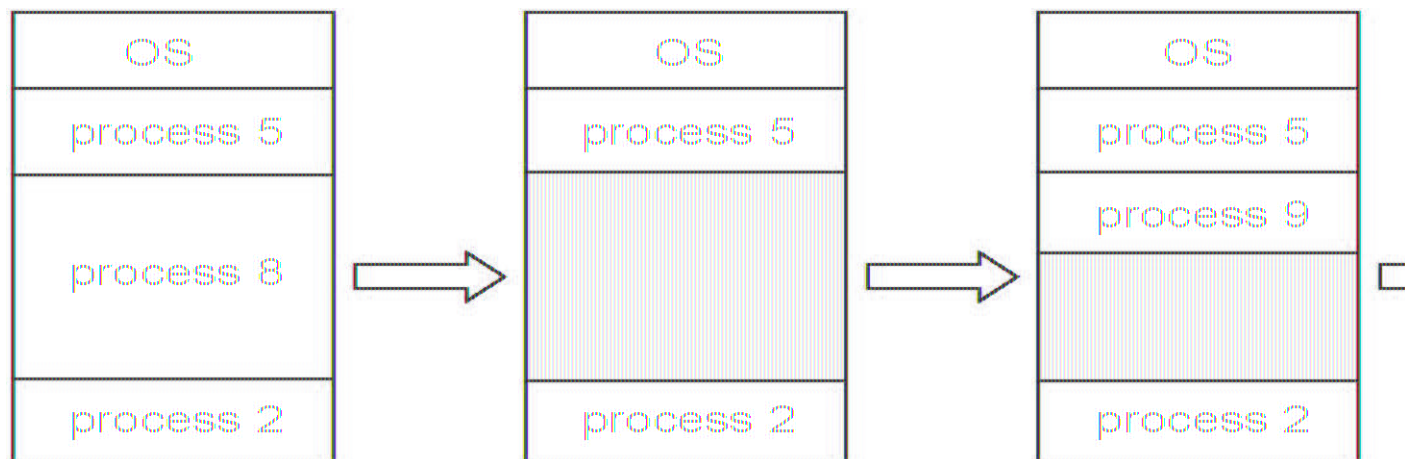
Partition size = process size
So, no internal Fragmentation





Multiple-partition allocation

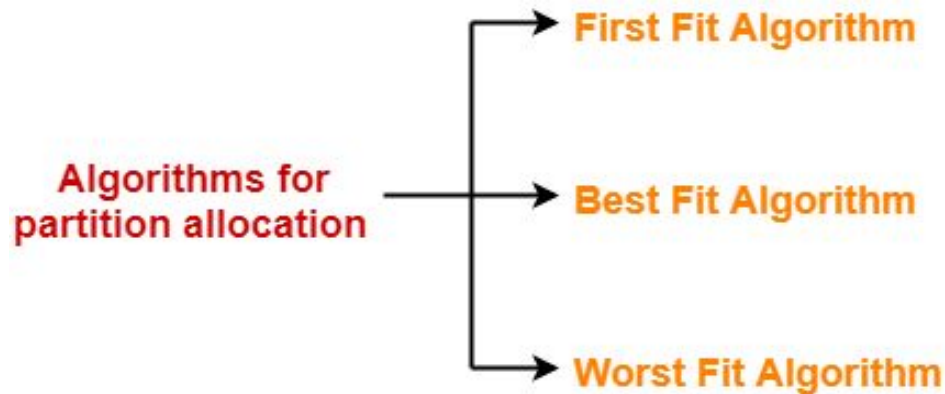
- Multiple-partition allocation
 - Degree of multiprogramming limited by number of partitions
 - **Variable-partition** sizes for efficiency (sized to a given process' needs)
 - **Hole** – block of available memory; holes of various size are scattered throughout memory
 - When a process arrives, it is allocated memory from a hole large enough to accommodate it
 - Process exiting frees its partition, adjacent free partitions combined
 - Operating system maintains information about:
 - a) allocated partitions b) free partitions (hole)





Dynamic Storage-Allocation Problem

How to satisfy a request of size n from a list of free holes?



- **First-fit**: Allocate the **first** hole that is big enough
- **Best-fit**: Allocate the **smallest** hole that is big enough; must search entire list, unless ordered by size
 - Produces the smallest leftover hole
- **Worst-fit**: Allocate the **largest** hole; must also search entire list
 - Produces the largest leftover hole

First-fit and best-fit better than worst-fit in terms of speed and storage utilization





First Fit

- First Fit : Allocate the first free block that is large enough for the new process.
- This is a fast algorithm.





First Fit Example

Initial memory
mapping

OS
P1 12 KB
<FREE> 10 KB
P2 20 KB
<FREE> 16 KB
P3 6 KB
<FREE> 4 KB





First Fit Example (Cont.)

P4 of 3KB
arrives

OS
P1 12 KB
<FREE> 10 KB
P2 20 KB
<FREE> 16 KB
P3 6 KB
<FREE> 4 KB





First Fit Example (Cont.)

P4 of 3KB
loaded here by
FIRST FIT

OS
P1 12 KB
P4 3 KB
<FREE> 7 KB
P2 20 KB
<FREE> 16 KB
P3 6 KB
<FREE> 4 KB





First Fit Example (Cont.)

P5 of 15KB
arrives

OS
P1 12 KB
P4 3 KB
<FREE> 7 KB
P2 20 KB
<FREE> 16 KB
P3 6 KB
<FREE> 4 KB





First Fit Example (Cont.)

P5 of 15 KB
loaded here by
FIRST FIT

OS
P1 12 KB
P4 3 KB
<FREE> 7 KB
P2 20 KB
P5 15 KB
<FREE> 1 KB
P3 6 KB
<FREE> 4 KB





Best fit

- Best Fit : Allocate the smallest block among those that are large enough for the new process.
- In this method, the OS has to search the entire list, or it can keep it sorted and stop when it hits an entry which has a size larger than the size of new process.
- This algorithm produces the smallest left over block.
- However, it requires more time for searching all the list or sorting it
- If sorting is used, merging the area released when a process terminates to neighboring free blocks, becomes complicated.





Best Fit Example

Initial memory
mapping

OS
P1 12 KB
<FREE> 10 KB
P2 20 KB
<FREE> 16 KB
P3 6 KB
<FREE> 4 KB





Best Fit Example (Cont.)

P4 of 3KB
arrives

OS
P1 12 KB
<FREE> 10 KB
P2 20 KB
<FREE> 16 KB
P3 6 KB
<FREE> 4 KB





Best Fit Example (Cont.)

P4 of 3KB
loaded here by
BEST FIT

OS
P1 12 KB
<FREE> 10 KB
P2 20 KB
<FREE> 16 KB
P3 6 KB
P4 3 KB
<FREE> 1 KB





Best Fit Example (Cont.)

P5 of 15KB
arrives

OS
P1 12 KB
<FREE> 10 KB
P2 20 KB
<FREE> 16 KB
P3 6 KB
P4 3 KB
<FREE> 1 KB





Best Fit Example (Cont.)

P5 of 15 KB
loaded here by
BEST FIT

OS
P1 12 KB
<FREE> 10 KB
P2 20 KB
P5 15 KB
<FREE> 1 KB
P3 6 KB
P4 3 KB
<FREE> 1 KB





Worst Fit

- Worst Fit : Allocate the largest block among those that are large enough for the new process.
- Again a search of the entire list or sorting it is needed.
- This algorithm produces the largest over block.





Worst Fit Example

Initial memory
mapping

OS
P1 12 KB
<FREE> 10 KB
P2 20 KB
<FREE> 16 KB
P3 6 KB
<FREE> 4 KB





Worst Fit Example (Cont.)

P4 of 3KB
Loaded here by
WORST FIT

OS
P1 12 KB
<FREE> 10 KB
P2 20 KB
P4 3 KB
<FREE> 13 KB
P3 6 KB
<FREE> 4 KB



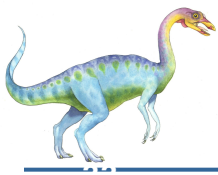


Worst Fit Example (Cont.)

No place to load
P5 of 15K

OS
P1 12 KB
<FREE> 10 KB
P2 20 KB
P4 3 KB
<FREE> 13 KB
P3 6 KB
<FREE> 4 KB





Worst Fit Example (Cont.)

No place to load
P5 of 15K

Compaction is
needed !!

OS
P1 12 KB
<FREE> 10 KB
P2 20 KB
P4 3 KB
<FREE> 13 KB
P3 6 KB
<FREE> 4 KB





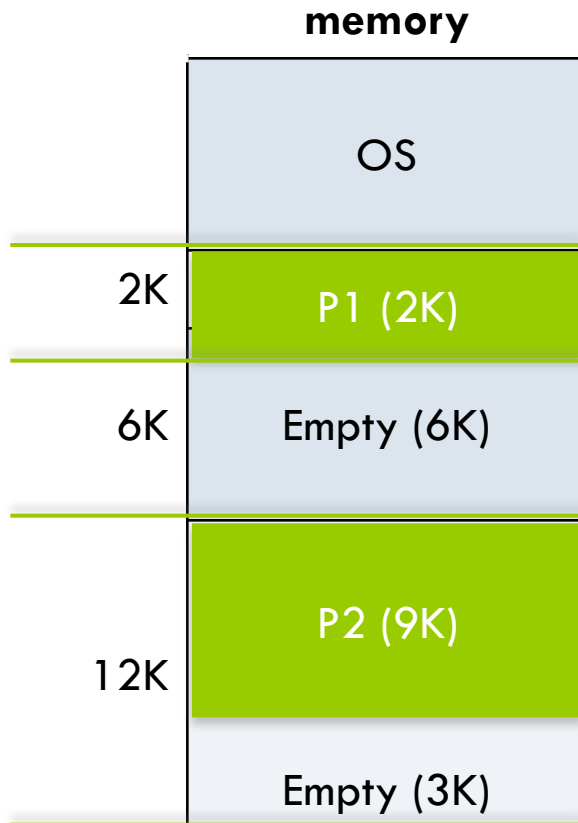
Fragmentation

- **External Fragmentation** – total memory space exists to satisfy a request, but it is not contiguous
- **Internal Fragmentation** – allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used





Fragmentation



If a whole partition is currently not being used, then it is called an *external fragmentation*.

If a partition is being used by a process requiring some memory smaller than the partition size, then it is called an *internal fragmentation*.





Fragmentation (Cont.)

- Reduce external fragmentation by **compaction**
 - Shuffle memory contents to place all free memory together in one large block
 - Compaction is possible *only* if relocation is dynamic, and is done at execution time
 - I/O problem
 - 4 Latch job in memory while it is involved in I/O
 - 4 Do I/O only into OS buffers
- Now consider that backing store has same fragmentation problems



