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Introduction

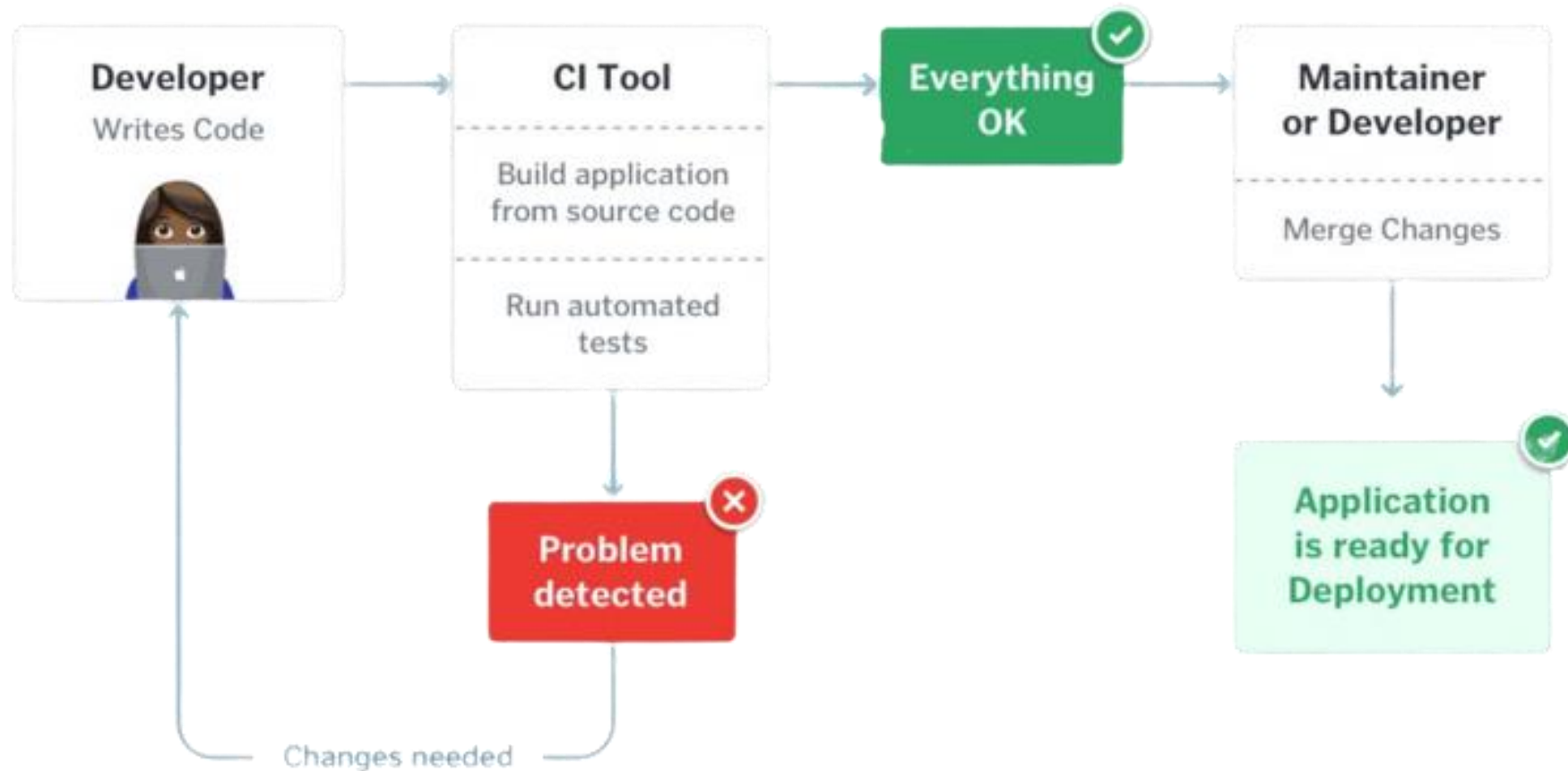
Continuous Integration

Continuous integration is a modern, widely used practice.

It urges developers to build and test their software whenever a new commit is submitted.



General Workflow



Benefits

- Faster failure detection
- Faster release cycles
- Lower risk of delivering defective changes
- Improved code quality

Problem

Constant use of computational resources to run and test changes.

Google estimates the cost of running its CI system in **millions of dollars**, and Mozilla estimates theirs as **\$201,000/month**.

For smaller-budget companies that have not yet adopted CI, its high cost can pose a strong barrier.

Optimization Strategies

- Test selection:
Running only subset of tests that are more relevant to the changes made.
- CI skip:
Skipping the execution of unnecessary commits.

Example

Some commits unnecessarily trigger the CI process.

The image shows a GitHub repository for `geoserver/geoserver` and its CI build status. The left panel displays the commit history and a diff for commit `7763b6e` (labeled with a red circle 1). The diff shows changes in `src/community/mapml/src/main/java/org/geoserver/mapml/MapMLController.java`. The right panel shows the CI build status for build `#10904` (labeled with a red circle 2). The build is passing and shows a table of build jobs.

Commit History:

- Commit `7763b6e`: fixed formatting

Build Status:

- Build `#10904` passed
- Ran for 38 min 20 sec
- Total time 1 hr 38 min 58 sec
- 6 months ago

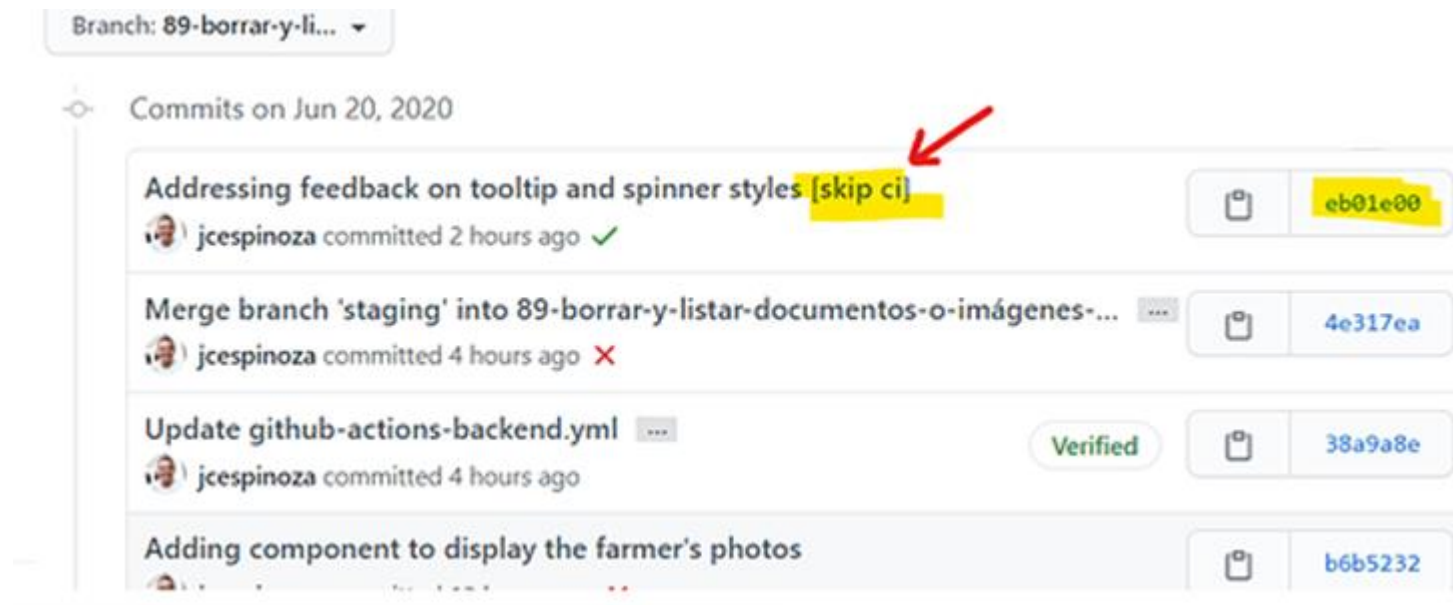
Build Jobs:

Job ID	Platform	Configuration	Duration
# 10904.1	amd64	JDK: oraclejd... ARGS="-Dfmt.skip=true"	32 min 43 sec
# 10904.2	amd64	JDK: oraclejd... ARGS="-Dfmt.skip=true"	38 min 17 sec
# 10904.3	amd64	JDK: oraclejd... ARGS="-Dfmt.action=check"	27 min 58 sec

Goals

Commits that won't cause a build failure or change the build result vainly use computation resources.

We aim to reduce the number of executed builds by skipping unnecessary ones.



Literature Review

The Travis Torrent dataset

Each row represents a build job executed on Travis CI.

It synthesizes information from three different sources:

- The project's git repository
- Data extracted from GitHub through GHTorrent
- Data and build logs from Travis CI's API



Dataset Features

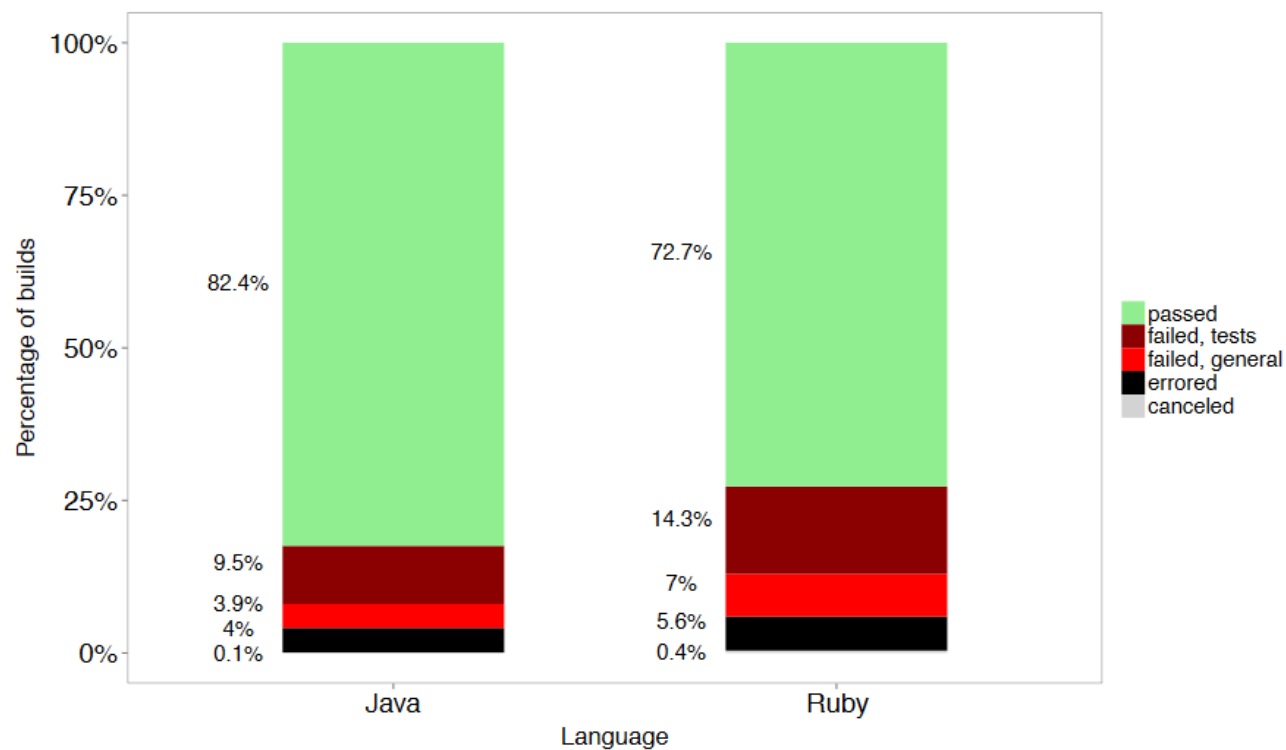
- 66 total features
- Extracted features fall under these categories:
 - Diffusion
 - Size
 - Purpose
 - History

Target is 'build status' (passed/failed)

→ a binary classification problem

Build Outcome

- Build status of projects in TravisTorrent
→ Data is heavily imbalanced



Machine Learning Approaches

- Several research projects make use of Machine Learning to tackle this problem.
 - Within project validation → existing project.
 - Cross project validation → new project with no history.
- Use of common classification metrics
 - F1 score
 - Area under the ROC curve
- RF usually yields the best results.

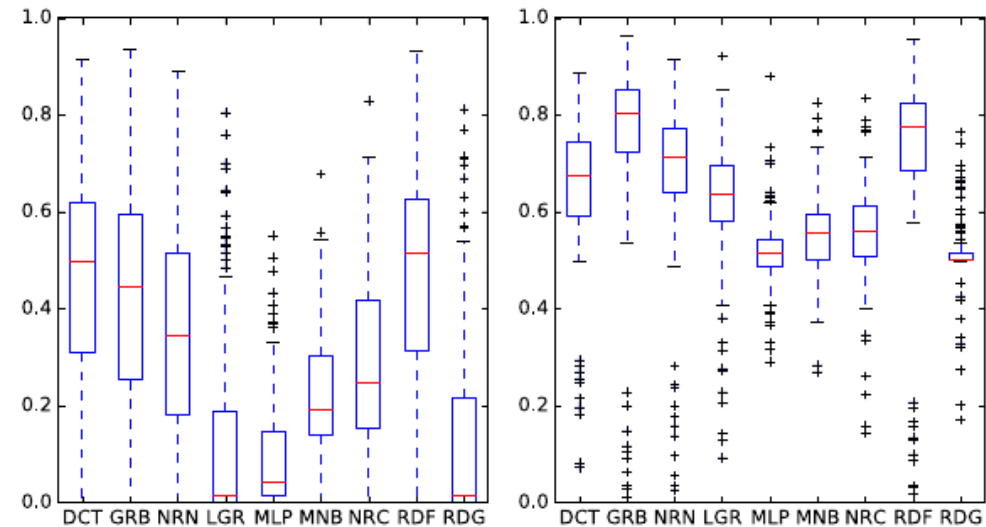
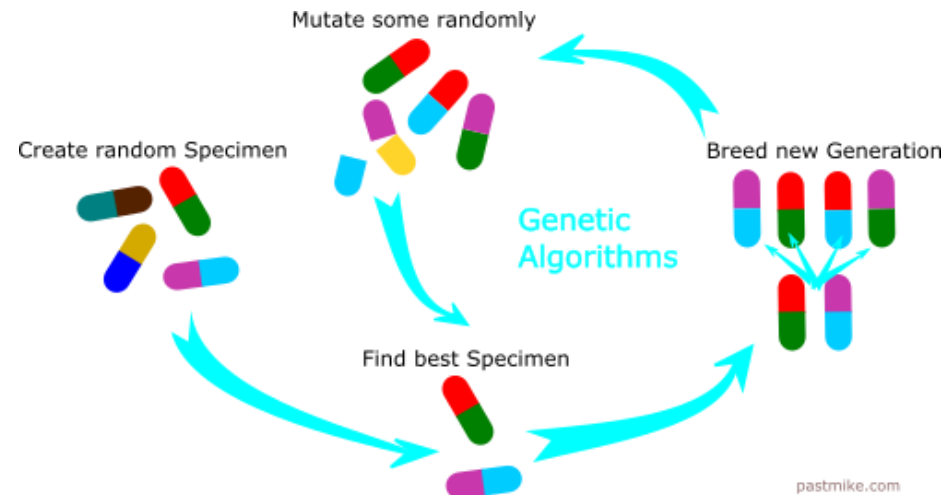


Fig. 2. F1-Score (left) and AUC (right) of Cross-validation Predictions

Genetic Algorithms



To adopt a genetic algorithm, we need to define the

- Candidate solutions
- Fitness function
- Crossover operation
- Mutation operation

Genetic Algorithms Approaches

- Finding the optimal IF -THEN rule using its binary tree representations.

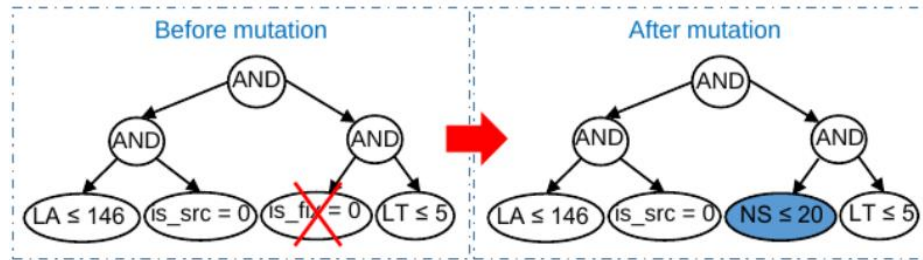
IF $LA \leq 146$ AND $IS_SRC = 0$ AND $IS_FIX = 0$
THEN Skip commit.



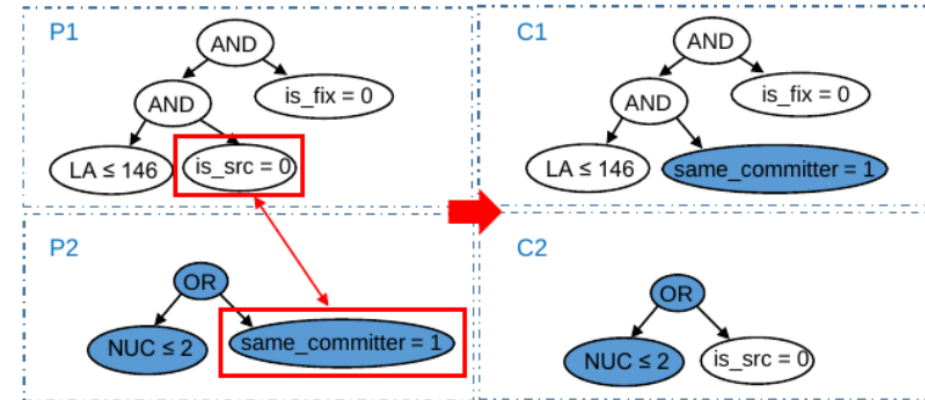
A candidate solution

- Motivation
 - Efficiency of manually defined rule based classification.
 - Promising results of GA in unbalanced classification.

Genetic Algorithms Approaches



Mutation



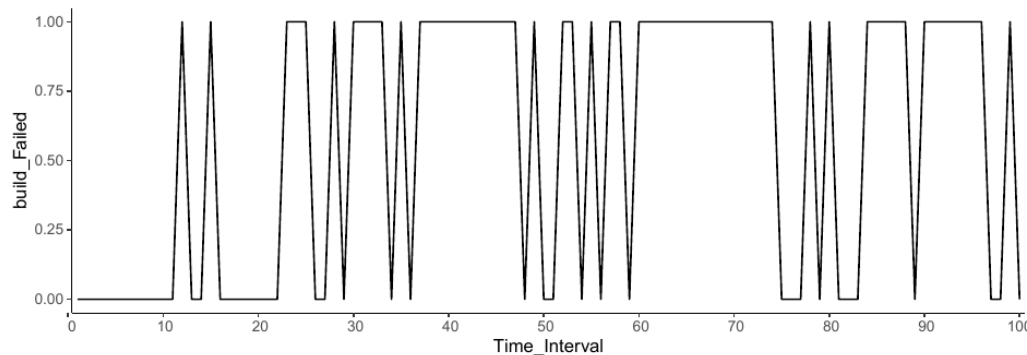
Crossover

$$\text{Fitness function: } \min_{i=1}^n \sqrt{(1 - TPR_i)^2 + FPR_i^2}$$

- 92% AUC for within-project validation
- 84% AUC for cross-project validation

Genetic Algorithms Approaches

- Failing builds prediction using LSTM



- Hyper-parameters optimization of LSTM using GA

Number of units = 64	Number of layers = 3	Batch Size =25	Number of epochs=5	Optimizer= 'Adam'	Dropout probability= 0.1	Time Step=60
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A candidate solution

Genetic Algorithms Approaches

- Fitness: validation loss

Parent

Number of units = 64	Number of layers = 3	Batch Size = 25	Number of epochs=5	Optimizer='Adam'	Dropout probability=0.1	Time Step=60
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Mutation

Child

Number of units = 64	Number of layers = 2	Batch Size = 25	Number of epochs=10	Optimizer='RMSprop'	Dropout probability=0.1	Time Step=60
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Parent 1

Number of units = 64	Number of layers = 3	Batch Size = 25	Number of epochs=5	Optimizer='Adam'	Dropout probability=0.1	Time Step=60
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Parent 2

Number of units = 32	Number of layers = 2	Batch Size = 40	Number of epochs=16	Optimizer='RMSprop'	Dropout probability=0.4	Time Step=40
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Crossover
K=3

Child 1

Number of units = 64	Number of layers = 3	Batch Size = 25	Number of epochs=16	Optimizer='RMSprop'	Dropout probability=0.4	Time Step=40
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Child 2

Number of units = 32	Number of layers = 2	Batch Size = 40	Number of epochs=5	Optimizer='Adam'	Dropout probability=0.1	Time Step=60
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The Project So Far

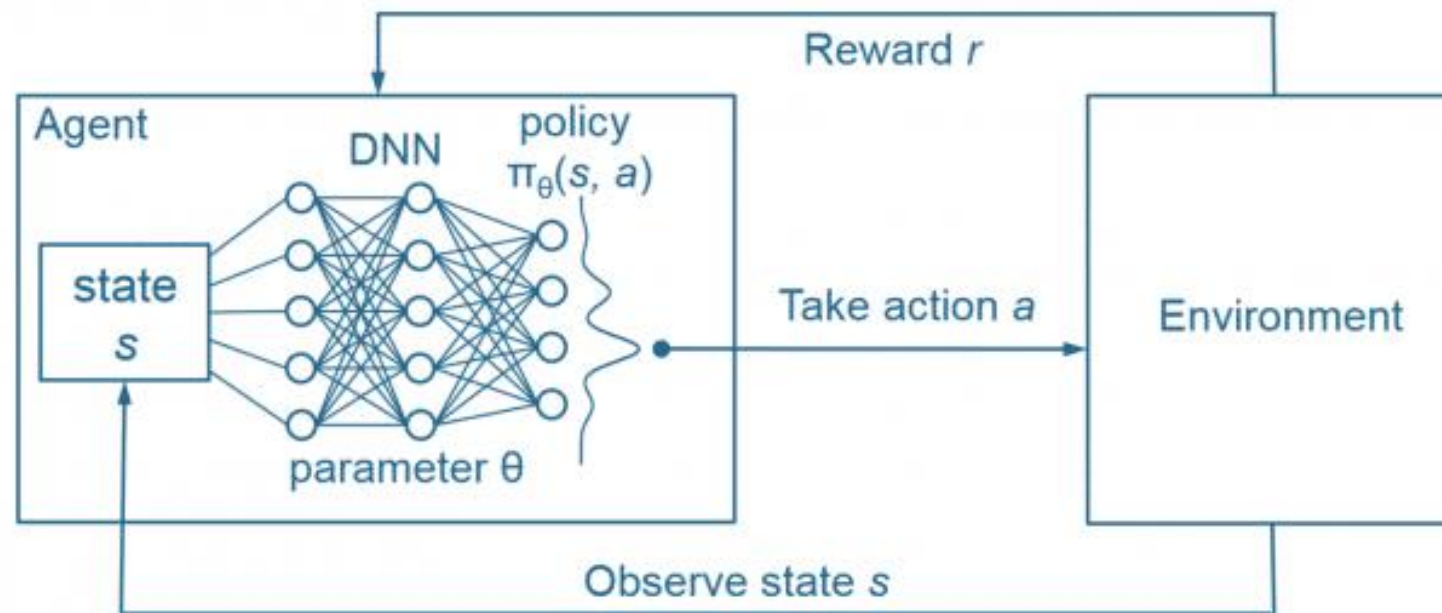
- Reimplementation of the previously mentioned approaches.
- Benchmark of several ML models on the TravisTorrent dataset using both within-project and cross-project validation.
- Working on a novel RL approach.

Towards a Novel Reinforcement Learning Approach

RL Approach

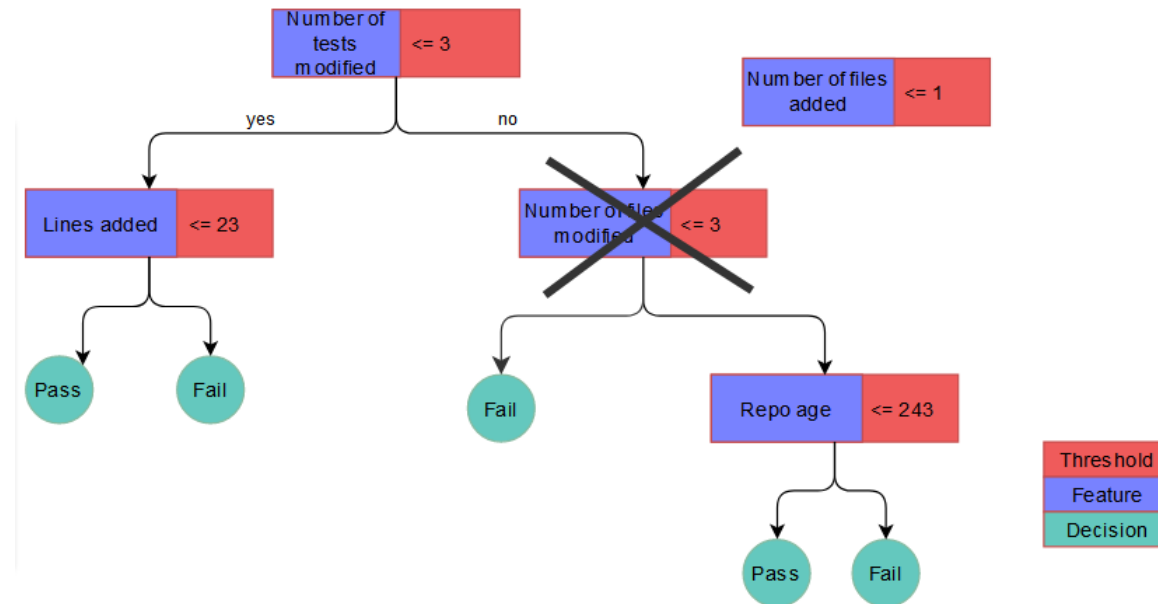
- A Deep Reinforcement Learning method to build decision trees.
- Based on “Building Decision Tree for Imbalanced Classification via Deep Reinforcement Learning”, Guixuan Wen, Kaigui Wu (2021)
- Experiments on 15 imbalanced datasets indicate that this approach outperforms baseline DT building methods.

Deep RL



Game Principle

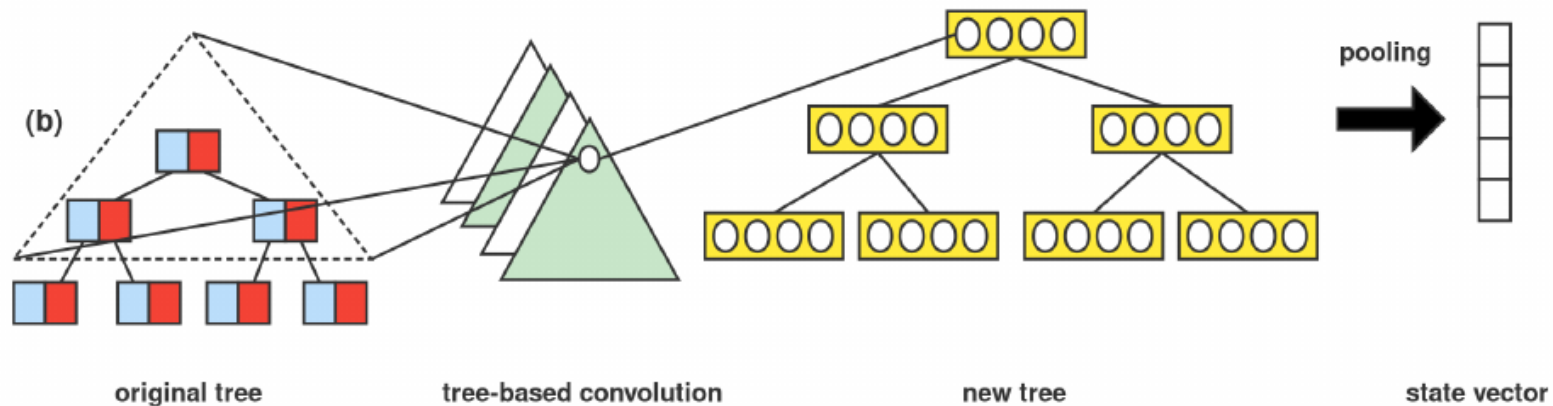
- A decision tree's node is composed of two parts: an attribute and a threshold value.



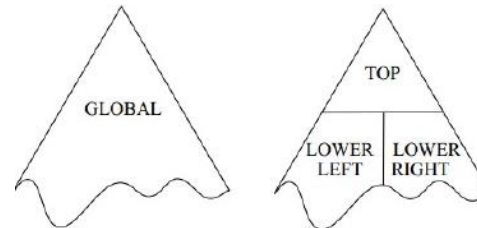
- Update tree nodes to improve the classification metrics.

Environment State

The state s is extracted by tree-based convolution.



- How to aggregate information?
- How to choose kernels?

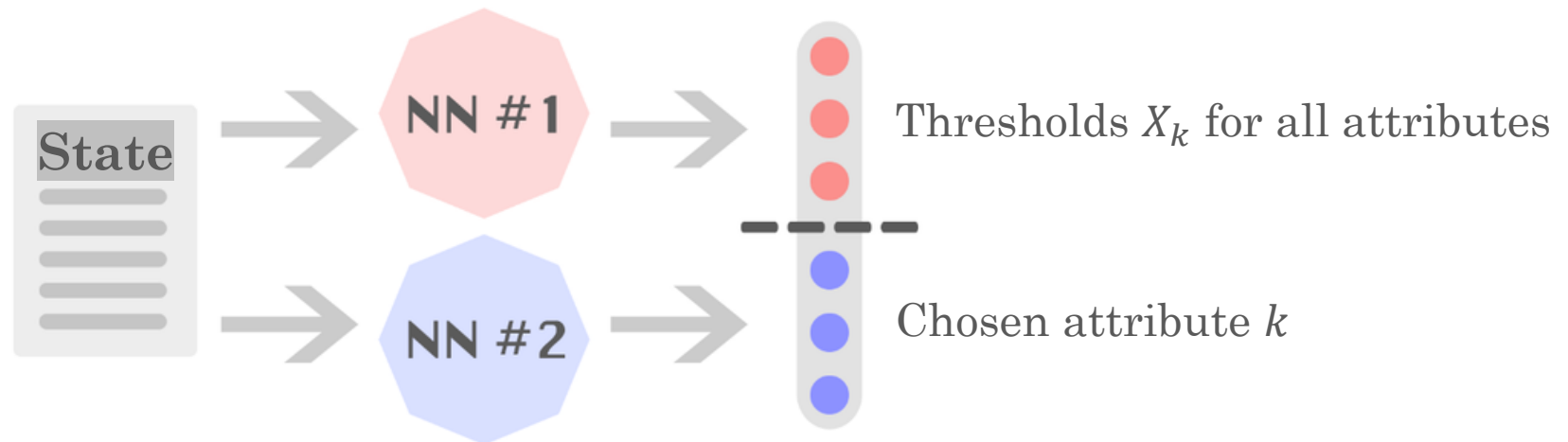


Agent's Actions

At each episode m , a set A_d of actions is taken to generate a new decision tree.

At each step t , we choose an action a_k for a single node.

- $A_d = \bigcup_{k \in [K]} \{a_k = (k, x_k) \mid x_k \in X_k \subseteq \mathbb{R}\}$
 - k is the feature/attribute
 - x_k is the threshold value



Reward Function

- After each node modification t , classify the data using the new tree.
- The predicted results \hat{Y}_t and the truth Y_t are used to calculate a classification metric m_t .
- $r_t = m_t - m_{t-1}$

Training Process

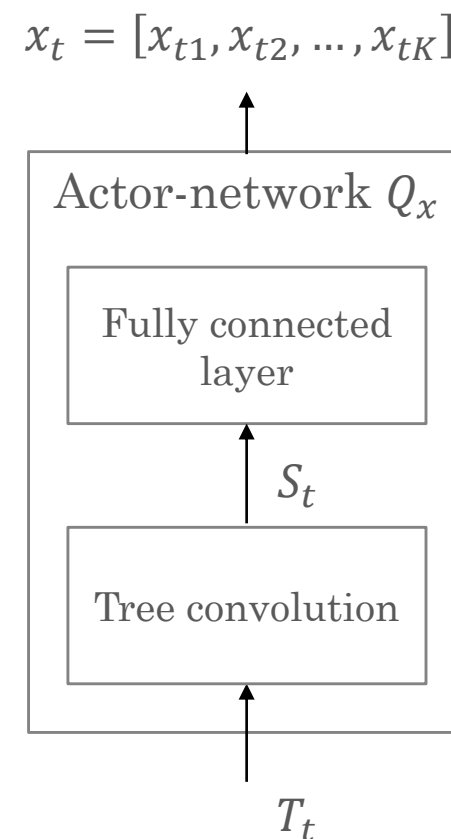
For each node t :

- The actor network computes
 - The state S_t
 - The threshold values for all attributes X_t

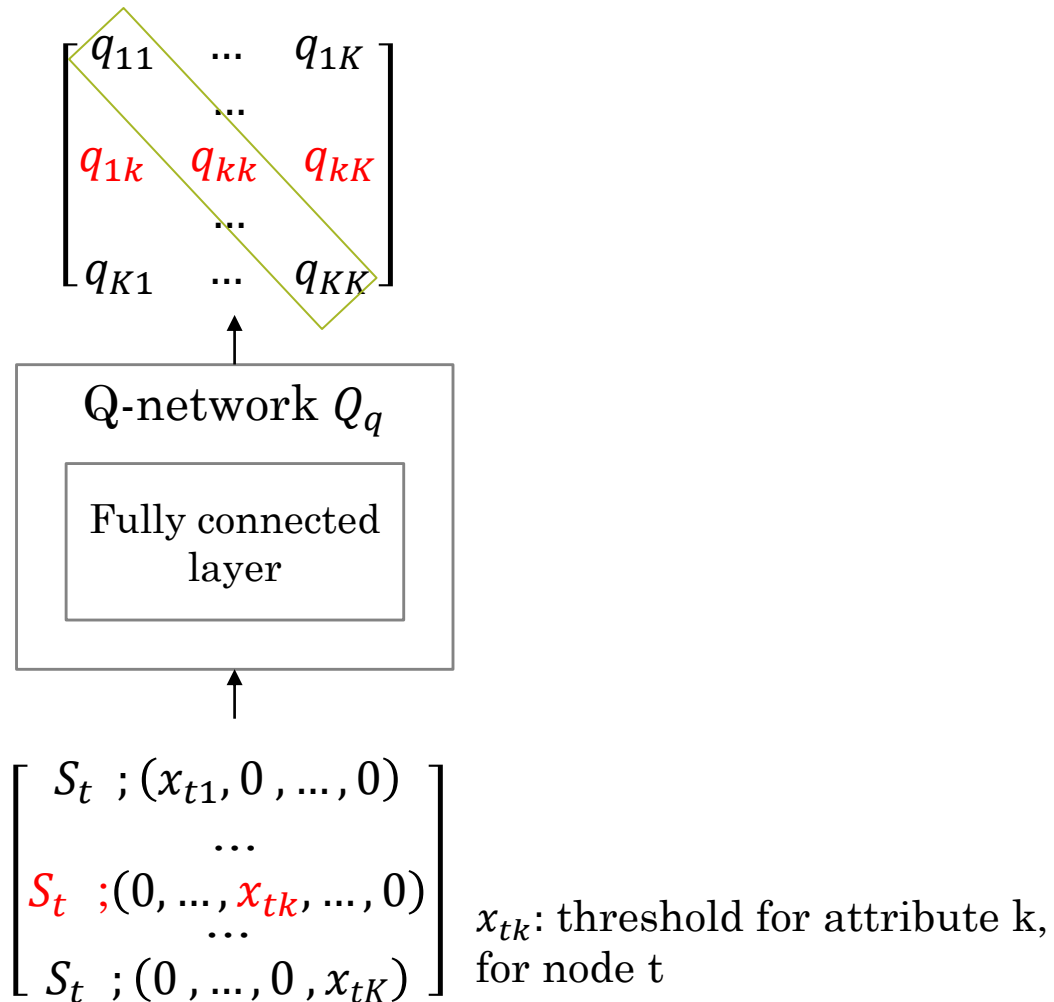
Output x_t :

26	5	6	...	
gh_diff_src_files	gh_team_size	gh_num_of_comments	...	

→ choose a pair



Training Process



$$Q_t = [q_{11}, q_{22}, \dots, q_{kk}, \dots, q_{KK}]$$

→ Expected reward for choosing k

Chose attribute K_t

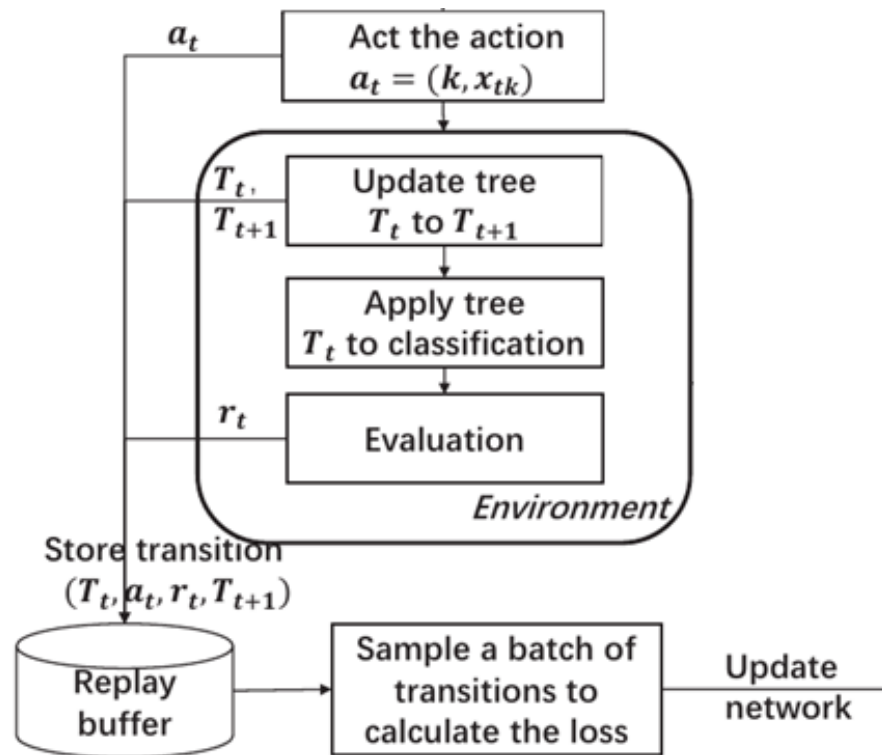
$$k_t = \operatorname{argmax} Q_t$$

$$= \operatorname{argmax}_{k \in [K]} Q_q(S_t, x_{tk}; \theta_q)$$

Choose action

$$a_t = \begin{cases} (k_t, x_{tk}) & \text{with probability } 1 - \varepsilon \\ \text{random action} & \text{with probability } \varepsilon \end{cases}$$

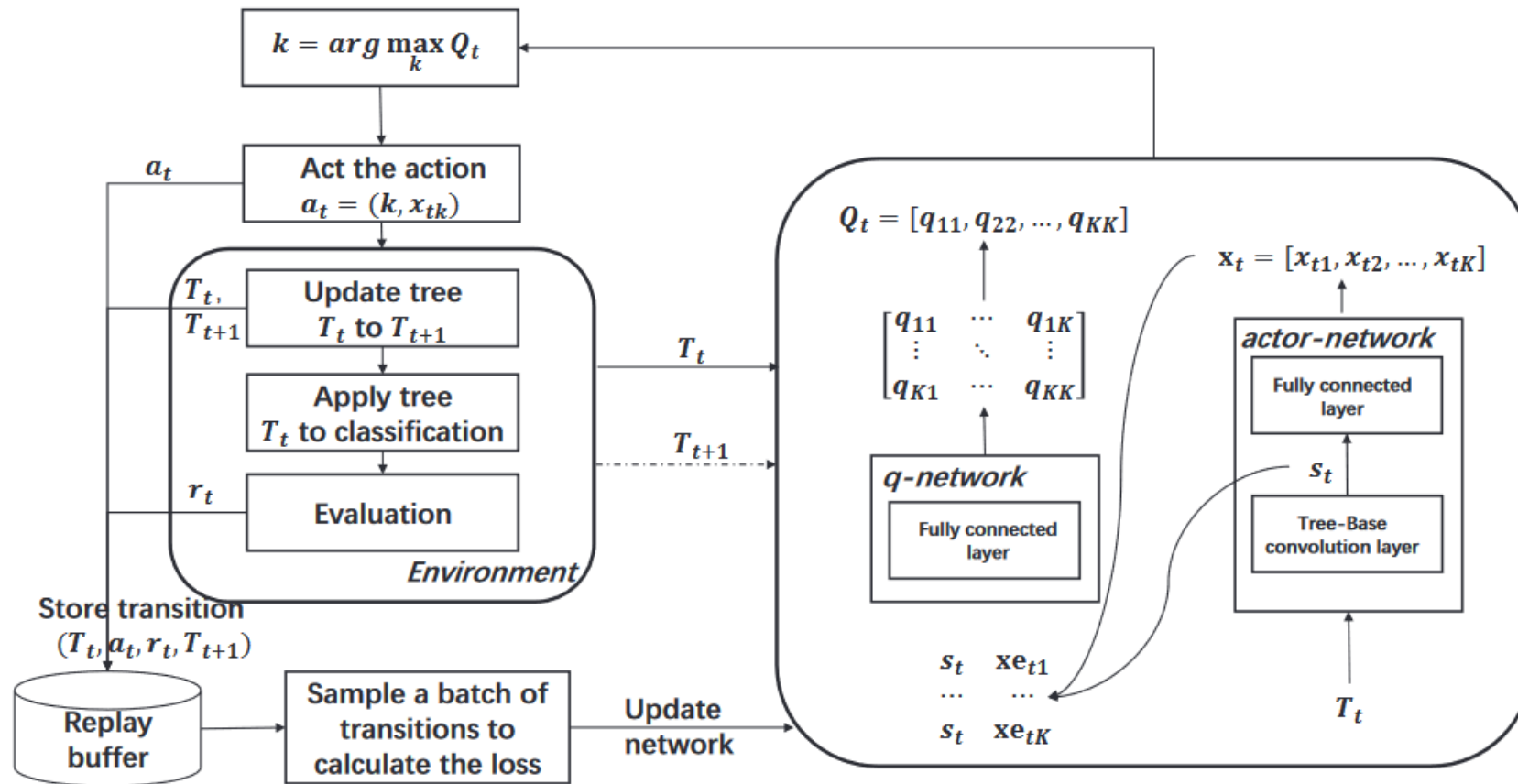
Training Process



Experience Replay

- prevent network weights from diverging due to temporal correlation.
- learn more from individual transitions multiple times.
- recall rare occurrences.

General Architecture



Difficulties

- State size $2(2^{depth} - 1)$
- Choice of the convolution operation
- Choice of hyper-parameters (tree depth, learning rate, etc.)

Conclusion

- We aim to propose a novel Deep Q-Learning approach, and compare its classification metrics to other approaches from literature.