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Yash Chandak

Education

2017-current MS/PhD, Computer Science, University of Massachusetts, Amherst, US.

2013–17 B.Tech, Computer Science & Engineering, VIT University, Chennai, India,

9.11/10.

Research Experience

current Skill discovery over large action space for continual learning

University of Massachusetts, Amherst, research project under **Dr. Philip Thomas** Working on dynamically expanding the set of useful skills to learn new tasks faster.

- Jan-Jun '17 Convolution Neural Networks with Attention for Unstructured Graph Classification Indian Institute of Technology Madras, research project under **Dr. Balaraman Ravindran** Learning node embeddings via context dependent kernels for neighborhood aggregation.
- Jun-Jul '16 **Semantic Graph based Image Retrieval**University of Technology Troyes, France, research internship under Prof. Babiga Birregah
 Extracting entity co-location graph from images for retrieving similar images using graph matching.
- Feb-Mar '16 **Target Detection for Autonomous Weapons**Defence Research & Development Organisation, research trainee under Sh. Jai Prakash Singh War-time vehicle detection for Off-Route mines, using neural networks on Raspberry Pi.
- Feb-May '15 **Optimizing Human-Machine Task Assignments** [AAAI HComp wip 2015]
 The Aspiring Researchers Challenge under **Prof. James Davis, UCSC** and **Rajan Vaish, Stanford**Judicious usage of crowd intelligence to increase the accuracy of computer vision algorithms.

Work Experience

Dec-Jan '16 R2Robotics, Internship.

Autonomous visual navigation of aerial drones by matching live camera feed with preloaded satellite images.

Jun-Sep '15 Microsoft Campus Connect, On-campus mentored project.

Developed module to convert non-IoT devices into IoT enabled and predict user settings from past usage.

Dec '14 **Uurmi Systems**, *Internship*.

Real-time day/night time lane detection for autonomous cars by exploiting structural properties of lane markers.

Related Academic Projects

Blind steganography obfuscation

Using entropy based scrambling in spatial domain and additive Gaussian noise in Fourier Transform.

Vanishing Point detection in 2D image

Depth estimation in individual images using point of convergence of major line segments.

Automated text generation using LSTMs

Recurrent Neural Networks for text generation using Tensorflow and Python.

Human tracking mobile robot

Arduino bot, controlled using offset of the detected face from the frame's center.

Technical Skills

Languages Python, C++, MATLAB, LATEX

Libraries OpenCV, Hadoop, Tensorflow, PyTorch

Platforms Linux, Windows, Arduino, Raspberry Pi

Extra-Curricular Activities

- Junior National Basketball player under Basketball Federation of India.
- Sketching, Mountaineering, rock-climbing, camping