Aditya Raj Maheshwari

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EDUCATION

Degree/Certificate	${\bf Institute/Board}$	CGPA/Percentage	Year
B.Tech. Electronics and Instrumentation Engg.	Nirma University	7.4(Current)	2021-Present
Senior Secondary	CBSE Board	90.4%	2021
Secondary	CBSE Board	91.5%	2019

PROJECTS

• Mission Chandra Sept. 2023

SAC ISRO Ahmedabad, Domain: Microcontroller integration and UI development

- Worked with a team of 4 to develop a 1:200 scale of two-stage Chandrayan-3 launch vehicle with parachute recovery.
- Used Arduino nano with burn wire setup for rocket separation and parachute deployment.
- Used barometer sensor and saved real time telemetry data logs on SD card connected to onboard Arduino along with sending to ground station.
- Created a WPF application using C# which acts as ground station and displays real time telemetry data and required graphs.
- Developed failsafe mechanisms in case of any in-flight error to safeguard the onboard electronics.

• Aerothon 2023 (Team Captain)

Nov. 2023

Domain: Systems Engineer

- Lead a team of 10 to develop a multirotor under 2kg with autonomous navigation and payload delivery capacity of 200g along with identification of four hotspots.
- Worked with NVIDIA's Jetson Xavier NX and ArduCam 12MP camera.
- Developed custom trained YOLOV5 algorithm for target detection and hotsopt identification.
- Developed algorithm to prevent same hotspot detection due to hotspot being identical in nature.

• SUAS 2023

June. 2023

AUVSI SUAS 2023: Maryland USA, Domain: Machine Learning and Autonomous Navigation

- Worked with a team of 10 to develop a multirotor under 25kg with autonomous navigation and five payload delivery each weighing 500g and cover path of 12miles under 30minutes.
- Worked with NVIDIA's Jetson Xavier NX and Viewpro Q10F 14MP camera.
- Employed a custom trained improved YOLOV5 based algorithm with transformer prediction head.
- Developed a new autonomous navigation algorithm for payload dropping with $0.1\mathrm{m}$ accuracy.

• Aerothon 2022 Nov. 2022

Domain: Machine Learning

- Worked with a team of 10 to develop a multirotor under 2kg with autonomous navigation and payload delivery capacity of 200g.
- Worked with NVIDIA's Jetson Xavier NX and ArduCam 12MP camera.
- Used custom trained YOLOV5 algorithm for target detection.
- Developed a relative navigational algorithm for payload delivery.

TECHNICAL SKILLS

- **Programming**: C/C++, Python, C#
- Databases: MySQL
- Operating System: Windows, Linux
- Other: Data Structures and Algorithms(DSA), Keras, Tensorflow, Pytorch, ROS, OpenCV, Database Management System(DBMS), Object Oriented Programming in python, mavlink, dronekit, Arduino

KEY COURSES TAKEN

- Mathematics: Calculus, Linear Algebra and Ordinary Differential Equation-I, Complex Analysis and Differential Equations-II, Numerical Methods
- Electrical Course: Circuit Theory, Basic electronics, Control theory, Industrial Electronics, Electrical and Electronics Measurement, Control System Design, Linear Integrated Circuits, Signals and Systems, Process Control, Transducers and Measurement
- Computer Science: Computer Programming, Machine Learning, Microprocessors and Microcontrollers, Cloud Computing, Data Science, Programming with Python and Matlab, Object Oriented Programming, Data Structures, Image Processing

Positions of Responsibility

• General Secretary, SAE Nirma Collegiate Club , Nirma University	Jan. 2024 - Present
• Team Captain, Team Arrow, Nirma University	Apr. 2023 - Present
• Computer Systems Lead, Team Arrow , Nirma University	Nov. 2022 - Present
• Member, SAE Nirma Collegiate Club , Nirma University	Jul. 2022 - Jan. 2024
• Member, Student Chapter of the Computer Society of India , Nirma University	Aug. 2021 - Present
 Member, Student Chapter of the Computer Society of India , Nirma University ACHIEVEMENTS Rank 5, SAE Aerothon 2022, Banglore 	Aug. 2021 - Present Nov. 2022
Achievements	