

importing libraries

```
In [ ]: # Importing libraries
import tensorflow as tf # deeplearning lib
import matplotlib.pyplot as plt # visualization
import numpy as np # arrays and matrices
import cv2 # computer vision
import os # communicate with system
import imghdr # handling image formats
```

C:\Users\mahig\AppData\Local\Temp\ipykernel_18720\877037246.py:7: DeprecationWarning: 'imghdr' is deprecated and slated for removal in Python 3.13
import imghdr # handling image formats

Importing Data

```
In [ ]: # base directory for dataset
data_dir = 'data'
```

```
In [ ]: # desired image formats
img_ext = ['.jpeg', '.jpg', '.bmp', '.png']
```

```
In [ ]: # getting the data directories inside base directory
os.listdir(data_dir)
```

```
Out[ ]: ['bottle', 'fishnet', 'metal_debris', 'plastic_bag', 'tyre']
```

Data Preparation

```
In [ ]: # getting the directories inside the data folder as list
for img_class in os.listdir(data_dir):
    for image in os.listdir(os.path.join(data_dir, img_class)): # iterate through every images in each folder
        img_path = os.path.join(data_dir, img_class, image) # file path for each images
        try:
            tip = imghdr.what(img_path)
            if tip not in img_ext: # checks for desired extensions
                print(f'Oops: {image} not found in ext list - {img_path}')
                os.remove(img_path) # removes the file from device
            except Exception as e:
                print(f'Issue with image {img_path}: {e}')
```

```
In [ ]: # getting number of images in each folders
print('bottle - ', len(os.listdir(os.path.join(data_dir, 'bottle'))))
print('fishnet - ', len(os.listdir(os.path.join(data_dir, 'fishnet'))))
print('metal_debris - ', len(os.listdir(os.path.join(data_dir, 'metal_debris'))))
print('plastic_bag - ', len(os.listdir(os.path.join(data_dir, 'plastic_bag'))))
print('tyre - ', len(os.listdir(os.path.join(data_dir, 'tyre'))))
```

```
bottle - 273
fishnet - 254
metal debris 223
plastic_bag - 229
tyre - 214
```

Importing data

```
In [ ]: # creates a dataset from images in directory
data=tf.keras.utils.image_dataset_from_directory('data')
```

Found 1193 files belonging to 5 classes.

```
In [ ]: data
```

```
Out[ ]: <_PrefetchDataset element_spec=(TensorSpec(shape=(None, 256, 256, 3), dtype=tf.float32, name=None), TensorSpec(
shape=(None,), dtype=tf.int32, name=None))>
```

```
In [ ]: # represent data as numpy array
data_iterator=data.as_numpy_iterator()
```

```
In [ ]: data_iterator.next()
```

```
Out[ ]: (array([[[[ 27.90625 ,  52.90625 ,  57.90625 ],
               [ 26.      ,  51.      ,  56.      ],
               [ 24.09375 ,  51.09375 ,  60.28125 ],
               ...,
               [ 20.      ,  34.      ,  37.      ],
               [ 22.      ,  33.      ,  37.      ]],
```

```

[ 19.90625 , 35.1875 , 38.09375 ]],

[[ 27. , 55.4375 , 63.15625 ],
 [ 26. , 54.4375 , 62.15625 ],
 [ 26.28125 , 56.71875 , 60. ],
 ...,
 [ 20. , 34. , 37. ],
 [ 18.28125 , 33. , 36. ],
 [ 19. , 33.28125 , 36.28125 ]],

[[ 28. , 58. , 66. ],
 [ 27. , 57. , 65. ],
 [ 27.0625 , 58.125 , 68.65625 ],
 ...,
 [ 20. , 34. , 37. ],
 [ 16. , 34. , 36. ],
 [ 18.0625 , 30.46875 , 34. ]],

...,

[[ 34.53125 , 97.53125 , 112.53125 ],
 [ 33.53125 , 92.53125 , 108.53125 ],
 [ 30.53125 , 87.53125 , 104.53125 ],
 ...,
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 [ 20.46875 , 42.46875 , 53.46875 ],
 [ 22. , 44. , 55. ]],

[[ 31.4375 , 89.875 , 106.15625 ],
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 [ 29. , 86. , 103. ],
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 [ 19.4375 , 47. , 55.71875 ],
 [ 22.71875 , 45.28125 , 56. ],
 [ 24. , 46.5625 , 57.28125 ]],

[[ 29.09375 , 84.8125 , 101.90625 ],
 [ 31. , 82. , 101. ],
 [ 31. , 88. , 105. ],
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 [ 17. , 47. , 55. ],
 [ 19.90625 , 46.90625 , 55.90625 ],
 [ 20.90625 , 47.90625 , 56.90625 ]]],

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 [ 32.289062 , 96.28906 , 106.28906 ],
 [ 28.773438 , 92.77344 , 102.77344 ],
 [ 25.257812 , 89.25781 , 99.25781 ]],

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 [ 38.515625 , 115.515625 , 133. ],
 [ 39.778442 , 118.92688 , 134.0675 ],
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 [ 33.534058 , 97.53406 , 107.53406 ],
 [ 29.867065 , 93.867065 , 103.867065 ],
 [ 26.669312 , 90.66931 , 100.66931 ]],

[ 39.066772 , 114.36719 , 132.87146 ],
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 [ 40.220825 , 119.36926 , 134.50989 ],
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 [ 35.060425 , 99.4823 , 109.261475 ],
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...,

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 [ 25.398438 , 50.65625 , 43.882812 ],
 [ 25.140625 , 50.140625 , 44.140625 ]],

[[ 49.47351 , 80.645386 , 64.55945 ],
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 [ 33.800293 , 73.96655 , 56.22937 ],
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 [ 25.705933 , 51.705933 , 42.705933 ],
 [ 25.124878 , 50.38269 , 43.609253 ],
 [ 24.528687 , 49.528687 , 43.528687 ]],

[[ 55.3125 , 86.484375 , 70.39844 ],
 [ 44.390625 , 78.9375 , 61.679688 ],

```

```

[ 40.445312 , 81.16406 , 62.734375 ],
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[ 25.429688 , 51.429688 , 42.429688 ],
[ 25. , 50.257812 , 43.484375 ],
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[[[ 35.95996 , 129.11328 , 199.11328 ],
[ 36.5 , 129.5 , 199.5 ],
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[ 22.80664 , 142.80664 , 228.80664 ]]],

[[ 33.91992 , 130.91992 , 199.91992 ],
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[ 22.95996 , 142.12012 , 226.04004 ],
[ 22.379883 , 141.54004 , 225.45996 ]]],

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[ 24.566406 , 141.9668 , 224.5 ]]],

...,

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[126.93262 , 128.63184 , 183.33105 ],
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[ 0. , 23.533203 , 27.533203 ]]],

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[ 0.6201172, 22.780273 , 52.060547 ],
[ 2.5800781, 27.080078 , 31.080078 ],
[ 0. , 24.080078 , 28.080078 ]]],

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[167.14648 , 184.80664 , 193.4668 ],
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[ 10.693359 , 36.7334 , 40.38672 ],
[ 1.9599609, 29.04004 , 32.34668 ]]],

...,

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[ 46.5 , 83.5 , 92.5 ],
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[ 99.796875 , 155.79688 , 172.79688 ],
[105.88281 , 161.88281 , 178.88281 ]]],

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[ 93.18555 , 149.18555 , 166.18555 ],
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[[ 10. , 19.314453 , 10.542969 ],
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```

```

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[ 0. , 6. , 4. ]]],

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[191. , 193. , 182. ],
[191. , 193. , 182. ]],

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[191. , 193. , 182. ],
[191. , 193. , 182. ]],

...,

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[ 5. , 6. , 1. ],
[ 5. , 6. , 1. ],
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[ 37.28125 , 39.28125 , 26.28125 ]],

[[ 5. , 6. , 1. ],
[ 5. , 6. , 1. ],
[ 5. , 6. , 1. ],
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[ 40.09375 , 42.09375 , 29.09375 ],
[ 40.09375 , 42.09375 , 29.09375 ]],

[[ 5. , 6. , 1. ],
[ 5. , 6. , 1. ],
[ 5. , 6. , 1. ],
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[ 43. , 45. , 32. ]]],

[[[ 86. , 137. , 184. ],
[ 86. , 137. , 184. ],
[ 86. , 137. , 184. ],
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[105. , 153. , 191. ],
[105. , 153. , 191. ]],

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[ 86.572266 , 137.57227 , 184.57227 ],
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[105. , 153. , 191. ],
[105. , 153. , 191. ]],

```

```

[[ 87.          , 138.          , 185.          ],
 [ 87.          , 138.          , 185.          ],
 [ 87.          , 138.          , 185.          ],
 ...,
 [105.18555     , 153.18555     , 191.18555     ],
 [105.          , 153.          , 191.          ],
 [105.          , 153.          , 191.          ]],

...,

[[ 50.38492     , 60.607574    , 55.08112     ],
 [ 23.638603    , 36.0571     , 32.2153     ],
 [ 14.216568    , 28.86979     , 29.192593    ],
 ...,
 [160.58571     , 169.63898     , 165.6404     ],
 [166.81111     , 175.81111     , 172.74718     ],
 [156.63834     , 165.63834     , 162.63834     ]],

[[ 21.914867    , 27.551338    , 24.26764     ],
 [ 12.04631     , 19.76878     , 17.021942    ],
 [ 22.043411    , 34.756115    , 35.661125    ],
 ...,
 [162.02591     , 171.02591     , 167.65482     ],
 [167.91956     , 176.91956     , 173.91956     ],
 [161.29321     , 170.29321     , 167.29321     ]],

[[ 0.           , 1.0371094    , 0.           ],
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 [ 28.226562    , 38.96875     , 40.339844     ],
 ...,
 [156.51562     , 165.51562     , 162.14453     ],
 [157.11133     , 166.11133     , 163.11133     ],
 [149.29688     , 158.29688     , 155.29688     ]]], dtype=float32),
array([3, 3, 3, 1, 0, 4, 4, 4, 1, 0, 2, 3, 1, 1, 0, 2, 0, 4, 3, 0, 2, 4,
       3, 1, 2, 1, 3, 0, 1, 2, 3, 2]))

```

```

In [ ]: # getting a batch from the iterator
batch = data_iterator.next()

```

```

In [ ]: batch

```

```

Out[ ]: (array([[[[0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 ...,
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00]],

 [[0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
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 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 ...,
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00]],

 [[0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 ...,
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
 [0.00000000e+00, 0.00000000e+00, 0.00000000e+00]],

 ...,

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 [0.00000000e+00, 1.56250000e-02, 0.00000000e+00],
 ...,
 [0.00000000e+00, 1.56250000e-02, 0.00000000e+00],
 [0.00000000e+00, 1.56250000e-02, 0.00000000e+00],
 [0.00000000e+00, 1.56250000e-02, 0.00000000e+00]],

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 [3.39062500e+00, 0.00000000e+00, 0.00000000e+00],
 ...,
 [3.39062500e+00, 0.00000000e+00, 0.00000000e+00],
 [3.39062500e+00, 0.00000000e+00, 0.00000000e+00],
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 [5.59375000e+00, 0.00000000e+00, 0.00000000e+00],
 ...,

```

```

[5.59375000e+00, 0.00000000e+00, 0.00000000e+00],
[5.59375000e+00, 0.00000000e+00, 0.00000000e+00],
[5.59375000e+00, 0.00000000e+00, 0.00000000e+00]]],

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[8.49531250e+01, 1.52000000e+02, 1.42906250e+02],
[8.36875000e+01, 1.51687500e+02, 1.40531250e+02],
...,
[5.92187500e+00, 8.10000000e+01, 1.04078125e+02],
[6.95312500e+00, 7.90937500e+01, 1.03046875e+02],
[1.09375000e+01, 8.19531250e+01, 1.03984375e+02]]],

[[7.61239624e+01, 1.43123962e+02, 1.34123962e+02],
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[6.86926880e+01, 1.36595947e+02, 1.25488068e+02],
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[5.02218628e+00, 8.20061035e+01, 1.05035858e+02],
[6.30496216e+00, 8.03030090e+01, 1.03666016e+02],
[1.09278259e+01, 8.44103394e+01, 1.05822449e+02]]],

[[6.93754272e+01, 1.36375427e+02, 1.27375427e+02],
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[6.37374268e+01, 1.30907776e+02, 1.20166351e+02],
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[4.83398438e+00, 8.55468750e+01, 1.07787872e+02],
[3.83468628e+00, 7.90951538e+01, 1.01364685e+02],
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[6.47311401e+00, 1.17048584e+02, 1.63538818e+02],
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[1.08769531e+01, 1.17355469e+02, 1.71873474e+02],
[1.40942993e+01, 1.22287201e+02, 1.77522491e+02],
[7.30227661e+00, 1.15571808e+02, 1.70841339e+02]]],

[[4.14184570e+00, 1.16481781e+02, 1.68147797e+02],
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[7.52816772e+00, 1.20229340e+02, 1.72544250e+02],
...,
[1.31375427e+01, 1.20802521e+02, 1.77135010e+02],
[8.54153442e+00, 1.18209503e+02, 1.74227356e+02],
[5.42700195e+00, 1.15188721e+02, 1.71188721e+02]]],

[[1.08750000e+01, 1.23843750e+02, 1.79843750e+02],
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[4.46875000e+00, 1.15375000e+02, 1.71421875e+02],
[5.96875000e+00, 1.16968750e+02, 1.72968750e+02]]],

[[[1.78000000e+02, 2.25000000e+02, 2.53000000e+02],
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[1.77218750e+02, 2.24218750e+02, 2.52218750e+02],
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[1.47754944e+02, 1.90300720e+02, 2.22300720e+02],
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...,
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[3.30000000e+01, 3.30000000e+01, 3.30000000e+01],
[3.30000000e+01, 3.30000000e+01, 3.30000000e+01]]],

```

```
[[[3.64218750e+01, 3.64218750e+01, 3.64218750e+01],
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[[[3.90000000e+01, 3.90000000e+01, 3.90000000e+01],
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...,

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[5.80000000e+01, 3.00000000e+01, 1.90000000e+01]],

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[2.45465698e+01, 1.07207031e+01, 1.07207031e+01],
...,
[5.38593750e+01, 2.58593750e+01, 1.48593750e+01],
[5.50019531e+01, 2.70019531e+01, 1.60019531e+01],
[5.88593750e+01, 3.08593750e+01, 1.98593750e+01]],

[[[3.35937500e+01, 1.80625000e+01, 1.80625000e+01],
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...,
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[6.00428772e+01, 3.20428772e+01, 2.10428772e+01],
[5.97656250e+01, 3.17656250e+01, 2.07656250e+01]]],

...,

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[0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
...,
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[0.00000000e+00, 0.00000000e+00, 0.00000000e+00]],

[[[0.00000000e+00, 0.00000000e+00, 0.00000000e+00],
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...,
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...,
[2.47656250e+00, 2.47656250e+00, 2.47656250e+00],
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[0.00000000e+00, 0.00000000e+00, 0.00000000e+00]]],

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...,
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[4.30000000e+01, 9.70000000e+01, 1.61000000e+02]],

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[1.20409546e+01, 4.80409546e+01, 7.40409546e+01],
...,
[4.30000000e+01, 9.70000000e+01, 1.61000000e+02],
[4.30000000e+01, 9.70000000e+01, 1.61000000e+02],
[4.30000000e+01, 9.70000000e+01, 1.61000000e+02]],

[[[1.20000000e+01, 4.80000000e+01, 7.40000000e+01],
```

```

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[4.30000000e+01, 9.70000000e+01, 1.61000000e+02],
[4.30000000e+01, 9.70000000e+01, 1.61000000e+02]],
...,

[[1.50000000e+01, 1.10000000e+01, 1.20000000e+01],
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[1.50000000e+01, 1.10000000e+01, 1.20000000e+01],
...,
[1.00000000e+00, 3.20000000e+01, 6.30000000e+01],
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[1.00000000e+00, 3.20000000e+01, 6.30000000e+01]],

[[1.50000000e+01, 1.10000000e+01, 1.20000000e+01],
[1.50000000e+01, 1.10000000e+01, 1.20000000e+01],
[1.50000000e+01, 1.10000000e+01, 1.20000000e+01],
...,
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[1.00000000e+00, 3.20000000e+01, 6.30000000e+01],
[1.00000000e+00, 3.20000000e+01, 6.30000000e+01]],

[[1.50000000e+01, 1.10000000e+01, 1.20000000e+01],
[1.50000000e+01, 1.10000000e+01, 1.20000000e+01],
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...,
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[6.31113281e+01, 1.04111328e+02, 1.48111328e+02]],

[[3.70610428e+01, 4.60610428e+01, 2.90610428e+01],
[3.08105469e+01, 3.96992188e+01, 2.29218750e+01],
[3.11121941e+01, 3.91121941e+01, 2.41121941e+01],
...,
[6.80167084e+01, 1.07379280e+02, 1.53336838e+02],
[6.67949219e+01, 1.06586685e+02, 1.50237076e+02],
[6.36835938e+01, 1.03539062e+02, 1.46966797e+02]],

[[3.17436256e+01, 4.01694069e+01, 2.34565163e+01],
[2.98805542e+01, 3.81950073e+01, 2.17047729e+01],
[3.36024399e+01, 4.10282211e+01, 2.63153305e+01],
...,
[7.30402832e+01, 1.09604736e+02, 1.53827393e+02],
[7.15292969e+01, 1.08982422e+02, 1.50801498e+02],
[6.81415100e+01, 1.05705963e+02, 1.47270416e+02]],

...,

[[9.12762604e+01, 7.25898209e+01, 6.46278229e+01],
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[6.78729095e+01, 4.98729057e+01, 3.90341377e+01],
...,
[4.94336205e+01, 3.61768837e+01, 3.98136024e+01],
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...,
[5.40664749e+01, 4.35013084e+01, 5.05535164e+01],
[4.90478020e+01, 4.13600235e+01, 5.21647110e+01],
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[[5.70000000e+01, 4.00000000e+01, 3.29628906e+01],
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[6.45878906e+01, 4.75878906e+01, 3.92167969e+01],
...,
[6.08867188e+01, 5.21445312e+01, 6.18457031e+01],
[4.95585938e+01, 4.51132812e+01, 5.87792969e+01],
[3.74082031e+01, 3.34082031e+01, 4.74082031e+01]]],
dtype=float32),
array([3, 1, 1, 3, 4, 2, 2, 4, 4, 1, 2, 2, 0, 3, 1, 0, 2, 4, 2, 4, 0, 0,
4, 1, 2, 3, 3, 4, 0, 2, 2, 0]))

```

In []: batch[0].shape # 32 images, 256x256 size, 3 channels(rgb)


```
Out[ ]: (32, 256, 256, 3)
```

```
In [ ]: # first image  
batch[0][0]
```

```
Out[ ]: array([[0.      , 0.      , 0.      ],  
              [0.      , 0.      , 0.      ],  
              [0.      , 0.      , 0.      ],  
              ...,  
              [0.      , 0.      , 0.      ],  
              [0.      , 0.      , 0.      ],  
              [0.      , 0.      , 0.      ]],  
          [[0.      , 0.      , 0.      ],  
           [0.      , 0.      , 0.      ],  
           [0.      , 0.      , 0.      ],  
           ...,  
           [0.      , 0.      , 0.      ],  
           [0.      , 0.      , 0.      ],  
           [0.      , 0.      , 0.      ]],  
          [[0.      , 0.      , 0.      ],  
           [0.      , 0.      , 0.      ],  
           [0.      , 0.      , 0.      ],  
           ...,  
           [0.      , 0.      , 0.      ],  
           [0.      , 0.      , 0.      ],  
           [0.      , 0.      , 0.      ]],  
          ...,  
          [[0.      , 0.015625, 0.      ],  
           [0.      , 0.015625, 0.      ],  
           [0.      , 0.015625, 0.      ],  
           ...,  
           [0.      , 0.015625, 0.      ],  
           [0.      , 0.015625, 0.      ],  
           [0.      , 0.015625, 0.      ]],  
          [[3.390625, 0.      , 0.      ],  
           [3.390625, 0.      , 0.      ],  
           [3.390625, 0.      , 0.      ],  
           ...,  
           [3.390625, 0.      , 0.      ],  
           [3.390625, 0.      , 0.      ],  
           [3.390625, 0.      , 0.      ]],  
          [[5.59375 , 0.      , 0.      ],  
           [5.59375 , 0.      , 0.      ],  
           [5.59375 , 0.      , 0.      ],  
           ...,  
           [5.59375 , 0.      , 0.      ],  
           [5.59375 , 0.      , 0.      ],  
           [5.59375 , 0.      , 0.      ]]], dtype=float32)
```

```
In [ ]: # min value in the array  
batch[0][0].min()
```

```
Out[ ]: 0.0
```

```
In [ ]: # max value in the array  
batch[0][0].max()
```

```
Out[ ]: 249.68848
```

Data Preprocesssing

```
In [ ]: data
```

```
Out[ ]: < PrefetchDataset element_spec=(TensorSpec(shape=(None, 256, 256, 3), dtype=tf.float32, name=None), TensorSpec(shape=(None,), dtype=tf.int32, name=None))>
```

```
In [ ]: data = data.map(lambda x,y : (x/255,y))
```

```
In [ ]: data.as_numpy_iterator().next()[0].min() # now the min value is 0
```

```
Out[ ]: 0.0
```

```
In [ ]: data.as_numpy_iterator().next()[0].max() # now the max value is 1
```

```
Out[ ]: 1.0
```

```
In [ ]: len(data) # split by 11b+2+2
```

```
Out[ ]: 38
```

```
In [ ]: # splitting test, train data
```

```
train = data.take(28)
val = data.skip(28).take(5)
test = data.skip(33).take(5)
```

Model Training

Building Model

```
In [ ]: from tensorflow.keras.models import Sequential
        from tensorflow.keras.layers import Conv2D, MaxPooling2D, Dense, Flatten, Dropout
```

```
In [ ]: model=Sequential()
```

```
In [ ]: # 1st layer
        """
        convo network with 16 filters of size 3*3 with stride 1
        activation fn - relu
        input shape- 256*256*3 . here 3 is 3 channel(rgb)

        """
        model.add(Conv2D(16, (3, 3), 1, activation="relu", input_shape=(256, 256, 3)))
        model.add(
            MaxPooling2D()
        ) # max pooling layer of size (2,2). takes the maximum over the input window
        model.add(Dropout(0.25)) # Add dropout after the first convolutional layer

        # 2nd layer
        """
        convo network with 32 filters of size 3*3 with stride 1
        activation fn - relu

        """
        model.add(Conv2D(32, (3, 3), 1, activation="relu"))
        model.add(
            MaxPooling2D()
        ) # max pooling layer of size (2,2). takes the maximum over the input window
        model.add(Dropout(0.25)) # Add dropout after the second convolutional layer

        # 3rd layer
        """
        convo network with 16 filters of size 3*3 with stride 1
        activation fn - relu

        """
        model.add(Conv2D(16, (3, 3), 1, activation="relu"))
        model.add(
            MaxPooling2D()
        ) # max pooling layer of size (2,2). takes the maximum over the input window
        model.add(Dropout(0.25)) # Add dropout after the third convolutional layer

        # flattening to 1D array
        model.add(Flatten())

        # building dense(fully connected) neuron network with 256 neurons
        model.add(Dense(256, activation="relu"))
        model.add(Dropout(0.5)) # Add dropout after the dense layer

        # output layer with 4 neurons (4-class classification - so softmax).
        model.add(Dense(5, activation="softmax"))
```

```
In [ ]: model.compile(optimizer='adam', loss='sparse_categorical_crossentropy', metrics=['accuracy'])
```

```
In [ ]: model.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
=====		
conv2d (Conv2D)	(None, 254, 254, 16)	448
max_pooling2d (MaxPooling2D)	(None, 127, 127, 16)	0
dropout (Dropout)	(None, 127, 127, 16)	0
conv2d_1 (Conv2D)	(None, 125, 125, 32)	4640
max_pooling2d_1 (MaxPooling2D)	(None, 62, 62, 32)	0
dropout_1 (Dropout)	(None, 62, 62, 32)	0
conv2d_2 (Conv2D)	(None, 60, 60, 16)	4624
max_pooling2d_2 (MaxPooling2D)	(None, 30, 30, 16)	0
dropout_2 (Dropout)	(None, 30, 30, 16)	0
flatten (Flatten)	(None, 14400)	0
dense (Dense)	(None, 256)	3686656
dropout_3 (Dropout)	(None, 256)	0
dense_1 (Dense)	(None, 5)	1285
=====		
Total params: 3697653 (14.11 MB)		
Trainable params: 3697653 (14.11 MB)		
Non-trainable params: 0 (0.00 Byte)		

Training Model

```
In [ ]: logdir = 'logs'
```

```
In [ ]: tensorboard_callback = tf.keras.callbacks.TensorBoard(log_dir=logdir)
```

```
In [ ]: hist = model.fit(
    train, epochs=40, validation_data=val, callbacks=[tensorboard_callback])
```

```

Epoch 1/40
28/28 [=====] - 67s 2s/step - loss: 1.9634 - accuracy: 0.2455 - val_loss: 1.6073 - val
_accuracy: 0.2562
Epoch 2/40
28/28 [=====] - 61s 2s/step - loss: 1.5503 - accuracy: 0.2857 - val_loss: 1.5943 - val
_accuracy: 0.2625
Epoch 3/40
28/28 [=====] - 40s 1s/step - loss: 1.5215 - accuracy: 0.3292 - val_loss: 1.5443 - val
_accuracy: 0.4125
Epoch 4/40
28/28 [=====] - 41s 1s/step - loss: 1.4739 - accuracy: 0.3806 - val_loss: 1.5057 - val
_accuracy: 0.4938
Epoch 5/40
28/28 [=====] - 35s 1s/step - loss: 1.4103 - accuracy: 0.4431 - val_loss: 1.4262 - val
_accuracy: 0.4688
Epoch 6/40
28/28 [=====] - 35s 1s/step - loss: 1.3063 - accuracy: 0.4944 - val_loss: 1.3323 - val
_accuracy: 0.5437
Epoch 7/40
28/28 [=====] - 49s 2s/step - loss: 1.1995 - accuracy: 0.5301 - val_loss: 1.2266 - val
_accuracy: 0.5562
Epoch 8/40
28/28 [=====] - 43s 1s/step - loss: 1.0853 - accuracy: 0.5636 - val_loss: 1.0951 - val
_accuracy: 0.5938
Epoch 9/40
28/28 [=====] - 45s 1s/step - loss: 0.9898 - accuracy: 0.6306 - val_loss: 0.9127 - val
_accuracy: 0.7188
Epoch 10/40
28/28 [=====] - 44s 2s/step - loss: 0.8802 - accuracy: 0.6629 - val_loss: 0.9952 - val
_accuracy: 0.6687
Epoch 11/40
28/28 [=====] - 48s 2s/step - loss: 0.8127 - accuracy: 0.6942 - val_loss: 0.9897 - val
_accuracy: 0.6500
Epoch 12/40
28/28 [=====] - 51s 2s/step - loss: 0.7774 - accuracy: 0.7176 - val_loss: 0.8579 - val
_accuracy: 0.6875
Epoch 13/40
28/28 [=====] - 51s 2s/step - loss: 0.6417 - accuracy: 0.7556 - val_loss: 0.7912 - val
_accuracy: 0.7250
Epoch 14/40
28/28 [=====] - 52s 2s/step - loss: 0.5469 - accuracy: 0.7958 - val_loss: 0.6187 - val
_accuracy: 0.8062
Epoch 15/40
28/28 [=====] - 52s 2s/step - loss: 0.5153 - accuracy: 0.8080 - val_loss: 0.6016 - val
_accuracy: 0.7937
Epoch 16/40
28/28 [=====] - 53s 2s/step - loss: 0.4323 - accuracy: 0.8516 - val_loss: 0.5970 - val
_accuracy: 0.8125
Epoch 17/40
28/28 [=====] - 52s 2s/step - loss: 0.3844 - accuracy: 0.8650 - val_loss: 0.5217 - val
_accuracy: 0.8062
Epoch 18/40
28/28 [=====] - 51s 2s/step - loss: 0.3967 - accuracy: 0.8739 - val_loss: 0.3933 - val
_accuracy: 0.8687
Epoch 19/40
28/28 [=====] - 51s 2s/step - loss: 0.3620 - accuracy: 0.8705 - val_loss: 0.5126 - val
_accuracy: 0.8313
Epoch 20/40
28/28 [=====] - 51s 2s/step - loss: 0.3520 - accuracy: 0.8739 - val_loss: 0.4980 - val
_accuracy: 0.8313
Epoch 21/40
28/28 [=====] - 52s 2s/step - loss: 0.2713 - accuracy: 0.9062 - val_loss: 0.3270 - val
_accuracy: 0.8750
Epoch 22/40
28/28 [=====] - 52s 2s/step - loss: 0.2444 - accuracy: 0.9196 - val_loss: 0.3705 - val
_accuracy: 0.8938
Epoch 23/40
28/28 [=====] - 54s 2s/step - loss: 0.2158 - accuracy: 0.9375 - val_loss: 0.2986 - val
_accuracy: 0.9062
Epoch 24/40
28/28 [=====] - 52s 2s/step - loss: 0.1885 - accuracy: 0.9386 - val_loss: 0.3686 - val
_accuracy: 0.8875
Epoch 25/40
28/28 [=====] - 66s 2s/step - loss: 0.2291 - accuracy: 0.9208 - val_loss: 0.3597 - val
_accuracy: 0.9062
Epoch 26/40
28/28 [=====] - 62s 2s/step - loss: 0.1891 - accuracy: 0.9364 - val_loss: 0.3924 - val
_accuracy: 0.8750
Epoch 27/40
28/28 [=====] - 63s 2s/step - loss: 0.1506 - accuracy: 0.9598 - val_loss: 0.3549 - val
_accuracy: 0.9000
Epoch 28/40
28/28 [=====] - 839s 31s/step - loss: 0.1476 - accuracy: 0.9565 - val_loss: 0.3384 - v
al_accuracy: 0.9250
Epoch 29/40
28/28 [=====] - ETA: 0s - loss: 0.1307 - accuracy: 0.9576

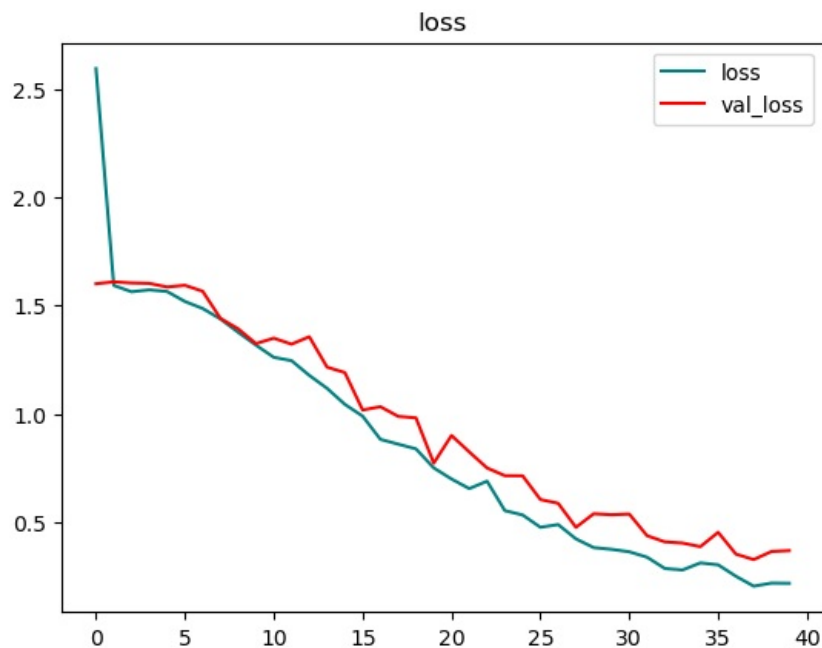
```

```
In [ ]: hist.history.keys()
```

```
Out[ ]: dict_keys(['loss', 'accuracy', 'val_loss', 'val_accuracy'])
```

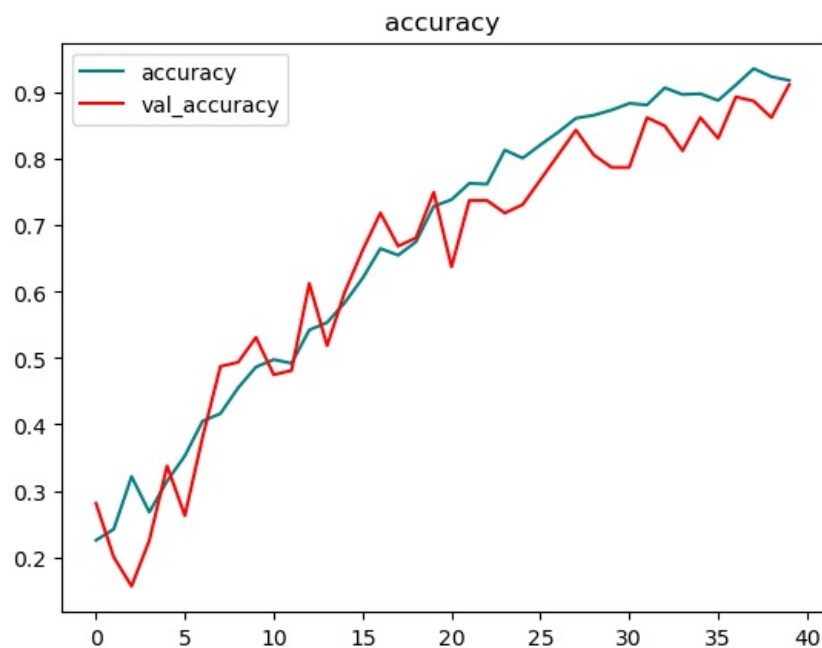
```
In [ ]: import matplotlib.pyplot as plt
plt.plot(hist.history["loss"], color="teal", label="loss")
plt.plot(hist.history["val_loss"], color="red", label="val_loss")
plt.legend()
plt.title("loss")
```

```
Out[ ]: Text(0.5, 1.0, 'loss')
```



```
In [ ]: plt.plot(hist.history["accuracy"], color="teal", label="accuracy")
plt.plot(hist.history["val_accuracy"], color="red", label="val_accuracy")
plt.legend()
plt.title("accuracy")
```

```
Out[ ]: Text(0.5, 1.0, 'accuracy')
```



```
In [ ]: model.save(os.path.join("models", "debris_classifier_model_4.h5"))
```

```
c:\Users\mahig\anaconda3\Lib\site-packages\keras\src\engine\training.py:3079: UserWarning: You are saving your
model as an HDF5 file via `model.save()`. This file format is considered legacy. We recommend using instead the
native Keras format, e.g. `model.save('my_model.keras')`.
  saving_api.save_model(
```

Testing

```
In [ ]: from tensorflow.keras.metrics import Precision, Recall, CategoricalAccuracy
```

```
In [ ]: pre = Precision()
```

```
re = Recall()
acc = CategoricalAccuracy()
```

```
In [ ]: for batch in test.as_numpy_iterator():

    x, y = batch
    yhat = model.predict(x)
    # Assuming y contains the integer class labels (0 to 4) for 5 classes
    num_classes = 5
    y_one_hot = tf.one_hot(y, num_classes)

    # Now, you can use y_one_hot in the metrics update_state calls
    pre.update_state(y_one_hot, yhat)
    re.update_state(y_one_hot, yhat)
    acc.update_state(y_one_hot, yhat)
    # pre.update_state(y, yhat)
    # re.update_state(y, yhat)
    # acc.update_state(y, yhat)

1/1 [=====] - 1s 558ms/step
1/1 [=====] - 0s 222ms/step
1/1 [=====] - 0s 222ms/step
1/1 [=====] - 0s 229ms/step
1/1 [=====] - 0s 143ms/step
```

```
In [ ]: print(
    f"""
precision = {pre.result().numpy()},
Recall = {re.result().numpy()}
Accuracy = {acc.result().numpy()}
    """)
)
```

```
precision = 0.9032257795333862,
Recall = 0.8175182342529297
Accuracy = 0.8613138794898987
```

Importing the saved model

```
In [ ]: import tensorflow as tf
from tensorflow.keras.preprocessing import image
from tensorflow.keras.models import load_model
import numpy as np
saved_model = tf.keras.models.load_model(r'C:\Users\mahig\OneDrive\Desktop\Project\models\debris_classifier_mod
```

INPUT

```
In [ ]: import matplotlib.pyplot as plt
import matplotlib.image as mpimg

def plot_image(file_path):
    # Load the image
    img = mpimg.imread(file_path)

    # Display the image
    plt.imshow(img)
    plt.axis('off') # Turn off axis labels
    plt.show()

if __name__ == "__main__":
    # Replace 'your_image_path.jpg' with the actual file path of your image
    image_path = r'C:\Users\mahig\OneDrive\Desktop\Predicated Output\WhatsApp Image 2023-11-16 at 11.58.02_fbe1
    plot_image(image_path)
```



```
In [ ]: import os
import numpy as np
from PIL import Image

img_path = r"C:\Users\mahig\OneDrive\Desktop\Predicated Output\WhatsApp Image 2023-11-16 at 11.58.02_fbe15a8c.j

# Check if the file exists
if os.path.exists(img_path):
    try:
        img = Image.open(img_path)
        if img:
            # Resize the image to match the expected input shape of the model
            img = img.resize((256, 256))

            img_array = np.array(img) # Convert the image to a numpy array

            # Expand dimensions to match the expected input shape
            img_array = np.expand_dims(img_array, axis=0)

            # Normalize the image
            img_array = img_array / 255.0

            # Make the prediction
            prediction = model.predict(img_array)

            # Get the predicted class label
            predicted_class = np.argmax(prediction, axis=1)

            # Print the predicted class
            print("Predicted Class:", predicted_class)

            # Print additional information based on predicted class
            if predicted_class == 0:
                print("Predicted Output: Bottle")
            elif predicted_class == 1:
                print("Predicted Output: Fishnet")
                # Add more conditions for other classes as needed
            elif predicted_class == 2:
                print("Predicted Output: Metal")
                # Add more conditions for other classes as needed
            elif predicted_class == 3:
                print("Predicted Output: Plastic")
                # Add more conditions for other classes as needed
            elif predicted_class == 4:
                print("Predicted Output: Tyre")
                # Add more conditions for other classes as needed

            else:
                print(f"Unable to open the image file at {img_path}.")
        except Exception as e:
            print(f"Error: {e}")
    else:
        print(f"No file found at {img_path}. Please provide the correct path to the image.")
```

```
1/1 [=====] - 0s 63ms/step
Predicted Class: [3]
Predicted Output: Plastic
```