

Heuristic in AI [What, Why, How]

⑤

What is Heuristic? - Kind of guess / Kind of quick solⁿ in AI

→ Rule of thumb
(Greedy method)

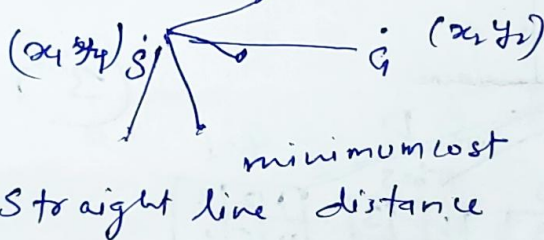
→ Heuristic Value low

- Heuristic function
↳ Guarantee - Good

NP → P

Optimal
(may be or not)

How / Euclidean distance



$$\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

Manhattan -

H/V

1	3	2
6	5	4
	8	7

1	2	3
4	5	6
7	8	

✓ $0 + 1 + 1 + 2 + 0 + 2$
 $+ 2 + 0 = 8$

✓ No. of misplaced tiles - 5

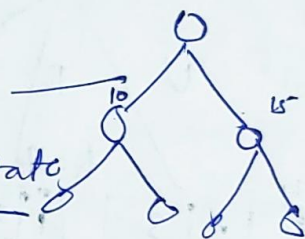
Why

$$\text{Cost} \times 2 = \text{Selling price}$$

$x = 100$
Cost price = this

All State

↓
goal state



exponentially grow

8 Puzzle

$$O(b^d)$$

3^{20}
 $3 \times 3 \times 4 \times 8$

15 Puzzle

Before

$$10^{13}$$

24 Puzzle

$$10^{24}$$

Time & space

↳ exponentially increase

NP

✓ Optimal

8-Puzzle with Heuristic - informed Search Tech (6)

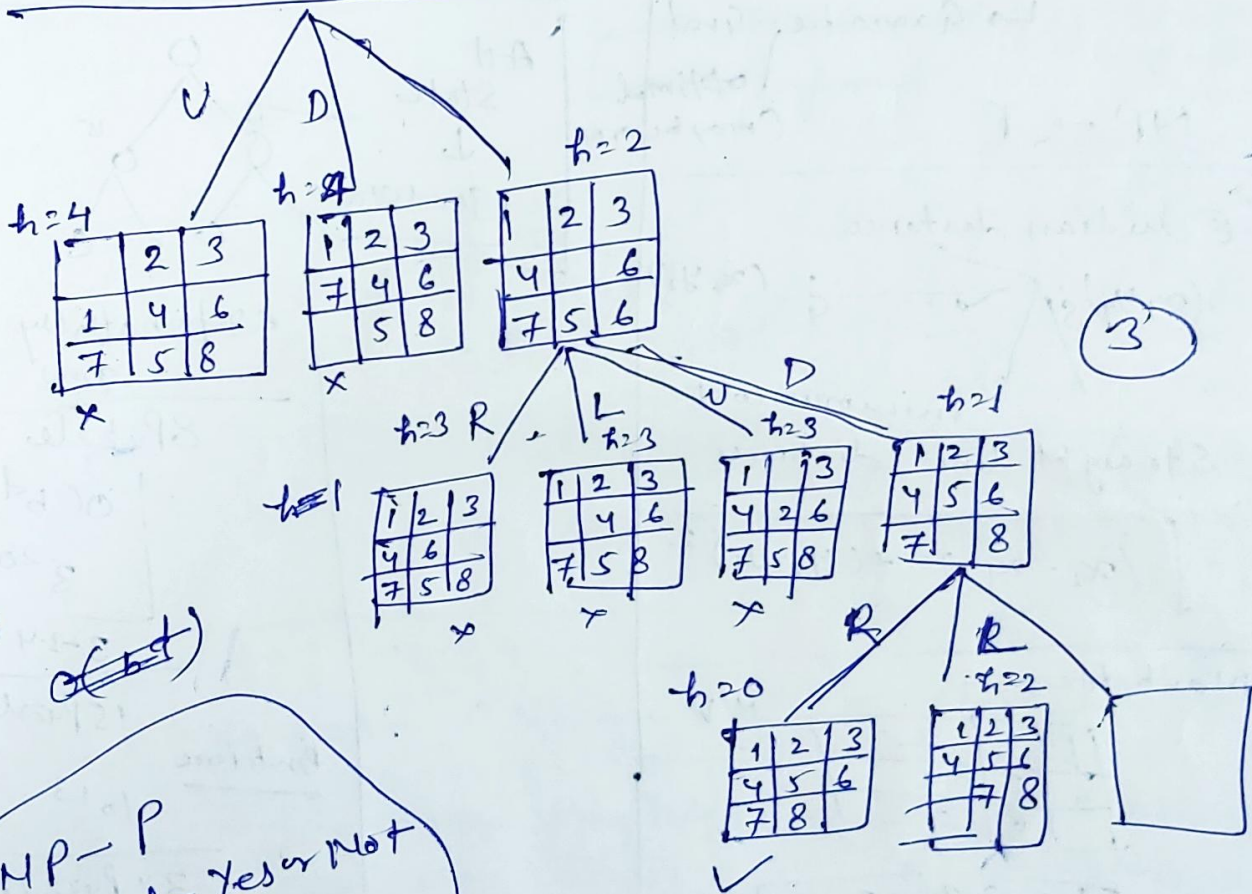
1	2	3
	4	6
7	5	8

S

1	2	3
4	5	6
7	8	

GT

$h =$ heuristic Value.

$$h = 3$$


NP - P
Optimal - Yes or Not
good solⁿ - Yes

Generate & Test

(Heuristic Techniques)

DFS with backtracking

Generate — Possible solⁿ.
Test — to see if this is Actual solⁿ.



Goal State Ach
solⁿ Accept

Properties of good generator

- Complete
↳ At least one solⁿ
- Non Redundant → No replica.
→ exponential increase
- Informed
↳ domain know.

100
0 0
0 0

100
0 0
0 0

100
0 0
0 1
0 2
0 3

3 No. Pin - 2 digit each

$$(100)^3 = 1M$$

exponential time
Brute force

$$1M = 5^7$$

$$1h = 5 \times 60 = 300 \text{ (linear = } \frac{N}{2} \text{)} = 5 \text{ lakh sol}^n \xrightarrow{24 \times 10^6}$$

heuristic → Problem Knowledge / → Domain Knowledge

0-99 0-99 0-99
00 00 00
25 25 25

Fireexp → All Non Prime

$$(25)^3 \text{ is } 1500$$

$$1M - 5 \times 60 = 30$$

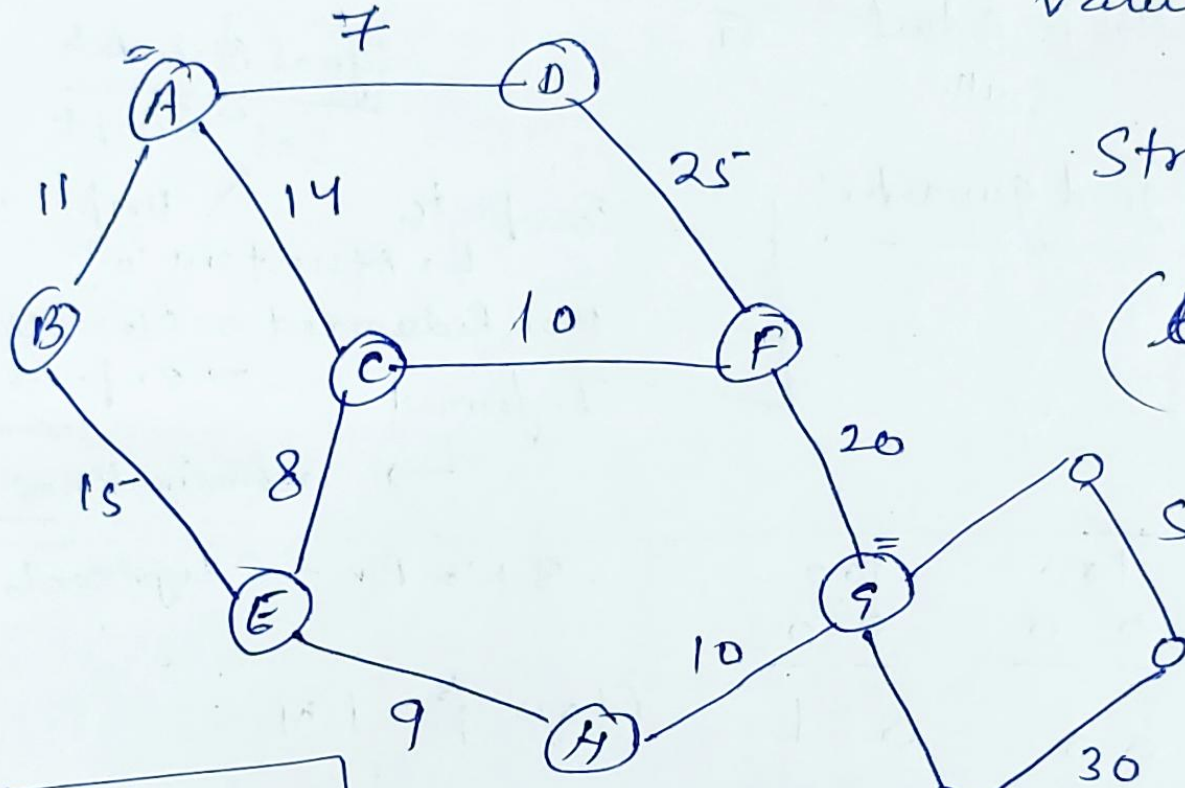
2 days.

Best first search — (Informed, Heuristic)

→ Select 'open' be a priority queue

(Node Heuristic

Value → priority



Straight line distance

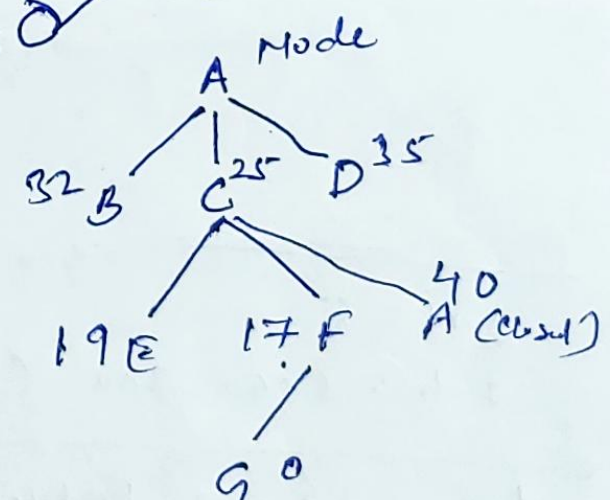
(Euclidean distance)

(Heuristic Value)

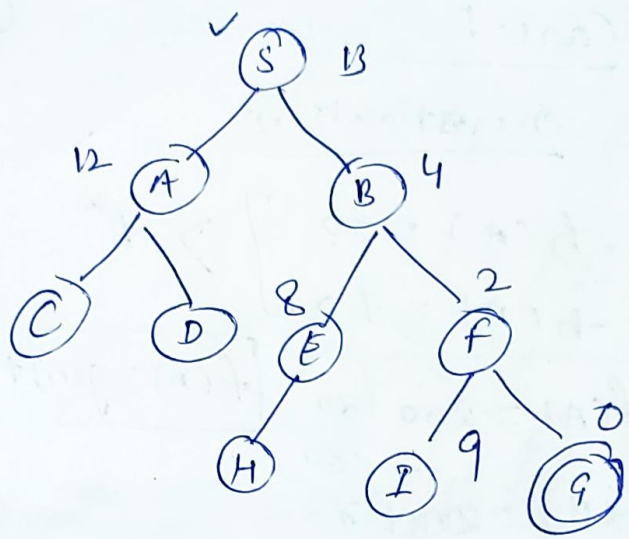
Less - best

A → G	= 40
B → G	= 32
C → G	= 25
D → G	= 35
E → G	= 19
F → G	= 17
H → G	= 10
G → G	= 0

~~A B D F E~~



A → C → F → G



node	h(v)
S	13
A	12
B	4
C	7
D	3
E	8
F	2
H	4
I	9
G	0

12
9

open close

Initialization

Open = {A, B} close [S]

① open {A}, close [S, B]

② open {E, A}, close [S, B, F]
 open {E, A}, close [S, B, F]

③ open {E, A, I, G}, close [S, B, F]
 open {E, A, I}, close [S, B, F, G]

S → B → F → G

A* Heuristic Algorithm

Informed search

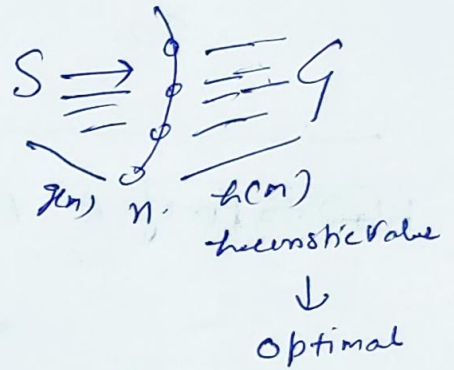
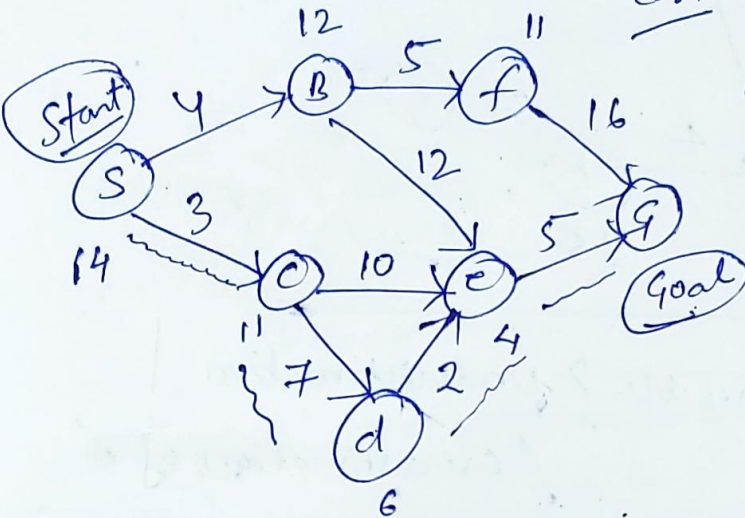
(10)

$$f(n) = g(n) + h(n)$$

Cost

Actual cost
from start node
to n

estimation
cost
from n to
Goal Node.



$$f(S) = 0 + 14 = 14$$

① $S \rightarrow B$ $S \rightarrow C$
 $4 + 12$ $3 + 11$
 $= 16$ $= 14$

② $SC \rightarrow E$ $SC \rightarrow D$
 $(3 + 10) + 4$ $(3 + 7) + 6$
 $= 17$ $= 16$

③ $SB \rightarrow f$ $SB \rightarrow e$
 $5 + 4 + 11$ $4 + 12 + 4$
 $= 20$ $= 20$

④ $SCD \rightarrow e$
 $3 + 7 + 2 + 4 = 16$

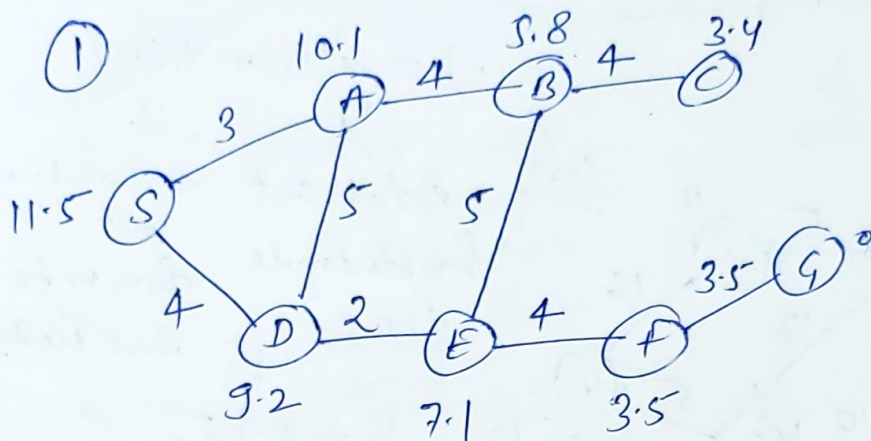
⑤ $SCDE \rightarrow G$
 $3 + 7 + 2 + 5 + 0 = 17$

Optimal cost = 17

$S \rightarrow C \rightarrow D \rightarrow E \rightarrow G$

$TC = A^* = O(V+E) \quad (O(b^d))$ $d \rightarrow \text{depth}$
 $SC = O(b^d)$ $b \rightarrow \text{branch}$

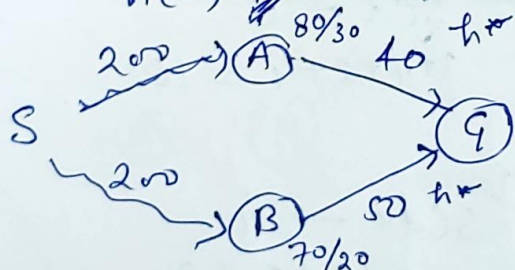
Underestimate
overestimate



How to Proof A^* Admissible? Underestimation / overestimation of A^*

$h(n) < h^*(n) \rightarrow$ Underestimation

$h(n) > h^*(n) \rightarrow$ overestimation.



$S \rightarrow n - G$
 $gen - h(n)$

Labtop: - optimal - 30000 / actual

estimation $\rightarrow ?$

Shop1 Shop2
Overestimation Underestimation

$40 > 30$

Next shop

~~20~~ 20 $20 < 30$

\downarrow
Next Shop

$h^*(n) \rightarrow$ optimal
 $h(n) -$ estimated

$$g(A) = 200$$

$$g(B) = 200$$

Case-2

Underestimation

Underestimation

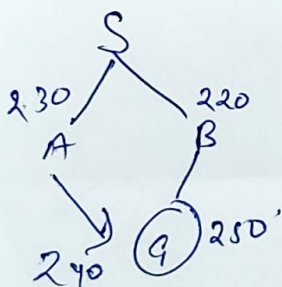
✗

$$h(A) = 30$$

$$h(B) = 20$$

$$f(A) = 200 + 30 = 230$$

$$f(B) = 200 + 20 = 220$$



$$f(G) = g(G) + h(G)$$

$$= 200 + 0$$

$$= 200$$

$$f(A/G) = g(A/G) + h(G)$$

$$= 240 + 0$$

Case-1

Overestimation

$$h(A) = 80$$

$$h(B) = 70$$

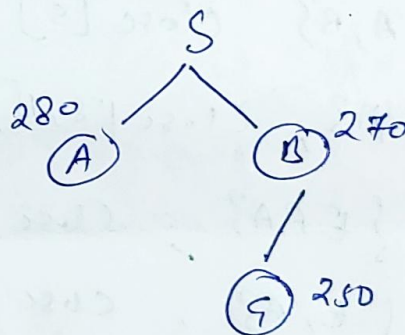
$> h^*$

$$f(A) = 200 + 80 = 280$$

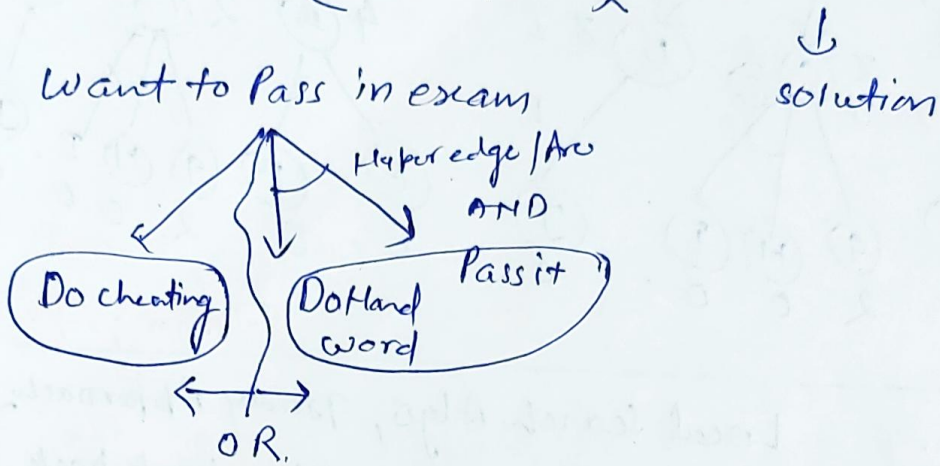
$$f(B) = 200 + 70 = 270$$

$$f(G) = g(G) + h(G)$$

$$= 200 + 0 = 200$$



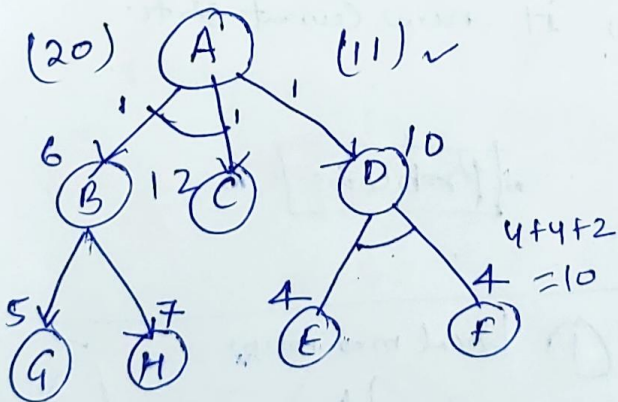
A_0^* \rightarrow Problem Decomposition (AND/OR) (13)
 (Break down ^{Complex} Problem to Smaller pieces.)

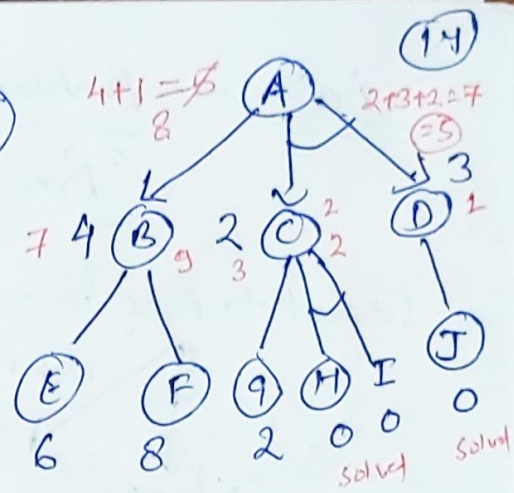
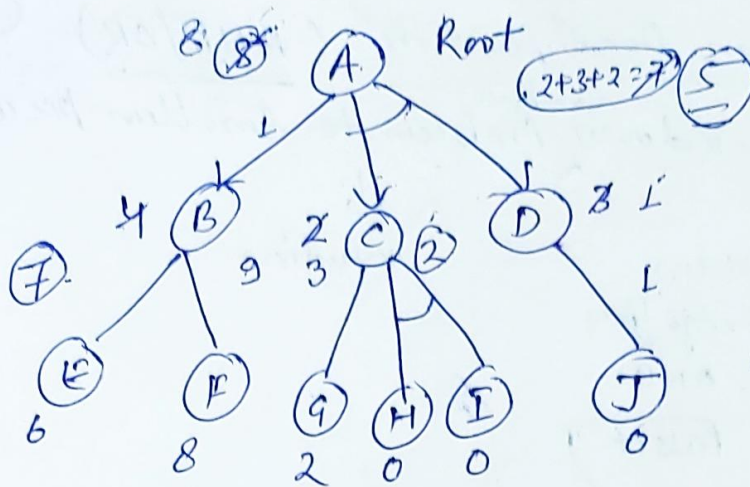


A_0^* $A^* \rightarrow$ informed Search

$A^* \rightarrow$ Underestimation
 \downarrow
 optimal

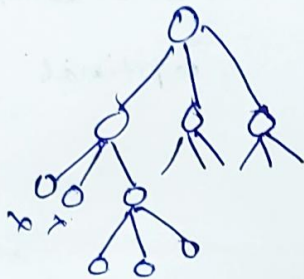
A_0^* does not explore all the solution paths once it got a solution



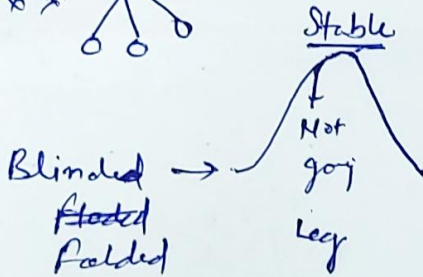


Solution graph

Hill climbing: - Local Search Algo, Greedy Approach, No. back track

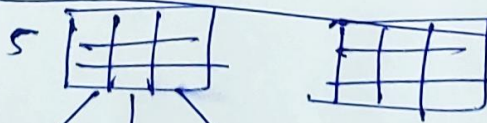


Find Best then stop

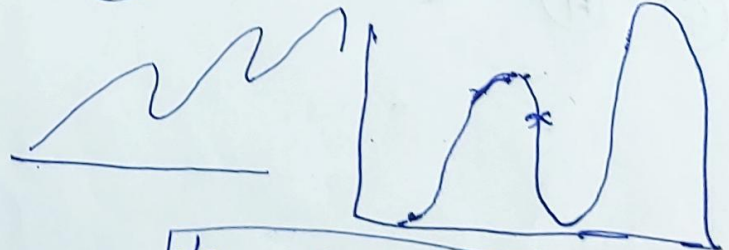


better than Current state then it new Current state.

Problems



① Local maximum

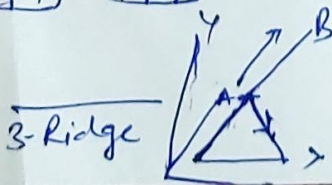


②

Plateau/flat maximum

Heuristic best ✓

Not Save in memory.



Exp: 8 puzzle. (Already discussed)

Tic-Tac-Toe

Heuristic-A*

0	0	X
X		0
		X

0	—
X	—

win

(15)

$E = X$'s winning Prob - O 's winning Probability

Heuristic Function

$E = 0 \rightarrow$ draw

$E = 1 \rightarrow$ Win

Present state

X's turn

0	0	X
X	X	0
		X

$$E = 2 - 0$$

0	0	X
X		0
X		X

$$E = 2 - 1 = 1$$

0	0	X
X		0
	X	X

$$E = 2 - 0$$

$$E = 2$$

O's turn

0	0	X
X	X	0
0		X

$$E = 0 - 0$$

Draw

X turn

0	0	X
X	X	0
0		X

$$E = 1 - 0$$

0	0	X
X	X	0
X	0	X

$$E = 1 (X)$$

0	0	X
X	0	0
X		X

$$E = 0$$

0	0	X
X	0	0
X	X	X

$$E = 1 \text{ win}(X)$$

0	0	X
X		0
X	0	X

$$E = 0$$

0	0	X
X	X	X
X	0	X

$$E = 1 \text{ win}(X)$$

0	0	X
X	X	0
	X	X

$$E = 1 - 0$$

$$1$$

0	0	X
X	X	0
X	X	X

$$E = 1 \text{ win}(X)$$

0	0	X
X		0
0	X	X

$$E = 0$$

Draw

This is best step.

Initial state

2	8	3
1	6	4
7		5

Final state

1	2	3
8		4
7	6	5

(16)

$$f(n) = g(n) + h(n)$$

$g(n)$ = depth of node

$h(n)$ = misplaced tiles

2	8	3
1	6	4
7		5

$g=0$

$h=4$

$f=4$

2	8	3
1	6	4
	7	5

$g=1$

$h=5$

$f=6$

2	8	3
1		4
7	6	5

$g=1$

$h=3$

$f=1+3=4$

2	8	3
2	6	4
7	5	

$g=1$

$h=5$

$f=1+5=6$

2	8	3
	1	4
7	6	5

$g=2$

$h=3$

$f=5$

2		3
1	8	4
7	6	5

$g=2$

$h=3$

$f=5$

2	8	3
1	4	
7	6	5

$g=2$

$h=4$

$f=6$

8	3	
2	1	4
7	6	5

$g=3$

$h=3$

$f=6$

2	8	3
7	1	4
	6	5

$g=3$

$h=4$

$f=7$

2	3	
1	8	4
7	6	5

$g=3$

$h=2$

$f=5$

2	3	
1	8	4
7	6	5

$g=3$

$h=4$

$f=7$

1	2	3
	8	4
7	6	5

$g=4$

$h=1$

$f=5$

Constraint Satisfaction Problem (CSP)

↳ way of representation is different

Informed / Uninformed (17)

↳ Tree - graph
state space

CSP (VDC)

V : - set of Variable (V_1, V_2, \dots, V_n)

D : - set of Domain ($D_1, D_2, D_3, \dots, D_n$) one for each Variable
real, whole, Alphabet, natural

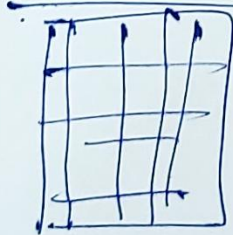
C : - set of Constraints (C_1, C_2, C_3) $V_1 - D_1$

↳ Kind of rule → Combination of values.

$C_i = (\text{Scope}, \text{rel})$

rel: - Value that Variable Take.

Scope - Set of Variable



9x9 = 81 Square
(3x3) - 9 box
| 1-9 |

(V_1, V_2)
| |
A B

(1,2) (2,4)

$C_i = ((V_1, V_2) \mid V_1 \neq V_2)$

$C_i = (V_1, V_2), (A, B)$

$C_i = (V_1, V_2) \mid (1,2)$

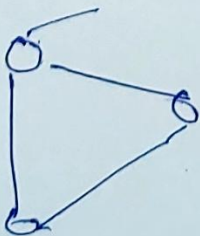
(1,4)

(2,4) }

Space: - Var - 81 -

domain → 1-9

Constraints: - Number not Same 3x3



Constraints - No Same Color in Neighbour

Active rule.