

# Ant Colony Optimization: A New Meta-heuristic

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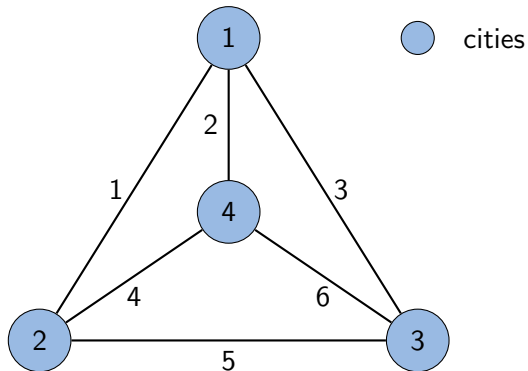
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# Problem Definition

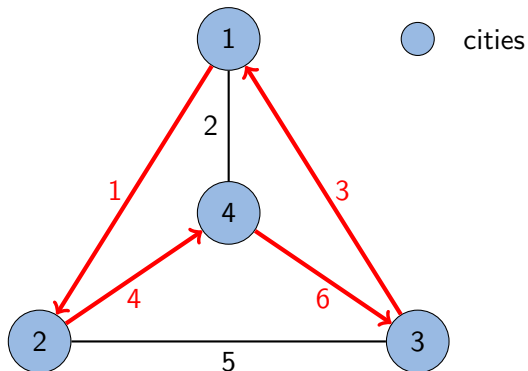
## The Traveling Salesman Problem

A salesman needs to visit a number of customers located in different cities and return to the starting city using the shortest route.

Input:



# Output:



# Known Methods

- Backtracking

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**We will use Ant Colony Optimization (ACO) to solve TSP more efficiently.**

# Ants collecting food-1

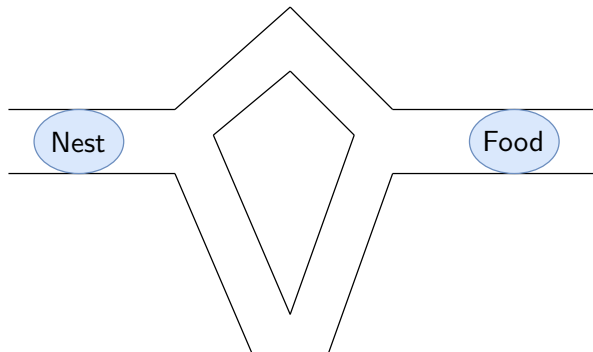


Figure: Paths From Food to Ants' Nest

## Ants collecting food-2

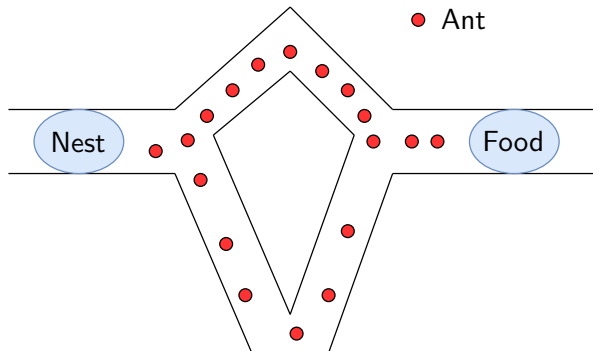


Figure: Ants Searching for Food

## Ants collecting food-3

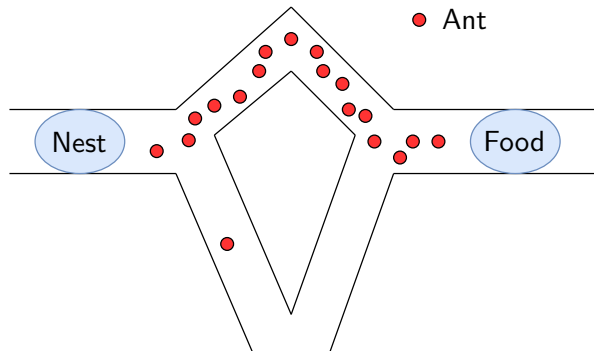


Figure: Ants Following An Optimal Path

So how do they communicate??

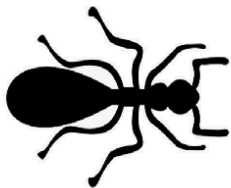
So how do they communicate??

# Pheromone



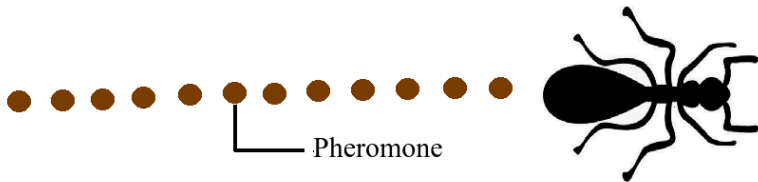
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# Pheromone



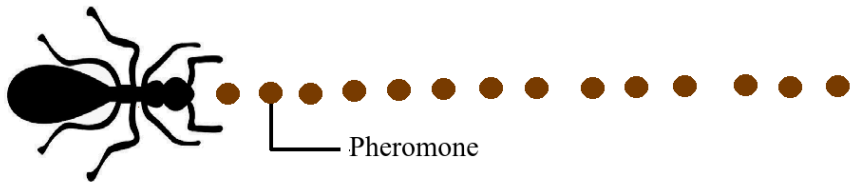
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## Pheromone



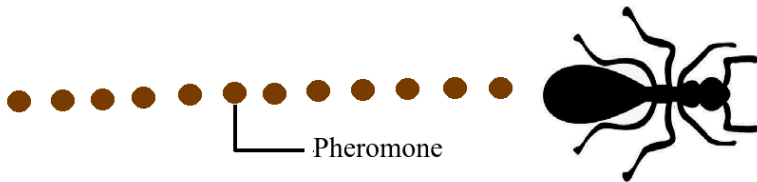
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## Pheromone



So how do they communicate??

## Pheromone



# Previous Works

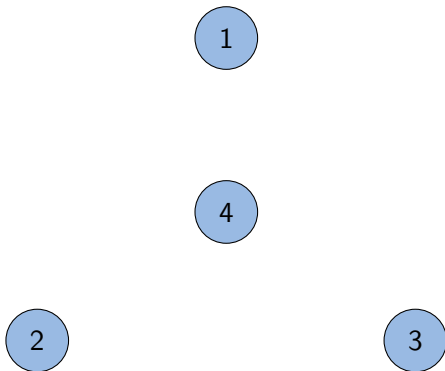
- In the year 1991, Marco Dorigo proposed an algorithm called "Ant System".
- AS was first applied to the Traveling Salesman Problem.



Figure: Marco Dorigo

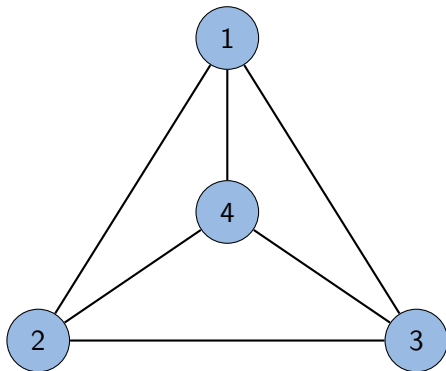
A more efficient algorithm to solve TSP is the ACO meta-heuristic.

# Notations



$C = \{c_1, c_2, \dots, c_{N_C}\}$  is the set of *cities*.

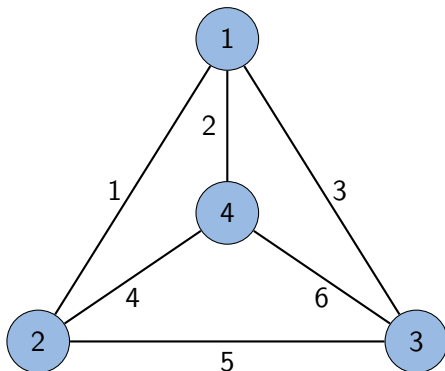
# Notations Continued..



$L = \{l_{c_i c_j} \mid (c_i, c_j) \in \tilde{\mathcal{C}}\}, |L| \leq N_C^2$   
is the set of *connections* between  
*cities*.

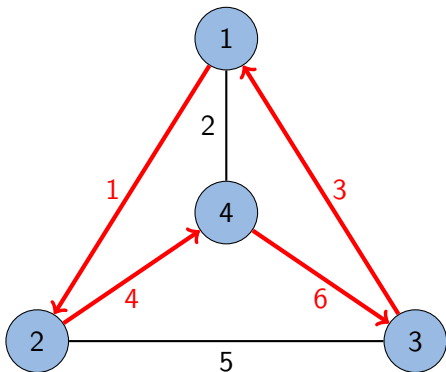


# Notations Continued..



$J_{c_i c_j} \equiv J(l_{c_i c_j})$  is a *cost* function associated with each *connection*  $l_{c_i c_j} \in L$ .

# Notations Continued..

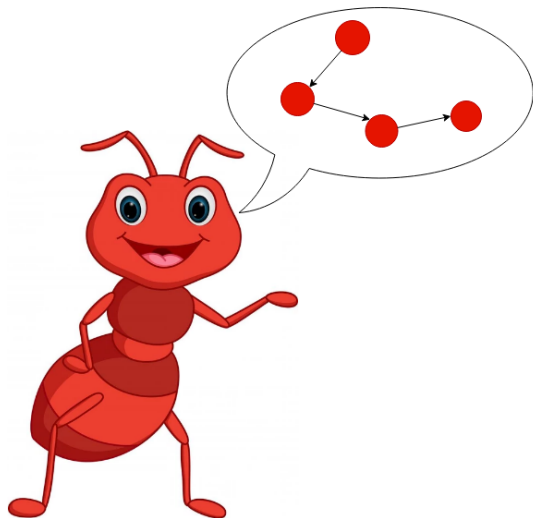


$J_\psi(L)$  is the *cost function* associated to each solution  $\psi$ . It is the summation of all the costs  $J(c_i, c_j)$  of all the connections belonging to the solution  $\psi$ .

The optimal cost here is  $1 + 4 + 6 + 3 = 14$

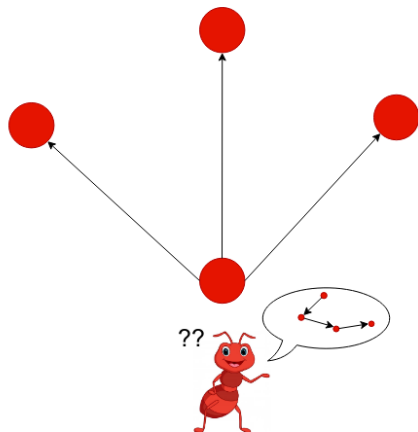
# Ant Properties

- Every ant has its own memory.



# Ant Properties Continued

- An ant chooses the next node to visit from its memory and the ant-routing table



# Ant Properties Continued

$$\begin{pmatrix} 0 & 5 & 3 & 1 \\ 4 & 0 & 1 & 6 \\ 9 & 3 & 0 & 9 \\ 12 & 4 & 15 & 0 \end{pmatrix}$$

Here,  $a_{ij}$  is a measurement of the quality of the edge from node  $i$  to node  $j$ .

Ant-routing table,  $a$

## Formula for ant-routing table

The formula for updating the ant-routing table is:

$$a_{ij} = \frac{[\tau_{ij}(t)]^\alpha [\eta_{ij}]^\beta}{\sum_{l \in \mathcal{N}_i} [\tau_{il}(t)]^\alpha [\eta_{il}]^\beta} \quad \forall j \in \mathcal{N}_i$$

- $\tau_{ij}$  is the intensity of pheromone trail of the edge  $l_{ij}$
- $\eta_{ij}$  is the heuristic value of the edge between  $i$  and  $j$ .

$$\eta_{ij} = \frac{1}{J_{c_i c_j}}$$

- $\alpha$  and  $\beta$  are two parameters that control the relative weight of pheromone trail and heuristic value.

## Formula for ant-routing table Continued

The probability  $p_{ij}^k(t)$  with which an ant  $k$  located in city  $i$  chooses the city  $j \in \mathcal{N}_i^k$  to move to at the  $t$ -th iteration is:

$$p_{ij}^k(t) = \frac{a_{ij}(t)}{\sum_{l \in \mathcal{N}_i^k} a_{il}(t)}$$

where  $\mathcal{N}_i^k \subseteq \mathcal{N}_i$  is the feasible neighborhood of node  $i$  for ant  $k$ .

# Pheromone Trail Evaporation

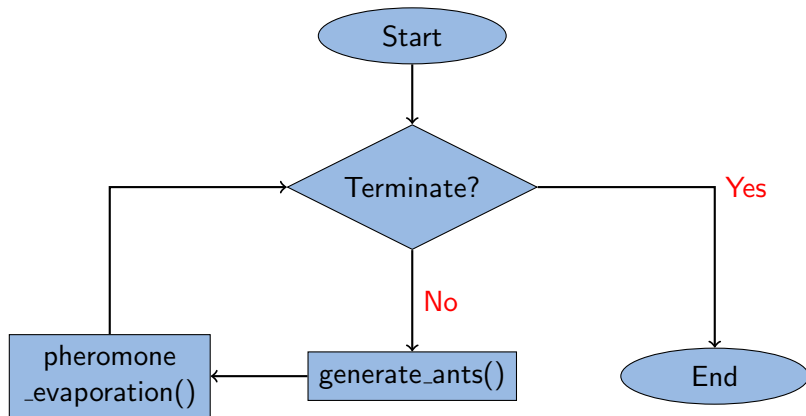
After pheromone updating has been performed by the ants, pheromone evaporation is triggered: the following rule is applied to all the edges  $l_{ij}$  of the graph  $G$

$$\tau_{ij}(t) \leftarrow (1 - \rho)\tau_{ij}(t)$$

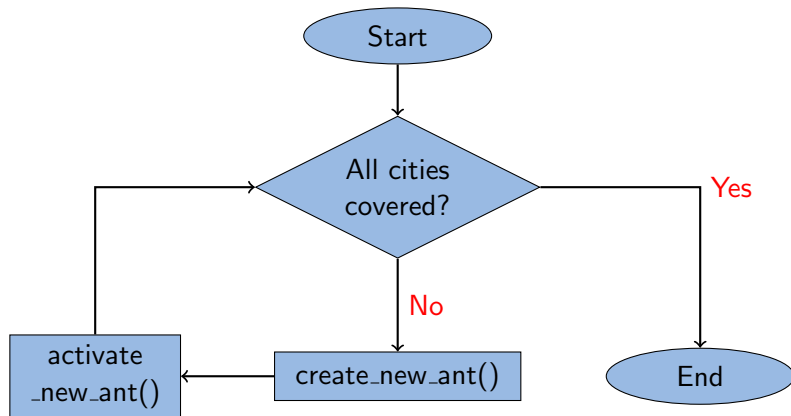
where  $\rho \in (0, 1]$  is the pheromone trail decay coefficient.



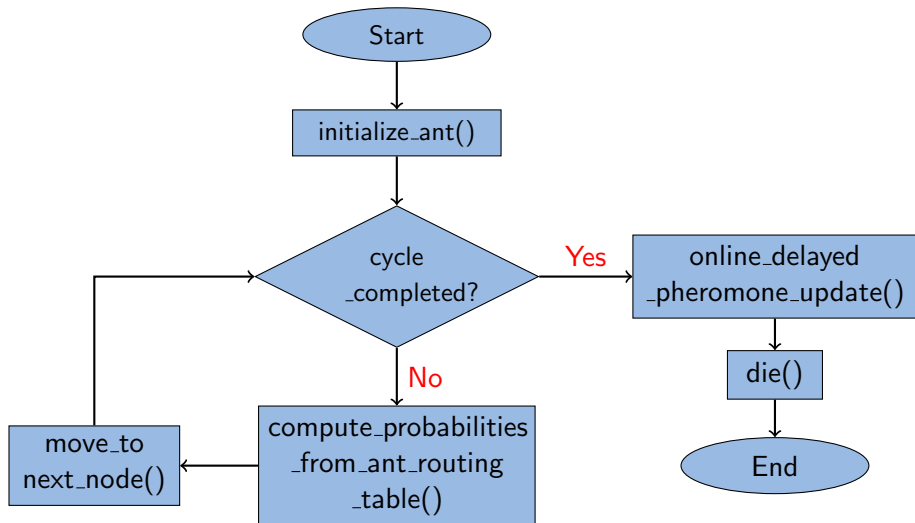
# procedure ACO\_meta-heuristic()



# procedure generate\_ants()



## procedure activate\_new\_ant() {Ant lifecycle}



# Conclusions

ACO is a new weapon to attack NP-hard graph problem!!