

# Ant Colony Optimization: A New Meta-heuristic

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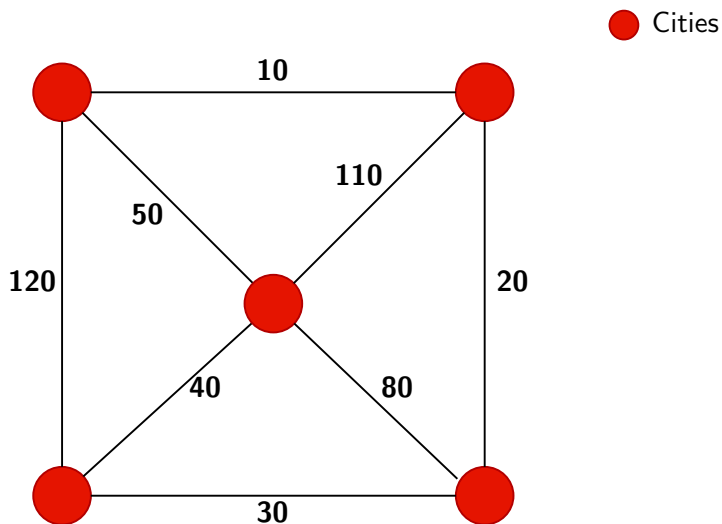
August 29, 2019

# Problem Definition

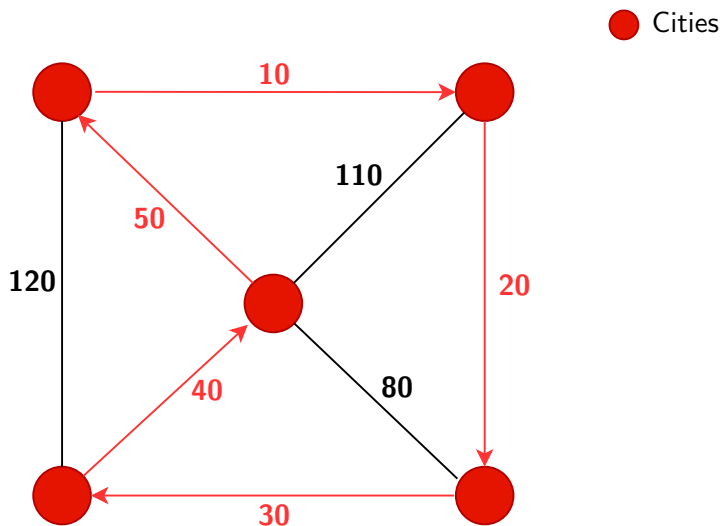
## The Traveling Salesman Problem

A salesman needs to visit a number of customers located in different cities and return to the starting city using the shortest route.

Input:



# Output:



# Known Methods

- Backtracking

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# Motivation

**We will use Ant Colony Optimization (ACO) to solve TSP more efficiently.**

# Ants collecting food-1

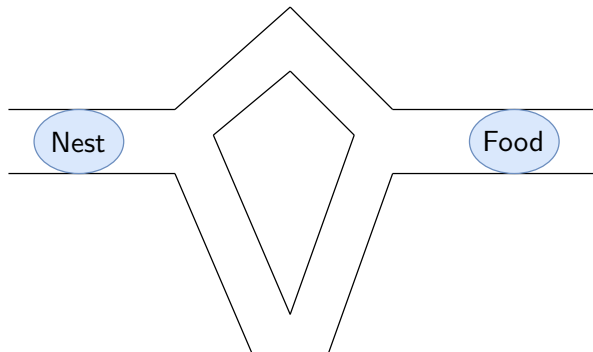


Figure: Paths From Food to Ants' Nest

## Ants collecting food-2

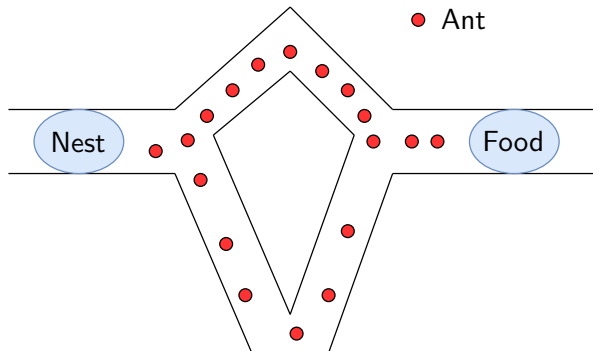


Figure: Ants Searching for Food

## Ants collecting food-3

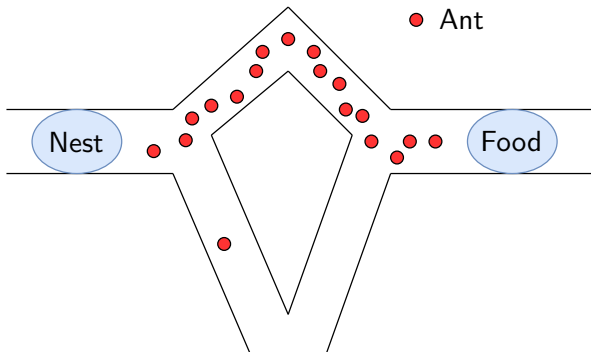


Figure: Ants Following An Optimal Path

So how do they communicate??

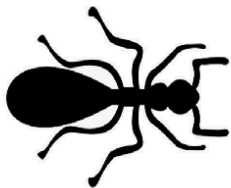
So how do they communicate??

# Pheromone



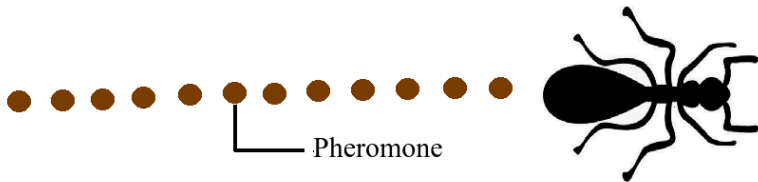
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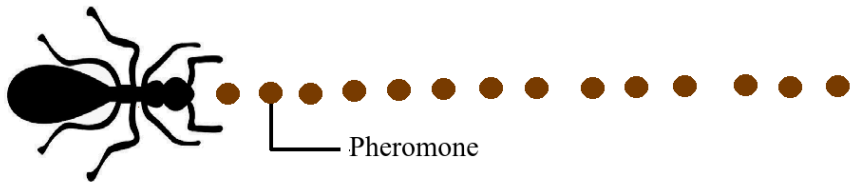
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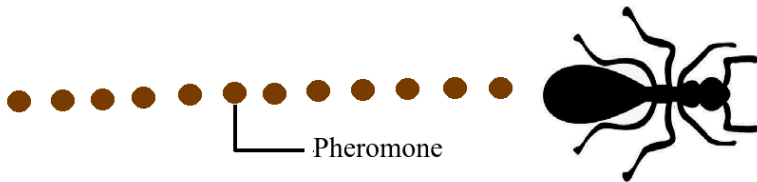
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## Pheromone



# Previous Works

- In the year 1991, Marco Dorigo proposed an algorithm called "Ant System".
- AS was first applied to the Traveling Salesman Problem.



Figure: Marco Dorigo

# Results

The ACO meta-heuristic is the result of an effort to define a common framework for all the versions of AS.

# Notations

- $C = \{c_1, c_2, \dots, c_{N_C}\}$  is a finite set of *components*.
- $L = \{l_{c_i c_j} \mid (c_i, c_j) \in \tilde{C}\}$ ,  $|L| \leq N_C^2$  is a finite set of possible *connections/transitions* among the elements of  $\tilde{C}$ , where  $\tilde{C}$  is a subset of the Cartesian product  $C \times C$ .
- $J_{c_i c_j} \equiv J(l_{c_i c_j}, t)$  is a *connection cost* function associated to each  $l_{c_i c_j} \in L$ , possibly parameterized by some time measure  $t$ .
- $\psi$  is a *solution* of the problem.
- $J_\psi(L, t)$  is a *cost* associated to each solution  $\psi$ .  $J_\psi(L, t)$  is a function of all the costs  $J(c_i, c_j)$  of all the connections belonging to the solution  $\psi$ .

# Adjacency Matrix

$$\begin{pmatrix}
 \times & \times & \times & \times \\
 0 & \times & \times & \times \\
 0 & 0 & \times & \times \\
 0 & 0 & 0 & \times \\
 a & b & c & d
 \end{pmatrix}$$

Here  $A(i,j)$  means row  $i$  and col  $j$



# Ant Properties

Ants of the colony have the following properties :

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- An ant  $k$  has a memory  $\mathcal{M}^k$  that it can use to store information on the path it followed so far. Memory can be used to build feasible solutions, to evaluate the solution found, and to retrace the path backward.
- An ant  $k$  located on node  $i$  can move to a node  $j$  chosen in  $\mathcal{N}_i^k$ . The move is selected applying a probabilistic decision rule.

## Ant properties continued...

- The ants' probabilistic decision rule is a function of (i) the values stored in a node local data structure  $\mathcal{A}_i = [a_{ij}]$  called ant-routing table, obtained by a functional composition of node locally available pheromone trails and heuristic values, (ii) the ant's private memory storing its past history, and (iii) the problem constraints.

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- When moving from node  $i$  to neighbor node  $j$  the ant can update the pheromone trail  $\tau_{ij}$  on the arc  $(i, j)$  This is called *online step-by-step pheromone update*.

## Ant properties continued...

- Once built a solution, the ant can retrace the same path backward and update the pheromone trails on the traversed arcs. This is called *online delayed pheromone update*.

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- Once it has built a solution, and, if the case, after it has retraced the path back to the source node, the ant dies, freeing all the allocated resources.

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- By moving, they incrementally build solutions to the problem.
- Once an ant has built a solution, it deposits information about the quality of the pheromone trails it used.

# How The Method Works continued...

Besides ants' activities an ACO algorithm might include too more procedures:

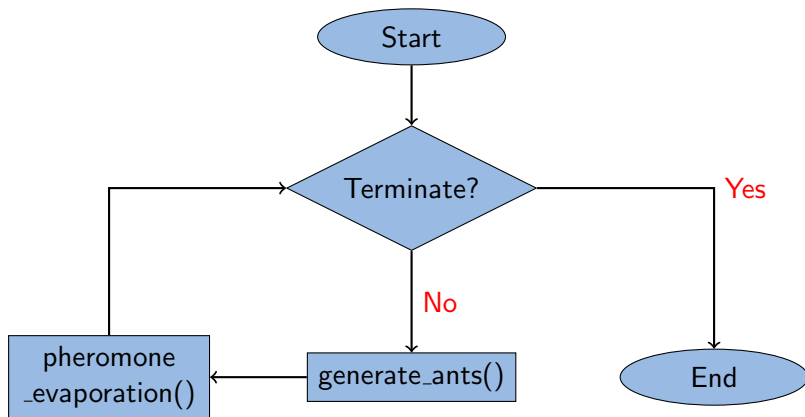
## Pheromone Trail Evaporation

The process by means of which the pheromone trail intensity on the connections automatically decreases over time.

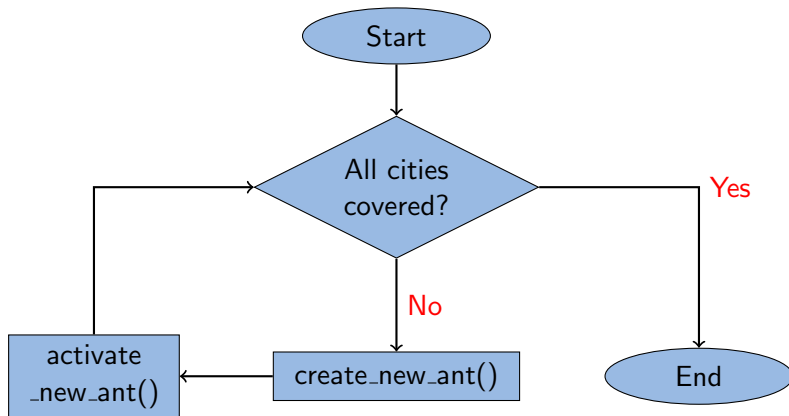
## Daemon Actions

Used to implement centralized actions which cannot be performed by single ants.

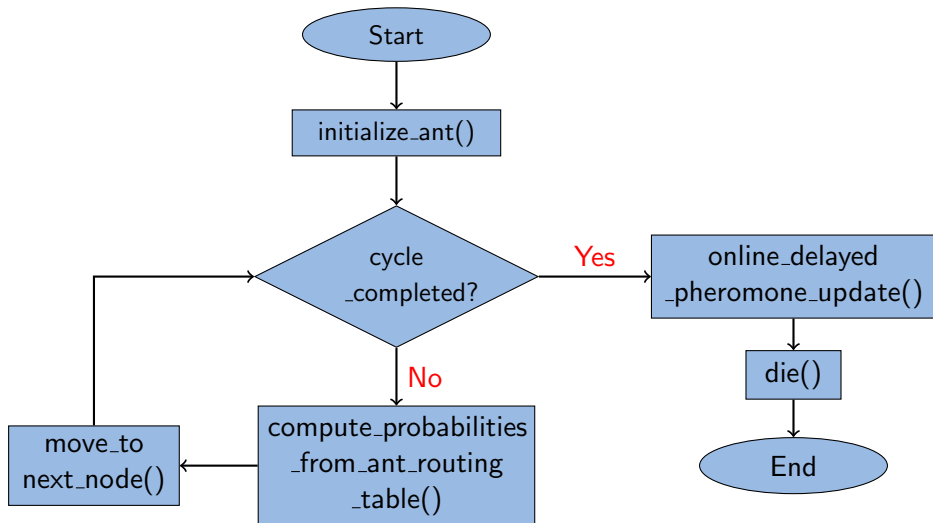
# procedure ACO\_meta-heuristic()



# procedure generate\_ants()



## procedure activate\_new\_ant() {Ant lifecycle}



# Traveling Salesman Problem

Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city and returns to the origin city?

# ACO for the Traveling Salesman Problem

- We construct a graph  $G = (C, L)$  where  $C$  is the set of components representing cities and  $L$  is the set of connections connecting the cities.
- $J_{c_i c_j}$  is the cost of the connection between the nodes  $c_i$  and  $c_j$ , the distance between cities  $i$  and  $j$ .
- A solution to this problem is a Hamiltonian circuit with minimal cost.



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- A number  $m$  of ants are positioned randomly in parallel on  $m$  cities. Then, they enter a cycle which lasts  $N_C$  iterations.

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- Once an ant has completed a tour, it uses its memory to evaluate the built solution. Then it retraces the same tour backward and updates the pheromone trails of the used edges.

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- Once an ant has completed a tour, it uses its memory to evaluate the built solution. Then it retraces the same tour backward and updates the pheromone trails of the used edges.
- It uses its memory to avoid visiting a city twice.

# ACO for the Traveling Salesman Problem Continued

The formula for updating the ant-routing table is:

$$a_{ij} = \frac{[\tau_{ij}(t)]^\alpha [\eta_{ij}]^\beta}{\sum_{l \in \mathcal{N}_i} [\tau_{il}(t)]^\alpha [\eta_{il}]^\beta} \quad \forall j \in \mathcal{N}_i$$

- $\tau_{ij}$  is the intensity of pheromone trail of the edge  $l_{ij}$
- $\eta_{ij}$  is the heuristic value of the edge between  $i$  and  $j$ .

$$\eta_{ij} = \frac{1}{J_{c_i c_j}}$$

- $\alpha$  and  $\beta$  are two parameters that control the relative weight of pheromone trail and heuristic value.

# ACO for the Traveling Salesman Problem Continued

The probability  $p_{ij}^k(t)$  with which an ant  $k$  located in city  $i$  chooses the city  $j \in \mathcal{N}_i^k$  to move to at the  $t$ -th iteration is:

$$p_{ij}^k(t) = \frac{a_{ij}(t)}{\sum_{l \in \mathcal{N}_i^k} a_{il}(t)}$$

where  $\mathcal{N}_i^k \subseteq \mathcal{N}_i$  is the feasible neighborhood of node  $i$  for ant  $k$ .

# ACO for the Traveling Salesman Problem Continued

After pheromone updating has been performed by the ants, pheromone evaporation is triggered: the following rule is applied to all the edges  $l_{ij}$  of the graph  $G$

$$\tau_{ij}(t) \leftarrow (1 - \rho)\tau_{ij}(t)$$

where  $\rho \in (0, 1]$  is the pheromone trail decay coefficient.

# Conclusions

In this paper we briefly described ACO and its basic applications. We mainly focused on the use in Traveling Salesman Problem.