

# Welcome to Advanced Data Analysis (PHYS 605)

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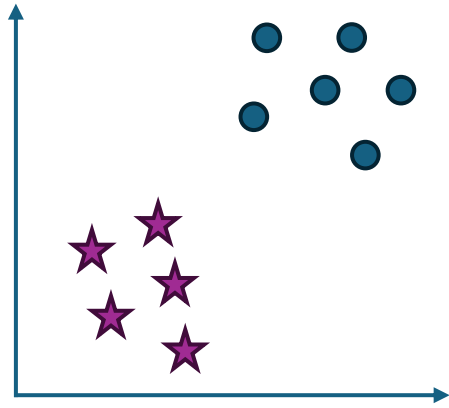


**Department of Physics and Astronomy  
Faculty of Science, University of Calgary**



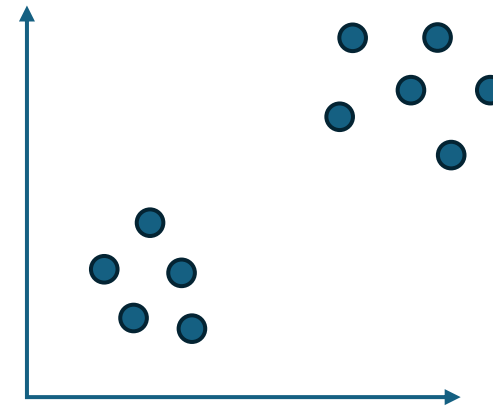
**UNIVERSITY OF  
CALGARY**

# Supervised learning



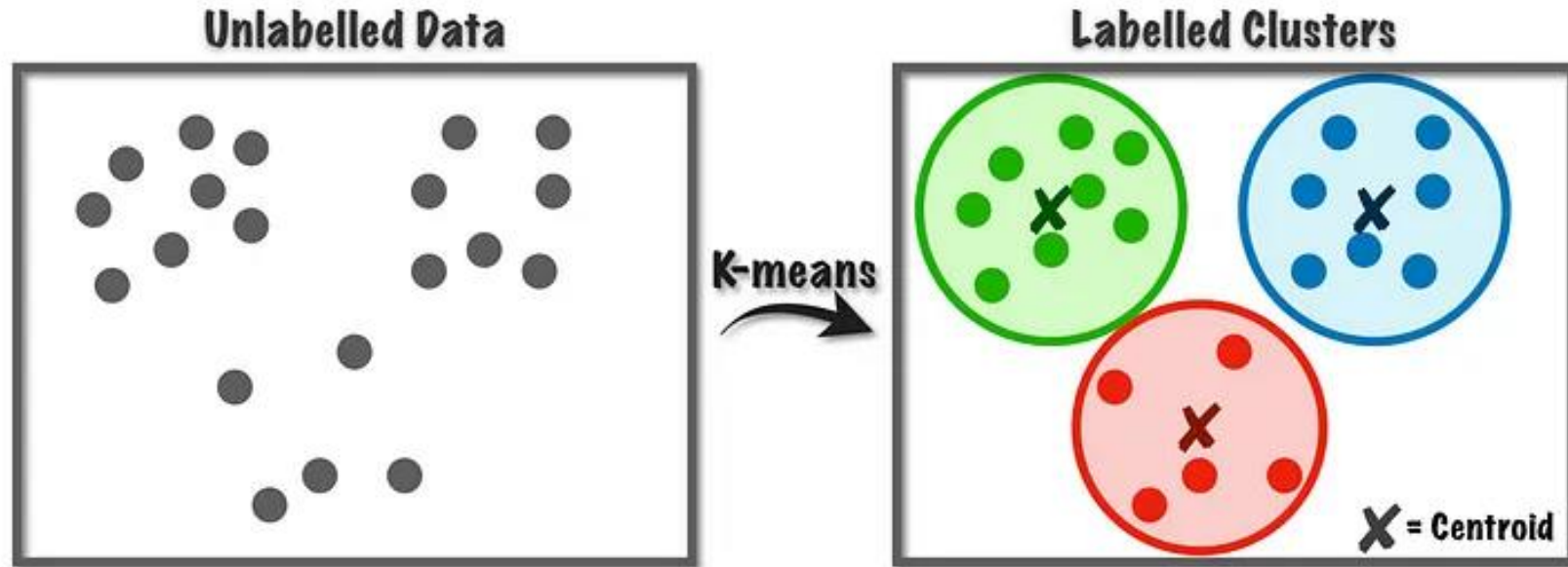
Labelled data

# Unsupervised learning



Unlabelled data

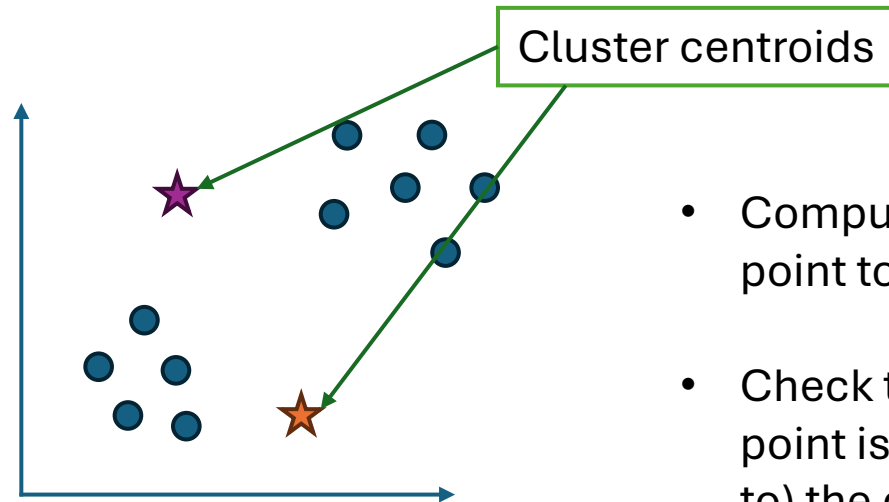
# K-means clustering



<https://towardsdatascience.com/k-means-a-complete-introduction-1702af9cd8c>

# K-means algorithm (illustration)

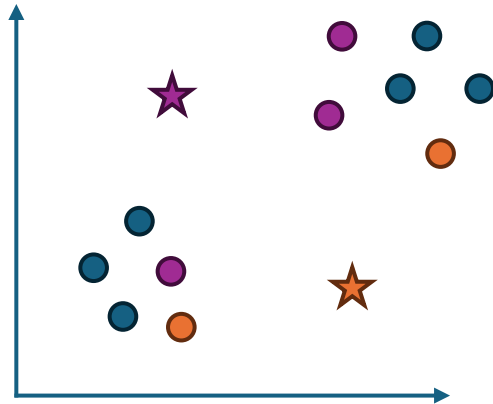
- Decide the number of centroids (equivalent to the number of clusters one wishes to identify,  $K$ );
- Randomly pick the coordinates of the position of the centroids;



- Compute the distance between each data point to the cluster centroids;
- Check to which centroid cluster a given data point is closer. Paint (or assign a cluster label to) the data point in the same colour as the colour of the cluster centroid.

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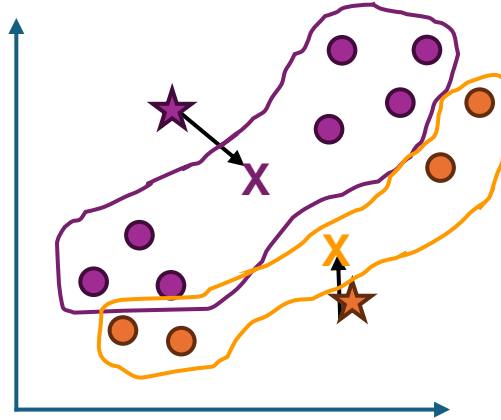
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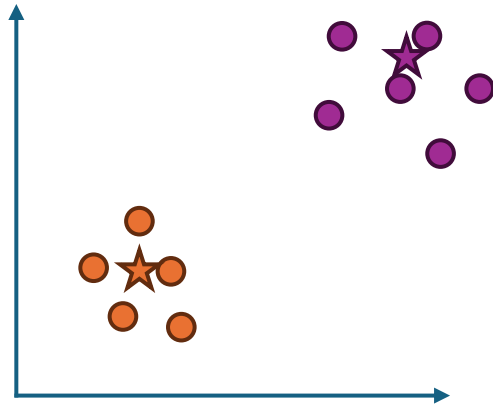
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- 
- Once all labels/colours are assigned to all data points, prepare to recompute the centroids! We will calculate the average coordinate for each of the clusters (purple and orange clusters);
  - The centroids will be relocated to these new (average) coordinates.
  - Then repeat the steps from the third bullet item until convergence.

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# K-means mathematically

**DEFINITION (Partition)** A partition of  $[n] = \{1, \dots, n\}$  of size  $k$  is a collection of non-empty subsets  $C_1, \dots, C_k \subseteq [n]$  that:

- are pairwise disjoint, i.e.,  $C_i \cap C_j = \emptyset, \forall i \neq j$
- cover all of  $[n]$ , i.e.,  $\cup_{i=1}^k C_i = [n]$ .

Wikipedia: “In centroid-based clustering, clusters are represented by a central vector, which may not necessarily be a member of the data set. When the number of clusters is fixed to  $k$ ,  $k$ -means clustering gives a formal definition as **an optimization problem**: find the  $k$  cluster centers and assign the objects to the nearest cluster center, such that the squared distances from the cluster are minimized.”

Under the  $k$ -means objective, the “cost” of  $C_1, \dots, C_k$  is defined as

$$\mathcal{G}(C_1, \dots, C_k) = \min_{\mu_1, \dots, \mu_k \in \mathbb{R}^d} \sum_{i=1}^k \sum_{j \in C_i} \|\mathbf{x}_j - \mu_i\|^2.$$

Here  $\mu_i \in \mathbb{R}^d$  is the representative – or center – of cluster  $C_i$ . Note that  $\mu_i$  need not be one of the  $\mathbf{x}_j$ ’s.

Our goal is to find a partition  $C_1, \dots, C_k$  that minimizes  $\mathcal{G}(C_1, \dots, C_k)$ , i.e., solves the problem

$$\min_{C_1, \dots, C_k} \mathcal{G}(C_1, \dots, C_k)$$

over all partitions of  $[n]$  of size  $k$ . This is a finite optimization problem, as there are only a finite number of such partitions. Note, however, that the objective function itself is an optimization problem over  $\mathbb{R}^d \times \dots \times \mathbb{R}^d$ , that is,  $k$  copies of  $\mathbb{R}^d$ .