1 Project Description

The main idea of this project is to predict the dependent variable (coordinates of the middle point of the box containing the mouse), based on a set of independent variables (coordinates of 7 joints of the mouse and the coordinates of the 2-point containing box). This is done by designing an automated model based on an artificial neural network. The training dataset is generated from the given images by annotations a set of points for each mouse in the images.

2 Data Analysis

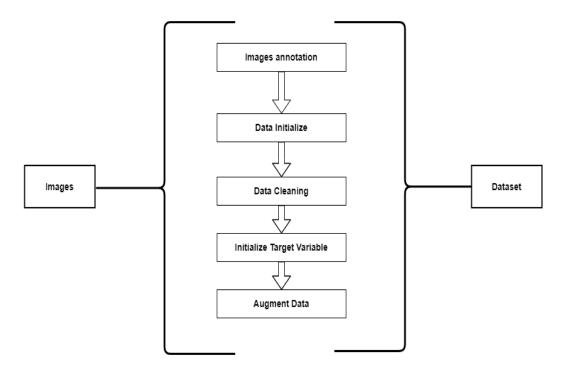


Figure 1: Stage of creating, processing and analyzing data

Figure (1) shows the stage of creating, processing and analyzing data. After that, sequential steps are taken in order to create a suitable data set for building a neural network model. Below we provide a brief summary of each of these steps.

2.1 Images Annotation

The training data set is created from the given images by using the annotation tool to locate 7 joints (nose, left ear, right ear, left hip, right hip, base of the tail, end of the tail), in addition to specifying two angles (top left, lower right) from Bounding box With the mouse inside this bounding box.

The output of this task is two files (CollectedData_annotation.csv , CollectedData_annotation.h5) that contain the same information and coordinates of the specified points.I chose the Collected-Data_annotation.h5 file to deal with it in the rest of the data analysis tasks.

2.2 Data Initialize

1 Load notations

The CollectedData_annotation.h5 file is loaded as shown in Figure (2).

df = pd.read df.head()	_hdf(path)									
	scorer	annotation								
	individuals	mouse1								
	bodyparts	topleft		rightdown		nose		leftear		righ
	coords	x	у	x	у	x	у	x	у	x
labeled- data 0004	A_male_in_a_new_cage_face_view_3_2022- 08-10_15-39-01_117.png		163.388924	354.817358	355.670287	NaN	NaN	200.900977	175.174665	
	A_male_in_a_new_cage_face_view_3_2022- 08-10_15-39-01_137.png		181.098197	313.698513	283.183201	NaN	NaN	NaN	NaN	28
	A_male_in_a_new_cage_face_view_3_2022- 08-10_15-39-01_266.png		64.309673	522.938424	340.171742	410.539804	72.383012	NaN	NaN	
	A_male_in_a_new_cage_face_view_3_2022- 08-10_15-39-01_794.png	278.684928	172.456684	420.454752	242.268629	410.177933	211.436922	NaN	NaN	39
	A_male_in_a_new_cage_side_view_4_2022- 08-10_15-39-03_1072.png		184.790366	236.165308	288.327620	NaN	NaN	NaN	NaN	
5 rows × 36 col	umns									

Figure 2: CollectedData_annotation.h5

We note that the contents of the h5 file are not well formatted, for the purpose of ease of analysis and data handling. I arranged the data and stored it in a data frame, as shown in Figure (3), the characteristics are a set of coordinates (X,Y) for 9 points, and thus the number of characteristics is 9*2=18, In addition to the name of the image, the total number of properties will be 19.



Figure 3: Initialize dataset

We note that each record of the data represents a mouse, and it can be more than one record with the same name as the image.

2.3 Data Cleaning

I cleaned the data by deleting all records that contain at least one empty point. Since it is not logical to use methods for processing null values in the data, for example, we cannot use average points. Therefore, in order to build an accurate model, it is better to delete these records, as shown in the Figure (4).

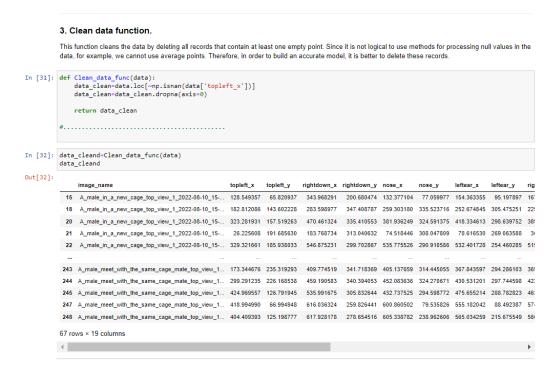


Figure 4: Data cleaned

When deleting empty records, the data decreased from 250 to 67 records. After that, a set of pictures is shown, and dots and boxes are drawn on the mice, as shown in the Figure (5).

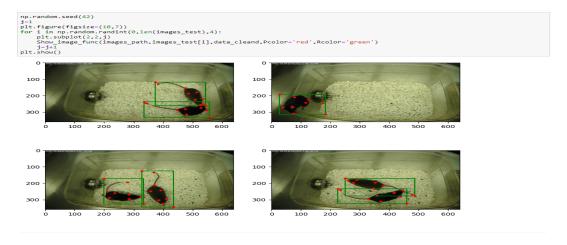


Figure 5: samples

2.4 Initialize Target Variable (Dependent Variable)

The dependent variable, which will be predicted by the machine learning model to be designed, represents the midpoint of the mouse enclosure. Since the dependent variable is not present in the data set, the dependent variable (the midpoint of the box) was formed through the two points (topleft, rightdown) as in equation (1).

$$center_{x} = \frac{topleft_{x} + rightdown_{x}}{2}$$

$$center_{y} = \frac{topleft_{y} + rightdown_{y}}{2}$$
(1)

By applying equation (1), the dependent variable (topleft, rightdown) is created in the data set file as shown in Figure (6).

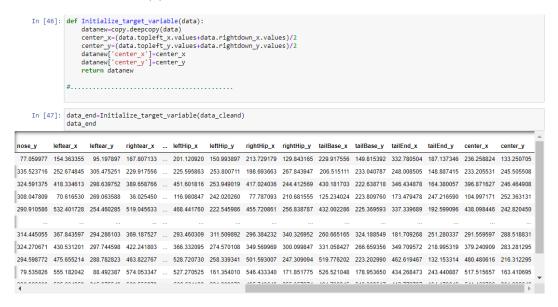


Figure 6: Data set after initialize target variable

The dependent variable is displayed on a set of images, as shown in Figure (7). The blue dots are the dependent variables that will be predicted by the machine learning model that will be designed based on a set of independent variables represented in the red dots.

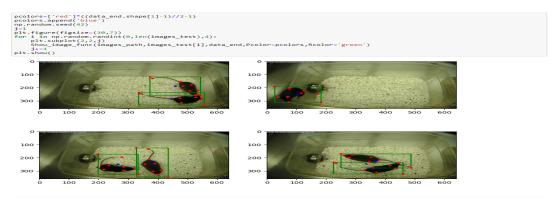


Figure 7: Dependent variables in the Images

2.5 Augment Data

After deleting the NaN rows, our total number of records decreased from 250 to 67.So we need to create new images to increase the number of data. Since our work depends on a set of points only, therefore we do not need to produce new images, but we need to produce new points i.e. mouse New), and in order to increase the number of rats I simply applied geometric transformations to the rat points in the data set, by applying the rotation transform by angles (30, 60, 90, 120, 150, 180, 210, 240, 270, 300) to the points of each mouse in the data set, I used homogeneous matrices to perform the rotation transformation As follows.

$$P^{(org)} = \begin{bmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ \vdots & \vdots & \vdots \\ x_{10} & y_{10} & 1 \end{bmatrix}$$

$$T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -x_c & -y_c & 1 \end{bmatrix} * \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} * \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ x_c & y_c & 1 \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ -\cos \theta + y_c \sin \theta + x_c & -x_c \sin \theta - y_c \cos \theta + y_c & 0 \end{bmatrix}$$
(2)

$$P^{(new)} = P^{(org)} * T (3)$$

The previous rotation matrix is applied to each mouse in the data set at different angles. This means that from each mouse in the original dataset, 10 mice with different orientations will be produced.

In the end, we obtained 737 mouse (record) as our final data set which we will use to build a neural network model.

3 Structure of machine learning model

Neural network models support multi-output regression and have the advantage of continuous function learning that can model a more graceful relationship between changes in input and output. Multi-output regression can be supported directly by neural networks simply by specifying how many target variables are present in the problem as the number of nodes in the output layer. This task contains two output variables (x, y) output layer of a neural network with two nodes in the output layer, each of which has a linear activation function.

We will define a multilayer model (MLP) for the multi-output regression task defined in this project, Since the data set is small, it is a good practice to use k-fold cross validation to evaluate several MLP models in our multiple-output regression tasks. The number of nodes and layers in the model can easily be adapted and customized according to the complexity of the data set. I built two multi-layer (MLP) models for the multi-output regression task which differ in the number of hidden layers and the number of nodes in each layer, as Figure (8) shows the structure of the models.

```
5.1 built Models.

In [10]: def Create_Model_One(n_inputs, n_outputs):
    model = Sequential()
    model.add(pense(18, input_dim=n_inputs, kernel_initializer='normal', activation='relu'))
    model.add(pense(n_outputs))
    model.compile(loss='mse', optimizer='adam',metrics=['mse'])
    return model

#.

def Create_Model_Tow(n_inputs, n_outputs):
    model = Sequential()
    model.add(pense(18, input_dim=n_inputs, kernel_initializer='normal', activation='relu'))
    model.add(pense(4, activation='relu'))
    model.add(pense(4, activation='relu'))
    model.add(pense(4, activation='relu'))
    model.add(pense(n_outputs))
    model.compile(loss='mse', optimizer='adam',metrics=['mse'])
    return model

#.
```

Figure 8: Structure models

- Each sample has 18 inputs and 2 outputs, thus, networks require an input layer that expects 18 inputs defined via the 'input_dim' argument in the first hidden layer and two nodes in the output layer.
- I used the ReLU activation function that is common in hidden layers. The first model contains two hidden layers, the first layer contains 18 nodes and the second layer contains 9 nodes, while the second model contains three hidden layers, the first containing 18 nodes, the second containing 9 and the third containing 4. The number of layers and the number of nodes in these models were chosen after some trial and error.
- We will fit the models using the mean square error (MSE) because it depends on the loss of L2, and Adams version of the random gradient origin.
- I evaluated these models using k-fold cross validation with 10 times and three iterations in order to choose the best model.

Models are defined, fit and evaluated on each fold, MSE scores are collected and can be summarized by reporting the mean and standard deviation , The following results were noted:

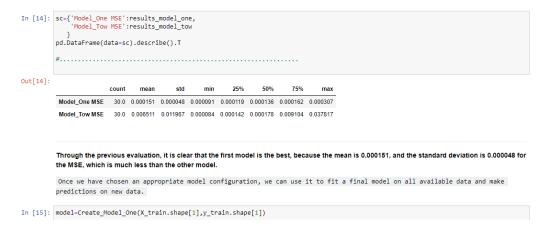


Figure 9: Evaluated-models using k-fold cross validation

Through the previous evaluation, it is clear that the first model is the best, because the mean is 0.000151, and the standard deviation is 0.000048 for the MSE, which is much less than the other model.

Once we have chosen an appropriate model configuration, we can use it to fit a final model on all available data and make predictions on new data.

4 Experiment results

In the experiment of predicting the midpoint of the mouse box, the data set is increased by performing rotation transformation with different angles. Finally, 737 samples are obtained, which are then divided into the training set 80% and the test set with 30%, after that the best model is identified and evaluated .In terms of the number of layers and the number of nodes, by using k-fold cross validation with 10 times and three iterations, it was noted that the best model is the first model that was designed, which achieved an average MSE of 0.000151 with a standard deviation of 0.000048.

After we choose the appropriate configuration of the model, it is trained on the available training data set and evaluated on the test data set, the model is trained with loss mse, epoch 300, optimizer adam .The changes of the mse cost function were observed during the training process, as shown in Figure (10).

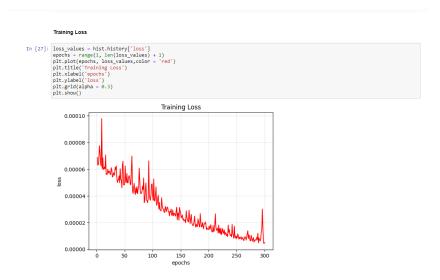


Figure 10: Training loss

We conclude from the previous figure that the training phase was somewhat better, because mse decreases in each epoch.

The model was evaluated using the test data set, the model achieves a mean square error (MSE) of 9.742738257045858e - 06.

Figure 11: Evaluate model

As Figure (12) shows a comparison between the points of the predicted centers and the real centers in the test data set, we notice that the prediction was better.

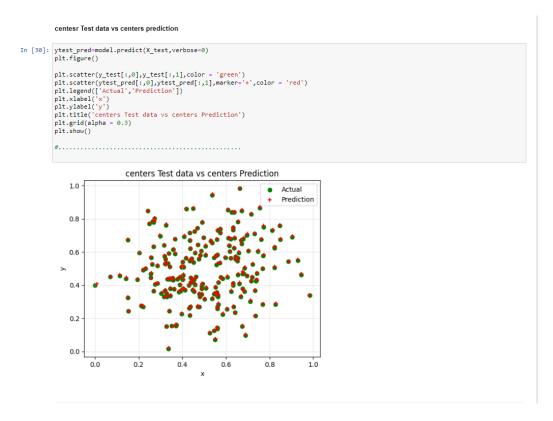


Figure 12: Centers Test data vs Centers prediction

We also evaluated for each of x,y coordinates, as shown in Figure (13).

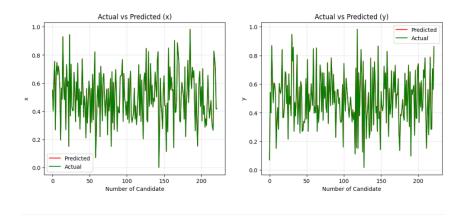


Figure 13: Evaluated (x,y) coordinates

We conclude from the previous figure that the model predicts both the x and y events well.

5 Instructions for running code

The project code consists of two files "ipynb"

- Initialize_dataset_section.ipynb
 This file is for the stage of data handling and analysis.
- built_model_section.ipynb This is a file for the process of building and analyzing the performance of the designed models.
- The "Initialize_dataset_section.ipynb" file is first run in order to perform all operations related to the original data set, and the new data set resulting from the implementation of this code is saved in the "data" folder named "initialize_dataset.csv".
- Then the "built_model_section.ipynb" file is executed, which uses the dataset generated from the previous file to build neural network models. And the trained model is saved as "my_model.h5"

Note: The codes in the two files were built using functions, and these functions are called when needed. This is for the purpose of organization and ease of dealing with it. It also contains a lot of annotations. Each file can be run using "Restart & Run All" and the results can be observed after completion of the execution

6 Conclusions

As we all know, deep learning relies on a large amount of data to train the model. Therefore, rotational transformation was used to address the lack of training data, although the data was increased from 67 to 737, but it is not sufficient to generalize a model based on neural networks. The data set was normalized using MinMaxScaler, after that it was divided into the 80% training set and the 30% test set.

Since the data set is small and in order to avoid overfitting problems of the MLP models (number of layers, number of nodes), k-fold cross validation with 10 times and three iterations was used in order to evaluate two multilayer models (MLP) for the multiple output regression task. The activation function was used.ReLU common in hidden layers. The first model contains two hidden layers, the first layer contains 18 nodes and the second layer contains 9 nodes, while the second model contains three hidden layers, the first contains 18 nodes, the second contains 9 and the third contains 4.Use the mean squared error (MSE) for the fit of these models because it is based on L2 loss and the Adams version of Stochastic Gradient Origin.

The first model is the best, because the mean is 0.000151, and the standard deviation is 0.000048 for the MSE which is much lower than the other model.

And after our proper selection of the model, it is trained on the available training data set and evaluated on the test data set, the model is trained with mse loss, epoch 300, adam optimizer. We conclude that the training phase was rather good. The model was evaluated using the test data set, where the model achieved a mean square error (MSE) of 9.742738257045858e - 06.