



Automotive Industry

Introduction to AUTOSAR

- [illegible]

- What is AUTOSAR ?



- **AUT**omotive **O**pen **S**ystem **AR**chitecture
- An open and standardized automotive software architecture, developed by
 - Car manufacturers
 - Suppliers
 - Tool developers

AUTOSAR Intro

● Who participates

9 Core Partners



56 Premium Partners



2 Strategic Partners



51 Development Partners



+ 144 Associate Partners
+ 24 Attendees

- AUTOSAR Statistics
 - AUTOSAR has been started in 2003
 - 288 worldwide organizations are involving in AUTOSAR (9 core members, 56 premium members)
 - AUTOSAR has been deployed on millions of ECUs
 - 9 major releases have been published: 2.1, 3.0, 3.1, 3.2, 4.0, 4.1, 4.2, 4.3, 4.4

AUTOSAR Intro

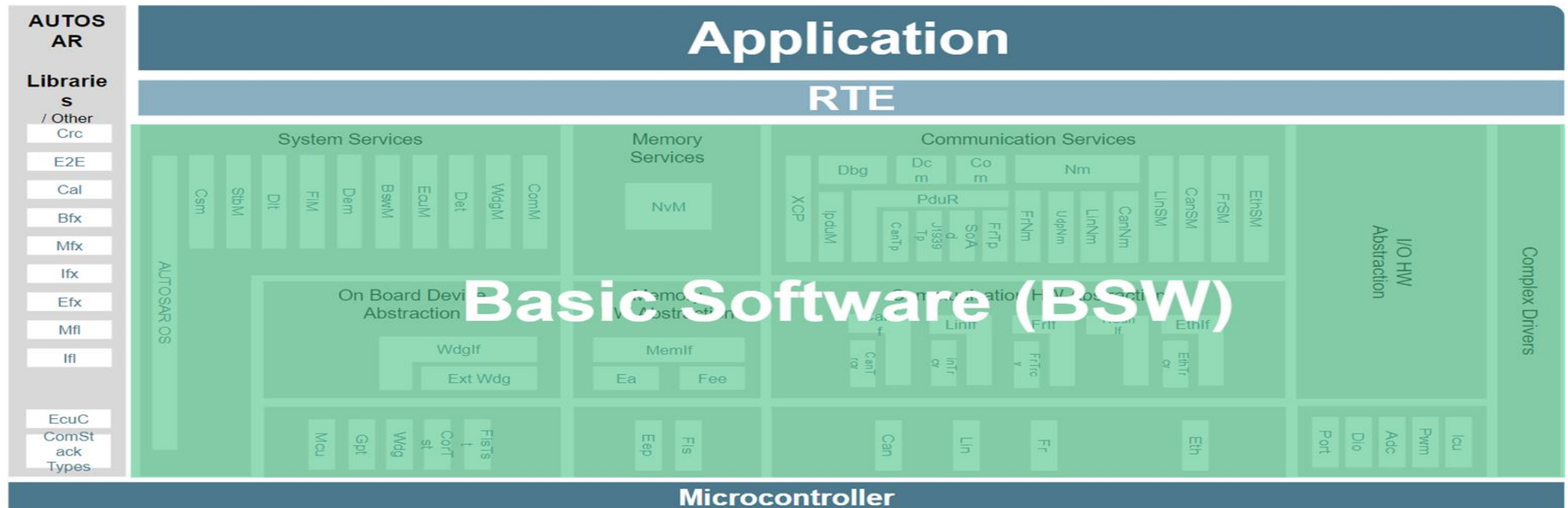
AUTOSAR slogan: "Cooperate on standards, compete on implementation"

- Why AUTOSAR ?
- Handle the increasing amount of software
- Technical and commercial benefits:
 - Scalability on different platforms / vehicles to reduce the cost and improve quality
 - Speed up application development to reduce the cost and the risks
 - Standard to reduce amount of bugs and ease the maintenance
 - Improve the software reliability for Quality and Safety
 - Integration of modules of multiple suppliers
 - Separate developing application from the utilities room for innovation

- Define a common software architecture for automotive domain
- Define how applications will communicate within AUTOSAR defining some application Interfaces
- Define a methodology to configure, generate and validate functionalities
- AUTOSAR Key Feature
 - Modularity and configurability
 - Standardized interfaces
 - application separated from the utilities (Runtime Environment)

Overview of Software Layers/Stacks

- AUTOSAR architecture consists of three main layers :
 - Basic software (BSW)
 - RTE
 - Application



Overview of Software Layers/Stacks

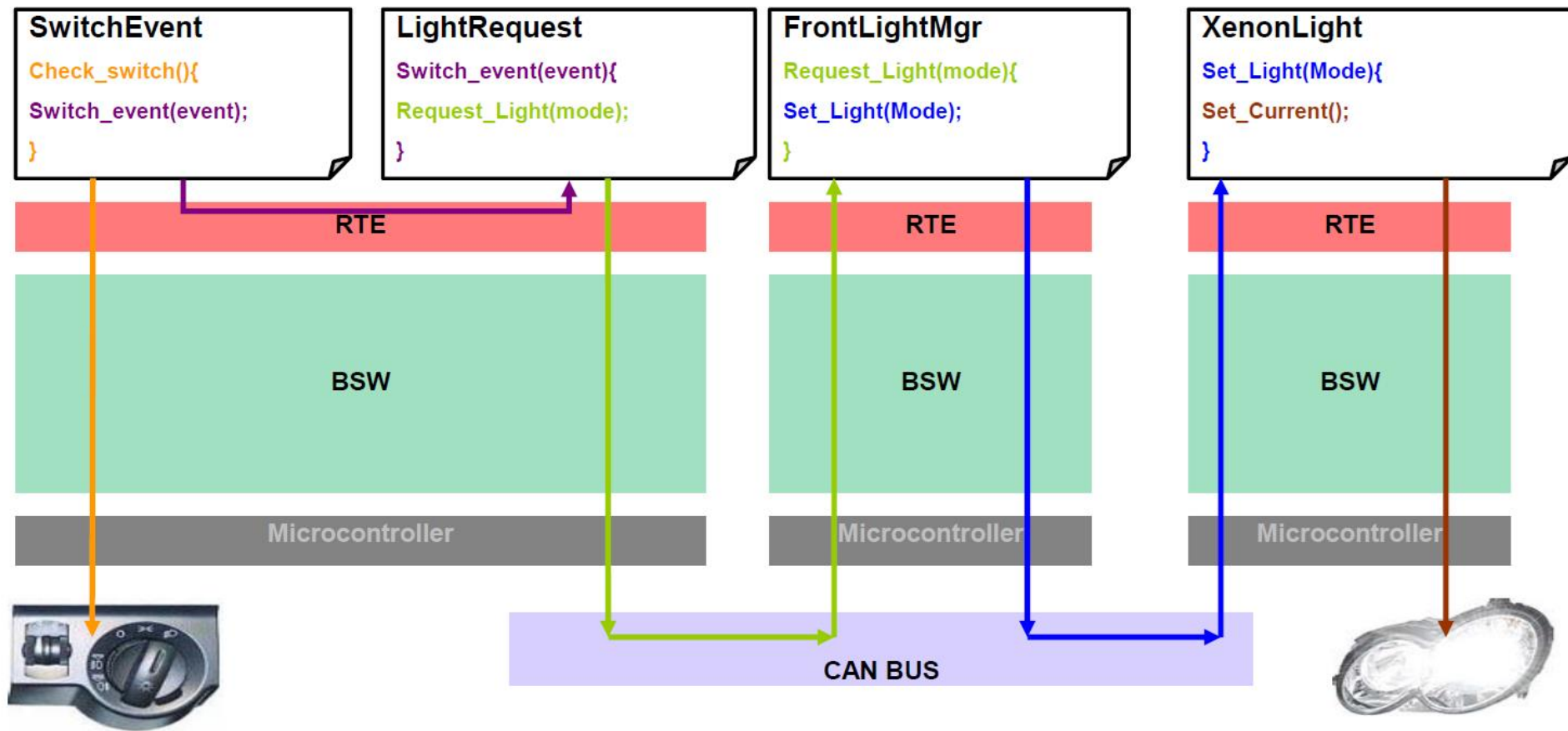
- Basic software (BSW) :
 - Provides services to the application
 - Responsible for running the functional part of the software
Ex. Communication (Can , LIN , ETHERNET ,), I/O management , network management , memory management , OS
 - Contains standardized and ECU specific components

Overview of Software Layers/Stacks

- Application : Software components mapped on the ECU which running the logical part of the software
- RTE :
 - Communication center for
 - intra : SWC/BSW , SWC/SWC
 - inter : ECU information exchange
 - It provides a communication abstraction to Application AUTOSAR Software Components by providing the same interface whether
 - inter-ECU communication channels are used (e.g. CAN , LIN , ..)
 - OR communication stays intra ECU

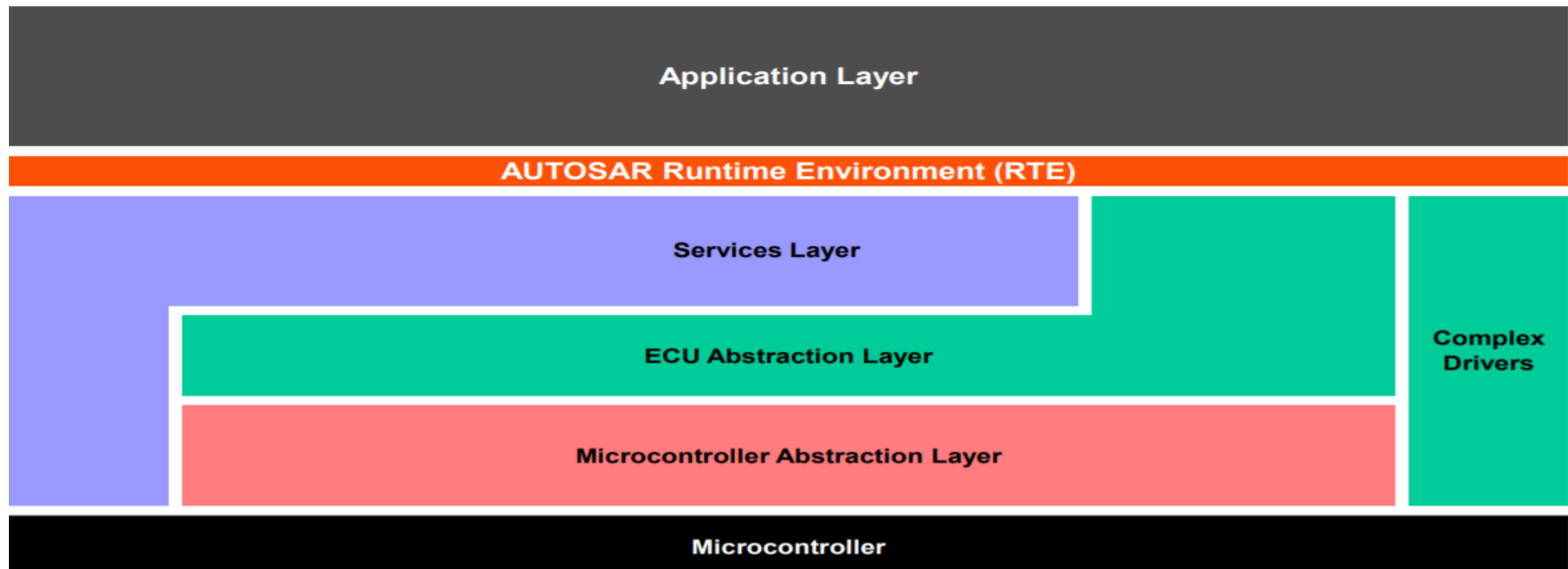
Overview of Software Layers/Stacks

- Intra/Inter ECU communication



Overview of Software Layers/Stacks

- BSW consists of three layers:
 - Microcontroller Abstraction layer (MCAL)
 - ECU Abstraction layer (ECUAL)
 - Services layer



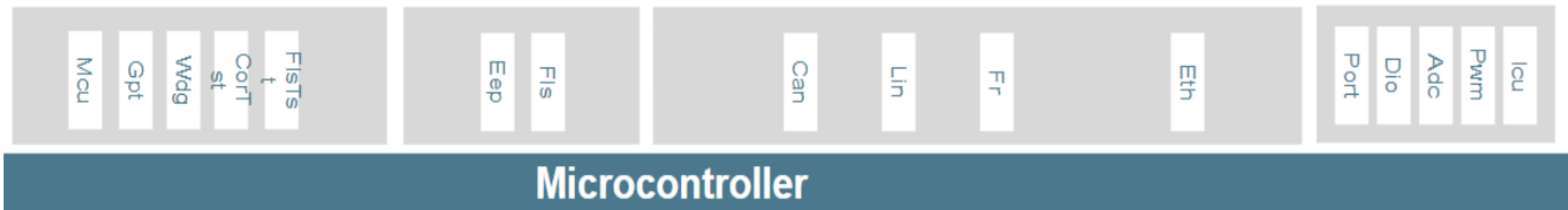
Overview of Software Layers/Stacks

- Microcontroller Abstraction layer (MCAL) :
 - Software layer containing drivers to enable the access of On-Chip peripheral devices of microcontroller
 - It abstracts the microcontroller details
 - MCAL is a hardware specific layer

Microcontroller Abstraction Layer

Overview of Software Layers/Stacks

- MCAL Drivers Examples :
 - ADC
 - CAN
 - Internal EEPROM
 - Internal Watchdog
 -



Overview of Software Layers/Stacks

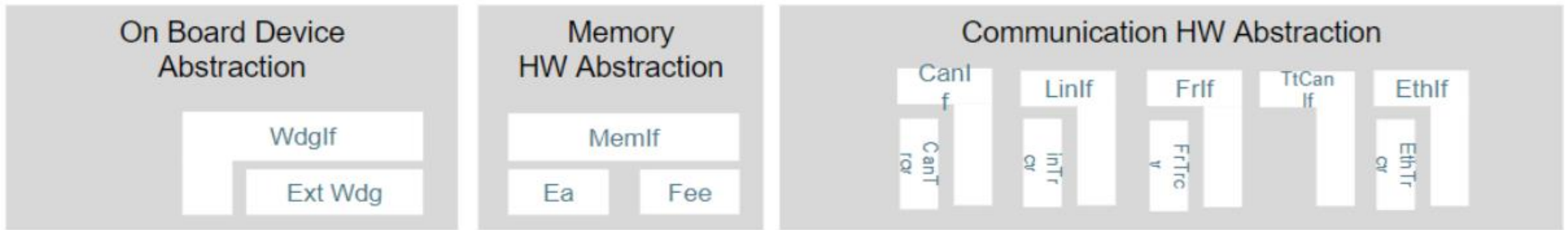
- ECU Abstraction layer (ECUAL) :
 - Offers API's to access peripherals regardless of
 - their location (internal/external of microcontroller)
 - their connection to microcontroller (port pins , interface type)
 - It abstracts the ECU hardware layout

A diagram showing a large green rectangular block representing the ECU Abstraction Layer. The text 'ECU Abstraction Layer' is written in white, bold, sans-serif font in the center of the block.

ECU Abstraction Layer

Overview of Software Layers/Stacks

- ECU Abstraction External Drivers Examples :
 - External EEPROM
 - External Watchdog
 - External Flash
- ECU abstraction Interface Modules Examples :
 - Can Interface (CanIF)
 - Memory Interface (MemIF)



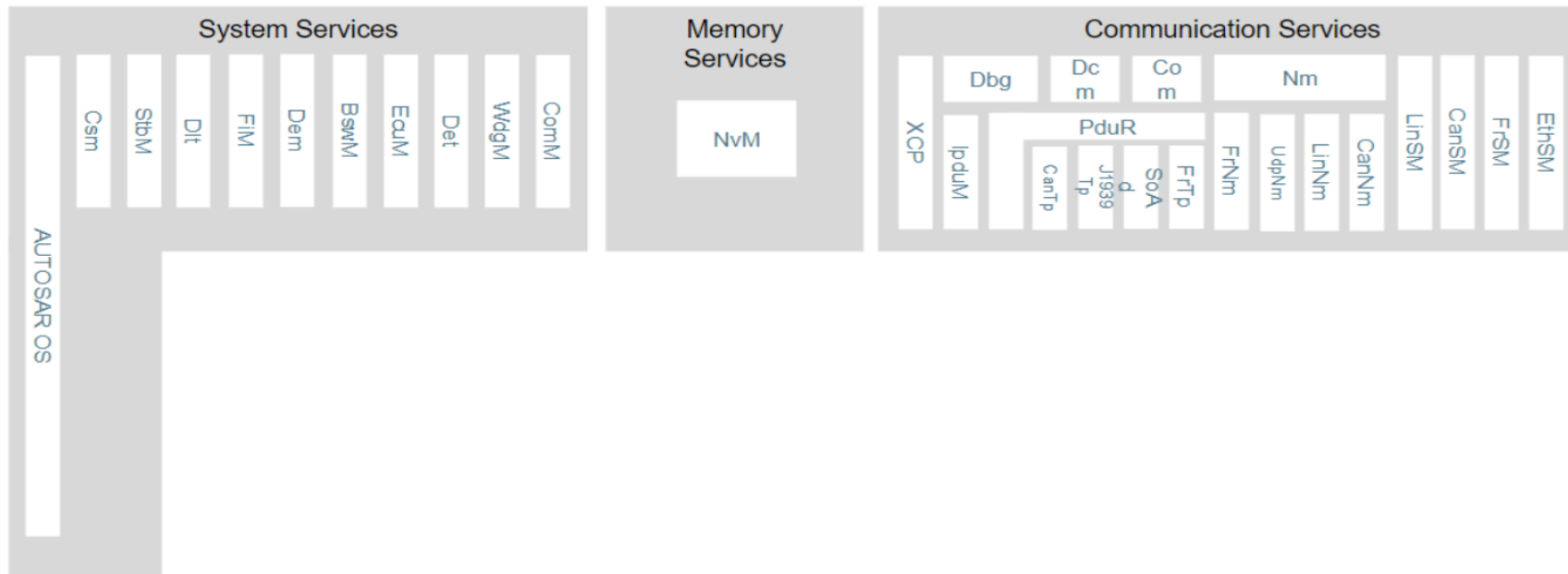
Overview of Software Layers/Stacks

- Services layer :
 - Provides basic services for application and basic software modules :
 - Operating system functionality
 - Vehicle network communication and management services
 - Memory services
 - Diagnostic services
 - Ecu state management and mode management



Overview of Software Layers/Stacks

- Service Managers Examples :
 - COM manager
 - NVRAM manager
 - ECU state manager



Overview of Software Layers/Stacks

- Complex Device Drivers (CDD)
 - Provide the possibility to integrate special purpose functionality
 - EX. driver for devices :
 - which are not specified within AUTOSAR
 - with very high timing constraints
- AUTOSAR libraries :
 - Collection of functions that can be called by BSW , RTE , SWCs
 - EX. CRC , E2E , ..

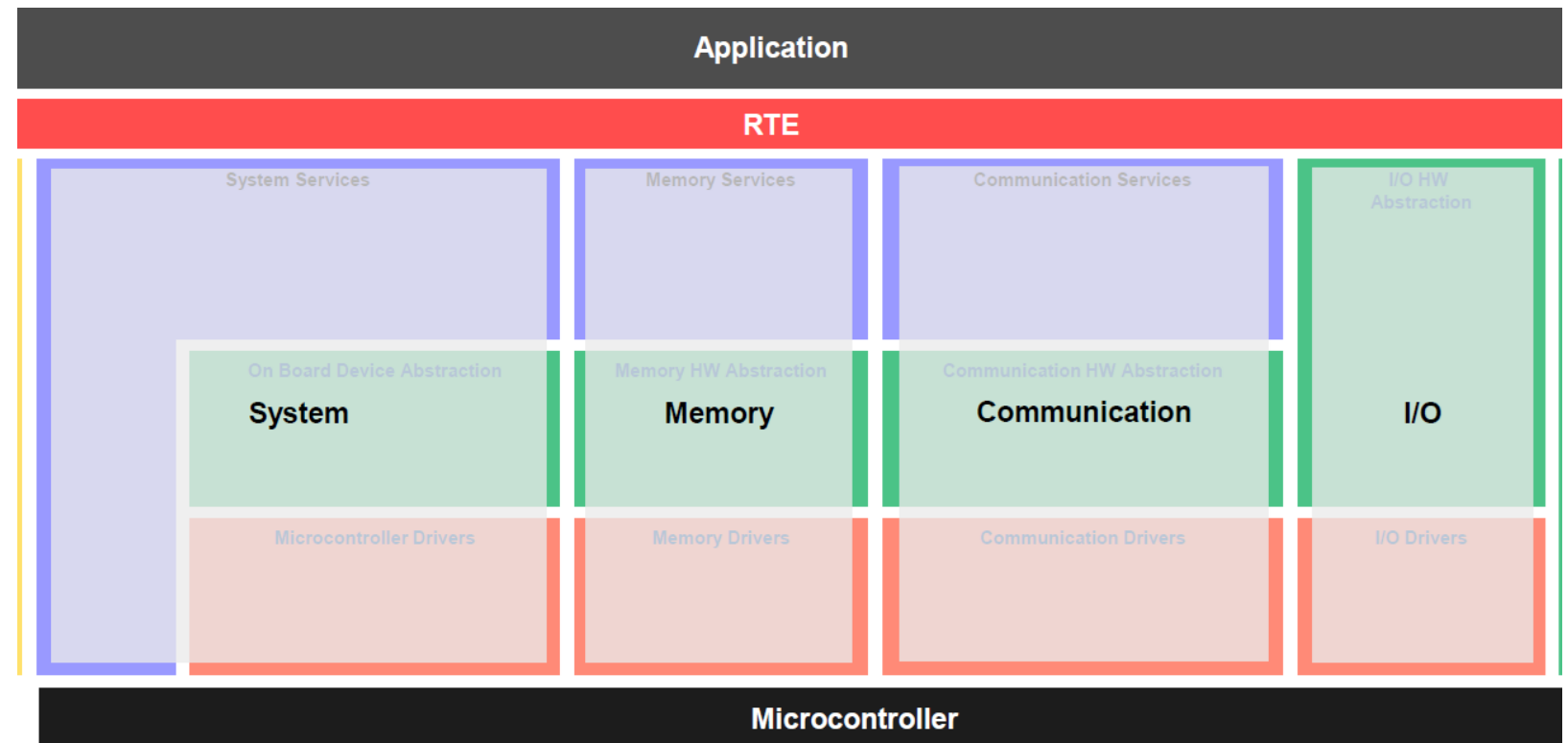
Complex
Drivers

AUTOSAR
Libraries

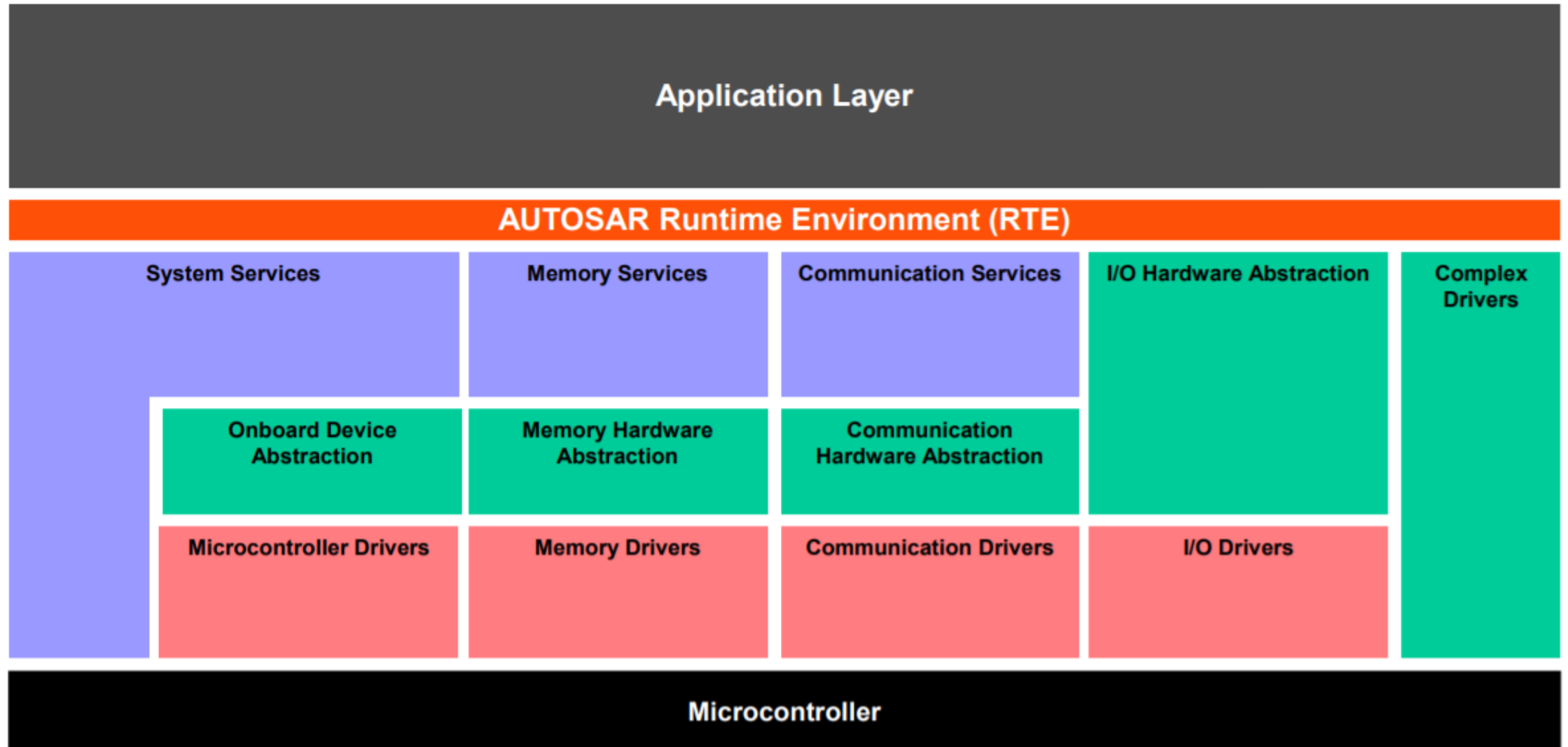
Overview of Software Layers/Stacks

- AUTOSAR architecture consists of four stacks:

- Communication stack
- Memory Stack
- System Stack
- I/O stack



Overview of Software Layers/Stacks









Overview of Software Layers/Stacks

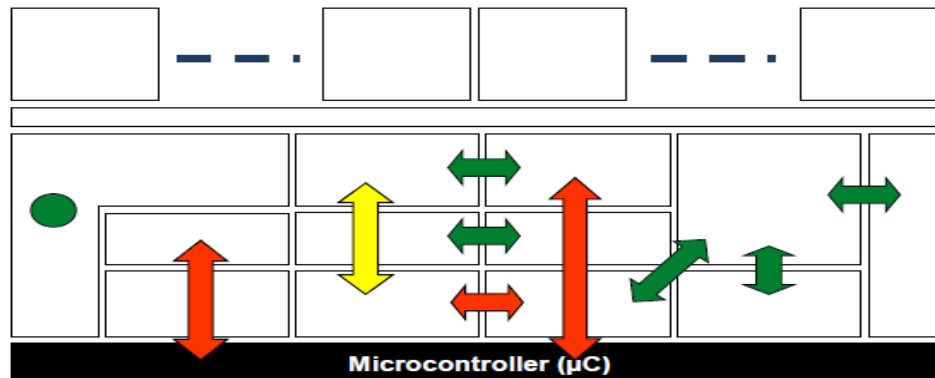
- System Stack :
 - Scheduling management
 - Error management
 - Mode management
 - Watchdog management
- Memory Stack :
 - Services for reading/writing to NV memory
- Communication Stack :
 - Message transmission/reception through communication protocols (CAN, LIN, ...)
 - Diagnostics
 - Network management
- I/O Stack :
 - Management of input/output peripherals

Interfaces: General Rules

General Interfacing Rules

Vertical Interfaces

-  One Layer may access all interfaces of the SW layer below
-  Bypassing of one software layer should be avoided
-  Bypassing of two or more software layers is not allowed
-  Bypassing of the μ C Abstraction Layer is not allowed
-  A module may access a lower layer module of another layer group (e.g. SPI for external hardware)
-  All layers may interact with system services.



Overview of Software Layers/Stacks

- Interfaces' Types
 - Provided services
 - The functions a module provides , usually to upper layer modules in the AUTOSAR layer model
 - Callbacks
 - The functions a module provides to receive notifications , usually from a lower layer module in the AUTOSAR layer model
 - Scheduled functions
 - EX. Main functions

1. Select your BSW modules :
 - Not all modules are used in all projects
2. Configure the selected modules
 - Using the configuration tool
3. Multiple iterations
 - As the setting of one module may impact other modules
4. Implement BSW Scheduling
 - Not defined by AUTOSAR (ECU integrator role)
5. Fix configuration and generation errors
6. Build generated files with static files

AUTOSAR materials

- Get all AUTOSAR documents from :
<https://www.autosar.org/standards/classic-platform/>
- Get free Elektrobit AUTOSAR package from :
<https://www.elektrobit.com/products/ecu/eb-tresos/evaluation-package/>

The End ...





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