

U-Boot

in order to linux image there are three elements are required:

- bootloader
- kernel
- file systems
- any each of them may be stored in adifferent storages for example flash memory, sd card, USB
- · file systems bay be stored remotely in NFT or TFTP servers.
- · kernel may be remotely in TFTP server

U-Boot in flash, kernel in a remote TFTP server and rootfs in a remote NFS server. This configuration is common for kernel/application development and debugging from a connected host machine



U-Boot

- Cloning the source code of u-boot from git-hub:
 - git clone https://github.com/u-boot/u-boot.git
- To set u-boot configuration use this
 - · Make menuconfig



```
U-Boot 2023.01 Configuration
Arrow keys navigate the menu. <Enter> selects submenus ---> (or empty submenus ----). Highlighted letters are hotkeys. Pressing <Y> includes, <N> excludes, <M>
modularizes features. Press <Esc><Esc> to exit, <?> for Help, </> for Search. Legend: [*] built-in [] excluded <M> module <> module capable
                                                 *** Compiler: arm-linux-gnueabi-gcc (Ubuntu 11.4.0-lubuntu1~22.04) 11.4.0 ***
                                                     Architecture select (ARM architecture) --->
                                                 [ ] Skip the calls to certain low level initialization functions
                                                 [ ] Skip the call to lowlevel init during early boot ONLY
                                                     ARM architecture --->
                                                 [ ] NXP ESBC (secure boot) functionality
                                                     *** Other functionality shared between NXP SoCs ***
                                                     General setup --->
                                                     API --->
                                                     Boot options --->
                                                     Console --->
                                                     Logging --->
                                                     Init options --->
                                                     Security support --->
                                                     Update support --->
                                                     Blob list --->
                                                 [ ] FDT tools for simplefb support
                                                     Command line interface --->
                                                     Partition Types --->
                                                     Device Tree Control --->
                                                     Environment --->
                                                 [*] Networking support --->
                                                 (4) Number of receive packet buffers
                                                     Device Drivers --->
                                                     File systems --->
                                                     Library routines --->
                                                     FWU Multi Bank Updates ----
                                                 [ ] Unit tests ----
                                                      Tools options --->
```



- · After make all configuration save it and exit
- Use / to search for any configuration
- check this if there is an error https://stackoverflow.com/questions/23050188/cant-makemenuconfig

```
root@mahmoud:/media/mahmoud/1e2c08e4-d43c-465c-bf6e-9a5a656676d5/embedded-linux-qemu-labs/bootloader/u-boot# make menuconfig scripts/kconfig/mconf Kconfig

*** End of the configuration.

*** Execute 'make' to start the build or try 'make help'.
```

Installing ARM compiler

Run make command to build the uboot



sudo apt install gcc-arm-linux-gnueabi

Set env CROSS_COMPILE variable to use this as a default compiler

export CROSS_COMPILE=arm-linux-gnueabi-

And set the PATH

export PATH=\$HOME/mahmoud/usr/bin/arm-linux-gnueabi/bin:\$PATH

Configuring u-boot to the target board

Make [board_name]

make vexpress_ca9x4_defconfig

Some errors may be occurs needed to install this

sudo apt install libssl-dev device-tree-compiler swig \python3-distutils python3-dev python3-setuptools

Installing QEMU User space emulator

sudo apt install qemu-system-arm



Test u-boot using Qemu emulator

Trying to set any env



qemu-system-arm -M vexpress-a9 -m 128M -nographic - kernel u-boot

- -M: emulated machine
- -m: amount of memory in the emulated machine
- -kernel: allows to load the binary directly in the emulated machine and run the machine with it. This way, you don't need a first stage bootloader. Of course, you don't have this with real hardware.

```
=> setenv embinux mahmoud
=> save
save saveenv
=> saveenv
Saving Environment to FAT... Card did not respond to voltage select! : -110
** Bad device specification mmc 0 **
Failed (1)
-> @ss■
```



We now need to add an SD card image to the QEMU virtual machine, in particular to get a way to store U-Boot's environment.

using the dd command, create a 1 GB file filled with zeros, called sd.img:

dd if=/dev/zero of=sd.img bs=1M count=1024

creating the partions we need cfdisk sd.img

oot@mahmoud:/media/mahmoud/le2c08e4-d43c-465c-bf6e-9a5a656676d5/e .024+0 records in .024+0 records out .073741824 bytes (1.1 GB, 1.0 GiB) copied, 2.1038 s, 510 MB/s



- ->One partition, 64MB big, with the FAT16 partition type. Mark this partition as bootable.
- ->One partition, 8 MB big3, that will be used for the root filesystem. Due to the geometry of the device, the partition might be larger than 8 MB, but it does not matter. Keep the Linux type for the partition.
- -> One partition, that fills the rest of the SD card image, that will be used for the data filesystem. Here also, keep the Linux type for the partition.



Disk: sd.imgSize: 1 GiB, 1073741824 bytes, 2097152 sectors
Label: dos, identifier: 0x28c8bf37

	Device	Boot	Start	End	Sectors	Size	Id Type	
>>	sd.imgl	*	2048	133119	131072	64M	6 FAT16	
	sd.img2		133120	149503	16384	8M	83 Linux	
	sd.img3		149504	2097151	1947648	951M	83 Linux	

Partition type: FAT16 (6) Attributes: 80



We will now use the loop driver4 to emulate block devices from this image and its partitions:

sudo losetup -f --show --partscan sd.img

- -f: finds a free loop device
- -- show: shows the loop device that it used
- --partscan: scans the loop device for partitions and creates additional /dev/loopp block devices.

Also run sudo dmesg to confirm that 3 partitions were detected for the loop device selected by losetup

Last but not least, format the first partition as FAT16 with a boot label:

sudo mkfs.vfat -F 16 -n boot /dev/loopp1

Now, you can release the loop device:

```
o.default-release/key4.db" pid=29885 comm="so

[57712.567862] loop26: detected capacity char

[57712.568009] loop26: p1 p2 p3

[57712.571749] loop26: p1 p2 p3

root@mahmoud:/media/mahmoud/le2c08e4-d43c-465
```



Testing U-Boot's environment

Start QEMU again, but this time with the emulated SD card

qemu-system-arm -M vexpressa9 -m 128M -nographic \ kernel u-boot/u-boot \ -sd sd.img

```
WARNING: Image format was not specified for 'sd.img' and probing guessed raw.
        Automatically detecting the format is dangerous for raw images, write operations on block 0 will be restricted.
        Specify the 'raw' format explicitly to remove the restrictions.
J-Boot 2023.01 (Jul 20 2024 - 11:26:40 +0300)
DRAM: 128 MiB
WARNING: Caches not enabled
Core: 18 devices, 10 uclasses, devicetree: embed
Flash: 64 MiB
MMC: mmci@5000: 0
Loading Environment from FAT... OK
      serial
      serial
      serial
      eth0: ethernet@3,02000000
Hit any key to stop autoboot: 0
  setenv embinux mahmoud
> saveenv
Saving Environment to FAT... OK
> printenv embinux
embinux=mahmoud
```



Now if you try to load the kernel

```
DHCP client bound to address 10.0.2.15 (2 ms)
Using ethernet@3,02000000 device
TFTP from server 10.0.2.2; our IP address is 10.0.2.15
Filename 'boot.scr.uimg'.
Load address: 0x60100000
Loading: *
TFTP error: 'Access violation' (2)
Not retrying...
smc911x: MAC 52:54:00:12:34:56
smc911x: detected LAN9118 controller
smc911x: phy initialized
smc911x: MAC 52:54:00:12:34:56
BOOTP broadcast 1
DHCP client bound to address 10.0.2.15 (1 ms)
Using ethernet@3,02000000 device
TFTP from server 10.0.2.2; our IP address is 10.0.2.15
Filename 'boot.scr.uimg'.
Load address: 0x60100000
Loading: *
TFTP error: 'Access violation' (2)
Not retrying...
smc911x: MAC 52:54:00:12:34:56
cp - memory copy
Usage:
cp [.b, .w, .l, .q] source target count
Wrong Image Format for bootm command
ERROR: can't get kernel image!
```



Setup networking between QEMU and the host

Craeting new bash script file named qemu-myifup Contaning to

```
#!/bin/sh
/sbin/ip a add 192.168.0.1/24 dev $1
/sbin/ip link set $1 up
```

you will need root privileges to run QEMU this time, because of the need to bring up the network interface:

```
sudo qemu-system-arm -M vexpress-a9 -m 128M -
nographic \
-kernel u-boot/u-boot \
-sd sd.img \
-net tap,script=./qemu-myifup -net nic
```

```
=> setenv ipaddr 192.168.0.100
=> setenv serverip 192.168.0.1
=> save
  save saveenv
=> savee
Saving Environment to FAT... OK
=> ping 192.168.0.1
smc911x: detected LAN9118 controller
smc911x: phy initialized
smc911x: MAC 52:54:00:12:34:56
Using ethernet@3,02000000 device
smc911x: MAC 52:54:00:12:34:56
host 192.168.0.1 is alive
```



Kernel - Cross-compiling

Define the value of the ARCH and CROSS_COMPILE

make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- vexpress_defconfig

Run make menuconfig to configure the kernel as you need

Run make -j<numberOfcore>

```
config - Linux/x86 6.1.97 Kernel Configuration
                                         Linux/x86 6.1.97 Kernel Configuration
  Arrow keys navigate the menu. <Enter> selects submenus ---> (or empty submenus ----). Highlighted letters are hotkeys.
  Pressing <Y> includes, <N> excludes, <M> modularizes features. Press <Esc> to exit, <?> for Help, </> for Search.
  Legend: [*] built-in [ ] excluded <M> module <> module capable
                         General setup --->
                         [*] 64-bit kernel
                             Processor type and features --->
                         [*] Mitigations for CPU vulnerabilities --->
                             Power management and ACPI options --->
                             Bus options (PCI etc.) ----
                             Binary Emulations --->
                         [*] Virtualization ----
                              General architecture-dependent options --->
                         [*] Enable loadable module support --->
                         -*- Enable the block layer --->
                             Executable file formats --->
                             Memory Management options --->
                         [*] Networking support --->
                             Device Drivers --->
                             File systems --->
                             Security options --->
                         -*- Cryptographic API --->
                             Library routines --->
                             Kernel hacking --->
                                         < Exit > < Help > < Save > < Load >
```

```
AS arch/x86/boot/header.o
LD arch/x86/boot/setup.elf
OBJCOPY arch/x86/boot/setup.bin
BUILD arch/x86/boot/bzImage
Kernel: arch/x86/boot/bzImage is ready (#3)
```



Load the kernel using u-boot

After building the kernel copy the zImage and DTB file according to your board to the directory exposed by the TFTP server.

You may find this directories in one of this paths

/var/lib/tftpboot Or /src/tftp/

sudo cp arch/arm/boot/zImage /src/tftp/

sudo cp arch/arm/boot/dts/vexpress-v2pca9.dtb /src/tftp/

Run Qemu and set the bootargs environment corresponding to the Linux kernel command line:

=> setenv bootargs console=ttyAMA0

=> saveenv

On the target (in the U-Boot prompt), load zImage from TFTP into RAM and DTB:

tftp 0x61000000 zImage tftp 0x62000000 vexpress-v2p-ca9.dtb

Boot the kernel with its device tree:

bootz 0x61000000 - 0x62000000

Why kernel panic?



```
1000a000.uart: ttyAMA1 at MMIO 0x1000a000 (irq = 39, base baud = 0) is a PL011 rev1
1000b000.uart: ttyAMA2 at MMIO 0x1000b000 (irq = 40, base baud = 0) is a PL011 rev1
1000c000.uart: ttyAMA3 at MMIO 0x1000c000 (irq = 41, base baud = 0) is a PL011 rev1
drm-clcd-pl111 1001f000.clcd: assigned reserved memory node vram@4c000000
drm-clcd-pl111 1001f000.clcd: using device-specific reserved memory
drm-clcd-pl111 1001f000.clcd: core tile graphics present
drm-clcd-pl111 1001f000.clcd: this device will be deactivated
drm-clcd-pl111 1001f000.clcd: Versatile Express init failed - -19
drm-clcd-pl111 10020000.clcd: DVI muxed to daughterboard 1 (core tile) CLCD
drm-clcd-pl111 10020000.clcd: initializing Versatile Express PL111
drm-clcd-pl111 10020000.clcd: DVI muxed to daughterboard 1 (core tile) CLCD
drm-clcd-pl111 10020000.clcd: initializing Versatile Express PL111
clk: Disabling unused clocks
ALSA device list:
  #0: ARM AC'97 Interface PL041 rev0 at 0x10004000, irq 37
input: ImExPS/2 Generic Explorer Mouse as /devices/platform/bus@40000000/bus@40000000:motherboard-bus@40000000/bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@400000000:motherboard-bus@400000000000:motherboard-bus@400000000:motherboard-bus@400000000:motherboard-bus@400000000:motherboard-bus@400000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboard-bus@40000000:motherboar
io1/input/input2
drm-clcd-pl111 10020000.clcd: DVI muxed to daughterboard 1 (core tile) CLCD
drm-clcd-pl111 10020000.clcd: initializing Versatile Express PL111
/dev/root: Can't open blockdev
VFS: Cannot open root device "(null)" or unknown-block(0,0): error -6
Please append a correct "root=" boot option; here are the available partitions:
                  131072 mtdblock0
 (driver?)
1f01
                    32768 mtdblock1
 (driver?)
                 1048576 mmcblk0
 driver: mmcblk
  b301
                      65536 mmcblk0p1 28c8bf37-01
  b302
                       8192 mmcblk0p2 28c8bf37-02
  h303
                     973824 mmcblk0p3 28c8bf37-03
Kernel panic - not syncing: VFS: Unable to mount root fs on unknown-block(0,0)
CPU: 0 PID: 1 Comm: swapper/0 Not tainted 6.1.97 #1
 Hardware name: ARM-Versatile Express
 unwind backtrace from show stack+0x10/0x14
 show stack from dump stack lvl+0x40/0x4c
dump stack lvl from panic+0x108/0x334
 panic from mount block root+0x190/0x230
 mount block root from prepare namespace+0x150/0x18c
 prepare namespace from kernel init+0x18/0x12c
 kernel init from ret from fork+0x14/0x28
Exception stack(0x88825fb0 to 0x88825ff8)
5fa0:
                                                        00000000 00000000 00000000 00000000
end Kernel panic - not syncing: VFS: Unable to mount root fs on unknown-block(0,0) ]---
```



Loading the file system using NFS

Create a nfsroot directory in the current lab directory. This nfsroot directory will be used to store the contents of our new root filesystem.

Install nfs server using

Sudo apt install nfs-kernel-server

edit the /etc/exports file as root to add the following line:

<nfsroot_path> 192.168.0.100(rw,no_root_squash,
no_subtree_check)

Run Qemu again and set this env variable

setenv bootargs \${bootargs} root=/dev/nfs ip=192.168.0.100 nfsroot=192.168.0.1:<nfsroot_path>=3,tcp rw

And boot! Kernel panic again. Why?



Busy box

Cloneing busybox from git-hub:

git clone https://git.busybox.net/busybox git checkout 1_36_stable

Configure the busybox:

make menuconfig

Then compile the busybox using make install

Note the path of nsfroot!

Run qemu again.

Not panic but need some file systems we need to create them

```
process '-/bin/sh' (pid 85) exited. Scheduling for restart. process '-/bin/sh' (pid 87) exited. Scheduling for restart. can't open /dev/tty3: No such file or directory can't open /dev/tty2: No such file or directory process '-/bin/sh' (pid 88) exited. Scheduling for restart. process '-/bin/sh' (pid 89) exited. Scheduling for restart. can't open /dev/tty4: No such file or directory process '-/bin/sh' (pid 90) exited. Scheduling for restart. can't open /dev/tty3: No such file or directory can't open /dev/tty2: No such file or directory
```

manmoud@manmoud:/media/manmo bin sbin usr mahmoud@mahmoud:/media/mahmo

Create proc, sys, etc and dev In etc creat init.d dir and in it create rcs file.In this startup script, mount the /proc and /sys filesystems.