

State chart:

We propose a state flow to solve the algorithm of multi store parking system the algorithm start with an

Events:

- R\_F\_S (request free slot)
- R\_R\_S (request retrieve slot)

Inputs:

- U (Object detection sensor)
- Index\_enterd for the retrieve event
- S\_B (safe Button)
- P\_S (power switch)
- Emergency Button

Outputs:

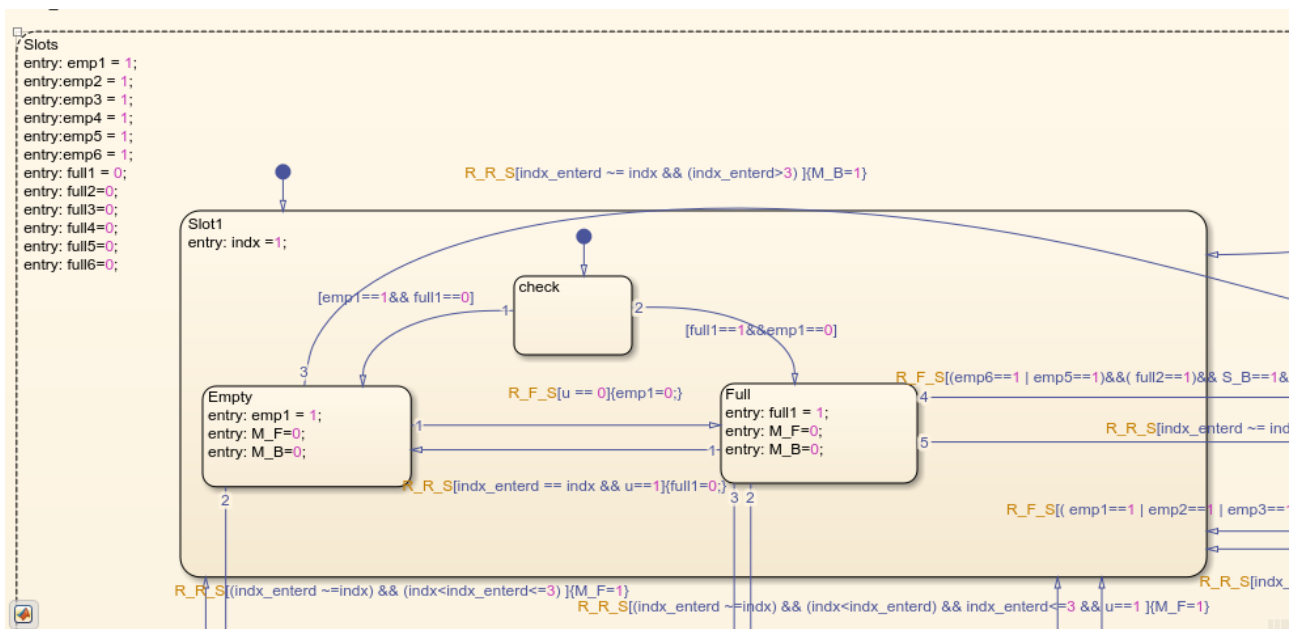
- Counter for the full slots
- Index, for specifying the slot that is in position of parking
- M\_F, Move forward one step
- M\_B, Move backwards one step
- Emp1~6 specify if the slot is empty
- Full1~6 specify if the slot is full

The state chart block is consisting of System, Emergency  
System:

1. Power OFF
2. Power ON

Power ON:

- Slots which contain the parking slots of the system for our model we use 6 slots.



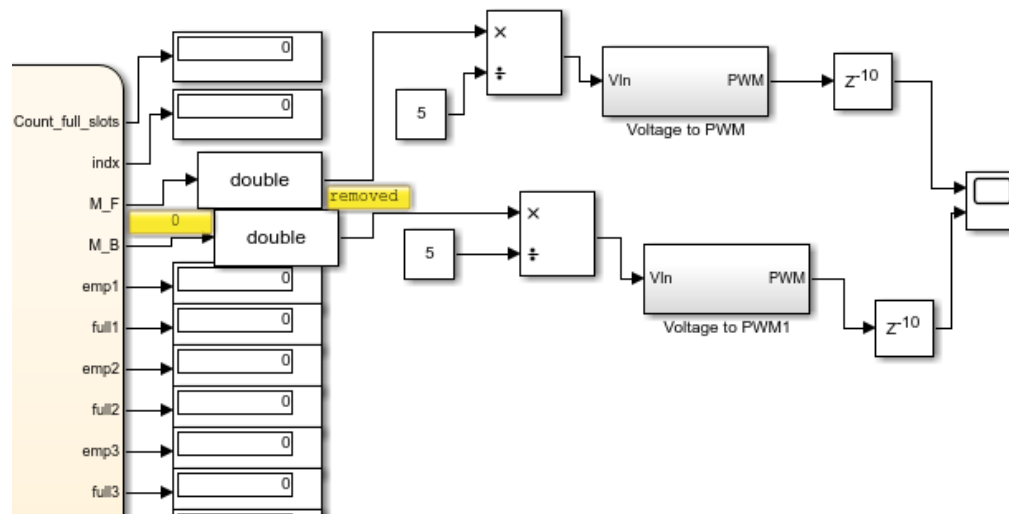
While the algorithm initially starts with a check to know if the slot is full or empty. The algorithm moves from one slot to another by two events which are specified above.

EX:

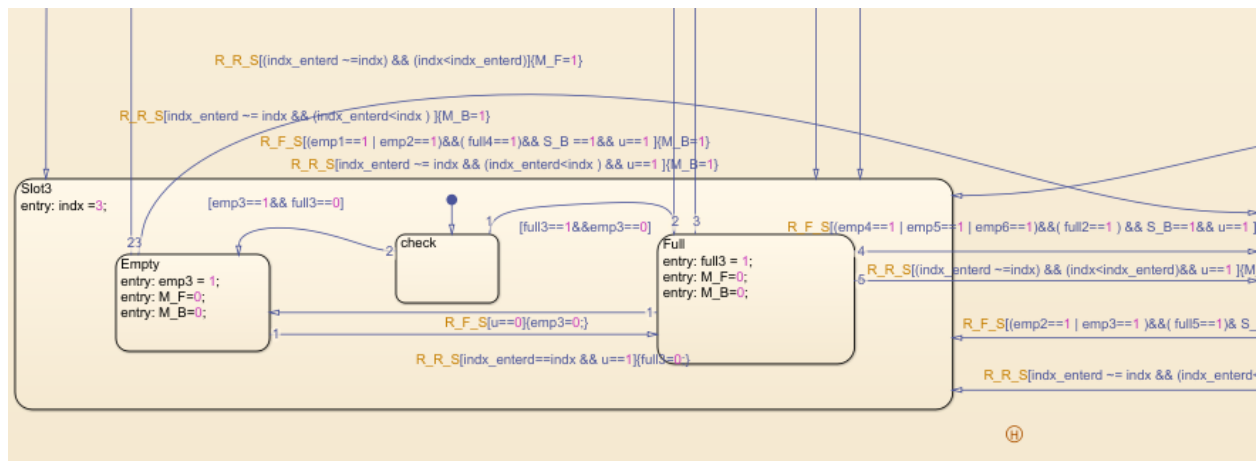
- $R\_R\_S[(\text{indx\_entered} \sim \text{indx}) \ \&\& \ (\text{indx} < \text{indx\_entered}) \ \&\& \ \text{indx\_entered} \leq 3 \ \&\& \ u == 1] \{M\_F = 1\}$
- $R\_F\_S[(\text{emp2} == 1 \mid \text{emp3} == 1 \mid \text{emp4} == 1) \ \&\& \ S\_B == 1 \ \&\& \ u == 1] \{M\_F = 1\}$

There are conditions for the algorithm to move and there is an action which is taking place.

$(M\_F == 1)$  and  $(M\_B == 1)$  creates a PWM for control of the motor.



There is a history for the system which is in the slots block:



## An LCD for the counter

