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1 Remarks

1.1 Warning!

- 1. Read every statement!
- 2. Do not copy-paste without thinking about it.
- 3. Be careful of overflows! Use long!
- 4. Do not trust this document!

1.2Operations on bits

- 1. Check parity of n : (n & 1) == 0
- 2. $2^n : 1L << n$.
- 3. Test of the *i*th bit of n is 0 : (n & 1L << i) != 0
- 4. Set the *i*th bit of n at $0 : n &= \sim (1L \ll i)$
- 5. Set the *i*th bit of n at 1 : $n = (1L \ll i)$
- 6. Union : a | b
- 7. Intersection: a & b
- 8. Subtraction bits : a & ~b
- 9. Verify if *n* is a power of 2 : (n & (n-1) == 0)
- 10. Least significant bit not null of n:(n & (-n))
- 11. Negate: 0 x7fffffff ^n

Complexity table

| n < | Maximum complexity |
|----------|--------------------------|
| [10, 11] | $O(n!), O(n^6)$ |
| [15, 18] | $O(2^n n^2)$ |
| [18, 22] | $O(2^n n)$ |
| 100 | $O(n^4)$ |
| 400 | $O(n^3)$ |
| 2K | $O(n^2 \log(n))$ |
| 10K | $O(n^2)$ |
| 1M | $O(n\log(n))$ |
| 10M | $O(n), O(\log(n)), O(1)$ |

Not so obvious complexity:

$$\sum_{k=1}^{n} \frac{1}{k} = O(\log(n))$$

2 Graphs

2.1 Basics

- Adjacency matrix : A[i][j] = 1 if i is connected to j and 0 otherwise
- Undirected graph : $A[i][j] = A[j][i] \ \forall \ i, j \ (A = A^T)$
- Adjacency list: LinkedList<Integer>[] g; g[i] stores all neighbors of i
- Useful alternatives:

HashSet<Integer >[] g; // for edge deletion $HashMap\!\!<\!\!Integer\;,\;\;Integer>[]\;\;g\;;\;\;//\;\;for\;\;weighted$

Basic classes

```
class Edge implements Comparable<Edge> {
  int o, d, w;
  public Edge(int o, int d, int w) {
    this.o = o; this.d = d; this.w = w;
  public int compareTo(Edge o) {
    return w - o.w;
}
```

2.2 BFS

Computes d, an array of distance from start vertex v. d[v] = 0, $d[u] = \infty$ if u not connected to v. If $(u, w) \in E$ and d[u] known and d[w] unknown, d[w] = d[u] + 1.

```
int[] bfsVisit(LinkedList < Integer > [] g, int v, int c[])
     { //c is for connected components only
  Queue<Integer> Q = new LinkedList<Integer>();
 Q. add(v);
 int[] d = new int[g.length];
 c[v]=v; //for connected components
  Arrays.fill(d, Integer.MAX_VALUE);
  // set distance to origin to 0
 d[v] = 0;
  while (!Q. isEmpty()) {
    int cur = Q. poll();
    // go over all neighbors of cur
    for (int u : g[cur]) {
      // if u is unvisited
      if(d[u] = Integer.MAX_VALUE) \{ //or c[u] = -1 \}
    if we calculate connected components
        c[u] = v; //for connected components
        Q.add(u);
         / set the distance from v to u
        d[u] = d[cur] + 1;
  return d;
```

2.2.1 Connected components

```
int[] bfs(LinkedList<Integer>[] g)
 int[] c = new int[g.length];
  Arrays. fill (c, -1);
  for(int v = 0; v < g.length; v++)
    if(c[v] = -1)
      bfsVisit(g, v, c);
 return c;
```

2.2.2 Girth

The girth of an undirected graph is the length of its shortest cycle (∞ if none). Complexity O(|V||E|).

```
int girth(LinkedList<Integer>[] g) {
 int girth = Integer.MAX_VALUE;
  for (int v = 0; v < g.length; v++) {
    girth = Math.min(girth, checkFromV(v, g));
  return girth;
int checkFromV(int v, LinkedList<Integer>[] g) {
  int[] parent = new int[g.length];
  Arrays. fill (parent, -1);
  int[] d = new int[g.length];
  Arrays.fill(d, Integer.MAX_VALUE);
  Queue<Integer > Q = new LinkedList<Integer >();
 Q.add(v);
 d[v] = 0;
  while (!Q. isEmpty()) {
    int cur = Q. poll();
    for(int u : g[cur]) {
      if(u != parent[cur]) {
        if(d[u] = Integer.MAX_VALUE) {
          parent[u] = cur;
          d[u] = d[cur] + 1;
          Q.add(u);
        } else {
          return d[cur] + d[u] + 1;
      }
```

```
}
}
return Integer.MAX_VALUE;
```

2.3 DFS

Equals to BFS with Stack instead of Queue or recursive implementation. Complexity O(|V| + |E|)

```
int UNVISITED = 0, OPEN = 1, CLOSED = 2;
boolean cycle; // true iff there is a cycle
void dfsVisit(LinkedList<Integer>[] g, int v,int[]
  label[v] = OPEN;
  \begin{array}{l} \text{for(int } u : g[v]) \ \{ \\ \text{if(label[u]} = \text{UNVISITED)} \end{array}
       dfsVisit(g, u, label);
    if(label[u] = OPEN)
       cycle = true;
  label[v] = CLOSED;
void dfs(LinkedList<Integer>[] g) {
  int[] label = new int[g.length];
  Arrays. fill(label, UNVISITED);
  cycle = false;
  for(int v = 0; v < g.length; v++)
    if(label[v] == UNVISITED)
       dfsVisit(g, v, label);
```

2.3.1 Topological order

Graph must be acyclic.

2.3.2 Strongly connected components

Uses BFS following the topologic order.

```
int[] scc(LinkedList < Integer > [] g) {
    compute the reverse graph
  LinkedList < Integer > [] gt = transpose(g);
  // compute ordering
  dfs(gt);
  // !! last position will contain the number of scc's
  int[] scc = new int[g.length + 1];
  Arrays. fill (scc, -1);
  int nbComponents = 0;
  // simulate bfs loop but in toposort ordering
  while(!toposort.isEmpty()) {
    int v = toposort.pop();
    if(scc[v] = -1) {
      nbComponents \!\!+\!\!+;
      bfsVisit(g, v, scc);
  scc[g.length] = nbComponents;
```

```
return scc:
2.3.3 SCC and Articulation Points in C
C version of SCC (shorter).
void tarjanSCC(int u)
  dfs_low[u] = dfs_num[u] = dfsNumberCounder++; //
    dfs_low[u] <= dfs_num[u]
  S.push_back(u); // stores u in a vector based on
    order of visitation
  visited[u] = 1;
  for(int j = 0; j < (int) AdjList[u].size(); j++) {
    ii v = AdjList[u][j];
    if (dfs_num[v.first] == UNVISITED)
    tarjanSCC(v.first);
    if(visited[v.first]) // condition for update
       dfs_low[u] = min(dfs_low[u], dfs_low[v.first]);
  if (dfs\_low[u] == dfs\_num[u]) \ \{ \ // \ if \ this \ is \ a \ root \ (
     start) of an SCC
    printf("SCC %d:", ++numSCC); // this part is done
    after recursion
    while (1) {
      int v = S.back(); S.pop\_back(); visited[v] = 0;
       printf(" %d", v);
      if (u == v) break;
    printf("\n");
}
int main() {
  \begin{array}{l} dfs\_num.assign\left(V,\ UNVISITED\right);\ dfs\_low.assign\left(V,\ 0\right);\\ visited.assign\left(V,\ 0\right);\ dfsNumberCounter = numSCC = 0; \end{array}
  for (int i = 0; i < V; i++)
    if (dfs_num[i] == UNVISITED)
      tarjanSCC(i);
Articulation points.
void articulationPointAndBridge(int u) {
  dfs_low[u] = dfs_num[u] = dfsNumberCounter++; //
    dfs_low[u] <= dfs_num[u]
  for(int j = 0; j < (int)AdjList[u].size(); j++) {
    ii v = AdjList[u][j];
    if(dfs_num[v.first] = UNVISITED) { // a tree edge}
       dfs_parent[v.first] = u;
       if(u == dfsRoot) rootChildren++; // special case
     if u is a root
       articulation Point And Bridge (v.\,first);\\
       \begin{array}{l} if(\,dfs\_low\,[\,v.\,first\,] >= \,dfs\_num\,[\,u\,]\,) \ // \ for \end{array}
     articulation point
         articulation_vertex[u] = true; // store this
    information first
       if(dfs\_low[v.first] > dfs\_num[u]) // for bridge
         printf("Edge (%d %d) is a bridge\n", u, v.first
       dfs_low[u] = min(dfs_low[u], dfs_low[v.first]);
     // update dfs_low[u]
    else if (v.first != dfs_parent[u]) // a back edge
    and not direct cycle
       dfs_low[u] = min(dfs_low[u], dfs_num[v.first]);
     // update dfs_low[u]
int main() {
  dfsNumberCounter = 0; dfs_num.assign(V, UNVISITED);
  dfs\_low.assign\left(V,\ 0\right);\ dfs\_parent.assign\left(V,\ 0\right);
     articulation_vertex.assign(V, 0);
```

// special case

dfsRoot = i; rootChildren = 0; articulationPointBridge(i);

articulation_vertex[dfsRoot] = (rootChildren > 1);

```
printf("Articulation Points:\n");
for(int i = 0; i < V; i++)
  if(articulation_vertex[i])
  printf("Vertex %d\n", i);</pre>
```

2.3.4 Directed Graph to toposorted DAG

In O(n+m), with Tarjan SCC algo, we merge the SCCs and take the resulting DAG, (remembering their size in scc_size) which is reverse toposorted (i.e. node 0 has no outgoing edge), ready for bottom up DP (starting with node 0 ending with node N)!

```
node N)!
static Integer[] dfs_num;
static int[] dfs_low, scc_id;
static BitSet visited;
static int dfsNumberCounter;
static Stack<Integer> S;
{\color{red} {\rm static}} \ \ {\color{red} {\rm void}} \ \ {\color{red} {\rm tarjanSCC}(LinkedList{<} Integer>[]} \ \ {\color{red} {\rm g}}, \ \ {\color{red} {\rm int}} \ {\color{red} {\rm u}},
    LinkedList< LinkedList<Integer>> SCCs)
  dfs_low[u] = dfsNumberCounter;
  dfs_num[u] = dfsNumberCounter++; // dfs_low[u] <=
    dfs_num[u]
  S.add(u); // stores u in a vector based on order of
     visitation
  visited.set(u);
  for(int v : g[u]) {
    if(dfs_num[v] = null)
       tarjanSCC(g, v, SCCs);
    if (visited.get(v)) // condition for update
       dfs_low[u] = Math.min(dfs_low[u], dfs_low[v]);
  if(dfs_low[u] = dfs_num[u])  { // if this is a root (
    start) of an SCC
    LinkedList<Integer> newSCC = new LinkedList<Integer
     >();
    int id = SCCs.size();
    for (;;) {
      int v = S.pop(); visited.clear(v);
      newSCC.add(v):
       scc_id[v] = id;
       if(u = v) break;
    SCCs.add(newSCC);
}
static LinkedList < Integer > [] DirectedGraphToDag (
    LinkedList<Integer>[] g) {
  int n = g.length;
  dfs_num = new Integer[n];
  dfs\_low = new int[n];
  scc_id = new int[n];
  visited = new BitSet(n);
  dfsNumberCounter = 0;
  S = new Stack < Integer > ();
  LinkedList< LinkedList<Integer>> SCCs = new
    LinkedList< LinkedList<Integer> >();
  for (int i = 0; i < n; i++)
    if (dfs_num[i] == null)
       tarjanSCC(g, i, SCCs);
  int N = SCCs.size();
  @SuppressWarnings("unchecked")
  LinkedList < Integer > [] G = new LinkedList [N];
  scc\_size = new int[N];
  int i = 0:
  for (LinkedList<Integer> SCC : SCCs) {
    G[i] = new LinkedList<Integer>();
    scc\_size[i] = SCC.size();
    BitSet reachable = new BitSet(N);
    reachable.set(i);
    for (int u : SCC)
       for (int v : g[u])
         i f
            (!reachable.get(scc_id[v])) {
           G[i].add(scc\_id[v]);
    i++;
```

```
return G;
}
static int[] scc_size; // bonus information
```

2.4 Minimum Spanning Tree

2.4.1 Prim

```
double prim(LinkedList<Edge>[] g) {
  boolean[] inTree = new boolean[g.length];
  PriorityQueue<Edge> PQ = new PriorityQueue<Edge>();
  // add 0 to the tree and initialize the priority
    aueue
  inTree[0] = true;
  for(Edge e : g[0]) PQ.add(e);
  double weight = 0;
  int size = 1;
  while (size != g.length) {
     / poll the minimum weight edge in PQ
    Edge minE = PQ. poll();
      if its endpoint in not in the tree, add it
    if (!inTree[minE.d]) {
      // add edge minE to the MST
      inTree[minE.d] = true;
      weight += minE.w;
      size++;
      // add edge leading to new endpoints to the PQ
      for (Edge e : g[minE.d])
        if (!inTree[e.d]) PQ.add(e);
 return weight;
```

2.4.2 Kruskal

```
Uses Union-Find (See section 7.4).
double kruskal(LinkedList<Edge> g, int n) {
   Collections.sort(g);
   UnionFind uf = new UnionFind(n);
   double w = 0;
   int c = 0;
   for(Edge e: g) {
      if(c == n-1) return w;
      if(uf.find(e.o) != uf.find(e.d)) {
        w+=e.w;
      c++;
      uf.union(e.o, e.d);
    }
}
return w;
}
```

2.5 Dijkstra

Shortest path from a node v to other nodes. Graph must not have any negative weighted cycle.

2.6 Bellman-Ford

Shortest path from a node v to other nodes. Graph can have negative weighted cycles: Bellman-Ford won't give the correct shortest path, but will warn that a negative cycle exists. static double[] bellmanFord(LinkedList<Edge> gt, int v, $int n) {$ double[] dist = new double[n]; Arrays.fill(dist, Double.POSITIVE_INFINITY); dist[v] = 0;for (int i=0; i < n-1; i++) for (Edge e : gt) if(dist[e.o] + e.w < dist[e.d])dist[e.d] = dist[e.o] + e.w;for (Edge e : gt) if(dist[e.o] + e.w < dist[e.d])return null; return dist; static double[] spfa (LinkedList<Edge>[] g, int s) { int n = g.length; double[] dist = new double[n]; Arrays.fill(dist, Double.POSITIVE_INFINITY); Queue<Integer> q = new LinkedList<Integer>(); BitSet inQueue = new BitSet(n);int[] timesIn = new int[n];dist[s] = 0;q.add(s); inQueue.set(s);
timesIn[s]++; while (!q.isEmpty()) { int cur = q.poll(); inQueue.clear(cur); for (Edge next : g[cur]) { int v = next.d, w = next.wif (dist[cur] + w < dist[v]) { dist[v] = dist[cur] + w;if (!inQueue.get(v)) { q.add(v);inQueue.set(v); timesIn[v]++;if (timesIn[v] >= n) {
 return null; // Infinite loop } } } return dist;

2.7 Floyd-Warshall

Shortest path from a node v to other nodes. Graph can have negative weighted cycles: Floyd-Warshall won't give the correct shortest path, but will warn that a negative cycle exists. Negative weighted cycles exists iif result[v][v] < 0. $O(|V|^3)$ in time and $O(|V|^2)$ in memory.

2.8 Directed Max flow

2.8.1 Edmonds-Karps (BFS)

Path in residual graph searched via BFS. $O(|V||E|^2)$.

```
int maxflowEK(TreeMap<Integer, Integer>[] g, int source
     , int sink) {
  int flow = 0;
  int pcap;
  while ((pcap = augmentBFS(g, source, sink)) != -1) {
     flow += pcap;
  return flow;
int augmentBFS(TreeMap<Integer, Integer>[] g, int
     source, int sink) {
    / initialize bfs
  Queue<Integer> Q = new LinkedList<Integer>();
  Integer[] p = new Integer[g.length];
  int[] pcap = new int[g.length];
  pcap[source] = Integer.MAX_VALUE;
  p[source] = -1;
  Q.add(source);
  // compute path
  \label{eq:while} \begin{aligned} & \text{while}(\texttt{p}[\, \text{sink} \,] \, = \, \text{null} \, \, \&\& \, \, !Q.\, \text{isEmpty}()) \, \, \, \{ \end{aligned}
     int u = Q.poll();
     \begin{array}{lll} & \text{for} \left( \text{Entry} {<} \text{Integer} \;,\;\; \text{Integer} > \; \text{e} \;\; : \; \text{g[u].entrySet()} \right) \;\; \{ \end{array}
       int v = e.getKey();
       if(e.getValue() > 0 \&\& p[v] = null) {
          p[v] = u;
          pcap[v] = Math.min(pcap[u], e.getValue());
         Q.add(v);
       }
     }
  if(p[sink] = null) return -1;
  // update graph
  int cur = sink;
  while (cur != source) {
     int prev = p[cur];
     int cap = g[prev].get(cur);
     g[prev].put(cur, cap - pcap[sink]);
     Integer backcap = g[cur].get(prev);
     g[cur].put(prev, backcap = null? pcap[sink] :
     backcap + pcap[sink]);
     cur = prev;
  return pcap[sink];
```

2.8.2 Ford-Fulkerson

Equals to Edmonds-Karps, vut with a DFS. $O(|E|f^*)$ where f^* is the value of the max flow.

```
int pcap;
int maxflowFF(TreeMap<Integer, Integer>[] g, int source
    , int sink) {
  int flow = 0;
  pcap = Integer.MAX_VALUE;
  while (augmentDFS(g, source, sink, new boolean[g.
    length])) {
    flow += pcap;
    pcap = Integer.MAX_VALUE;
  return flow;
}
boolean augmentDFS(TreeMap<Integer, Integer>[] g, int
    cur, int sink, boolean[] done) {
  if(cur == sink) return true;
  if(done[cur]) return false;
  done[cur] = true;
  for(Entry<Integer, Integer> e : g[cur].entrySet()) {
    if(e.getValue() > 0) {
```

```
int oldcap = pcap;
pcap = Math.min(pcap, e.getValue());
if(augmentDFS(g, e.getKey(), sink, done)) {
    g[cur].put(e.getKey(), e.getValue() - pcap);
    Integer backcap = g[e.getKey()].get(cur);
    g[e.getKey()].put(cur, backcap == null? pcap :
backcap + pcap);
    return true;
} else {
    pcap = oldcap;
}

return false;
```

2.8.3 Min cut

We search, between two nodes s and t, V_1 and V_2 so as $s \in V_1$, $t \in V_2$ and $\sum_{e \in E(V_1, V_2)} w(e)$ minimum.

We just have to compute the max-flow between s and t and to apply a BFS/DFS on the residual graph. All node which are visited are in V_1 , others in V_2 . The weight from the cut is the max-flow.

2.8.4 Maximum number of disjoint paths

For edge disjoint paths just compute the max flow with unit capacities. For vertex disjoint paths split vertices into two with unit capacity edge between them.

2.8.5 Maximum weighted bipartite matching

Assignment problem: Given a set of n persons and n jobs, an a cost matrix M assign a job to each person to that the sum of the costs is minimized. It also works for n persons and m jobs with $n \neq m$. Just fill make a square matrix using dummy values. Can also be solve with min cost max flow but it is slower.

```
O(n^3) solution:
static int[][] cost;
static int n;
static int[] lx, ly;
static int maxMatch;
static boolean[] S, T;
static int[] slack, slackx, prev, xy, yx;
static int[] minHungarian(int[][] M) {
  for (int i = 0; i < M. length; i++)
    for (int j = 0; j < M. length; j++)
      M[\;i\;]\;[\;j\;]\;=\!-\!M[\;i\;]\;[\;j\;]\;;
  return maxHungarian(M);
static int[] maxHungarian(int[][] M) {
  cost = M;
  n = cost.length;
  slack = new int[n];
  slackx = new int[n];
  prev = new int[n];
  xy = new int[n];
  yx = new int[n];
  \max Match = 0;
  for (int i = 0; i < n; i++) {
    xy[i] = -1;
    yx[i] = -1;
  initLabels();
  augment();
  int ret = 0;
  int[] assignment = new int[n];
  for (int x = 0; x < n; x++) {
    ret += cost[x][xy[x]];
    assignment[x] = xy[x];
```

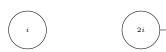
```
return assignment;
static void initLabels() {
  lx = new int[n];
  ly = \underline{new} \ \underline{int} [n];
  for (int x = 0; x < n; x++)
    for (int y = 0; y < n; y++)
      lx[x] = Math.max(lx[x], cost[x][y]);
static void augment() {
  if (maxMatch == n) {return;}
  int x, y, root = 0;
  int[] q = new int[n];
  int wr = 0, rd = 0;
  S = new boolean[n];
  T = new boolean[n];
  for (x = 0; x < n; x++)
    \operatorname{prev}[x] = -1;
  for (x = 0; x < n; x++) {
    if(xy[x] = -1) {
      q[wr++] = root = x;
      \operatorname{prev}[x] = -2;
      S[x] = true;
      break;
    }
  for(y = 0; y < n; y++) {
    slack[y] = lx[root] + ly[y] - cost[root][y];
    slackx[y] = root;
  while(true) {
    while (rd < wr) {
      x \, = \, q \, [\, rd +\! +\! ]\,;
      for (y = 0; y < n; y++) {
        T[y] = true;
          q[wr++] = yx[y];
          addToTree(yx[y], x);
      if (y < n) \{break;\}
    if (y < n) \{break;\}
    updateLabels();
    wr = rd = 0;
    for (y = 0; y < n; y++) {
      if (!T[y] \&\& slack[y] == 0) {
        if(yx[y] = -1) {
          x = slackx[y];
          break:
        } else {
          T[y] = true;
           if (!S[yx[y]]) {
            q[wr++] = yx[y];
             addToTree(yx[y], slackx[y]);
    if(y < n) \{break;\}
  if(y < n) {
    maxMatch++;
    for (int cx=x, cy=y, ty; cx!=-2; cx=prev[cx], cy=ty)
      ty = xy[cx];
      yx[cy] = cx;
      xy[cx] = cy;
    augment();
  }
}
static void updateLabels() {
  int delta = Integer.MAX_VALUE;
```

```
for (int y = 0; y < n; y++)
    if (!T[y])
       delta = Math.min(delta, slack[y]);
  for (int i = 0; i < n; i++) {
    if(S[i]) \{lx[i] = delta;\}
    if(T[i]) \{ly[i] \leftarrow delta;\}
    if (!T[i]) {slack[i] -= delta;}
static void addToTree(int x, int prevx) {
  S[x] = true;
  prev[x] = prevx;
  for (int y = 0; y < n; y++) {
    if(lx[x] + ly[y] - cost[x][y] < slack[y]) {
      slack[y] = lx[x] + ly[y] - cost[x][y];
      slackx[y] = x;
    }
}
O(n2^n) solution using DP (very simple to code):
int n;
{\color{red} \textbf{double}} \ [\ ] \ [\ ] \ \ w;
Double [] memo;
double minCostMatching(int paired) {
  if (memo[paired] != null) return memo[paired];
  if (paired = (1 << n) - 1) return 0.0;
  double min = Double.POSITIVE_INFINITY;
  int i = 0;
  while (((paired >> i) \& 1) == 1) i++;
  for (int j = i + 1; j < n; j++) {
    if(((paired >> j) \& 1) == 0) {
      min \, = \, Math.\,min\big(min\,,\ w[\ i\ ]\,[\ j\ ] \, + \, minCostMatching(
     paired | (1 << i) | (1 << j));
  memo[paired] = min;
  return min:
}
```

2.9 Directed Min cost flow

Avoinding parallel edges:

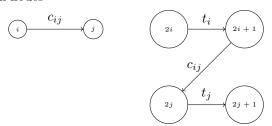
1. Split nodes



where t_i is the number of times node i can be used (usualy ∞).

2i + 1

2. Link nodes



```
}
h[2*v].put(2*v+1, new Edge(Integer.MAX_VALUE,0));
}
return h;
```

Min cost flow analogous to max flow but using Bellman-Ford to find paths (can be made faster using Dijkstra by chaning costs). Using SPFA achieves similar perfomance than Dijkstra if test cases are not designed to break it.

```
int[] p;
int minCostFlow(TreeMap<Integer, Edge>[] g, int s, int
    t) {
  int mincost = 0;
  while(spfa(g, s) != null && p[t] != −1) {
    // compute path capacity
    int cur = t;
    int pcap = Integer.MAX VALUE;
    while (cur != s) {
      int prev = p[cur];
      pcap \,=\, Math.\,min(\,pcap\,,\ g\,[\,prev\,]\,.\,get\,(\,cur\,)\,.\,cap\,)\,;
      cur = prev;
    // update graph
    cur = t;
    int pcost = 0;
    while (cur != s) {
      int prev = p[cur];
      Edge epath = g[prev].get(cur);
pcost += epath.cost * pcap;
      // update current edge
      if(epath.cap = pcap) g[prev].remove(cur);
      else epath.cap -= pcap;
       // update reverse edge
      Edge eback = g[cur].get(prev);
      if(eback != null) eback.cap += pcap;
      else g[cur].put(prev, new Edge(pcap, -epath.cost)
    )
      cur = prev;
    mincost += pcost;
  return mincost;
```

Some changes to SPFA may be necessary. Computation of global variable p containing parents is required.

2.10 Chinese Postman Problem

Given an undirected weighted graph, compute the minimum length tour that visits every edge (edges may be visited several times, unavoidable if odd degree vertices exist). The number of odd degree vertices is even. Hence we can compute the minimum weight bipartite matching between them where w_{ij} is the length of the shortest path between i and j. Then the length of the tour is given by the sum of the lengths of all edges plus the weight of the matching.

2.11 Bipartite graph

```
 \begin{array}{l} Check \ if \ bipartite \\ \hline boolean \ is Bipartite (LinkedList < Integer > [] \ g) \\ \{ \\ int [] \ d = bfs(g); \\ for (int \ u = 0; \ u < g.length; \ u++) \\ for (Integer \ v : g[u]) \\ if ((d[u]\%2)! = (d[v]\%2)) \ return \ false; \\ return \ true; \\ \} \end{array}
```

Matching 2.11.1 Max Cardinality **Bipartite** (MCBM)

Pairing of adjacent nodes. No node in two different pairs.

- Max Flow.
- Augmenting Path: path starting at non-matched, ending at non-matched, even edges are matching. MCBM ssi no augmenting path. Start from non-matched, if augmenting path, augment (do not have to take all matching in the augmenting path).

MCBM: Number of matching.

2.11.2 Independent Set (or Dominating Set)

Set of vertices with no edges between them. MIS, add a vertex create an edge. In **bipartite** graph, MIS + MCBM = V.

2.11.3 Vertex Cover

Vertices such that each edge is adjacent to at least one vertex. Min Vertex Cover (MVC). In bipartite graph, MVC = MCBM.

In **general** graph, MVC = MIS and the MVC is the complementary of MIS.

```
static int n; // V
static int m; // vertex on the left subset of V
static LinkedList<Integer>[] g;
static int[] match;
static BitSet visited;
private static int Aug(int left) {
  if (visited.get(left)) return 0;
  visited.set(left);
  for (int right : g[left]) {
     if \ (match[right] = -1 \ || \ Aug(match[right]) = 1) \ \{ \\
      match[right] = left;
      return 1; // we found one matching
  return 0; // no matching
static int mcbm () {
  int MCBM = 0;
  match = new int[n];
  for (int i = 0; i < n; i++) {
   \mathrm{match}\left[i\right] = -1;
  for (int l = 0; l < m; l++) {
    visited = new BitSet(n);
   MCBM += Aug(1);
  return MCBM;
```

Dynamic programming

3.1Bottom-up

Give n objects of value v[i] to 3 people such that $\max_i V_i$ $\min_{i} V_{i}$ is minimum (V_{i} is total value for person i). $canDo[i][v_1][v_2] = 1$ if we can give the objects $0, 1, \ldots, i$ such that v_1 is going to P_1 and v_2 to P_2 , 0 otherwise. v_3 is determined from the sum.

```
Case i \geq 1:
Base case i = 0:
                                 canDo[i][v_1][v_2] =
   -- canDo[0][0][0] = 1
                                  canDo[i-1][v_1][v_2] \vee
   -- canDo[0][v[0]][0] = 1
                                  canDo[i-1][v_1-v[i]][v_2] \lor
   -- canDo[0][0][v[0]] = 1
                                  canDo[i-1][v_1][v_2-v[i]]
```

```
Sol.: \min_{v_1, v_2: canDo[n-1][v_1][v_2]} \quad [max(v_1, v_2, S - v_1 - v_2) - v_1] = \sum_{i=1}^{n} \sum_{j=1}^{n} \sum_{j=1}^{n} \sum_{i=1}^{n} \sum_{j=1}^{n} \sum_{j
min(v_1, v_2, S - v_1 - v_2)
int solveDP() {
        boolean\,[\,]\,[\,]\,[\,]\,\,canDo\,=\,new\,\,boolean\,[\,v\,.\,length\,]\,\lceil\,sum\,+\,\,1\,]\,\lceil\,
                 sum + 1;
         // initialize base cases
        canDo[0][0][0] = true;
         canDo [0]
                                          [v[0]][0] = true;
        canDo[0][0][v[0]] = true;
         // compute solutions using recurrence relation
         for (int i = 1; i < v.length; i++) {
                  for (int a = 0; a \le sum; a++) {
                          for (int b = 0; b \le sum; b++) {
                               boolean give A = a - v[i] >= 0 \&\& canDo[i - 1][a
                      - v[i]][b];
                                 boolean giveB = b - v[i] >= 0 \&\& canDo[i - 1][a
                  |[b - v[i]];
                                 boolean giveC = canDo[i - 1][a][b];
                                 canDo[i][a][b] = giveA || giveB || giveC;
                }
         // compute best solution
         int best = Integer.MAX_VALUE;
         for (int a = 0; a \le sum; a++) {
                 for (int b = 0; b \le sum; b++) {
                          if(canDo[v.length - 1][a][b]) {
                                 best = Math.min(best, max(a, b, sum - a - b) -
                 min(a, b, sum - a - b));
                         }
         return best;
```

Top-down 3.2

Same problem as bottom-up. Main idea: memoization (Remember intermediate results).

```
int solve(int i, int a, int b) {
  if(i == n) {
   memo[i][a][b] = max(a, b, sum - a - b) - min(a, b,
    sum - a - b);
    return memo[i][a][b];
  if(memo[i][a][b] != null) {
    return memo[i][a][b];
 int giveA = solve(i + 1, a + v[i], b);
 int giveB = solve(i + 1, a, b + v[i]);
 int giveC = solve(i + 1, a, b);
 memo[i][a][b] = min(giveA, giveB, giveC);
  return memo[i][a][b];
```

Knapsack problem

Given n objects of value v[i] and weight w[i], an integer W:

- $\begin{array}{ll} -- & \text{Maximize } \sum_{i} x[i]v[i] \\ -- & \text{Such that } \sum_{i} x[i]w[i] \leq W \end{array}$ where x[i] = 0 (not taken) or 1 (taken)

3.3.1 No repetition

best[i][w]= best way to take objects $0, 1, \ldots, i$ in a knapsack of capacity w.

```
Other cases:
Base case:
                              best[i][w] =
   -best[0][w] = v[0]
                                \max\{best[i-1][w],
      si \ w[0] \le w
                                 best[i-1][w-w[i]] + v[i]
   — 0 else
```

3.3.2 An object can be repeated

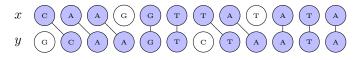
```
 -best[0] = 0 
 -best[w] = \max_{i:w[i] \le w} \{best[w - w[i]] + v[i]\}
```

3.3.3 Several knapsacks

 $best[i][w_1][w_2] = best$ way to take objects 0, 1, ..., i in knapsacks of capacity w_1 and w_2 .

3.4 Longest common sub-sequence (LCS)

Given two String x and y. Find the longest common subsequence between x and y.



- Formulation : lcs[i][j] = size of $LCS(x[0]x[1] \cdots x[i-1], y[0]y[1] \cdots y[j-1])$
- Base case : lcs[0][j] = 0 lcs[i][0] = 0
- Other cases:
 - Other cases:

 Si x[i-1] = y[i-1] alors: lcs[i][j] = 1 + lcs[i-1][j-1]Si $x[i-1] \neq y[i-1]$ alors: $lcs[i][j] = \max\{lcs[i-1][j], lcs[i][j-1]\}$

3.5 Matrix Chain Multiplication (MCM)

Given a list of matrices, find the order minimizing the number of multiplications to compute their product.

- Number to multiply a matrix of size $n \times m$ by a matrix of size $m \times r : n \cdot m \cdot r$.
- Example : $A : 10 \times 30$, $B : 30 \times 5$ et $C : 5 \times 60$.
- For $(AB)C: 10 \cdot 30 \cdot 5 + 10 \cdot 5 \cdot 60 = 4500$ multiplications.
 - For $A(BC): 30 \cdot 5 \cdot 60 + 10 \cdot 30 \cdot 60 = 27000$ multiplications.
- Formulation : $best[i][j] = min cost to multiply A_i, ..., A_j$
- Base case : best[i][i] = 0
- Other cases:

$$best[i][j] = \min_{i \le k < j} best[i][k] + best[k+1][j] \\ + A_i.n_1 \times A_k.n_2 \times A_j.n_2$$

3.5.1 Generalized MCM

Given a list of objects $x[0], \ldots, x[n-1]$ and an operation \odot with an associated cost, find the order in which perform the operations to minimize the total cost. The matrix product is replaced by \odot .

$$best[i][j] = \min_{i \leq k < j} best[i][k] + best[k+1][j] + cost(i,j,k)$$

cost(i, j, k) is the cost of $(x[i] \odot \cdots \odot x[k]) \odot (x[k+1] \odot \cdots \odot x[j])$.

```
int bestParenthesize() {
  int n = x.length; // x is a global variable
  int[][] best = new int[n][n];
  for(int i = 0; i < n; i++) {
    best[i][i] = 0;
  }
  for(int l = 1; l <= n; l++) {</pre>
```

```
for(int i = 0; i < n - 1; i++) {
   int j = i + 1;
   int min = Integer.MAX_VALUE;
   for(int k = i; k < j; k++) {
      min = Math.min(min, best[i][k] + best[k + 1][j]
      + cost(i, j, k)); // cost is problem-independent
   }
   best[i][j] = min;
   }
}
return best[0][n - 1];
}</pre>
```

3.6 Edit distance

Given two String x and y, by performing operations on en x, compute the minimal cost to transform x into y.

We can (operation cost):

- 1. Remove a character (D=1)
- 2. Insert a character (I=1)
- 3. Replace a character(R=2)
- **Formulation** : editDist[i][j] = min. cost to transform $x_0 \cdots x_{i-1}$ into $y_0 \cdots y_{i-1}$
- Base case : $editDist[i][0] = i \cdot D \quad editDist[0][j] = j \cdot I$ Other cases :

```
editDist[i][j] = min editDist[i-1][j] + D,

editDist[i][j-1] + I,

editDist[i-1][j-1] + R^*
```

where $R^* = R$ if $x[i-1] \neq y[j-1]$, 0 else.

```
int editDistance(String txt1, String txt2, int I, int D
     , int R) {
  int[][] d = new int[txt1.length()+1][txt2.length()
    +1];
  for(int i=0; i <= txt1.length(); i++)</pre>
    d[i][0] = i*D;
  for(int j=0; j \le txt2.length(); j++)
    d[0][j]=j*I;
  for(int i=1; i \le txt1.length(); i++){
    for (int j=1; j \le txt2.length(); j++){
       int cost;
       // Non-equality cost
       if(txt1.charAt(i-1)=txt2.charAt(j-1))
         cost = 0;
         cost = R;
        / Deletion, Insertion, Replacement
      d[i][j] = Math.min(Math.min(d[i-1][j] + D, d[i][j])
    -1] + I), d[i-1][j-1] + cost);
  // Last computed element is the edit distance
  \begin{array}{ll} \textbf{return} & d\,[\,txt1\,.\,length\,(\,)\,\,]\,[\,txt2\,.\,length\,(\,)\,\,]; \end{array}
```

3.7 Suffix array



3.7.1 $O(n \log(n)^2)$, full matrix, need $n \leq 10K$

- Suffix array of *algorithm* = algorithm, gorithm, hm, ithm, lgorithm, m, orithm, rithm, thm
- Characterized by its starting index Example: Suffix array of algorithm:

Example: Given suf_j suffix beginning at index j, and C(i, j, k) comparison result of suf_j and suf_k on the 2^i first characters.

$$C(i, j, k) = C(i - 1, j, k)$$
 si $C(i - 1, j, k) \neq 0$
 $C(i - 1, j + 2^{i-1}, k + 2^{i-1})$ else

— Define a matrix so such that :

$$\begin{split} so[i][j] &= so[i][k] \Leftrightarrow C(i,j,k) = 0 \\ so[i][j] &< so[i][k] \Leftrightarrow C(i,j,k) < 0 \\ so[i][j] &> so[i][k] \Leftrightarrow C(i,j,k) > 0 \end{split}$$

so[i] is the order of sorted suffixes on the 2^i first characters.

- Base case: so[0][j] = (int)s.charAt(i)Example: for s = ccacab we have s[0] = [97, 97, 95, 97, 95, 96]
- For every j we define a triplet (l, r, j):

$$(s[i-1][j], s[i-1][j+2^{i-1}], j)$$
 si $j+2^{i-1} < n$
 $(s[i-1][j], -1, j)$ si $j+2^{i-1} \ge n$

```
class Triple implements Comparable<Triple> {
  int l, r, index;
  public Triple(int half1, int half2, int index) {
    this.l = half1;
    this.r = half2;
    this.index = index;
  };
  public int compareTo(Triple other) {
    if(l != other.l) {
      return l - other.l;
    }
    return r - other.r;
  }
}
```

```
int[][] suffixOrder(String s) { // O(n log^2(n))
  int n = s.length();
  int lg = (int)Math.ceil((Math.log(n) / Math.log(2)))
    + 1;
  int[][] so = new int[lg][n];
  // initialize so[0] with character order
  for (int i = 0; i < n; i++) {
    so[0][i] = s.charAt(i);
  Triple [] next = new Triple [n];
  for (int i = 1; i < lg; i++) {
    // build the next array
    for (int j = 0; j < n; j++) {
      int k = j + (1 << (i - 1));
      next[j] = new Triple(so[i-1][j], k < n ? so[i-1][j])
     1][k] : -1, j);
    // sort next array
    Arrays.sort(next);
    // build so[i]
    for (int j = 0; j < n; j++) {
      if(j = 0) {
      // smallest elements gets value 0
      so[i][next[j].index] = 0;
     } else if (next[j].compareTo(next[j-1]) == 0) {
      // equal to previous so it gets the same value
      so[i][next[j].index] = so[i][next[j-1].index];
     } else {
      // largest than previous so get + 1
      so[i][next[j].index] = so[i][next[j-1].index] +
     1;
  }
 return so;
//Calcule le Suffix Array pour un so donne :
int[] suffixArray(int[][] so) {
  int[] sa = new int[so[0].length];
  for (int j = 0; j < so[0]. length; j++) {
sa[so[so.length - 1][j]] = j;
  return sa:
//Retourne le plus long prefixe commun de suf_j (le
    suffixe de s commencant a j = s.substr(j)) et suf_k
     pour un so donne:
int lcp(int[][] so, int j, int k) { // O(log(n))
  int lcp = 0;
  int n = so[0]. length;
  for (int i = so.length - 1; i >= 0; i--) {
    if(j < n \&\& k < n \&\& so[i][j] = so[i][k]) {
      lcp += (1 << i);
      j += (1 << i);
      k += (1 << i);
    }
 return lcp;
//Quelques exemples
String maxStrRepeatedKTimes(String s, int k) {
 int[][] so = suffixOrder(s);
  int[] SA = suffixArray(so);
  int n = s.length();
 int max = Integer.MIN_VALUE;
  int j = 0;
  for (int i = 0; i \le n - k; i++) {
    int lcp = lcp(so, SA[i], SA[i+k-1]);
    if(lcp > max) {
      \max = lcp;
      j = SA[i];
  return s.substring(j, j + \max);
```

```
String minLexicographicRotation(String s) {
  int n = s.length();
  s += s;
  int[] SA = suffixArray(suffixOrder(s));
  int i = 0;
  while (!(0 \le SA[i] \&\& SA[i] < n)) {
   i++;
  return s.substring(SA[i], SA[i] + n);
}
class MaxLexConc implements Comparator<String> {
 public int compare(String x, String y) {
    String xy = x + y;
    String yx = y + x;
    if(xy.compareTo(yx) < 0 \mid \mid
       (xy.equals(yx) && x.length()<y.length())) {
      return 1;
    return -1;
}
3.7.2 O(n \log(n)), only last line, need n \leq 100K
static final int MAX_N = 100010;
static Integer[] tempSA, sa;
static int[] c, ra;
static int[] lcp, plcp;
static void countingSort(int n, int k) {
  int i, sum, maxi = Math.max(300, n); // up to 255
    ASCII chars or length of n
  for (i = 0; i < MAX_N; i++) c[i] = 0; // clear
    frequency table
  for (i = 0; i < n; i++) // count the frequency of
    each rank
    c[i + k < n ? ra[i + k] : 0]++;
  for (i = sum = 0; i < maxi; i++) {
    int t = c[i]; c[i] = sum; sum += t;
  for (i = 0; i < n; i++)
                                              // shuffle the
    suffix array if necessary
    tempSA[c[sa[i] + k < n ? ra[sa[i] + k] : 0]++] = sa
    [i];
  for (i = 0; i < n; i++)
                                                          //
    update the suffix array SA
    sa[i] = tempSA[i];
}
\mathbf{static} \ \ \mathbf{void} \ \ \mathbf{constructSA} \\ (\mathbf{char}[] \ \ \mathbf{s}) \ \ \{ \ \ // \ \ O(n \ \log{(n)}) \ -\!\!\!> n \\
     <= 100 K
  int i, k, r, n = s.length;
  tempSA = new \ Integer[n]; \ sa = new \ Integer[n];
  ra = new int[n]; int[] tempRA = new int[n];
  c = new int [MAX_N];
  \label{eq:formula} \mbox{for } (\,i \,=\, 0\,; \ i \,<\, n\,; \ i+\!\!\!\!+) \,\, ra\,[\,i\,] \,=\, s\,[\,i\,]\,;
           // initial rankings
  \mbox{for } (\,i \,=\, 0\,; \ i \,<\, n\,; \ i+\!\!\!\!+) \,\, sa\,[\,i\,] \,=\, i\,; \label{eq:formula}
    initial SA: {0, 1, 2, ...,
                                   n-1
  for (k = 1; k < n; k <<= 1) {
                                                 // repeat
    sorting process log n times
    countingSort(n, k);
                               // actually radix sort:
    sort based on the second item
    countingSort(n, 0);
                                            // then (stable)
    sort based on the first item
    tempRA[sa[0]] = r = 0;
                                                  // re-
    {\tt ranking}\,;\ {\tt start}\ {\tt from}\ {\tt rank}\ {\tt r}\,=\,0
    for (i = 1; i < n; i++)
                                                           //
    compare adjacent suffices
                             // if same pair => same rank
      tempRA[sa[i]] =
     r; otherwise, increase r
       [i-1]+k]) ? r : ++r;
    for (i = 0; i < n; i++)
     update the rank array RA
      ra[i] = tempRA[i];
  } }
static void computeLCP(char[] s) {
  int i, L, n = s.length;
```

```
int[] phi = new int[n];
  lcp = new int[n]; plcp = new int[n];
  phi[sa[0]] = -1; // default value
  for (i = 1; i < n; i++) // compute Phi in O(n)
    phi[sa[i]] = sa[i-1]; // remember which suffix is
    behind this suffix
  for (i = L = 0; i < n; i++) { // compute Permuted LCP
     in O(n)
    if (phi[i] == -1) { plcp[i] = 0; continue; } //
     special case
    while (i + L < n \&\& phi[i] + L < n \&\& s[i + L] == s
     [phi[i] + L]) L++; // L will be increased max n
     times
    plcp[i] = L;
    L = Math.max(L-1, 0); // L will be decreased max n
  for (i = 1; i < n; i++) // compute LCP in O(n) lcp[i] = plcp[sa[i]]; // put the permuted LCP back
    to the correct position
static int strncmp(char[] a, int i, char[] b, int j,
    int n){
  for (int k=0; i+k < a.length && j+k < b.length; <math>k++){
    if (a[i+k] = b[j+k]) return a[i+k] - b[j+k];
  return 0;
static int[] stringMatching(char[] s, char[] p) { //
    string matching in O(m log n)
  int n = s.length, m = p.length;
  constructSA(s);
  int lo = 0, hi = n-1, mid = lo; // valid matching =
     [0 \dots n-1]
  while (lo < hi) \{ // find lower bound mid = (lo + hi) / 2;
    int res = strncmp(s, sa[mid], p, 0, m); // try to
     find P in suffix 'mid'
    if (res >= 0) hi = mid;
                    lo = mid + 1;
    else
  if (strncmp(s, sa[lo], p, 0, m) != 0) return new int
    []\{-1, -1\}; // \text{ not found }
  int[] ans = new int[]{ lo, 0};
  lo = 0; hi = n - 1; mid = lo;
  while (lo < hi) { // if lower bound is found, find
    upper bound
    mid = (lo + hi) / 2;
    \label{eq:int_res} \begin{array}{ll} \mbox{int} & \mbox{res} \, = \, \mbox{strncmp} \left( \mbox{s} \, , \, \, \, \mbox{sa} \, [\, \mbox{mid} \, ] \, , \, \, \, \mbox{p} \, , \, \, \mbox{m} \right); \end{array}
    if (res > 0) hi = mid;
                   lo = mid + 1:
  if (strncmp(s, sa[hi], p,0, m) != 0) hi--; // special
      case
  ans[1] = hi;
  return ans;
} // return lower/upper bound as the first/second item
     of the pair, respectively
static String LRS(char[] s) { // Longest Repeating
    substring
  int n = s.length;
  constructSA(s);
  computeLCP(s);
  int i, idx = 0, maxLCP = 0;
  for (i = 1; i < n; i++) // O(n)
    if (lcp[i] > maxLCP) {
      maxLCP \,=\, lcp\,[\,i\,\,]\,;
      idx = i;
  return new String(s).substring(sa[idx], sa[idx]+
    maxLCP);
static int owner(int idx, int n, int m) { return (idx < n)
```

```
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    -m-1) ? 1 : 2; }
static String LCS(String T, String P) { // Longest
   common substring
  int i, idx = 0;
  int m = P.length();
  char[] s = (T + "\$" + P + "\#") \cdot toCharArray(); //
    append P and '#'
  int n = s.length; // update n
  constructSA(s); // O(n log n)
  computeLCP(s); // O(n)
  int \max LCP = -1;
  for (i = 1; i < n; i++)
    if (lcp[i] > maxLCP && owner(sa[i],n,m) != owner(sa
    [i-1],n,m)) { // different owner
      maxLCP = lcp[i];
      idx = i;
    }
  return new String(s).substring(sa[idx], sa[idx] +
    maxLCP):
}
4
     Geometry
Be careful of rounding errors. Define E in function of the pro-
blem. Double.parseDouble est bien plus lent que Integer.parseInt.
boolean eq(double a, double b) {return Math.abs(a - b) <=
     E;
boolean le (double a, double b) {return a < b - E;}
boolean leq(double a, double b) {return a <= b + E;}
4.1
      Vectors
(x,y) \leftrightarrow x + yi
(x,y) rotated by \alpha is (\cos(\alpha)x - \sin(\alpha)y, \sin(\alpha)x + \cos(\alpha)y)
```

4.1.1 Rotation around (0,0)

```
\rho e^{i\theta} = \rho \cos(\theta) + i\rho \sin(\theta)
```

4.2 Points

```
class Point implements Comparable<Point>
  public int compareTo(Point o) { //xcomp
    if(a.x < b.x) \ return \ -1;
    if(a.x > b.x) return 1;
    if(a.y < b.y) return -1;
    if(a.y > b.y) return 1;
    return 0;
}
class yComp implements Comparator<Point> {
  public int compare(Point p, Point q) {
    if(p.y = q.y) \{return Double.compare(p.x, q.x);\}
    return Double.compare(p.y, q.y);
4.2.1 Point in box
boolean inBox(Point p1, Point p2, Point p) {
  return Math.min(p1.x, p2.x) \le p.x && p.x \le Math.max
    (p1.x, p2.x) &&
          {\rm Math.min}\,(\,{\rm p1\,.\,y}\,,\ {\rm p2\,.\,y}\,)\,<=\,{\rm p\,.\,y}\,\,\&\&\,\,{\rm p\,.\,y}\,<=\,{\rm Math.max}
     (p1.y, p2.y);
4.2.2 Polar sort
```

LinkedList<Point> sortPolar(Point[] P, Point o)

LinkedList<Point> above = new LinkedList<Point>(); LinkedList<Point> samePos = new LinkedList<Point>();

```
LinkedList<Point> sameNeg = new LinkedList<Point>();
  LinkedList < Point > bellow = new LinkedList < Point > ();
  for (Point p : P)
    if(p.y > o.y)
      above.add(p);
    else if (p.y < o.y)
      bellow.add(p);
    else
      if(p.x < o.x)
        sameNeg.add(p);
      else
        samePos.add(p);
 {\rm PolarComp}\ comp\ =\ \underset{}{\rm new}\ {\rm PolarComp}\,(o)\ ;
  Collections.sort(samePos, comp);
  Collections.sort(sameNeg, comp);
  Collections.sort(above, comp);
  Collections.sort(bellow, comp);
  LinkedList<Point> sorted = new LinkedList<Point>();
  for(Point p : samePos) sorted.add(p);
  for (Point p : above) sorted.add(p);
  for(Point p : sameNeg) sorted.add(p);
  for(Point p : bellow) sorted.add(p);
  return sorted;
class PolarCmp implements Comparator<Point> {
  static Point orig = new Point (0, 0);
  public int compare(Point p, Point q) {
    double o = orient(orig, p, q);
    if(o = 0)  {
      if(p.x * p.x + p.y * p.y > q.x * q.x + q.y * q.y)
        return 1;
      return -1;
    return -(int)Math.signum(o);
 }
4.2.3 Closest pair of points
double closestPair(Point[] points) {
  if (points.length == 1) {return Double.
    POSITIVE_INFINITY;}
  Arrays.sort(points, new xComp());
  double min = dist(points[0], points[1]);
  // keep track of the leftmost point
  int leftmost = 0;
  TreeSet<Point> candidates = new TreeSet<Point>(new
    yComp());
  candidates.add(points[0]);
  candidates.add(points[1]);
  for (int i = 2; i < points.length; i++) {
    Point cur = points[i];
    // eliminate points s.t cur.x - x > min
    while(cur.x - points[leftmost].x > min) {
      candidates.remove(points[leftmost]);
      leftmost++:
    Point low = new Point(0, cur.y - min);
    Point high = new Point(0, cur.y + min);
    // check all points in the rectangle
    for (Point point : candidates.subSet(low, high))
      min = Math.min(min, dist(cur, point));
    candidates.add(cur);
  return min;
4.2.4 Orientation
```

$$orient(p, q, r) = \begin{vmatrix} 1 & p_x & p_y \\ 1 & q_x & q_y \\ 1 & r_x & r_y \end{vmatrix}$$

```
orient(p,q,r) \begin{cases} = 0 & p,q,r \text{ are collinear} \\ < 0 & p -> q -> r \text{ is clockwise} \\ > 0 & p -> q -> r \text{ is counterclockwise} \end{cases} |orient(p,q,r)| = 2 \cdot area \ \triangle(p,q,r) \text{double orient (Point p, Point q, Point r) } \{ \text{return q.x * r.y - r.x * q.y - p.x * (r.y - q.y) + p.}  \text{y * (r.x - q.x);} \}
```

4.2.5 Angle visibility

x lies strictly inside the angle formed by p, q, r iff

```
\begin{split} sgn(orient(p,q,x)) &= sgn(orient(p,x,r)) \\ sgn(orient(p,r,x)) &= sgn(orient(p,x,q)) \end{split}
```

To allow it to lie on the border simply check if

```
sgn(orient(p, q, x)) = 0 or sgn(orient(p, r, x)) = 0
```

4.2.6 Fixed radius neighbors (1D)

```
List<Double[] > findPairs1D(double[] x, double r) {
  HashMap < Integer, List < Double >> H = new HashMap <
    Integer , List<Double>>();
    fill buckets
  for (int i = 0; i < x.length; i++) {
    int b = (int)(x[i] / r);
    if(H.containsKey(b)) {
      H. get(b).add(x[i]);
    } else {
      List < Double > L = new ArrayList < Double > ();
      L.add(x[i]);
      H.put(b, L);
  // find pairs in consecutive buckets
 List<Double[] > pairs = new LinkedList<Double[] > ();
for(int i = 0; i < x.length; i++) {</pre>
    int b = (int)(x[i] / r);
    List < Double > bucket = H. get(b + 1);
    if (bucket != null)
      for (double y : bucket)
         i\hat{f}(y - x[i] \ll r)
          pairs.add(new Double[] {x[i], y});
  // add points in buckets
  for(List<Double> bucket : H. values())
    for(int i = 0; i < bucket.size(); i++)
      for (int j = i + 1; j < bucket.size(); j++)
         pairs.add(new Double[] {bucket.get(i), bucket.
    get(j)});
  return pairs;
```

4.2.7 Fixed radius neighbors (2D)

```
List<Point[]> findPairs2D(Point[] points, double r) {
   HashMap<Integer, List<Point>> H = new HashMap<Integer
   , List<Point>>();
   // fill buckets
   for(int i = 0; i < points.length; i++) {
     int bx = (int)(points[i].x / r);
     int by = (int)(points[i].y / r);
     int key = 33 * bx + by;
     if(H.containsKey(key)) {
        H.get(key).add(points[i]);
     } else {
        List<Point> L = new ArrayList<Point>();
        L.add(points[i]);
        H.put(key, L);
    }
}
```

```
// find pairs in adjacent buckets
List<Point[] > pairs = new LinkedList<Point[] > ();
int[][] dir = new int[][] {new int[] {1,0}, new int[]
   \{0,1\}, new int[] \{1,1\}\};
for(int i = 0; i < points.length; i++) {
  int bx = (int)(points[i].x / r);</pre>
   int by = (int)(points[i].y / r); 
  for(int[] d : dir) {
    List <Point> bucket = H. get (33 * (bx + d[0]) + (by
   + d[1]);
    if (bucket != null)
      for(Point y : bucket)
         if(sqDist(points[i], y) \le r * r)
           pairs.add(new Point[] {points[i], y});
// add points in buckets
for(List<Point> bucket : H.values())
  for(int i = 0; i < bucket.size(); i++)
    for(int j = i + 1; j < bucket.size(); j++)
      if(sqDist(bucket.get(i), bucket.get(j)) <= r *</pre>
         pairs.add(new Point[] {bucket.get(i), bucket.
  get(j)});
return pairs;
```

4.3 Lines

General equation :Ax + By = C. The line through $(x_1, y_1), (x_2, y_2)$ is given by $:A = y_2 - y_1, B = x_1 - x_2, C = Ax_1 + By_1$.

4.3.1 Intersections

Intersection exists there is a solution for $A_1x + B_1y = C_1$ and $A_2x + B_2y = C_2$. This happens if and only if

$$d := \det \begin{pmatrix} A_1 & B_1 \\ A_2 & B_2 \end{pmatrix} \neq 0$$

Intersection is given by

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} A_1 & B_1 \\ A_2 & B_2 \end{pmatrix}^{-1} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = \frac{1}{d} \begin{pmatrix} B_2 & -B_1 \\ -A_2 & A_1 \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}$$

4.3.2 Perpendicular line

The lines perpendicular to Ax + By = C are

$$-Bx + Ay = D$$
 for $D \in \mathbb{R}$

If we want the one that goes through (x_0, y_0) set

$$D = -Bx_0 + Ay_0$$

4.3.3 Orthogonal Symmetry

For a line, find X', the point which is the orthogonal symmetry of X on line a.

Computes the perpendicular of the given line that goes through X. Compute intersection Y. X' = Y - (X - Y).

4.4 Segments

4.4.1 Intersection

- Treat segments as lines.
- If $d \neq 0$, compute line intersection (x, y).
- Segments intersect iff

$$\min(x_1, x_2) \le x \le \max(x_1, x_2)$$

 $\min(y_1, y_2) \le y \le \max(y_1, y_2)$

4.4.2 Intersections problem

Given a lot of segments, return true if it exists a pair that intersects.

```
boolean segmentIntersection (Segment [] S)
  Event[] events = new Event[2 * S.length];
  // create event points
  for (int i = 0, j = 0; i < S.length; i++) {
    events[j++] = new Event(S[i].l.x, true, S[i]);
    events[j++] = new Event(S[i].r.x, false, S[i]);
  Arrays.sort(events);
  SegmentCmp \ cmp = new \ SegmentCmp();
  TreeSet<Segment> T = new TreeSet<Segment>(cmp);
  // sweep line
  for(Event event : events) {
    Segment s = event.s;
    cmp.x = event.x;
    if(event.isLeft) {
      // new segment found. check if it intersects one
    of its neighbors
      T. add(s);
      Segment above = T. higher(s);
      Segment bellow = T.lower(s);
      if((above != null && intersects(above, s)) ||
         (\,bellow \,\, \mathrel{!=} \,\, \underset{}{\text{null}} \,\,\&\& \,\, intersects (\,bellow \,, \,\, s \,) \,))
    } else {
      // end of segment. check if its neighbors
    intersect
      Segment above = T. higher(s);
      Segment bellow = T.lower(s);
      if (above != null && bellow != null && intersects(
    above, bellow))
        return true;
      T.remove(s);
  return false;
class Event implements Comparable<Event> {
  double x;
  boolean isLeft;
  Segment s;
  public Event(double x, boolean isLeft, Segment s) {
    this.x = x;
    this.isLeft = isLeft;
    this.s = s;
  public int compareTo(Event other) {
    int cmp = Double.compare(x, other.x);
     / ensure that left comes before right
    if(cmp = 0) return isLeft? -1 : 1;
    return cmp;
 public String toString() {
  return x + " " + isLeft;
class SegmentCmp implements Comparator<Segment> {
  double x:
```

```
public int compare(Segment s1, Segment s2) {
   // compute A,B,C from eq Ax + by = C for each
   segment
   double A1 = s1.r.y - s1.l.y;
   double C1 = A1 * s1.l.x + B1 * s1.l.y;
   double A2 = s2.r.y - s2.l.y;
   double B2 = s2.1.x - s2.r.x;
   double C2 = A2 * s2.1.x + B2 * s2.1.y;
    // no divisions =)
   double t1 = B2 * (C1 - A1 * x);
   double t2 = B1 * (C2 - A2 * x);
   if(t1 == t2) {
     return s1 = s2? 0 : -1;
   else\ if(B1 * B2 > 0)
     return Double.compare(t1, t2);
     else {
     return Double.compare(t2, t1);
 }
}
```

4.5 Circles

4.5.1 Circles from 3 points

- 3 non collinear points define a unique circle.
- c = intersection of bisectors of XY and YZ.

4.6 Polygon

4.6.1 Triangles

```
- côtés a, b, c, angles A, B, C, hauteurs h_A, h_B, h_C, s = \frac{a+b+c}{2}, aire S.

- Aire : S = ah_A/2, S = ab\sin C/2, S = \sqrt{s(s-a)(s-b)(s-c)}.

- Inradius r = \frac{S}{s}.

- Outradius 2R = \frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}.

- rR = \frac{abc}{4s}.
```

4.6.2 Check convexity

```
boolean isConvex(Point[] P) {
   if(P.length < 3) return false;
   double o1 = orient(P[P.length-1], P[0], P[1]);
   for (int i = 0; i < P.length; i++) {
      double o2 = orient(P[i], P[i + 1], P[i + 2]);
      if(o1 * o2 < 0) {
        return false;
      } else if (o2 != 0) {
        o1 = o2;
      }
   }
  return true;
}</pre>
```

4.6.3 Winding number

```
// assumes p is not on P double winding(Point[] P, Point p) { 
    //make a translation so p = (0, 0) 
    for(Point q : P) { 
        q.x -= p.x; 
        q.y -= p.y; 
    } 
    double w = 0; 
    for(int i = 0; i < P.length - 1; i++) { 
        if(P[i].y * P[i + 1].y < 0) { 
            // segment crosses the x-axis 
            double r = (P[i].y - P[i+1].y) * P[i].x + P[i].y 
    * (P[i+1].x - P[i].x); 
            //check for intersection with the positive x-axis
```

```
if((P[i].y - P[i+1].y > 0 \&\& r > 0) || (P[i].y -
    P[i+1].y < 0 && r < 0) {
           segment fully crosses the x-axis
        // - to + add 1, + to - subtract 1
        w += P[i].y < 0? 1 : -1;
      else\ if(P[i].y = 0 \&\& P[i].x > 0) 
        // the segment starts at the x-axis
        // 0 to + add 0.5, 0 to - subtract 0.5
        w += P[i+1].y > 0? 0.5 : -0.5;
      } else if (P[i+1].y = 0 \&\& P[i+1].x > 0) {
        // the segment ends at the x-axis
        // - to 0 add 0.5, + to 0 subtract 0.5
        w \mathrel{+}\!\!= P[\:i\:] \,.\, y \,<\, 0\,?\ 0.5\ :\ -0.5\,;
    }
  return w:
}
4.6.4 Convex Hull
Point[] convexHull(Point[] points) {
  // sort points by increasing x coordinates
  Arrays.sort(points, new xComp());
  // build upper chain
  Point[] upChain = buildChain(points, 1);
  // build lower chain
  Point [] loChain = buildChain(points, -1);
  Point \, [\,] \quad hull \, = \, \underset{}{new} \quad Point \, [\, upChain \, . \, length \, \, + \, \, loChain \, .
    length - 2];
  int i;
  // build convex hull from upper and lower chain
  for (i = 0; i < \text{upChain.length}; i++)
    hull[i] = upChain[i];
  for (int j = loChain.length - 2; j >= 1; j--) {
    hull[i] = loChain[j];
  return hull;
Point[] buildChain(Point[] points, int sgn) {
  Point [] S = new Point [points.length];
  int k = 0;
  S[k++] = points[0]; // push points[0]
  S[k++] = points[1]; // push points[1]
  // build chain
  for (int i = 2; i < points.length; i++) {
    //double orient = orient(S[k - 2], S[k - 1], points
    while (k \ge 2 \&\& sgn * orient(S[k-2], S[k-1],
    points[i]) >= 0) {
      S[k-1] = null; // pop
    S[k++] = points[i]; // push points[i]
  return Arrays.copyOf(S, k);
4.7 Interval Tree
```

root = new Node();

```
25
                            18
                                                  22
                             х, у
                  15
                                                   22
                                                             25
                             18
                                        20
                      x = [10, 20]
                                      z = [18, 22]
class IntervalTree {
  Node root;
  public IntervalTree(int[] x) {
```

```
buildTree(root, 0, x.length -1, x);
public int measure() {
  return root.measure:
public void buildTree(Node node, int i, int j, int[]
  x) {
  if(j - i = 1)  {
    node.l = x[i];
    node.\, r \,=\, x\,[\,j\,]\,;
    node.m = -1;
  } else {
    node.l = x[i];
    node.r = x[j];
    int mid = (i + j) / 2;
    Node left = new Node();
    buildTree(left, i, mid, x);
    Node right = new Node();
    buildTree(right, mid, j, x);
    node.m = x[mid];
    node.left = left;
    left.parent = node;
    node.right = right;
    right.parent = node;
 }
public void remove(int x1, int x2) {
 remove(\,root\,\,,\,\,x1\,,\,\,x2\,)\,;
private void remove(Node node, int x1, int x2) {
  if(node.l = x1 \&\& node.r = x2)  {
    node.count = Math.max(0, node.count - 1);
    if (node.left = null | | node.right = null) {
      node.measure = node.count == 0 \ ? \ 0 \ : node.
  measure;
    } else {
      node.measure = node.count == 0? node.left.
  measure + node.right.measure : node.measure;
    // go down the three to delete new interval
    int mid = node.m;
    if(x1 < mid \&\& mid < x2) {
      // split
      remove(node.left, x1, mid);
      remove(node.right, mid, x2);
    else\ if(node.l <= x1 \&\& x2 <= mid) 
      // contained on left
      remove(node.left, x1, x2);
     else {
      // contained on right
      remove(node.right, x1, x2);
      update measures when going up
    if(node.count == 0) {
      node.measure = node.left.measure + node.right.
  measure;
public void add(int x1, int x2) {
  add(root, x1, x2);
private void add(Node node, int x1, int x2) {
  if(node.l = x1 \&\& node.r = x2) {
    node.measure = x2 - x1;
    node.count++;
  } else {
    // go down the three to add new interval
    int mid = node.m;
    if(x1 < mid \&\& mid < x2) {
      // split
      add(node.left, x1, mid);
      \mathrm{add}(\,\mathrm{node}\,.\,\mathrm{right}\,\,,\,\,\mathrm{mid}\,,\,\,\mathrm{x2}\,)\,;
    else\ if(node.l <= x1 \&\& x2 <= mid) 
      // contained on left
      add(node.left, x1, x2);
      else {
      // contained on right
```

```
add(node.right, x1, x2);
}
// update measures when going up
if(node.count == 0) {
    node.measure = node.left.measure + node.right.
    measure;
}
}

public class Node {
    int l, r, m;
    int count, measure;
    Node left, right, parent;
}
```

4.8 Area of union of rectangles

```
long area(R[] r) {
  // sort y coordinates
  int[] y = new int[2 * r.length];
  int k = 0;
  for(R rect : r) {
   y[k++] = rect.y1;
   y[k++] = rect.y2;
  Arrays.sort(y);
  // build interval tree
  IntervalTree T = new IntervalTree(y);
  // initialize event queue
  PriorityQueue<Event> Q = new PriorityQueue<Event>();
  for (R rectangle : r) {
   Q.add(new Event(rectangle.x1, rectangle));
   Q.add(new Event(rectangle.x2, rectangle));
  long area = 0:
  Event previous = null;
  // loop over all events
  while (!Q. isEmpty()) {
    // poll next event
    Event e = Q. poll();
    if(previous = null) {
      // first vertical line
      T.add(e.r.y1, e.r.y2);
    } else {
      // found a new vertical line
      // update area by dx * tree measure
      int dx = e.x - previous.x;
      area += dx * T. measure();
      if(e.x = e.r.x1) {
        // new rectangle, add segment to T
       T.add(e.r.y1,\ e.r.y2);
      } else {
         / exiting rectangle, remove segment from T
        T.remove(e.r.y1, e.r.y2);
      }
    // update previous
   previous = e;
  return area;
class Event implements Comparable<Event> {
  int x;
 R. r:
  public Event(int x, R r) {
   this.x = x;
    this.r = r;
  public int compareTo(Event other) {
    return x - other.x;
class R {
 int x1, y1, x2, y2;
  public R(int x1, int y1, int x2, int y2) {
    this.x1 = x1; this.y1 = y1; this.x2 = x2; this.y2 = y2
```

```
16
  }
}
4.9 C library by Xiao
#include <cmath>
#include <algorithm>
#include <iostream>
#include <vector>
using namespace std;
#define PI acos(-1)
#define EPS 1E-9
//_point _vector
typedef struct _point {double x, y;
                                            _point(<mark>double</mark> _x =
 0, double y = 0:x(x), y(y) {} bool operator==(_point other) const {return (fabs(x -
     other.x) \langle EPS \rangle && (fabs(y - other.y) \langle EPS \rangle;};
}_vector; //_vector(AB) = _point(B) - _point(A)
_vector operator+(_vector v1, _vector v2) {return
     _{\text{vector}}(v1.x + v2.x, v1.y + v2.y);
_vector operator-(_vector v1, _vector v2) {return
     \_vector(v1.x - v2.x, v1.y - v2.y);}
_vector operator*(_vector v, double p) {return _vector (v.x * p, v.y * p);}
_vector operator/(_vector v, double p) {return _vector
     (v.x / p, v.y / p);
double norm(_vector v) {return v.x * v.x + v.y * v.y;}
//product of 2 vectors
double dot(_vector v1, _vector v2) {return v1.x * v2.x
     + v1.y * v2.y;
double cross(_vector v1, _vector v2) {return v1.x * v2. y - v1.y * v2.x;}
//add_square / hypot
double add_square(double x, double y) {return x * x + y
      * y;}
double hypot(double dx, double dy) {return sqrt(
     add_square(dx, dy));}
//distance between 2 points
double distance(_point p1, _point p2) {return hypot(p1.
    x - p2.x, p1.y - p2.y);}
//rotate vector (if t is not in rad, just do: t = t *
     PI / 180)
 vector rotate_counter_clockwise(_vector_v, double_t)
\frac{1}{\text{freturn }} \text{vector}(v.x * \cos(t) - v.y * \sin(t), v.x * \sin(t)
     t) + v.y * cos(t));
_vector rotate_clockwise(_vector v, double t)
{return _vector(v.x * cos(t) + v.y * sin(t), v.y * cos(
     t) - v.x * sin(t));};
//_line (ax + by + c = 0 with b = 0 for vertical lines;
    b = 1 for non vertical lines)
struct _line {double a, b, c;
_line(double _a = 0, double _b = 0, double _c = 0) :a(_a ), b(_b), c(_c) {}};
//build line with 2 points
```

_line points_to_line(_point p1, _point p2)

bool are_parallel(_line l1, _line l2)

{if(are_parallel(11, 12)) return false;

intersection point)

< EPS);}

a * 12.b);

EPS);}

 $la * p1.x - p1.y; return _line(la, 1, lc);}$

//test if 2 lines are parallel / same / intersect(with

 $\{return (fabs(11.a - 12.a) < EPS) \&\& (fabs(11.b - 12.b)\}$

p.x = (12.b * 11.c - 11.b * 12.c) / (12.a * 11.b - 11.

bool are_same(_line l1 , _line l2) {return are_parallel(l1 , l2) && (fabs(l1.c - l2.c) <

bool are_intersect(_line l1, _line l2, _point &p)

```
if(fabs(l1.b) > EPS) p.y = -(l1.a * p.x + l1.c); else
    p.y = -(12.a * p.x + 12.c);
 return true;}
//intersection of a line(AB) and a segment(pq)
_point line_intersect_segment(_point p, _point q,
     _point A, _point B)
\{double\ a=B.y-A.y,\ b=A.x-B.x,\ c=B.x*A.y-A
    .x * B.y, u = fabs(a * p.x + b * p.y + c), v = fabs
    (a * q.x + b * q.y + c);
 return _point((p.x * v + q.x * u) / (u + v), (p.y * v
    + q.y * u) / (u + v));
//distance from point to line defined by 2 points and
    find the closest point
double distance_to_line(_point p, _point a, _point b,
     point &c)
\{\text{\_vector ap = p - a, ab = b - a; double u = dot(ap, ab)}\}
     / norm(ab);
 c = a + ab * u; return distance(p, c);}
//distance from point to line segment defined by 2 end
    points and find the closest point
double distance_to_line_segment(_point p, _point a,
    _point b, _point &c)
\{\text{\_vector ap = p - a, ab = b - a; double u = dot(ap, ab)}\}
     / norm(ab);
 if (u < 0) {c = _point(a.x, a.y); return distance(p, a)
    ;}
 if (u > 1) {c = _point(b.x, b.y); return distance(p, b)
    ; }
 return distance_to_line(p, a, b, c);}
//given 3 points / 2 vectors, compute the angle
double angle(_point a, _point o, _point b) \{\text{-vector oa} = a - o, ob = b - o; return acos(dot(oa, ob))\}
    ) / sqrt(norm(oa) * norm(ob)));}
double angle(_vector v1, _vector v2) {_point o(0, 0);
    return angle(o + v1, o, o + v2);}
//test if a point is on the left of a line defined by 2
     points / they are all collinear
bool is_on_the_left(_point p, _point a, _point b) { return cross(b - a, p - a) > 0;}
bool are_collinear(_point p, _point a,
                                            _point b) {
    return fabs(cross(b - a, p - a)) \langle EPS; \}
//test if a point is inside a circle (0:inside 1:border
     2:outside)
int is_inside(_point p, _point o, double r)
{double dx = p.x - o.x, dy = p.y - o.y, Euc = add_square(dx, dy), rSq = r * r;
 return Euc < rSq ? 0 : Euc == rSq ? 1 : 2;}
//length of arc / chord (if t is not in rad, just do: t
      = t * PI / 180)
//area of circular segment 弓形
double length_arc(double r, double t) {return r * t;}
double length_chord(double r, double t) {return sqrt(2
    * r * r * (1 - \cos(t)));
double area_circular_segment(double r, double t) {
   return r * r / 2 * (PI * t - sin(t));}
//given 2 points and radius, find the center of circle
    (max 2 possible circles)
bool circle_center(_point p1, _point p2, double r,
     _point &o)
\{ \mbox{double d2 = add\_square(p1.x - p2.x, p1.y - p2.y), det} \\
    = r * r / d2 - 0.25;
 if (det < 0) return false; //reverse p1 and p2 to get
    another circle center if there're 2 circles
 double h = sqrt(det); o.x = (p1.x + p2.x) * 0.5 + (p1.x)
    y - p2.y)^{-*} h;
 o.y = (p1.y + p2.y) * 0.5 + (p2.x - p1.x) * h; return
//number of tangents from a point to a circle (with
    tangent vectors)
```

```
int getTangents(_point p, _point o, double r,_vector *
       tangents)
\{\text{\_vector } u = o - p; \text{ double dist = norm}(u); \text{ if } (\text{dist } < r)
        return 0; else if (fabs(dist - r) < EPS)
 {tangents[0] = rotate_counter_clockwise(u, PI / 2);
      return 1;} else {double ang = asin(r / dist);
  tangents[0] = rotate_counter_clockwise(u, -ang);
       tangents[1] = rotate_counter_clockwise(u, ang);
       return 2;}}
//area of triangle
double area (double a, double b, double c)
{double p = (a + b + c) / 2; return sqrt(p * (p - a) *
       (p - b) * (p - c);
double area(_point a, _point b, _point c) {return fabs(
       cross(b - a, c - a));
//inscribed circle of triangle
double r_inscribed_circle(double a, double b, double c)
{return area(a, b, c) / (0.5 * (a + b + c));}
double r_inscribed_circle(_point a, _point b, _point c)
\{ \mbox{return $r$\_inscribed\_circle(distance(a, b), distance(b, b), distance
       c), distance(c, a));}
bool inscribed_circle(_point a, _point b, _point c,
       _point &oic, double &ric)
{ric = r\_inscribed\_circle(a, b, c); if(fabs(ric) < EPS)}
        return false;
 double ratio = distance(a, b) / distance(a, c);
 _point p = b + (c - b) * ratio / (1 + ratio); _line l1
        = points_to_line(a, p);
 ratio = distance(b, a) / distance(b, c); p = a + (c -
      a) * ratio / (1 + ratio);
   _line 12 = points_to_line(b, p); are_intersect(11, 12,
        oic); return true;}
//circumcircle of triangle
double r_circum_circle(double a, double b, double c)
{return a * b * c / (4.0 * area(a, b, c));}
double r_circum_circle(_point a, _point b, _point c)
{return r_circum_circle(distance(a, b), distance(b, c),
         distance(c, a));}
//test if 3 segments can form a triangle
bool can_form_triangle(double a, double b, double c)
\{ return (a + b - c > 0) \&\& (a + c - b > 0) \&\& (b + c - b) \}
      a > 0);
//law \ of \ Cosines : c^2 = a^2 + b^2 - 2 * a * b * cos(
      opposite_angle_c)
//law of Sines: for any side s of triangle, we have: s
       / sin(opposite_angle_s) = 2 * radius_circum_circle
double opposite_angle_c(double a, double b, double c)
{return acos((a * a + b * b - c * c) / 2 / a / b);}
double c(double a, double b, double opposite_angle_c)
{return sqrt(a * a + b * b - 2 * a * b * cos(
       opposite_angle_c));}
//polygon representation : vector \_point > poly; remember
        that poly[0] = poly[n-1] (the last point = the
       first point)
//add points: poly.push_back(_point(1, 1)); poly.
       push_back(_point(2, 4)); poly.push_back(_point(3,
       7)); poly.push_back(P[0]);
//parimeter / area of polygon
double perimeter(const vector \( _point \> &poly)
{double result = 0; for(int i = 0; i < (int)poly.size()
        -1; i++) result += distance(poly[i], poly[i + 1])
       ; return result;}
double area(const vector<_point> &poly)
{double result = 0, x1, x2, y1, y2; for(int i = 0; i <
       (int) poly.size() - 1; i++)
\{x1 = poly[i].x; x2 = poly[i + 1].x; y1 = poly[i].y; y2
         = poly[i + 1].y; result += (x1 * y2 - x2 * y1);}
       return fabs(result / 2);}
//test if polygon is convex
bool is_convex(const vector<_point> &poly)
\{int s = (int)poly.size(); if(s \le 3) return false;
       bool l = is\_on\_the\_left(poly[2], poly[0], poly[1]);
```

```
for(int i = 1; i < s - 1; i++) if(is_on_the_left(poly
       [(i + 2) == s ? 1 : i + 2], poly[i], poly[i + 1])
       != 1) return false; return true;}
//test if point is in polygon
bool is_inside(_point p, const vector<_point> &poly)
{if((int)poly.size() == 0) return false; double sum =
       0; for(int i = 0; i < (int)poly.size() - 1; i++) {
  if(is_on_the_left(poly[i + 1], p, poly[i])) sum +=
       angle(poly[i], p, poly[i + 1]); else sum -= angle(
       poly[i], p, poly[i + 1]);}
 return fabs(fabs(sum) -2 * PI) \langle EPS; \}
//cut polygon along a line(result is the left part
       after cutting)
vector < _point > cut_polygon(_point a, _point b, const
       vector < _point > &poly)
{vector < point > result; for (int i = 0; i < (int) poly.
       size() - 1; i++) {double left1 = cross(b - a, poly[}
       i] - a), left2 = 0;
 if (i != (int) poly.size() - 1) left2 = cross(b - a,
       poly[i + 1] - a); if (left1 > -EPS) result.push_back
       (poly[i]);
  if(left1 * left2 < -EPS) result.push_back(</pre>
       line_intersect_segment(poly[i], poly[i + 1], a, b))
  if(!result.empty() && !(result.back() == result.front
       ())) result.push_back(result.front()); return
       result;}
//find the convex hull of a set of points
_point pivot(0, 0);
bool angle_compare(_point a, _point b)
{if(are_collinear(b, pivot, a)) return distance(pivot,
       a) < distance(pivot, b);</pre>
 double d1x = a.x - pivot.x, d1y = a.y - pivot.y, d2x =
        b.x - pivot.x, d2y = b.y - pivot.y;
 return (atan2(d1y, d1x) - atan2(d2y, d2x)) > 0;
vector<_point> convex_hull(vector<_point> P)
\{int i, j, n = (int)P.size(); if(n <= 3) \{if(!(P[0] ==
       P[n - 1])) P.push_back(P[0]); return P;}
  int P0 = 0; for(int i = 1; i < n; i++) if(P[i].y < P[
       P0].y || (P[i].y == P[P0].y && P[i].x > P[P0].x))
       P0 = i;
 point temp = P[0]; P[0] = P[P0]; P[P0] = temp; pivot
       = P[0]; sort(++P.begin(), P.end(), angle_compare);
  vector \leq point > S: S.push\_back(P[n - 1]): S.push_back(P[n - 1]): 
       [0]); S.push_back(P[1]); i = 2;
  while (i < n) { j = (int)S.size() - 1; if(is_on_the_left)
       (P[i], S[j-1], S[j])) S.push_back(P[i++]); else S
       .pop_back();} return S;}
//area / radius of inscribed circle / radius of
circumcircle of regular polygon double area(double a, int n) {return n * a * a / 4 /
       tan(PI / n);}
double r_inscribed_circle(double a, int n) {return a /
       2 / tan(PI / n);}
double r_circum_circle(double a, int n) {return a / 2 /
         sin(PI / n);}
//volume of pyramid
//surface area of pyramid with regular bottom
double surface_area_pyramid_regular(double a, int n,
       double h)
double volume_pyramid(double area_bottom, double h) {
      return area_bottom * h / 3;}
double volume_pyramid_regular(double a, int n, double h
       ) {return volume_pyramid(area(a, n), h);}
//surface area(include the bottom) / volume of cone 圆
      锥
double surface_area_cone(double r, double h) {return PI
        * r * (r + hypot(r, h));}
double volume_cone(double r, double h) {return PI * r *
        r * h / 3;}
```

```
//surface area / volume of sphere
double surface_area_sphere(double r) {return 4 * PI * r
     * r;}
double volume_sphere(double r) {return 4 * PI / 3 * r *
     r * r;}
//surface area(include the top and the bottom) / volume
     of spherical segment 球
double surface_area_spherical_segment(double rt, double
     rb, double R, double h) {return 2 * PI * R * h +
    PI * rt * rt + PI * rb * rb;}
double volume_spherical_segment(double rt, double rb,
    double R, double h) {return PI * h / 6 * (3 * rt *
    rt + 3 * rb * rb + h * h);
//surface area(include the bottom) / volume of
    spherical cap 球
double surface_area_spherical_cap(double r, double R,
     double h) {return 2 * PI * R * h + PI * r * r:}
double volume_spherical_cap(double r, double h) {return
     PI * h / 6 * (3 * r * r + h * h);
```

5 Math

5.1 Permutations, Combinations, Arrangements... untested

```
void nextPerm(int[] p) {
  int n = p.length;
  int k = n - 2;
  while (k \ge 0 \&\& p[k] \ge p[k + 1]) \{k--;\}
  int l = n - 1;
  while (p[k] >= p[l]) \{l--;\}
  swap(p, k, l);
  reverse (p, k + 1, n);
LinkedList<Integer> getIPermutation(int n, int index) {
  LeftRightArray lr = new LeftRightArray(n);
  lr.freeAll();
  LinkedList < Integer > perm = new
  LinkedList<Integer>();
  getPermutation(lr , index , fact(n) , perm);
  return perm;
void getPermutation(LeftRightArray lr, int i, long fact
     LinkedList<Integer> perm) {
  int n = lr.size();
  if(n = 1) {
    perm.add(lr.freeIndex(0, false));
  } else {
    fact /= n;
    int j = (int)(i / fact);
    {\tt perm.add(lr.freeIndex(j,\ true));}
    i -= j * fact;
    getPermutation(lr , i , fact , perm);
}
int[] getICombinadic(int n, int k, long i) {
  int[] comb = new int[k];
  int j = 0;
  for(int z = 1; z \le n; z++) {
    if (k = 0) 
      break:

\frac{1}{n} = C(n - z, k - 1);

    if (i < threshold) {
      comb[j] = z - 1;
      i++;
      k = k - 1:
    } else if (i >= threshold) {
      i = i - threshold;
  return comb:
```

```
}
void combinations (int n, int k) {
  combinations(n, 0, new int[k], 0);
}
void combinations(int n, int j, int[] comb, int k) {
  if (k == comb.length) {
    System.out.println(Arrays.toString(comb));
  } else {
    for (int i = j; i < n; i++) {
      comb[k] = i:
      combinations(n, i + 1, comb, k + 1);
  }
void subsets(int[] set) {
  int n = (1 \ll \text{set.length});
  for (int i = 0; i < n; i++) {
    int[] sub = new int[Integer.bitCount(i)];
    int k = 0, j = 0;
    while ((1 \ll j) \ll i)  { if ((i \& (1 \ll j)) = (1 \ll j))  {
        sub[k++] = set[j];
      j++;
    System.out.println(Arrays.toString(sub));
}
```

5.2 Decomposition in unit fractions untested

```
 \begin{aligned} & \text{Write } 0 < \frac{p}{q} < 1 \text{ as a sum of } \frac{1}{k} \\ & \text{void expandUnitFrac(long p, long q) } \{ \\ & \text{if } (\text{p != 0}) \ \{ \\ & \text{long i = q \% p == 0 ? q/p : q/p + 1;} \\ & \text{System.out.println("1/" + i);} \\ & \text{expandUnitFrac(p*i-q, q*i);} \\ & \} \\ \} \end{aligned}
```

5.3 Combination

```
Number of combinations of k elements within n ones (C_n^k) Special case : C_n^k \mod 2 = n \oplus m long C(int n, int k) { double r = 1; k = Math.min(k, n - k); for (int i = 1; i <= k; i++) r /= i; for (int i = n; i >= n - k + 1; i--) r *= i; return Math.round(r);
```

5.3.1 Catalan numbers

```
 \begin{split} \operatorname{cat}(n) &= \frac{C_n^{2n}}{n+1} \operatorname{cat}(n+1) = \frac{(2n+2)(2n+1)}{(n+2)(n+1)} \operatorname{cat}(n) \\ &- \operatorname{distinct} \text{ binary trees with } n \text{ vertices.} \\ &- \operatorname{expressions containing } n \text{ pairs of parentheses correctly} \\ &\operatorname{matched} \text{ (e.g. } n = 3 \text{ ()()(), ()()), (())), ((())), ((())))}. \\ &- \operatorname{parenthesize } n + 1 \text{ factors (e.g. } n = 3 \\ & (ab)(cd), a(b(cd)), ((ab)c)(d), (a(bc))(d), a((bc)d)). \\ &- \operatorname{triangulate a convex polygon of } n + 2 \text{ sides.} \\ &- \operatorname{number of monotonic paths along the edge of a } n \times n \\ & \operatorname{grid which do not pass above de diagonal.} \end{aligned}
```

```
Compute all Catalan number \leq n long[] allCatalan(int n) { long[] catalanNumbers = new long[n]; catalanNumbers[0] = 1; for (int i = 1; i < n; i++) { int j = i - 1; long b = j * j;
```

```
long a = 4 * b + 6 * j + 2;
b += 3 * j + 2;
catalanNumbers[i] = catalanNumbers[j] * a/b;
}
return catalanNumbers;
}
```

5.4 Fibonacci series

f(0) = 0, f(1) = 1 et f(n) = f(n-1) + f(n-2). The following relation enables us to compute every number of the series in $O(\log(n))$:

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}^n = \begin{pmatrix} f_{n+1} & f_n \\ f_n & f_{n-1} \end{pmatrix}$$

5.5 Cycle finding

```
 \begin{array}{lll} & \text{int} \; [] \; \; floydCycleFinding \; (int \; x0) \; \{ \\ & \text{int tortoise} \; = \; f(x0) \,, \; hare \; = \; f(f(x0)) \,; \\ & \text{while} \; (\text{tortoise} \; != \; hare) \; \{ \\ & \text{tortoise} \; = \; f(\text{tortoise}) \,; \\ & \text{hare} \; = \; f(f(\text{hare})) \,; \; \} \\ & \text{int } \; mu = \; 0 \,; \; hare \; = \; x0 \,; \; // \; \; first \\ & \text{while} \; (\text{tortoise} \; != \; hare) \; \{ \\ & \text{tortoise} \; = \; f(\text{tortoise}) \,; \; hare \; = \; f(\text{hare}) \,; \; mu++; \; \} \\ & \text{int } \; lambda \; = \; 1 \,; \; hare \; = \; f(\text{tortoise}) \,; \; // \; length \\ & \text{while} \; (\text{tortoise} \; != \; hare) \; \{ \\ & \text{hare} \; = \; f(\text{hare}) \,; \; lambda++; \; \} \\ & \text{return new int} \; [] \; \{ mu, \; lambda \} \,; \\ \} \end{array}
```

5.6 Number theory

5.6.1 Misc

```
ax \leq b \Leftrightarrow x \leq \left\lfloor \frac{b}{a} \right\rfloor \quad ax \geq b \Leftrightarrow x \leq \left\lceil \frac{b}{a} \right\rceil \quad \left\lceil \frac{a}{b} \right\rceil = \left\lfloor \frac{a+b-1}{b} \right\rfloor. long gcd (long a, long b) { return (b = 0) ? a : gcd(b, a % b); } long lcm (long a, long b) { return a * (b / gcd(a,b)); } long modInverse (long a, long b) { return big(a).modInverse(big(b)).longValue(); } long modInverse (long a, long b) { extendedEuclid(a, b); return x; } long prime factorization of n, the power of p is
```

$$\sum_{i=1}^{\infty} \left\lfloor \frac{n}{p^i} \right\rfloor$$

```
int factopower (int n, int p) {
  int pow = 0;
  while (n > 0) {
    pow += n / p;
    n /= p;
  }
  return pow;
}
```

5.6.2 Équations diophantiennes

ax+by=c. $d=\gcd(a,b),$ no sol si d divise pas c sinon (a,b)=(x(n/d)+(b/d)n,y(n/d)+(a/d)n) où ax+by=d $n\in\mathbb{Z}.$

```
static int x, y;
static int extendedEuclid(int a, int b) {
  if (b == 0) { x = 1; y = 0; return a; }
  int d = extendedEuclid(b, a % b);
  int <math>x1 = y;
  int y1 = x - (a / b) * y;
  x = x1;
  y = y1;
  return d;
}
```

5.6.3 Chinese remainder theorem

```
static long[] chinese (long[] b, long[] m) {
  long x = b[0], l = m[0];
  for (int i = 1; i < m.length; i++) {
    long ml = m[i], bl = b[i];
    long d = gcd(l, ml);
    if ((x - bl) % d != 0) return null;
    long lcm = l * (ml / d);
    long t1 = ((((x - bl) / d) % lcm) * (modInverse(ml/d, l/d) % lcm)) % lcm;
    x = (bl + ((tl * ml) % lcm)) % lcm;
    l = lcm;
  }
  return new long[] {x, l};
}</pre>
```

5.6.4 Euler phi

```
\begin{array}{l} \phi(N) = N \times \prod_{p \mid N} (1 - \frac{1}{p}) = \#\{k < N | \gcd(k, N) = 1\} \\ \text{long phi(long n, int primes[]) } \{ \\ \text{long ans = n; } / \text{ Method 1} \\ \text{for (int i = 0; i < primes.length \&\& primes[i] * primes[i] <= n; i++) } \{ \\ \text{int p = primes[i];} \\ \text{if (n \% p = 0) ans } -= \text{ans } / \text{ p;} \\ \text{while (n \% p = 0) ans } /= \text{ p;} \\ \} \\ \text{if (n != 1) ans } -= \text{ans } / \text{ n;} \\ \text{return ans;} \\ \} \\ \text{for (int i = 1; i <= 1000000; i++) phi[i] = i;} \\ \text{for (int i = 2; i <= 1000000; i++) } / \text{ Method 2} \\ \text{if (phi[i] = i) } / / \text{ i is prime} \\ \text{for (int j = i; j <= 1000000; j += i)} \\ \text{phi[j] = (phi[j] / i) * (i - 1);} \\ \text{-- If } \phi(1) = 1, n = \sum_{d \mid n} \phi(d). \end{array}
```

- p prime iff there exists a number relatively prime with p of order p-1 (primitive root of p).
- There is $\phi(d)$ number of orders d modulo p.
- If g is order $d \mod p$, $\{g^k | k = 1, \dots, d-1 : (k, d) = 1\}$ are the $\phi(d)$ numbers of order $d \mod p$.

Let $\phi_S(n) = \sum_{i=1}^n \phi(i)$.

$$\phi_S(n) = \frac{n^2 + n}{2} - \sum_{d=2}^{n} \phi_S\left(\left\lfloor \frac{n}{d} \right\rfloor\right).$$

Discrete log

$$a^x \equiv a^y \pmod{n} \Leftrightarrow x \equiv y \pmod{O_n(a)}$$

 $\Leftarrow x \equiv y \pmod{\phi(n)}$

and in particular, if g is a primitive root of p,

$$g^x \equiv g^y \pmod{p} \Leftrightarrow x \equiv y \pmod{p-1}$$

so for an equation $(p \nmid a, b)$

$$a^{k_1} \equiv b^{k_2} \pmod{p}$$

we take ℓ_1 and ℓ_2 such that $a=g^{\ell_1}$ and $b=g^{\ell_2}$ and it becomes

$$k_1\ell_1 \equiv k_2\ell_2 \pmod{p-1}$$

5.6.5 Quadratic residue (QR)

p odd prime. Let g primitive root mod p. $\forall n$, g^{2n} is QR mod p and g^{2n+1} is not. There is $\frac{p-1}{2}$ QR and $\frac{p-1}{2}$ not QR.

$$\left(\frac{a}{p}\right) \equiv a^{\frac{p-1}{2}} \pmod{m}$$
$$= \prod_{r=1}^{\frac{p-1}{2}} \varepsilon(ar)$$

where $\varepsilon(x) = 1$ if $x \equiv 1, \dots, \frac{p-1}{2} \pmod{p}$ and -1 otherwise. $b \text{ odd } (\left(\frac{a}{b}\right) = 1 \text{ does not mean } a \text{ QR mod } b!!!)$

$$\left(\frac{a}{b}\right) \triangleq \prod \left(\frac{a}{p_i}\right)^{e_i}$$

b odd

$$\left(\frac{ac}{b}\right) = \left(\frac{a}{b}\right) \left(\frac{c}{b}\right)$$

a, b odd

$$\left(\frac{a}{b}\right)\left(\frac{b}{a}\right) = (-1)^{\frac{a-1}{2}\frac{b-1}{2}}.$$

```
static long modpow (long a, long n, long m) {
  if (n = 0) {
    return 1 % m;
  if (n % 2 == 0) {
    long demi = modpow(a, n/2, m);
    return (demi * demi) % m;
  } else {
    return (\text{modpow}(a, n-1, m) * a) \% m;
}
static long modular_sqrt(long a, long p) {
     Solve the congruence of the form:
     x^2 = a \pmod{p}
     And returns x. Note that p - x is also a root.
     0 is returned is no square root exists for
     these a and p.
     The Tonelli-Shanks algorithm is used (except
     for some simple cases in which the solution
     is known from an identity). This algorithm
     runs in polynomial time (unless the
     generalized Riemann hypothesis is false).
    Simple cases
  if (legendre_symbol(a, p) != 1) {
    return 0;
    else if (a == 0) {
    return 0;
    else if (p == 2) {
    else if (p \% 4 == 3) {
    return modpow(a, (p + 1) / 4, p);
    Partition p-1 to s * 2^e for an odd s (i.e.
     reduce all the powers of 2 from p-1)
  long s = p - 1;
  long e = 0;
  while (s % 2 == 0) {
    e += 1;
```

```
}
  /* Find some 'n' with a legendre symbol n|p = -1.
     Shouldn't take long.*/
  long n = 2;
  while (legendre\_symbol(n, p) != -1) {
   n += 1;
    x is a guess of the square root that gets better
   * with each iteration.
   * b is the "fudge factor" — by how much we're off * with the guess. The invariant x^2 = ab \pmod{p}
   * is maintained throughout the loop.
   * both a and b
   * r is the exponent – decreases with each update
  long x = modpow(a, (s + 1) / 2, p);
  long g = modpow(n, s, p);
  long r = e;
  for (;;) {
    long t = b;
    long m = 0;
    for (m = 0; m < r; m++) {
      if (t == 1) {
        break;
      t = (t * t) \% p;
    if (m == 0) {
      return x;
    long pow2 = 1;
    for (int i = 0; i < r-m-1; i++) { pow2 *= 2; }
    long gs = modpow(g, pow2, p);
    g = (gs * gs) \% p;
    x = (x * gs) \% p;

b = (b * g) \% p;
    r = m:
}
static long legendre_symbol1(long a, long p) {
  // p is prime and a is rel. prime to b
  long ls = modpow(a, (p-1) / 2, p);
return ls == p - 1 ? -1 : ls;
static long legendre_symbol(long a, long b) {
  // b is odd and rel. prime to a
  a %= b;
  if (a = 0) {
   return 0;
  int \exp 2 = 0;
  while (a \% 2 == 0) {
    a /= 2;
    \exp 2++;
  int cur = 1;
  if (\exp 2 \% 2 = 1 \&\& (b \% 8 = 3 || b \% 8 = 5)) {
    \operatorname{cur} *= -1;
  if (a < 0) {
    if (b % 4 == 3) {
      \operatorname{cur} *= -1;
    a *= -1;
  if (a = 1) {
    return cur:
  if (a % 4 == 3 && b % 4 == 3) {
    \operatorname{cur}^* = -1;
```

```
return cur * legendre_symbol(b, a);
     Linear equations
Solve Ax = b.
double[] gaussElim(double[][] A, double[] b) {
  int N = b.length;
  for (int p = 0; p < N; p++) {
    int max = p;
    for (int i = p + 1; i < N; i++) {
       if(Math.abs(A[i][p])>Math.abs(A[max][p])) {
         \max = i;
    swap(A, p, max);
    swap(b,\ p,\ max)\,;
    // singular or nearly singular
    if(Math.abs(A[p][p]) \le E)  {
       return null;
     // pivot within A and b
    for (int i = p + 1; i < N; i++) {
       double alpha = A[i][p] / A[p][p];
       b[i] -= alpha * b[p];
       for (int j = p; j < N; j++) {
        A[i][j] = alpha * A[p][j];
    }
  }
  // back substitution
  double[] x = new double[N];
  for (int i = N - 1; i >= 0; i ---) {
    double sum = 0.0;
    for (int j = i + 1; j < N; j++) {
      sum += A[i][j] * x[j];
    x[i] = (b[i] - sum) / A[i][i];
  return x;
       Ternary Search
5.8
Find minimum of unimodal function.
double ternarySearch(double left, double right) {
  if(right - left < E) {</pre>
    return (right + left) / 2;
  double leftThird = (left * 2 + right) / 3;
  double rightThird = (left + right * 2) / 3;
  //minimize >, maximize <
  if(f(leftThird) > f(rightThird)) {
    return ternarySearch(leftThird, right);
  return ternarySearch(left, rightThird);
      Integration
Compute integral.
double integral (double a, double b) {
  double h = b - a;
  double c = (a + b) / 2.0;
  \begin{array}{l} \mbox{double } d = (a + c) \ / \ 2.0; \\ \mbox{double } e = (b + c) \ / \ 2.0; \\ \mbox{double } Q1 = h/6 \ ^* \ (f(a) + 4^*f(c) + f(b)); \\ \mbox{double } Q2 = h/12 \ ^* \ (f(a) + 4^*f(d) + 2^*f(c) + 4^*f(e) \end{array}
                         +f(b);
```

if $(Math.abs(Q2 - Q1) \leftarrow E)$ {

} else {

return Q2 + (Q2 - Q1) / 15;

```
\begin{array}{c} \text{return integral(a, c)} + \text{integral(c, b);} \\ \} \end{array} \}
```

6 Strings untested

Reverse a String
new StringBuilder(line).reverse().toString()

6.1 Longest palindrome

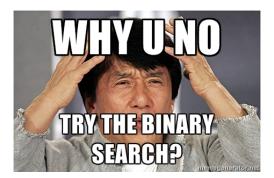
```
int[] calculateAtCenters(String s) {
  int n = s.length();
  int[] L = new int[2 * n + 1];
  int i = 0, palLen = 0, k = 0;
  while (i < n)
    if ((i > palLen) &&
       (s.charAt(i - palLen - 1) = s.charAt(i))) {
      palLen += 2;
      i += 1;
      continue;
   L[k++] = palLen;
    int e = k - 2 - palLen;
    boolean found = false;
    for (int j = k - 2; j > e; j---) {
      if(L[j] = j - e - 1) {
        palLen = j - e - 1;
        found = true;
        break:
     L[k++] = Math.min(j - e - 1, L[j]);
    if (!found) {
      i += 1;
      palLen = 1;
 L[k++] = palLen;
  int e = 2 * (k - n) - 3;
  for(i = k - 2; i > e; i--) {
   int d = i - e - 1;
   L[k++] = Math.min(d, L[i]);
  return L;
}
String getPalindrome(String s, int[] L) {
  int max = L[0];
  int maxI = 0;
  for (int i = 1; i < L. length; i++) {
    if(L[i] > max)  {
     \max = L[i];
     \max I = i;
 e = maxI / 2 + L[maxI] / 2;
  e += \max_{i=0}^{n} \% 2 == 0 ? 0 : 1;
  return s.substring(b, e);
}
String getPalindrome(String s)
  return getPalindrome(s, calculateAtCenters(s));
```

6.2 Occurrences in a string

```
\begin{split} & KMP(s,p) \ returns \ occurences \ index \ of \ p \ in \ s. \\ & int \ [] \ kmpPreprocess(char[] \ p) \ \{ \\ & int \ m = p.length; \\ & int \ [] \ b = new \ int \ [m+1]; \\ & int \ i = 0, \ j = -1; \ b[0] = -1; \ // \ starting \ values \\ & while \ (i < m) \ \{ \ // \ pre-process \ the \ pattern \ string \ p \\ & while \ (j >= 0 \ \&\& \ p[i] \ != p[j]) \ j = b[j]; \ // \ if \\ & different \ , \ reset \ j \ using \ b \end{split}
```

```
i++; j++; // if same, advance both pointers
    b[i] = j;
 return b; }
LinkedList<Integer> kmpSearchAll(char[] s, char[] p) {
       text, pattern
  int[] b = kmpPreprocess(p); // back table
  int n = s.length, m = p.length;
 LinkedList<Integer> found = new LinkedList<Integer>()
 int i=0, j=0; // starting values while (i < n) { // search through string s
    while (j \ge 0 \&\& s[i] != p[j]) j = b[j]; // if
    different, reset j using b
    i++; j++; // if same, advance both pointers if (j == m) { // a match found when j == m
      found.add(i-j);
      j = b[j]; // prepare j for the next possible
    match
  return found; }
int kmpSearchFirst(char[] s, char[] p) { // text,
    pattern
  int[] b = kmpPreprocess(p); // back table
  int n = s.length, m = p.length;
 int i=0,\ j=0;\ //\ {\rm starting\ values} while (i < n) { // search through string s
    while (j = 0) & s[i] != p[j]) j = b[j]; // if
    different, reset j using b
    i++; j++; // if same, advance both pointers
    if (j = m) { // a match found when j = m
      } }
 return n - j;
```

7 Miscellaneous



7.1 The answer

```
7.2 Sort algorithms untested int findKth(int[] A, int k, int n)
```

int reponse() { return 42; }

```
int findKth(int[] A, int k, int n) {
  if(n \le 10) {
    Arrays.sort(A, 0, n);
    return A[k];
  int nG = (int)Math.ceil(n / 5.0);
  int[][] group = new int[nG][];
  int[] kth = new int[nG];
  for (int i = 0; i < nG; i++) {
    if (i == nG − 1 && n % 5 != 0) {
      group [i] = Arrays.copyOfRange(A, (n/5)*5, n);
      kth[i] = findKth(group[i], group[i].length / 2,
                     group[i].length);
    } else {
      group[i] = Arrays.copyOfRange(A, i*5, (i+1)*5);
      kth[i] = findKth(group[i], 2, group[i].length);
  int M = findKth(kth, nG / 2, nG);
```

```
int[] S = new int[n];
  int[] E = new int[n];
  int[] B = new int[n];
  \quad \text{int } s = 0\,, \ e = 0\,, \ b = 0\,;
  for(int i = 0; i < n; i++) {
    if(A[i] < M) {
     S[s++] = A[i];
    } else if(A[i] > M) {
B[b++] = A[i];
    else \{E[e++] = A[i];\}
  if(k < s) {
    return findKth(S, k, s);
  else if(k >= s + e)
    return findKth(B, k - s - e, b);
  return M:
}
int[] countSort(int[] A, int k) { // O(n + k)}
  int[] C = new int[k];
  for (int j = 0; j < A. length; j++) {
   C[A[j]]++;
  for (int j = 1; j < k; j++) {
   C[j] += C[j-1];
  int[] B = new int[A.length];
  for (int j = A. length - 1; j >= 0; j--) {
   B[C[A[j]] - 1] = A[j];
   C[A[j]] - -;
  return B;
}
int[][] radixSort(int[][] nums, int k) { // O(d*(n+k))
  int n = nums.length;
  int m = nums[0].length;
  int[][] B = null;
  for (int i = m - 1; i >= 0; i--) {
    int[] C = new int[k];
    for (int j = 0; j < n; j++) {
      C[nums[j][i]]++;
    for (int j = 1; j < k; j++) {
     C[j] += C[j - 1];
   B = new int[n][];
    for (int j = n - 1; j >= 0; j--) {
      B[C[nums[j][i]] - 1] = nums[j];
      C[nums[j][i]] = C[nums[j][i]] - 1;
    nums = B;
  return nums;
}
int mergeSort(int[] a) {
  int n = a.length;
  if (n == 1) \{return \ 0;\}
  int m = n / 2;
  int[] left = Arrays.copyOfRange(a, 0, m);
  int[] right = Arrays.copyOfRange(a, m, n);
  int inv = mergeSort(left);
  inv += mergeSort(right);
  inv += merge(left, right, a);
  return inv;
}
int merge(int[] left, int[] right, int[] a) {
 int i = 0, l = 0, r = 0, inv = 0;
  if(left[l] <= right[r]) {</pre>
      \dot{a}[i++] = left[l++];
    } else {
      inv += left.length - l;
      a[i++] = right[r++];
  }
```

```
for (int j = l; j < left.length; j++) {
    a[i++] = left[j];
  for(int j = r; j < right.length; j++) {
    a[i++] = right[j];
  return inv;
int countMinSwapsToSort(int[] a) {
  int[] b = a.clone();
  Arrays.sort(b);
  int nSwaps = 0;
  for (int i = 0; i < a.length; i++) {
    // cuidado com elementos repetidos!
    int j = Arrays.binarySearch(b, a[i]);
    if(b[i] == a[j] && i != j) {
      nSwaps++;
      swap(a, i, j);
    }
  for (int i = 0; i < a.length; i++) {
    if (a[i] != b[i]) {
      nSwaps++;
  return nSwaps;
//\text{Count (i, j) :} h[i] \le h[k] \le h[j], k = i+1,...,j-1.
int countVisiblePairs(int[] h) { // O(n)
  int n = h.length;
  int \,[\,]\ p = new\ int \,[\,n\,]\,;
  int[] r = new int[n];
  Stack<Integer> S = new Stack<Integer>();
  for (int i = 0; i < n; i++) {
    int c = 0;
     if(S.isEmpty()) {
      S.push(h|i|);
      p[i] = 0;
    } else {
       if(S.peek() == h[i])  {
        p[i] = p[i - 1] + 1 - r[i - 1];
       } else {
        while (!S.isEmpty() \&\& S.peek() < h[i]) {
     S.pop();
     c++;
   p[i] = c;
   r[i] = c;
   if (!S.isEmpty()) {
     p[i]++;
    S. push (h[i]);
  return sum(p);
void shuffle (Object [] a)
{
  \quad \text{int } N = a. \, length \, ; \\
  for (int i = 0; i < N; i++) {
    int r = i + (int) (Math.random() * (N-i));
    swap(a, i, r);
}
```

7.3 Huffman (compression)

Usually used for characters, but usable with everything in which we can count occurrences.

Make a prefix tree we use to decode and we unstack to encode.

class HuffmanNode implements Comparable<HuffmanNode>
{
 public boolean isLeaf;
 public int occurences;
 public int charIndex;

```
public HuffmanNode left , right;
  public HuffmanNode (HuffmanNode left, HuffmanNode
    right)
    this.occurences = left.occurences+right.occurences;
    this.left = left;
    this.right = right;
    isLeaf = false;
  public HuffmanNode(int charIndex, int occurences)
    this . charIndex = charIndex:
    this.occurences = occurences;
    isLeaf = true;
  @Override
  public int compareTo(HuffmanNode o) {
    return occurences-o.occurences;
HuffmanNode getHuffmanTree(int[] occurences) {
  PriorityQueue<HuffmanNode> q = new PriorityQueue<
    HuffmanNode>();
  for (int i = 0; i < occurences.length; i++)
    q.add(new HuffmanNode(i, occurences[i]));
  while(q.size() != 1)  {
   HuffmanNode right = q.poll();
    HuffmanNode left = q.poll();
    q.add(new HuffmanNode(left, right));
  return q.poll();
}
void getHuffmanTable(HuffmanNode tree, BitSet[] result,
     BitSet current, int pos){
  if(tree.isLeaf) {
    BitSet finalBitSet = new BitSet();
    for(int i = 0; i < pos; i++)
      finalBitSet.set(i, current.get(pos-i-1));
    result[tree.charIndex] = finalBitSet;
   else {
    BitSet leftBitSet = new BitSet();
    leftBitSet.or(current);
    leftBitSet.set(pos, false);
    {\tt getHuffmanTable(tree.left\;,\;result\;,\;leftBitSet\;,\;pos}
    +1);
    BitSet rightBitSet = new BitSet();
    rightBitSet.or(current);
    rightBitSet.set(pos, true);
    getHuffmanTable(\,tree.\,right\,,\ result\,,\ rightBitSet\,,
    pos+1);
}
//n=occurences.length
static BitSet[] getHuffmanTable(int n, HuffmanNode tree
  BitSet[] result = new BitSet[n];
  getHuffmanTable(tree, result, new BitSet(), 0);
  return result:
```

7.4 Union Find

```
static class UnionFind {
  int[] depth; int[] leader; int[] size;
```

```
public UnionFind(int n) {
    depth = new int[n]; leader = new int[n]; size = new
     int[n];
    Arrays.fill(depth, 1); Arrays.fill(size, 1);
    for (int i = 0; i < n; i++) leader [i] = i;
  public int find(int a) {
    if(a != leader[a])
     leader[a] = find(leader[a]);
    return leader[a];
  public void union(int a, int b) {
    int leaderA = find(a);
    int leaderB = find(b);
    if(leaderA == leaderB) return;
    if (size [leaderA] > size [leaderB]) {
      union(leaderB, leaderA); return;
    leader [leaderA] = leaderB;
    depth[leaderB] = Math.max(depth[leaderA]+1, depth[
    leaderB]);
    size[leaderB] += size[leaderA];
7.5
     Fenwick Tree (RSQ solver)
static class FenwickTree {
 private int[] ft;
  private int LSOne(int S) { return (S & (-S)); }
  public FenwickTree(int n) { // ignore index 0
    ft = new int[n+1];
    for (int i = 0; i \le n; i++) ft [n] = 0;
  public int rsq(int b) { // returns RSQ(1, b)
    PRE 1 <= b <= n
    int sum = 0; for (; b > 0; b = LSOne(b)) sum += ft
    [b];
    return sum;
  public int rsq(int a, int b) { // returns RSQ(a, b)
    PRE 1 \le a, b \le n
    return rsq(b) - (a = 1 ? 0 : rsq(a - 1));
  \label{eq:void_adjust(int_k, int_v) { ( // n = ft.size() - 1)}} \\
    PRE 1 \le k \le n
    for (; k < ft.length; k += LSOne(k)) ft[k] += v;
             ICED YOU ONLY USE 15
                      PAGES
```