

Auto regressive Moving Average Process of order 1 (~~ARMA(1,1)~~)

ARMA(1,1)

Stationary solⁿ to the eqⁿ

$$x_t - \phi x_{t-1} = z_t + \theta z_{t-1}, \quad \theta, \phi \in \mathbb{R} \quad (\theta + \phi \neq 0)$$
$$\{z_t\} \sim \text{WN}(0, \sigma^2)$$

case 1: $|\phi| < 1$

$$(1 - \phi B)x_t = (1 + \theta B)z_t$$

$$\Rightarrow x_t = \frac{1}{1 - \phi B} (1 + \theta B) z_t$$

$$\Rightarrow x_t = (1 + \phi B + \phi^2 B^2 + \dots) (1 + \theta B) z_t$$

$$= (1 + (\theta + \phi) \sum_{j=1}^{\infty} \phi^{j-1} B^j) z_t$$

$$= z_t + (\theta + \phi) \sum_{j=1}^{\infty} \phi^{j-1} z_{t-j}$$

case 2: $|\phi| > 1$

$$x_t = \frac{1}{1 - \phi B} (1 + \theta B) z_t$$

$$= \frac{-\phi^{-1} B^{-1}}{1 - \phi^{-1} B^{-1}} (1 + \theta B) z_t$$

$$= -(\phi^{-1} B^{-1} + \phi^{-2} B^{-2} + \dots) (1 + \theta B) z_t$$

$$= -[\theta \phi^{-1} z_t + (1 + \theta \phi^{-1}) \sum_{j=1}^{\infty} \phi^{-j} B^{-j} z_t]$$

$$= -[\theta \phi^{-1} z_t + (1 + \theta \phi^{-1}) \sum_{j=1}^{\infty} \phi^{-j} z_{t+j}]$$

case 3: $|\phi|=1$

We do for $\phi=1$

$$x_t - x_{t-1} = z_t + \theta z_{t-1}, \quad \forall t$$

$$x_{t-1} - x_{t-2} = z_{t-1} + \theta z_{t-2}$$

\vdots

$$x_{t-k} - x_{t-k-1} = z_{t-k} + \theta z_{t-k-1}$$

$$\therefore x_t - x_{t-k-1} = z_t + (1+\theta) \sum_{j=1}^k z_{t-j} + \theta z_{t-k-1}$$

RHS has variance $\rightarrow \infty$ as $\theta \neq -1$

LHS has variance $\leq 4\gamma(0)$ [If x_t is stationary with ACVF $\gamma(h)$]

Hence for $\phi=1$, \nexists any stationary solⁿ to ARMA(1,1)

Summary:

- 1) $|\phi| < 1 \rightarrow$ causal stationary solⁿ
- 2) $|\phi| > 1 \rightarrow$ non-causal stationary solⁿ
- 3) $|\phi| = 1 \rightarrow$ no stationary solⁿ.

Defⁿ (Invertibility): We call a process invertible if z_t can be written linearly in terms of x_s 's ($s \leq t$).

Let's check for what values of θ , the ARMA(1,1) process is invertible.

Case 1: ~~$|\theta| < 1$~~ $|\theta| < 1$,

$$Z_t = \frac{1}{1+\theta B} (1-\phi B) X_t$$

$$= (1-\theta B + \dots) (1-\phi B) X_t$$

$$= X_t - (\theta+\phi) \sum_{j=1}^{\infty} (-\theta)^j X_{t-j}$$

Case 2: $|\theta| > 1$

$$Z_t = \frac{1}{1+\theta B} (1-\phi B) X_t$$

$$= \frac{\theta^{-1} B^{-1}}{1+\theta^{-1} B^{-1}} (1-\phi B) X_t$$

$$= \theta^{-1} B^{-1} (1 - \theta^{-1} B^{-1} + \theta^{-2} B^{-2} - \dots) (1-\phi B) X_t$$

$$= -\phi \theta^{-1} X_t + (\theta+\phi) \sum_{j=1}^{\infty} (-\theta)^{-j-1} X_{t+j}$$

\therefore The process is non-invertible.

Remark: For $|\theta| > 1$, the process is non-invertible in the sense of infinite linear combⁿ of $\{X_s\}_{s=-\infty}^{\infty}$ to get Z_t .

• The process is non-invertible in the sense that Z_t can be written as mean-square limit of variables which are finite linear combⁿ of X_s 's ($s \leq t$) \downarrow L^2 convergence

Eg: $Y_t = U + Z_t$, $U \sim N(0,1)$
 $Z_t \not\sim N(0,1)$ > indep.

U can not be written as infinite linear combⁿ of Z_t 's

But $\bar{Y}_k \xrightarrow{L^2} U$

ACVF of ARMA(1,1)

$$|\phi| < 1,$$

$$x_t = z_t + (\theta + \phi) \sum_{j=1}^{\infty} \phi^{j-1} z_{t-j}$$

$$E(x_t) = 0$$

$$\text{Var}(x_t) = \sigma^2 + (\theta + \phi)^2 \sum_{j=1}^{\infty} \phi^{2(j-1)} \sigma^2$$

$$= \sigma^2 \left[1 + (\theta + \phi)^2 \frac{1}{1 - \phi^2} \right]$$

$$\gamma(1) = \text{Cov}(x_t, x_{t+1})$$

$$= \text{Cov} \left(z_t + (\theta + \phi) \sum_{j=1}^{\infty} \phi^{j-1} z_{t-j}, z_{t+1} + (\theta + \phi) \sum_{j=1}^{\infty} \phi^{j-1} z_{t+1-j} \right)$$

$$= \left((\theta + \phi) + (\theta + \phi)^2 \sum_{j=1}^{\infty} \phi^{2j-1} \right) \sigma^2$$

$$= \sigma^2 \left[(\theta + \phi) + (\theta + \phi)^2 \frac{\phi}{1 - \phi^2} \right]$$

$$\gamma(h) = \text{Cov}(x_t, x_{t+h})$$

$$= E(x_t x_{t+h})$$

$$= (\theta + \phi)^2 \sum_{j=1}^{\infty} \phi^{2j-1}$$

$$x_t - \phi x_{t-1} = z_t + \theta z_{t-1}$$

$$\Rightarrow x_t x_{t-h} - \phi x_{t-1} x_{t-h} = z_t x_{t-h} + \theta z_{t-1} x_{t-h}$$

$$\Rightarrow \gamma(h) - \phi \gamma(h-1) = 0$$

$$\Rightarrow \gamma(h) = \phi \gamma(h-1) = \phi^{(h-1)} \gamma(1)$$

The time series occurring in practical situation in population studies/economic/social studies are usually non-stationary. So far we have considered stationary time series.

Additive Model:

$$X_t = m_t + s_t + c_t + \varepsilon_t \quad [\text{occurring in practical situation}]$$

$m_t \rightarrow$ trend component

slowly changing component of the series that ~~is~~ indicates overall increase/decrease.

[population in India has increasing trend from $t=1901$ to $t=2001$]

$s_t \rightarrow$ seasonal component

component of time series that depends on particular parts/quarter/month of a year.

[rainfall in a city has seasonal component]

$c_t \rightarrow$ cyclical component

The component that is due to change in perspective generating the time series/long period cycles those are present in the series.

[cyclical component in stock values due to long term change in international or national market]

$\varepsilon_t \rightarrow$ random component

component whose cause is unaccounted

Sometimes it may be more useful to consider product model.

$$X_t = m_t \times s_t \times c_t \times \varepsilon_t$$

e.g. production of wheat / size of population in a country may depend on previous year and change proportionately.

$$X_{t+1} \approx (1+r) X_t$$

Then product model is necessary.

② We take logarithm to transform product model to additive model for easier analysis.

③ If ε_t are iid noise then we estimate future values of ε_t by 0. Otherwise we ~~use~~ assume ε_t follows is stationary time series and using its results we predict its future values.

Estimation / Elimination of trend component

Method 1: Curve fitting

$$m_t = c_0 + c_1 t + c_2 t^2 + \dots + c_k t^k$$

Assume,

$$X_t = m_t + \varepsilon_t$$

$$W = \sum_{t=1}^n (X_t - m_t)^2$$

$$\frac{\partial W}{\partial c_i} = 0, \quad i = 0, 1, 2, \dots, k$$

$$B_{(k+1) \times (k+1)} \begin{pmatrix} c_0 \\ c_1 \\ \vdots \\ c_k \end{pmatrix} = \begin{pmatrix} d_0 \\ d_1 \\ \vdots \\ d_k \end{pmatrix}$$

$$b_{ij} = \sum_{t=1}^n t^{i+j}$$

$$d_i = \sum_{t=1}^n t^i x_t$$

B is vandermond matrix and it's non-singular.

$\therefore \exists$ unique $\hat{c}_0, \hat{c}_1, \dots, \hat{c}_k$ s.t.

$$\hat{m}_t = \sum_{i=0}^k \hat{c}_i t^i$$

Method 2: Moving Average Method

$$x_t = m_t + \varepsilon_t$$

$$\frac{1}{2q+1} \sum_{j=-q}^q x_{t+j} = \frac{1}{2q+1} \sum_{j=-q}^q m_{t+j} + \underbrace{\frac{1}{2q+1} \sum_{j=-q}^q \varepsilon_{t+j}}_{\substack{? \\ 0}}$$

Now if $m_t = a + bt$ (linear component)

$$\frac{1}{2q+1} \sum_{j=-q}^q m_{t+j} = m_t$$

$$\therefore \frac{1}{2q+1} \sum_{j=-q}^q x_{t+j} \approx m_t$$

absorbs high freqn components allowing low freqn components to survive. So it is called Low-Pass Filter.

General Form of Moving Average:

$$\sum_{j=-q}^q c_j x_{t+j}$$

It can be designed in such a way choosing c_j 's s.t. it allows to pass m_t undistorted

for fixed k , m_t is a polynomial of degree $\leq k$

Also it can be designed to absorb seasonal components of fixed period.

Remark: Moving Average filter absorbs high frequency part and allows to pass low frequency part.
(Low Pass Filter).

Exercise:

$$1. \quad x_t - \phi x_{t-1} = z_t + z_{t-1} \quad [|\phi| < 1]$$

$$z_t \sim WN(0, \sigma^2)$$

Show that z_t cannot be expressed as

$$z_t = \sum_{j=0}^{\infty} \psi_j x_{t-j}$$

$$\rightarrow x_t = (1 - \phi B)^{-1} (1 + B) z_t$$

$$= (1 - \phi B)^{-1} (1 + B) \alpha(B) x_t$$

$$= (1 + B) \beta(B) x_t$$

$$\Rightarrow x_t = (1 + B) \left(\sum_{j=0}^{\infty} \eta_j B^j \right) x_t$$

$$= \eta_0 x_t + \underbrace{\sum_{j=1}^{\infty} (\eta_j + \eta_{j-1}) x_{t-j}}_{\text{uncorrelated with } z_t}$$

$$\text{Cov}(x_s, z_t) = 0$$

$$s < t$$

$$\Rightarrow \eta_0 = 1$$

$$\Rightarrow \sum_{j=1}^{\infty} (\eta_j + \eta_{j-1}) x_{t-j} = 0$$

$$\Rightarrow (\eta_0 + \eta_1) x_{t-1} = - \underbrace{\sum_{j=2}^{\infty} (\eta_j + \eta_{j-1}) x_{t-j}}_{\text{uncorrelated with } z_{t-1}}$$

$$\therefore \eta_1 + \eta_0 = 0$$

$$\Rightarrow \eta_1 = -\eta_0 = -1$$

$$\text{Similarly, } \eta_4 = -\eta_3 = \eta_2 = -\eta_1 = \eta_0 = 1$$

$$\therefore \eta_i \rightarrow 0 \text{ as } i \rightarrow \infty$$

$$\Rightarrow \sum_{i=0}^{\infty} |\eta_i| = \infty$$

$$\Rightarrow \beta(B) \text{ is not defined at all.}$$

$$2. \text{ If } X_t = Z_t - Z_{t-1}$$

$$\text{then, } Z_t \in \text{closure} \left\{ \text{span} \{X_j : -\infty < j \leq t\} \right\}$$

~~then~~ $[Z_t \text{ can be written as limit of finite linear comb}^n \text{ of } X_t \text{'s.}]$

[Book 2: 3.8 problem]