EXPERIMENT 5
18CSC305J

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AIM: To implement Best First Algorithm and A* Algorithm using python.

BEST FIRST SEARCH

Description:

In BFS and DFS, when we are at a node, we can consider any of the adjacent as next node. So both BFS and DFS blindly explore paths without considering any cost function. The idea of Best First Search is to use an evaluation function to decide which adjacent is most promising and then explore.

Algorithm:

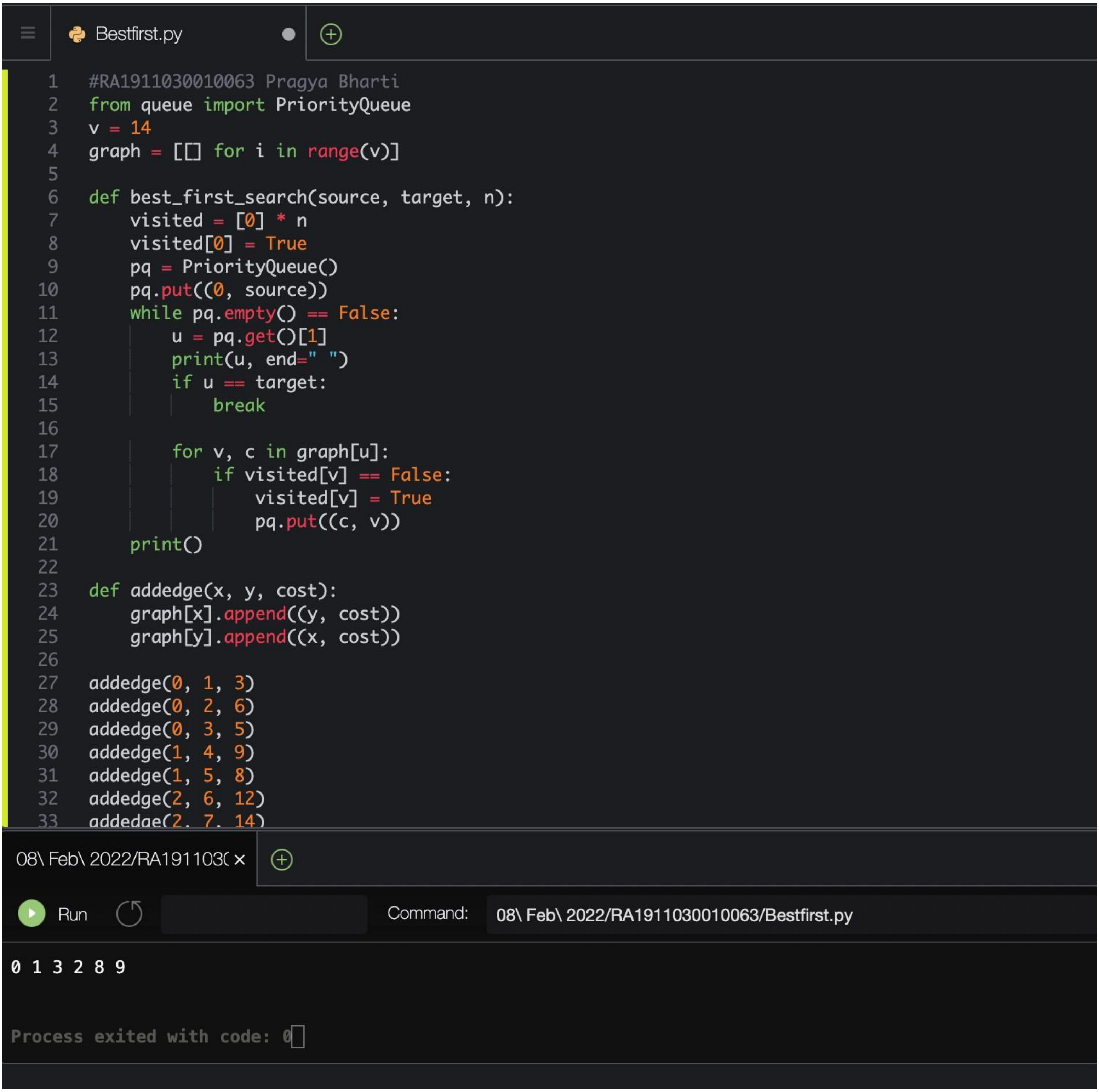
- Define a list, OPEN, consisting solely of a single node, the start node, *s*.
- IF the list is empty, return failure.
- Remove from the list the node *n* with the best score (the node where *f* is the minimum), and move it to a list, CLOSED.
- Expand node *n*.
- IF any successor to *n* is the goal node, return success and the solution (by tracing the path from the goal node to *s*).
- FOR each successor node: 1.apply the evaluation function, *f*, to the node. 2. IF the node has not been in either list, add it to OPEN.
- looping structure by sending the algorithm back to the second step.

Code:

```
from queue import PriorityQueue
v = 14
graph = [[] for i in range(v)]

def best_first_search(source, target, n):
    visited = [0] * n
    visited[0] = True
```

```
    pq = PriorityQueue()
    pq.put((0, source))
    while pq.empty() == False:
        u = pq.get()[1]
        print(u, end=" ")
        if u == target:
            break

        for v, c in graph[u]:
            if visited[v] == False:
                visited[v] = True
                pq.put((c, v))
    print()

def addedge(x, y, cost):
    graph[x].append((y,   cost))
    graph[y].append((x, cost))

addedge(0, 1, 3)
addedge(0, 2, 6)
addedge(0, 3, 5)
addedge(1, 4, 9)
addedge(1, 5, 8)
addedge(2, 6, 12)
addedge(2, 7, 14)
addedge(3, 8, 7)
addedge(8, 9, 5)
addedge(8, 10, 6)
addedge(9, 11, 1)
addedge(9, 12, 10)
addedge(9, 13, 2)

source = 0
target = 9 best_first_search(source,
target, v)
```

Output:



Bestfirst.py

```python
#RA1911030010063 Pragya Bharti
from queue import PriorityQueue
v = 14
graph = [[] for i in range(v)]

def best_first_search(source, target, n):
    visited = [0] * n
    visited[0] = True
    pq = PriorityQueue()
    pq.put((0, source))
    while pq.empty() == False:
        u = pq.get()[1]
        print(u, end=" ")
        if u == target:
            break

        for v, c in graph[u]:
            if visited[v] == False:
                visited[v] = True
                pq.put((c, v))
    print()

def addedge(x, y, cost):
    graph[x].append((y, cost))
    graph[y].append((x, cost))

addedge(0, 1, 3)
addedge(0, 2, 6)
addedge(0, 3, 5)
addedge(1, 4, 9)
addedge(1, 5, 8)
addedge(2, 6, 12)
addedge(2, 7, 14)
```

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Run

Command: 08\ Feb\ 2022/RA1911030010063/Bestfirst.py

```
0 1 3 2 8 9


Process exited with code: 0
```

A Best First Search*

Description:

A* is an informed search algorithm, or a best-first search, meaning that it is formulated in terms of weighted graphs: starting from a specific starting node of a graph, it aims to find a path to the given goal node having the smallest cost (least distance travelled, shortest time, etc.). It does this by maintaining a tree of paths originating at the start node and extending those paths one edge at a time until its termination criterion is satisfied.

Code:

```
def aStarAlgo(start_node, stop_node):

        open_set = set(start_node)
        closed_set = set()
        g = {} #store distance from starting node
        parents = {}# parents contains an adjacency map of all
nodes

        #ditance of starting node from itself is zero
        g[start_node] = 0
        #start_node is root node i.e it has no parent nodes
        #so start_node is set to its own parent node
        parents[start_node] = start_node


        while len(open_set) > 0:
            n = None

            #node with lowest f() is found
            for v in open_set:
                if n == None or g[v] + heuristic(v) < g[n] + heuristic(n):
                    n = v
```

```
        if n == stop_node or Graph_nodes[n] == None:
            pass
        else:
            for (m, weight) in get_neighbors(n):
                #nodes 'm' not in first and last set are added  to
first
                #n is set its parent
                if m not in open_set and m not in closed_set:
                    open_set.add(m)
                    parents[m] = n
                    g[m] = g[n] + weight


                #for each node m,compare its distance from start
i.e g(m) to the
                #from start through n node
                else:
                    if g[m] > g[n] + weight:
                        #update g(m)
                        g[m] = g[n] + weight
                        #change parent of m to n
                        parents[m] = n

                        #if m in closed set,remove and add to open
                        if m in closed_set:
                            closed_set.remove(m)
                            open_set.add(m)

        if n == None:
            print('Path does not exist!')
            return None

        # if the current node is the stop_node
        # then we begin reconstructin the path from it to the
start_node
        if n == stop_node:
```

```
            path = []

            while parents[n] != n:
                path.append(n)
                n = parents[n]

            path.append(start_node)

            path.reverse()

            print('Path found: {}'.format(path))
            return path


        # remove n from the open_list, and add it to closed_list
        # because all of his neighbors were inspected
        open_set.remove(n)
        closed_set.add(n)

    print('Path does not exist!')
    return None

#define fuction to return neighbor and its distance
#from the passed node
def get_neighbors(v):
    if v in Graph_nodes:
        return Graph_nodes[v]
    else:
        return None
#for simplicity we ll consider heuristic distances given
#and this function returns heuristic distance for all nodes
def heuristic(n):
    H_dist =
        { 'A':
        11,
        'B': 6,
        'C': 99,
```

```
            'D': 1,
            'E': 7,
            'G': 0,

        }

        return H_dist[n]

#Describe your graph here
Graph_nodes = {
    'A': [('B', 2), ('E', 3)],
    'B': [('C', 1),('G', 9)],
    'C': None,
    'E': [('D',6)],
    'D': [('G',1)],

}
aStarAlgo('A', 'G')
```

Output:

a.py

```python
def aStarAlgo(start_node, stop_node):

        open_set = set(start_node)
        closed_set = set()
        g = {} #store distance from starting node
        parents = {}# parents contains an adjacency map of all nodes

        #ditance of starting node from itself is zero
        g[start_node] = 0
        #start_node is root node i.e it has no parent nodes
        #so start_node is set to its own parent node
        parents[start_node] = start_node


        while len(open_set) > 0:
            n = None

            #node with lowest f() is found
            for v in open_set:
                if n == None or g[v] + heuristic(v) < g[n] + heuristic(n):
                    n = v


            if n == stop_node or Graph_nodes[n] == None:
                pass
            else:
                for (m, weight) in get_neighbors(n):
                    #nodes 'm' not in first and last set are added to first
                    #n is set its parent
```

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Run   Command: 08\ Feb\ 2022/RA1911030010063/a.py

```
Path found: ['A', 'E', 'D', 'G']


Process exited with code: 0
```

Result: Best first and A* algorithm were successfully executed in python.