

Morphological Network: With applications to Computer Vision

Bhabatosh Chanda

Indian Statistical Institute, Kolkata

Acknowledgement

- Ranjan Mandal
- Sanchayan Santra

Outline

- Digital image

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- Mathematical Morphology: Basics

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- Brief introduction to ANN-CNN

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- Automatic Learning of Structuring Element
 - De-raining problem

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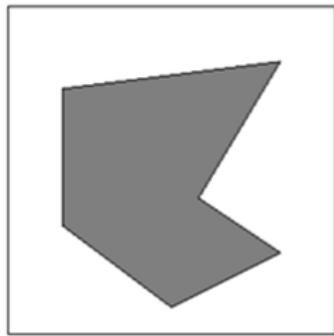
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 - De-raining problem
- Opening-Closing Network
 - De-raining problem
 - De-hazing problem

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 - De-hazing problem
- Conclusion

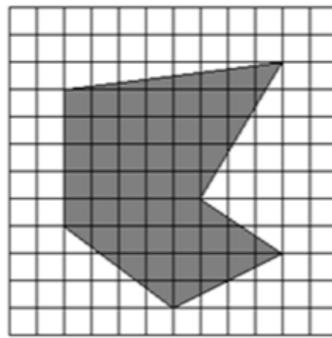
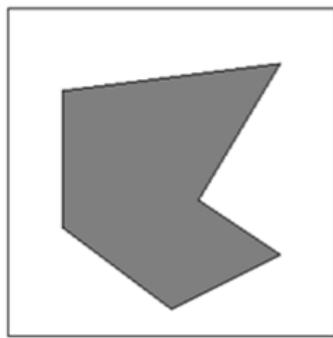
Digital image

Digital binary image: example



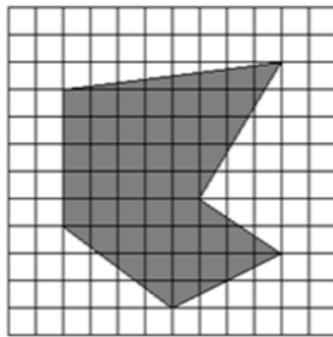
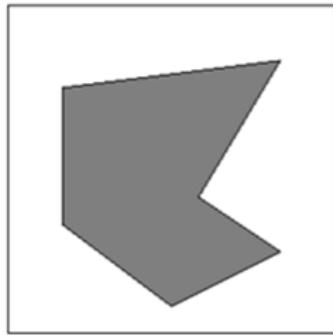
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0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	1	1	1	1	0	0
0	0	1	1	1	1	1	1	1	0	0	0
0	0	1	1	1	1	1	1	1	0	0	0
0	0	1	1	1	1	1	1	1	0	0	0
0	0	1	1	1	1	1	1	1	0	0	0
0	0	1	1	1	1	1	1	1	0	0	0
0	0	1	1	1	1	1	1	1	0	0	0
0	0	0	1	1	1	1	1	1	0	0	0
0	0	0	0	1	1	1	1	1	1	0	0
0	0	0	0	0	1	1	1	1	1	0	0
0	0	0	0	0	0	1	1	1	1	1	0

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Digital grayscale image: example



Digital image representation

Digital image (grayscale or binary) can be defined over a two-dimensional space $(i, j) \in \mathcal{Z}^2$ such that

$$[g(i,j)] = \begin{bmatrix} g(0,0) & g(0,1) & \cdots & g(0,N-1) \\ g(1,0) & g(1,1) & \cdots & g(1,N-1) \\ g(2,0) & g(2,1) & \cdots & g(2,N-1) \\ \vdots & \vdots & \cdots & \vdots \\ g(M-1,0) & g(M-1,1) & \cdots & g(M-1,N-1) \end{bmatrix}$$

where $g(i,j) \in \{0, \dots, L-1\}$ are non-negative integers.

For binary image $L = 2$ and for graylevel image $L = 255$

Digital colour image: example



109	106	106	110	111	106	60	98	142	114	94	98	102	120	103	109
115	126	126	137	137	136	106	146	157	146	124	128	98	96	89	82
137	118	134	145	151	147	142	157	154	140	120	105	85	77	67	63
189	150	123	131	145	143	143	134	123	110	90	65	65	67	83	102
193	191	157	85	182	161	126	170	188	181	167	158	153	151	155	155
193	189	185	85	178	147	125	171	183	192	181	167	157	155	160	152
168	103	74	78	179	145	139	163	171	190	195	176	164	161	162	162
90	106	112	75	177	148	50	163	169	186	197	191	169	167	167	160
125	133	136	64	169	142	142	114	94	98	102	120	103	109	185	167
143	154	165	54	171	172	185	178	147	125	171	183	192	181	167	155
170	185	187	82	190	189	178	179	145	139	163	171	190	195	176	164
180	179	174	74	166	168	175	177	148	150	163	169	186	197	191	169
142	116	128	69	165	162	164	169	142	154	171	172	182	190	189	174
141	148	154	50	163	165	163	165	139	153	175	163	179	189	187	178
160	163	164	39	153	175	162	161	136	144	164	163	171	189	176	179
168	171	181	63	179	189	109	106	106	110	111	106	60	98	142	114
87	170	166	115	126	126	137	137	136	106	146	157	146	174	128	98
67	170	169	157	146	124	128	98	96	89	82	193	189	185	168	103
70	168	162	112	125	133	136	143	154	165	170	154	140	120	105	85
61	136	144	185	187	180	179	174	142	116	128	141	148	154	160	163
181	185	178	173	179	171	162	153	153	160	162	164	164	163	165	167
183	184	175	149	177	179	165	164	155	153	159	164	160	159	163	164
154	140	120	105	85	77	67	63	123	110	90	65	65	67	83	102
95	98	84	94	107	119	138	155	112	125	133	136	143	154	165	170

Digital colour image representation

Digital colour image can be defined over a two-dimensional space
 $(i, j) \in \mathcal{Z}^2$ such that

$$[g_c(i, j)] = \begin{bmatrix} g_c(0, 0) & g_c(0, 1) & \cdots & g_c(0, N - 1) \\ g_c(1, 0) & g_c(1, 1) & \cdots & g_c(1, N - 1) \\ g_c(2, 0) & g_c(2, 1) & \cdots & g_c(2, N - 1) \\ \vdots & \vdots & \ddots & \vdots \\ g_c(M - 1, 0) & g_c(M - 1, 1) & \cdots & g_c(M - 1, N - 1) \end{bmatrix}$$

where $g_c(i, j) = [g_R(i, j), g_G(i, j), g_B(i, j)]$ and $g_k(i, j) \in \{0, \dots, L - 1\}$ (for $k = R$ or G or B) are non-negative integers. Usually $L = 255$.

Mathematical Morphology

Basics

- **Mathematical Morphology** is a nonlinear tool which is useful for the analysis and processing of geometrical structures in image.

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 - It directly operates on shape.
 - It is defined using set theoretic operations.
 - It employs neighbourhood operators involving add (or subtract) followed by max (resp.min).

Elementary operations of Morphology

- **Dilation (\oplus)**: The value of the output pixel is the maximum of sum of pixels values of the image and that of a kernel, i.e.,

$$(I \oplus S_d)(x, y) = \max_{i \in a; j \in b} \{I(x - i, y - j) + S_d(i, j)\}$$

- **Structuring Element**: The kernel S , called *Structuring element* (SE), is defined over a small region or domain ($a \times b$).

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- **Structuring Element**: The kernel S , called *Structuring element* (SE), is defined over a small region or domain ($a \times b$).
- **Erosion (\ominus)**: The value of the output pixel is the minimum of subtracting kernel pixels from that of the image, i.e.,

$$(I \ominus S_e)(x, y) = \min_{i \in a; j \in b} \{I(x + i, y + j) - S_e(i, j)\}$$

Dilation and erosion: Examples

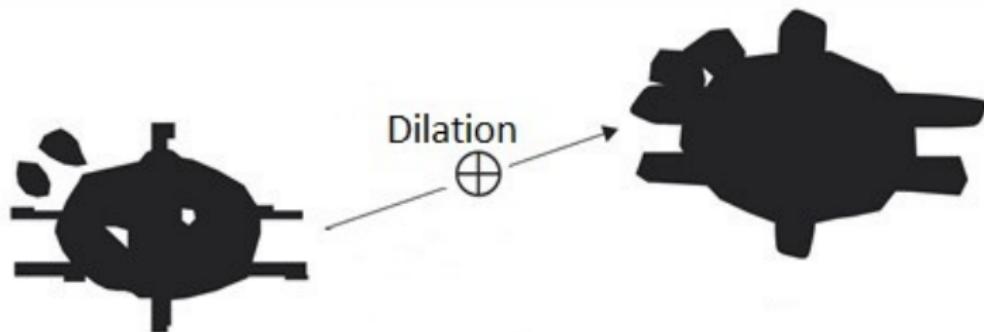


Figure: Results of Dilation and Erosion

Dilation and erosion: Examples

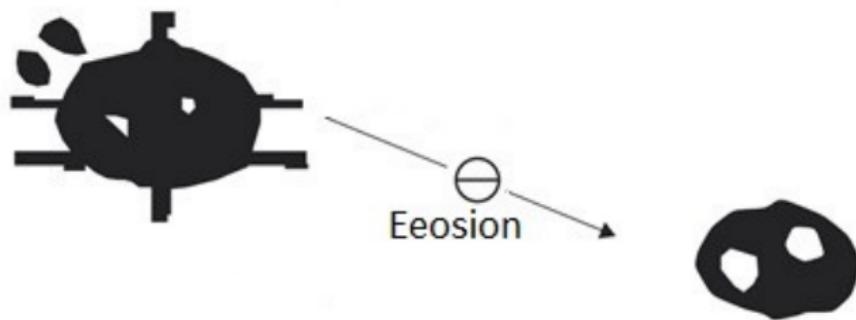


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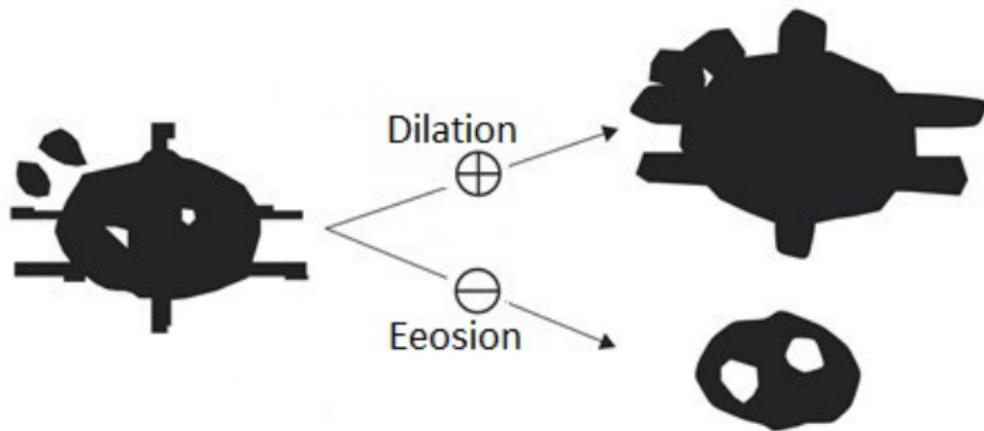


Figure: Results of Dilation and Erosion

Dilation with different SE

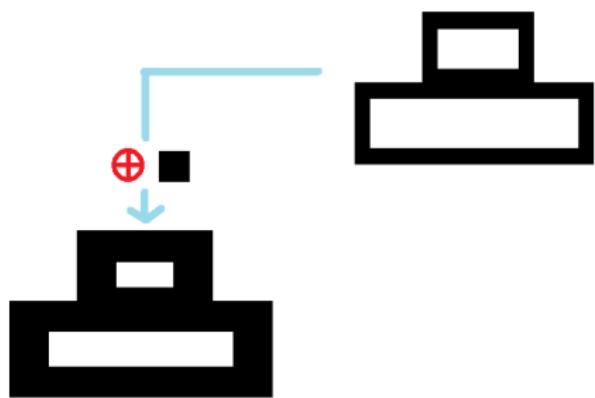


Figure: Results of Dilation.

Dilation with different SE

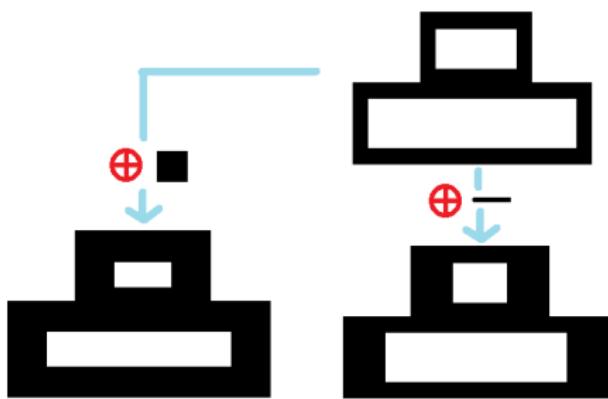


Figure: Results of Dilation.

Dilation with different SE

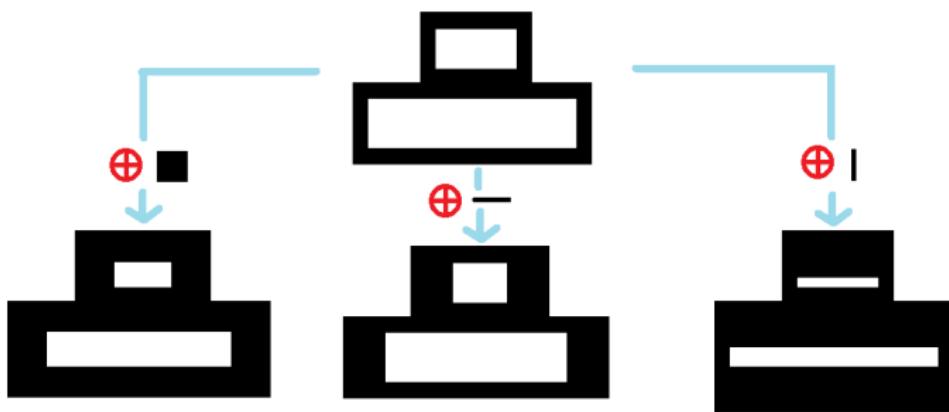


Figure: Results of Dilation.

Dilation Operation (gray-scale images)

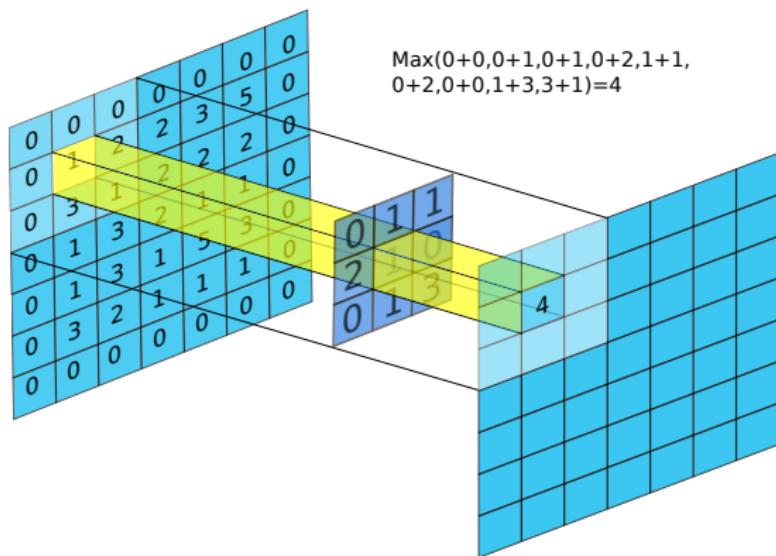


Figure: Dilation Operation with structuring elements of size 3×3

Noise cleaning: Example

Input: Gray scale image with noise

Output: Remove noise from the image

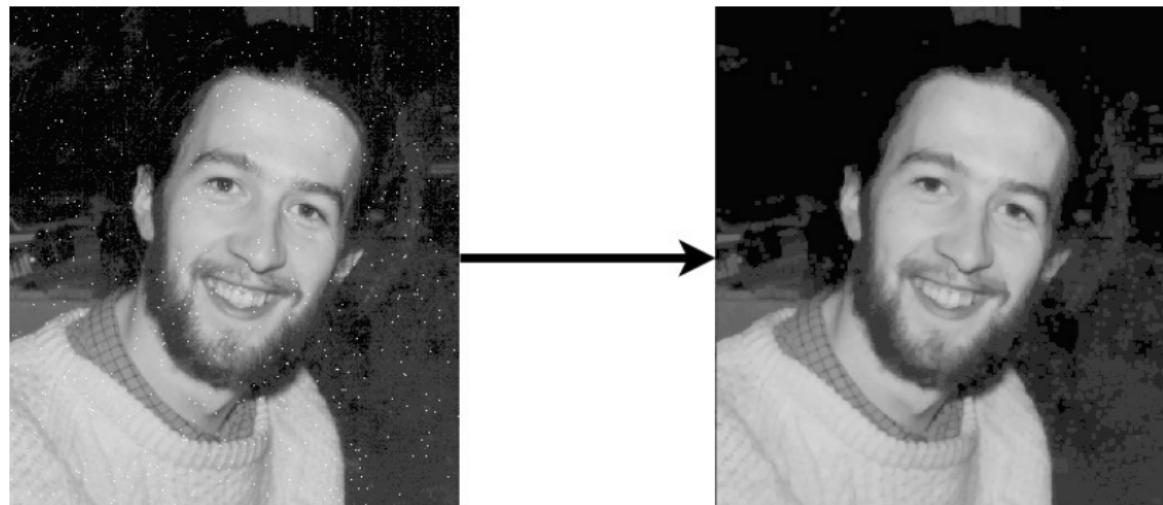


Figure: Result of erosion followed by a dilation with a 3×3 square SE.

Limitations

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- Determining operations to be used and their order.
- It is even harder when it comes to gray scale or color images.

Motivation

Can we learn the Structuring Elements and the sequence of operations?

ANN and CNN

Neuron and node

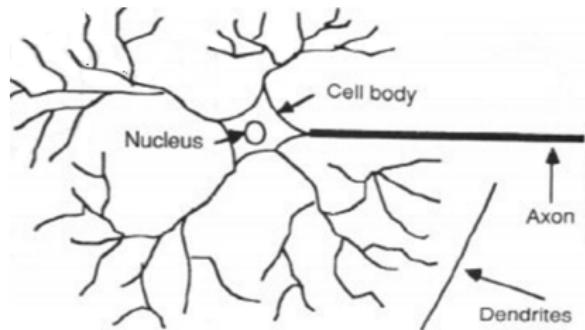


Figure: Biological neuron

Neuron and node

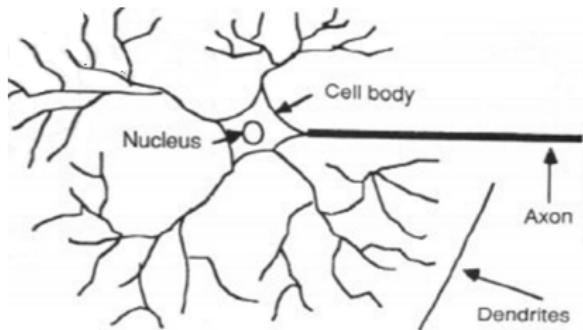


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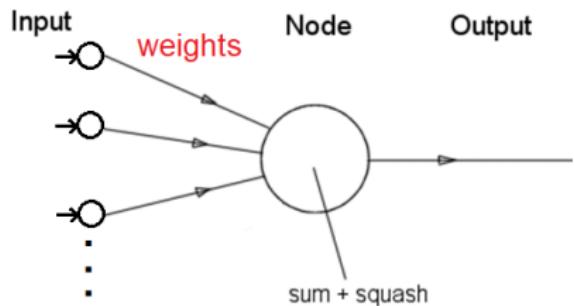


Figure: Artificial neural network node

ANN node

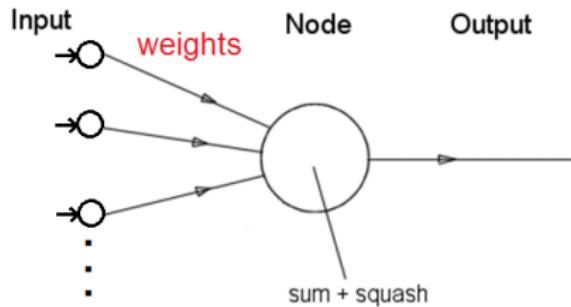


Figure: Artificial neural network node

At node: Output $y = \sigma(\sum(w_i f_i))$
where $\sigma(\cdot)$ is a *squashing / activation function*.

ANN node

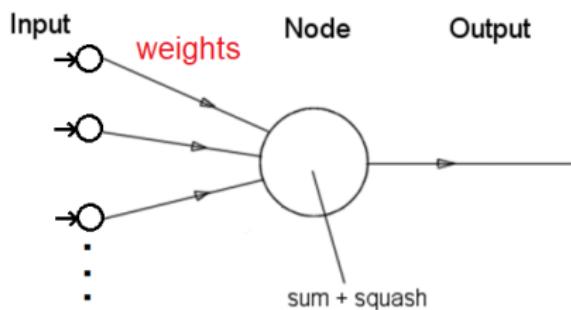


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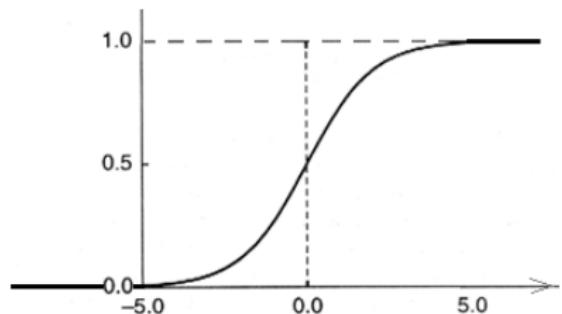
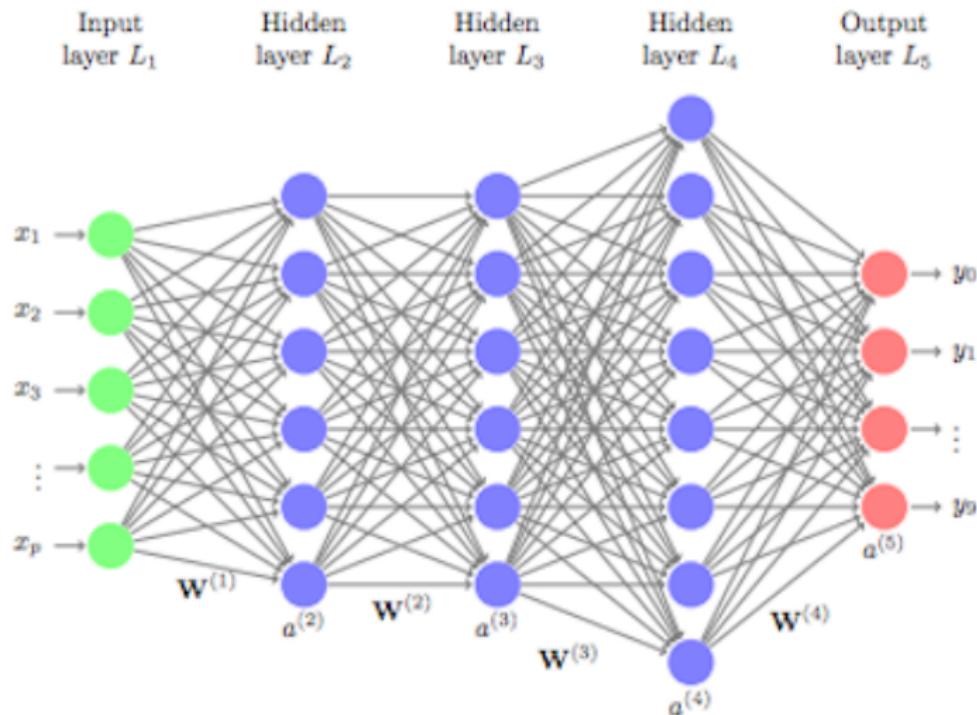


Figure: Squashing / activation function

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Multi-layer feedforward ANN



Convolutional neural network (CNN)

CNN has two parts: (i) feature learning (Conv, Relu and Pool) and (ii) Classification (Fully-connected network).

- CNN architectures for images:

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- CNN architectures for images:

- The explicit assumption that the inputs are images.
- Allows us to extract certain features.
- Large images do not fit into fully-connected structure.
- Pooling vastly reduces the number of parameters.

1D Discrete function



$f(j)$ [a | b | c | d | e | f | g | h | l | m | n]

$g(j)$ [p | q | r | s | t]

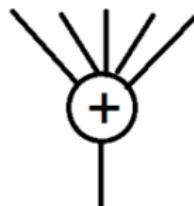
$$1\text{D Convolution : } (f * g)(k) = \sum_j g(k - j)f(j)$$

1D Discrete Convolution

$f(j)$	a	b	c	d	e	f	g	h		m	n
$g(j)$	p	q	r	s	t						

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	*	*	*	*	*						

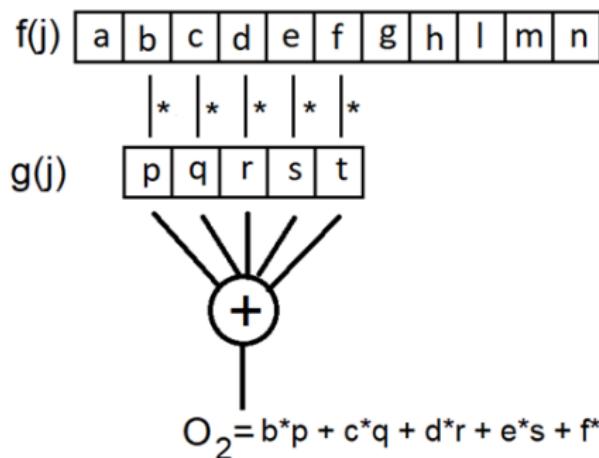
$g(j)$	p	q	r	s	t
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$$O_1 = a^*p + b^*q + c^*r + d^*s + e^*t$$

1D Discrete Convolution

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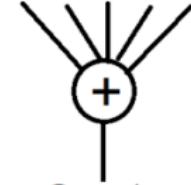
$f(j)$	a b c d e f g h l m n	$g(j)$	p q r s t
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$f(j)$	a b c d e f g h l m n
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* * * * *

$g(j)$	p q r s t
--------	-------------------

Y



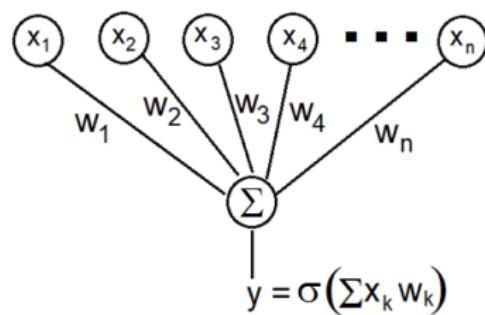
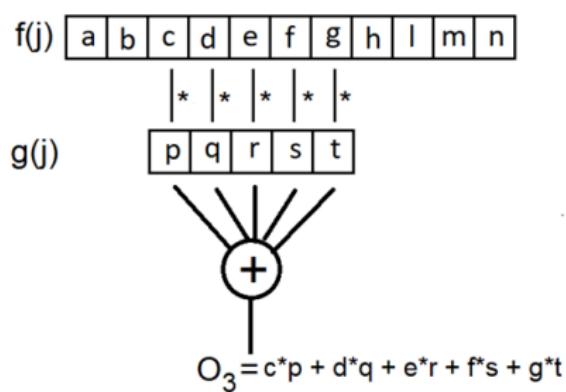
$$O_3 = c*p + d*q + e*r + f*s + g*t$$

$f * g(x)$	O_1	O_2	O_3	O_4	...
------------	-------	-------	-------	-------	-----

1D Discrete Convolution

$$O_k = (f * g)(k) = \sum_j g(k-j)f(j)$$

$$y = \sigma\left(\sum_j w_j x_j\right)$$



Convolutional neural network (CNN)

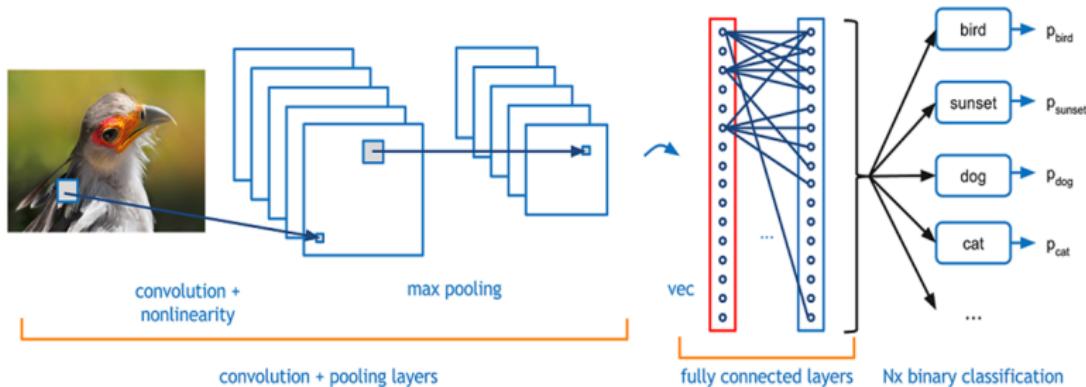


Figure: Illustrates a basic CNN for classification¹.

Convolution kernel along with other parameters is learned based on feedback due to error between output of the network and the ground truth.

¹Liu et al., A survey of deep neural network architectures and their applications. Neurocomputing 234: 11-26 (2017)

Morphological and Convolution Operators: Similarity

Both are neighbourhood operators.

- **Convolution(*):** The value of the output pixel is the sum of product of kernel pixels and that of the image, i.e.,

$$(I * S_c)(x, y) = \sum_{i \in a; j \in b} (I(x + i, y + j) S_c(i, j))$$

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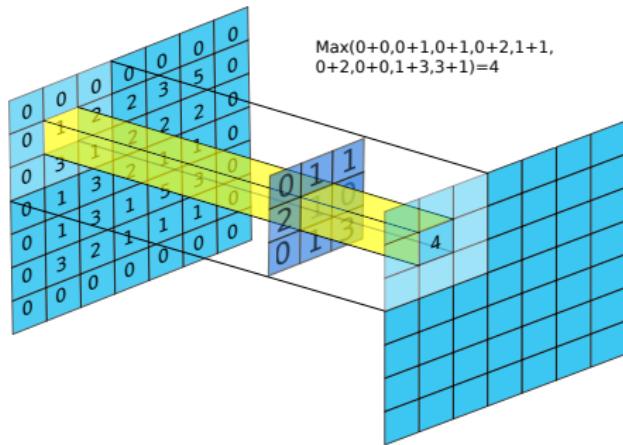
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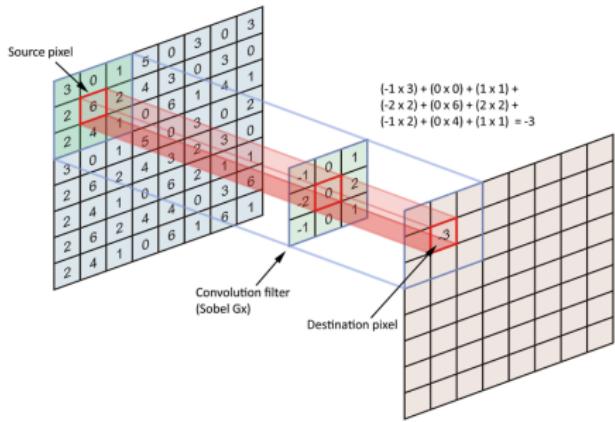
- **Erosion(\ominus):** The value of the output pixel is the minimum of subtracting kernel pixels from that of the image, i.e.,

$$(I \ominus S_e)(x, y) = \min_{i \in a; j \in b} \{I(x + i, y + j) - S_e(i, j)\}$$

Morphological and Convolution Operations: Similarity



(a) Dilation



(b) Convolution

Figure: Comparison with Convolution and Dilation operation

Automatic Learning of Structuring Element

De-raining problem

Input: Gray Scale Rainy Image

Expected Output: Gray Scale De-rained Image



Figure: Left: Rainy image ; Right: De-rained desired Image

Challenges

- In reality different rainy images have rain drops of different shapes and sizes.

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- In reality different rainy images have rain drops of different shapes and sizes.
- What would be the shape and size of the structuring elements?
- Finally, in which order morphological operators be applied to solve the problem?

Learning Morphological Network

- Build a network using dilation and erosion operation.

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Learning Morphological Network

- Build a network using dilation and erosion operation.
- Randomly initialize all the structuring elements of the network and define a loss function.
- Learn morphological structuring elements with back-propagation algorithm.
 - Dilation (Erosion) involves *max* (resp. *min*) operation.
 - *max* and *min* are not fully differentiable. However, they are piecewise differentiable.

Learning Structuring Elements: Image De-raining

Network can be presented pictorially as

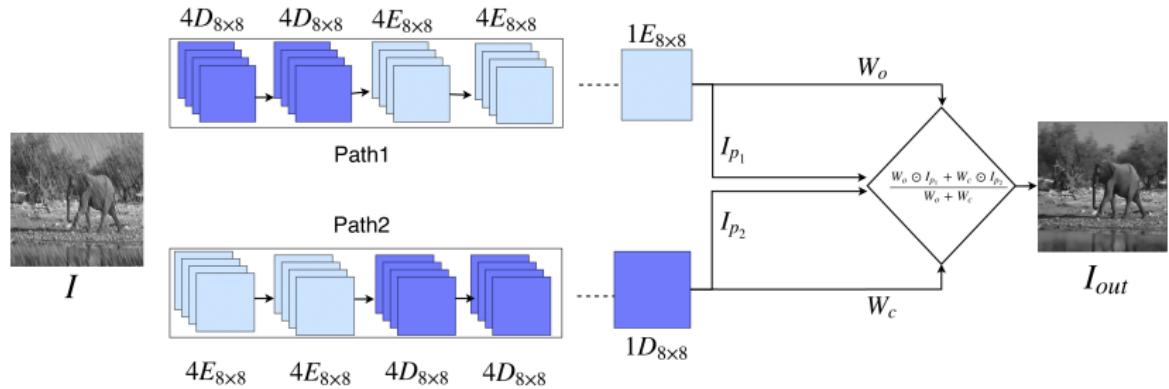


Figure: Morphological Network for Image De-raining

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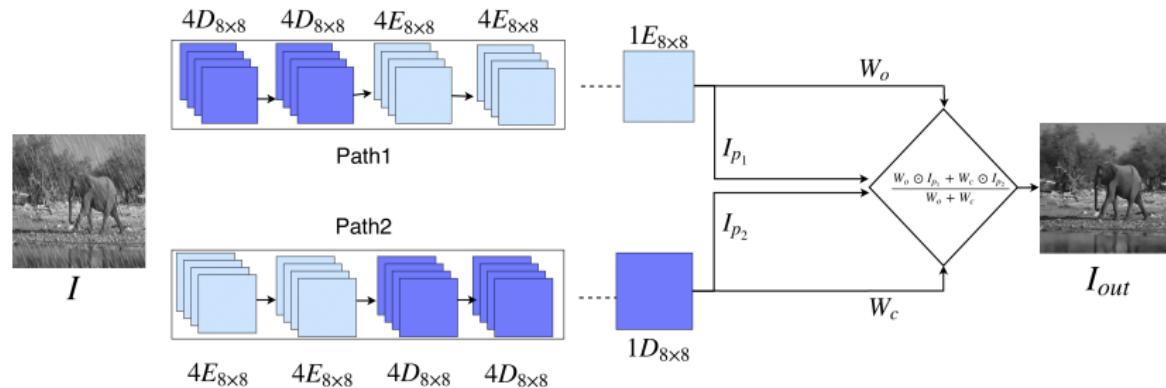


Figure: Morphological Network for Image De-raining

- Path 1 works like a kind of removing dark noise
- Path 2 works like a kind of removing white noise
- Multiple dilation and erosion layers can deal with varied sizes of artifacts.

Qualitative Results



(a) Input

(b) Path1

(c) Path2

(d) Morph-Net

Quantitative Results

Table: Comparison of Morpho-Net² with a CNN (U-Net)³ on rain dataset⁴.

Metric	Input	CNN	Path1	Path2	Morph-Net
#Parameters	-	6,110,773	7,680	7,680	16,780
#Params w.r.t. CNN	-	100.0%	0.12%	0.12%	0.27%
SSIM	0.85	0.92	0.87	0.90	0.92
PSNR	24.3	29.12	26.27	27.20	28.03

²Mondal et al., Morphological networks for image de-raining. Int. Conf. DGCI, 262–275, Springer, 2019.

³Ronneberger et al., U-net: Convolutional networks for biomedical image segmentation, ICMICCI, Springer, 234–241, 2015.

⁴Fu et al., Clearing the skies: A deep network architecture for single-image rain removal, IEEE TIP 26.6, 2944–2956, 2017.

Observations

- Structuring Elements can be learned in form of network.
- It needs less number of parameters compared to CNN.

Opening-Closing Network

Opening and Closing Operations

Opening: $(X \circ S)(x, y) = ((X \ominus S) \oplus S)(x, y)$ (1)

Closing: $(X \bullet S)(x, y) = ((X \oplus S) \ominus S)(x, y)$ (2)

Simulation of opening and closing

Table: Network architecture in 2nd column; the operation suggested in 1st column

Morphological Operation to be Achieved	Network Architecture	Learned Structuring elements from the first layer
Dilation	$X \rightarrow E_{10 \times 10}^1 \rightarrow D_{10 \times 10}^1 \rightarrow Y$	 
Erosion	$X \rightarrow E_{10 \times 10}^1 \rightarrow D_{10 \times 10}^1 \rightarrow Y$	 
Opening	$X \rightarrow E_{10 \times 10}^1 \rightarrow D_{10 \times 10}^1 \rightarrow Y$	 

Simulation of opening and closing

Table: Network architecture in 2nd column; the operation suggested in 1st column

Morphological Operation to be Achieved	Network Architecture	Learned Structuring elements from the first layer
Opening	$X \rightarrow E_{10 \times 10}^1 \rightarrow D_{10 \times 10}^1 \rightarrow$ $E_{10 \times 10}^1 \rightarrow D_{10 \times 10}^1 \rightarrow Y$	
Closing	$X \rightarrow E_{10 \times 10}^1 \rightarrow D_{10 \times 10}^1 \rightarrow$ $E_{10 \times 10}^1 \rightarrow D_{10 \times 10}^1 \rightarrow Y$	

Dilation: examples

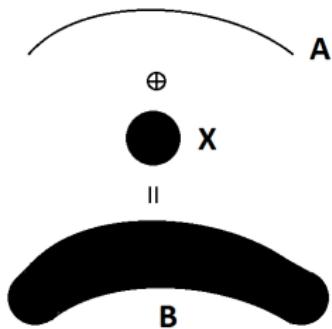


Figure: Dilation by different structuring elements.

Dilation: examples

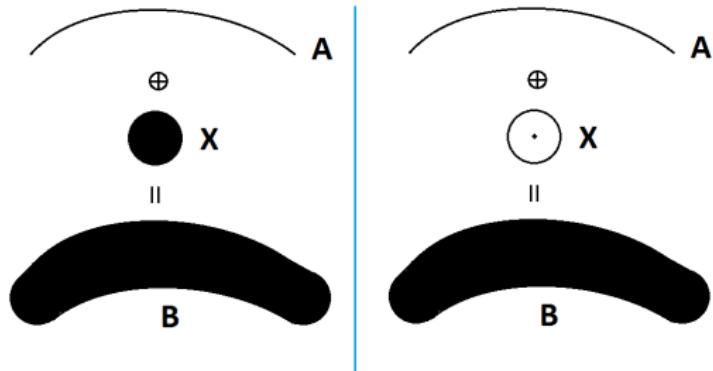


Figure: Dilation by different structuring elements.

Dilation: examples

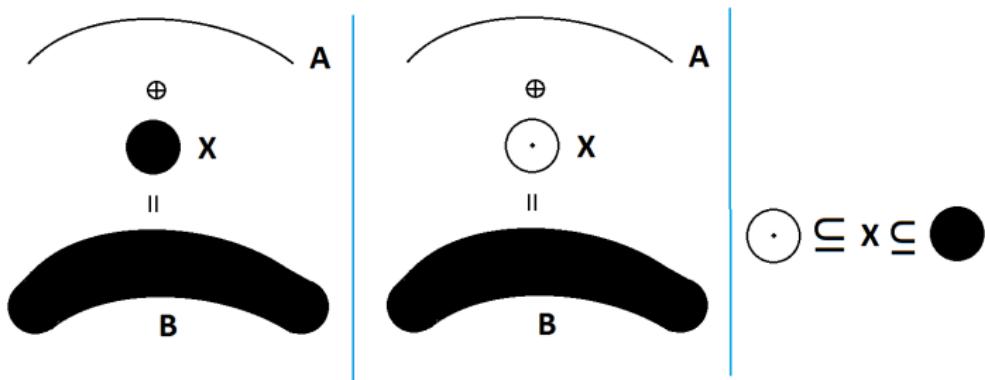


Figure: Dilation by different structuring elements.

Opening-Closing network for image de-raining

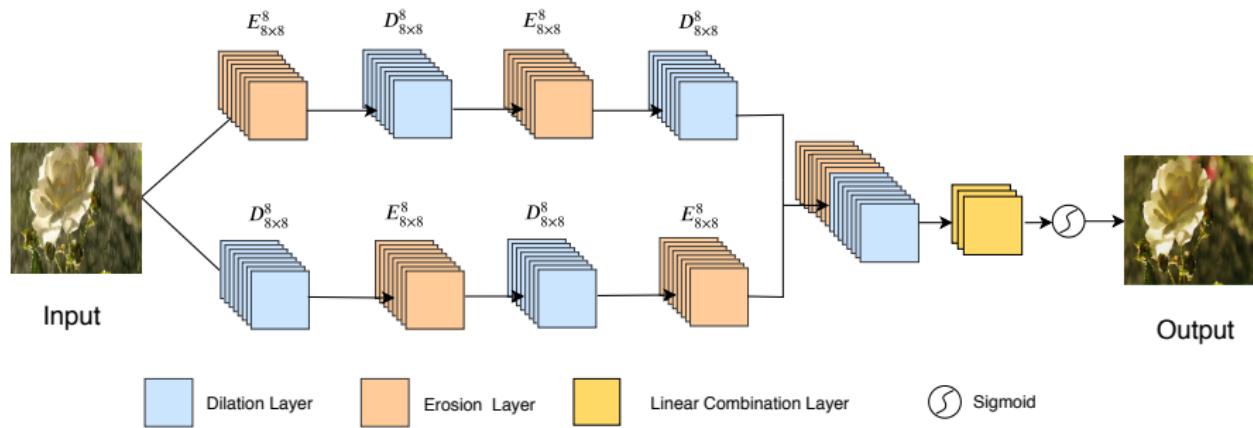


Figure: The network for color image de-raining. It consists of 2 parallel paths containing a complementary sequence of Erosion and Dilatation layers.

Qualitative Results on Image de-raining



(a) Input Frame

(b) Opening-Closing Net

(c) CNN

(d) Ground Truth

Figure: Result of De-rain network over color images from Rain dataset. In few places of output from CNN gets blurred compared to opening-closing net.

Quantitative Results on Image de-raining

Table: Results of de-raining on both grayscale and color images of Rain dataset.

	Metric	Base Line	Closing Net	Opening Net	Opening-Closing Net	CNN
Gray	SSIM	0.85	0.90	0.90	0.91	0.93
	PSNR	24.41	26.00	25.99	27.29	29.24
Color	SSIM	0.84	0.88	0.87	0.89	0.91
	PSNR	24.06	24.81	24.28	25.01	27.33

Image De-hazing using Opening-Closing Network

De-hazing Problem



(a) Image without haze



(b) Hazy image

Figure: Effect of haze on image.

Opening-Closing network for image de-hazing

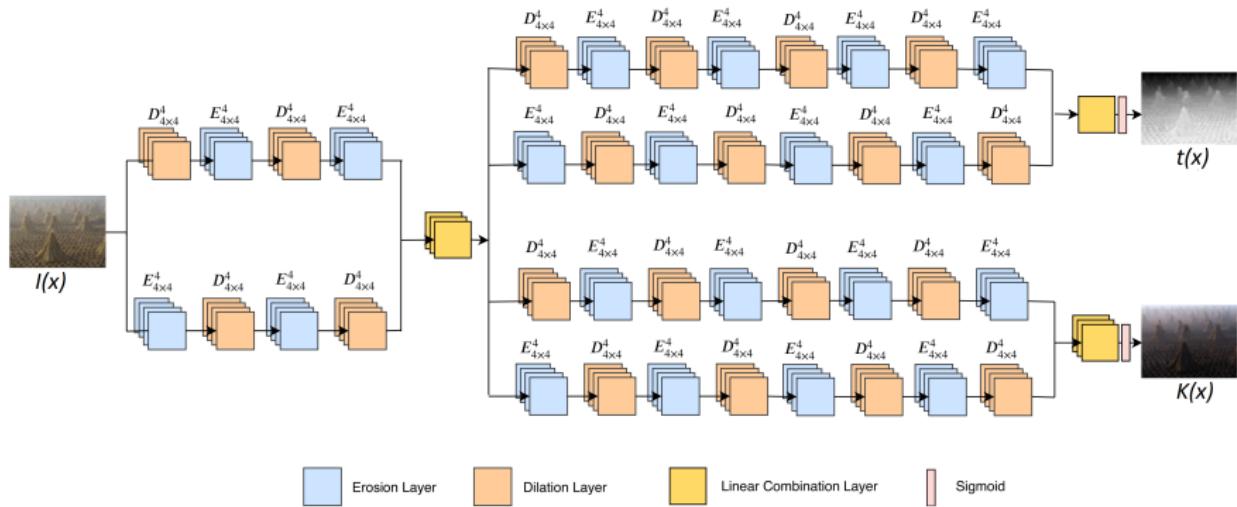


Figure: The network for image de-hazing. It consists of 2 parallel paths containing a complementary sequence of Erosion and Dilation layers.

Image de-hazing by Morpho-net on O-HAZE dataset

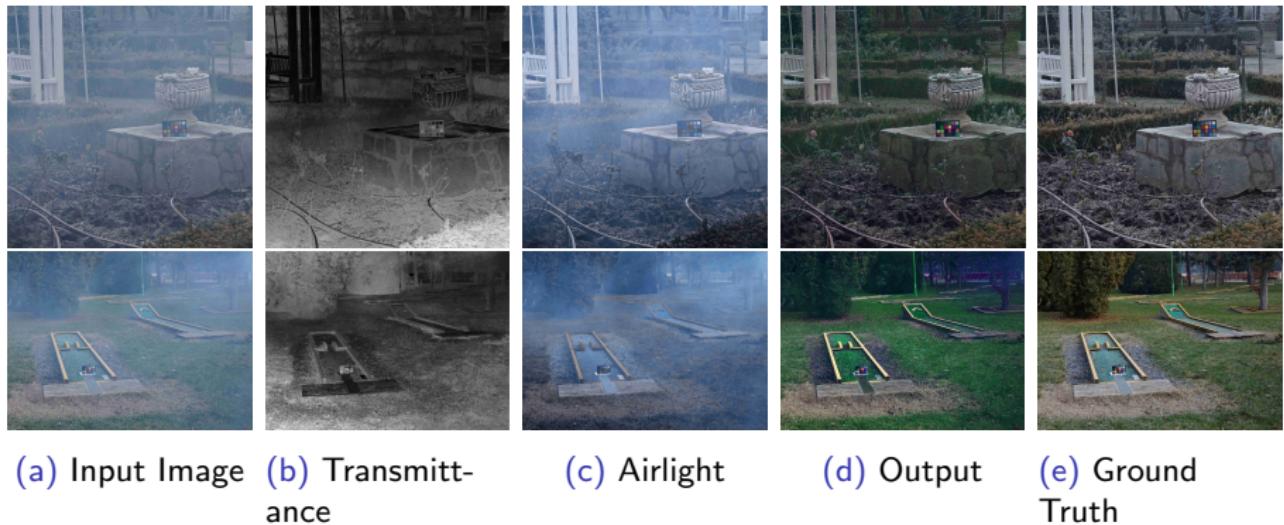


Figure: Results of opening-closing de-haze network over O-HAZE dataset. The transmittance and airlight map along with ground truth is shown for qualitative evaluation.

Conclusion

- Morphological Network may be used parallel to Neural Network or CNN.
- Use of Max/Min operation increases the training time.
 - Training time may be reduced by adopting soft dilation and erosion.
- Morphological operations need fewer parameters to be trained compared to NN or CNN.
- The use of sum-Max (or diff-Min) operation in a morphological network is computationally efficient than use of multiplication-sum-squash in NN or CNN.

Thank You