

## Till now Frequentist Methods

Unknown  $\theta$   
constant

$$l(\theta) = \log P(\text{data}; \theta)$$

$$-l(\theta) = \text{loss func}^n$$

$$\hat{\theta} = \arg \min_{\theta} -l(\theta)$$
$$= \arg \max_{\theta} l(\theta)$$

Now,

## Bayesian Method

$\theta \rightarrow$  Random variable unobserved

$\theta \sim$  Prior distribution

$$X(\text{Data}) \sim P(X|\theta)$$

$$\underbrace{P(\theta|X)}_{\text{Posterior Distb}^n} = \frac{P(X|\theta) \cdot P(\theta)}{P(X)}$$
$$= \frac{P(X|\theta) \cdot P(\theta)}{\int P(X|\theta) \cdot P(\theta) \cdot d\theta}$$

In supervised ML

$$\theta \perp X$$

$\theta \sim$  Prior

$$Y \sim P(Y|X, \theta)$$

$$\text{Posterior: } P(\theta|X, Y) = \frac{P(Y|X, \theta) \cdot P(\theta)}{P(Y|X)}$$

Posterior  
Predictive  
Dist<sup>n</sup>.

$$p(y_* | x, y, x_*) = \int p(y_* | x_*, \theta) \cdot p(\theta | x, y) \cdot d\theta$$
$$= E [p(y_* | x_*, \theta)]$$
$$\theta \sim p(\theta | x, y)$$

Parametric

$$y/x; \theta = \frac{1}{1 + e^{-\theta^T x}}$$

## BAYESIAN LINEAR REGRESSION

$$S = \{x^{(i)}, y^{(i)}\}_{i=1}^n$$

$$y^{(i)} = \theta^T x^{(i)} + \epsilon^{(i)}$$

$$\epsilon^{(i)} \sim N(0, \sigma^2)$$

$$\theta \sim N(0, \tau^2 \mathbf{I})$$

$$\theta \in \mathbb{R}^d$$

$$x^{(i)} \in \mathbb{R}^d$$

$$p(\theta | S) \sim N\left(\frac{1}{\sigma^2} A^{-1} X^T \vec{y}, A^{-1}\right)$$

$$\text{where } A = \frac{1}{\sigma^2} X^T X + \frac{1}{\tau^2} \mathbf{I}$$



Posterior Predictive

$$y_* | x_*, S \sim N\left(\frac{1}{\sigma^2} x_*^T A^{-1} X^T \vec{y}, x_*^T A^{-1} x_* + \sigma^2\right)$$

## Gaussian Processes

Prop. of M.V. Gaussians

① Normalization:  $\int_{\mathbf{x}} p(\mathbf{x}; \mu, \Sigma) \cdot d\mathbf{x} = 1$

② Marginalization

$$\mathbf{x} = \begin{bmatrix} x_A \\ x_B \end{bmatrix} \sim N\left(\underbrace{\begin{bmatrix} \mu_A \\ \mu_B \end{bmatrix}}_{\mu}, \underbrace{\begin{bmatrix} \Sigma_{AA} & \Sigma_{AB} \\ \Sigma_{BA} & \Sigma_{BB} \end{bmatrix}}_{\Sigma}\right)$$

$$p(x_A) = \int_{x_B} p(\mathbf{x}; \mu, \Sigma) \cdot dx_B = N(\mu_A, \Sigma_{AA})$$

$$p(x_B) = \int_{x_A} p(\mathbf{x}; \mu, \Sigma) \cdot dx_A$$

③ Conditioning

$$x_A | x_B \sim N\left(\mu_A + \Sigma_{AB} \Sigma_{BB}^{-1} (x_B - \mu_B), \Sigma_{AA} - \Sigma_{AB} \Sigma_{BB}^{-1} \Sigma_{BA}\right)$$

$$\begin{bmatrix} a \\ b \end{bmatrix} \sim N\left(\begin{bmatrix} \mu_a \\ \mu_b \end{bmatrix}, \begin{bmatrix} \sigma_a^2 & \rho \sigma_a \sigma_b \\ \rho \sigma_a \sigma_b & \sigma_b^2 \end{bmatrix}\right)$$

$$a/b \sim N\left(\mu_a + \frac{\rho \sigma_a \sigma_b}{\sigma_b^2} (b - \mu_b), \sigma_a^2 - \frac{\rho^2 \sigma_a^2 \sigma_b^2}{\sigma_b^2}\right)$$

$$\sim N\left(\mu_a + \rho \cdot \sigma_a \left(\frac{b - \mu_b}{\sigma_b}\right), \sigma_a^2 (1 - \rho^2)\right)$$

④ Summation

$$x \sim N(\mu_1, \Sigma_1)$$

$$y \sim N(\mu_2, \Sigma_2)$$

$$x+y \sim N(\mu_1 + \mu_2, \Sigma_1 + \Sigma_2)$$

M.V Gaussian

Gaussian Process

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_d \end{bmatrix} \sim N\left(\begin{bmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_d \end{bmatrix}, \begin{bmatrix} \quad \end{bmatrix}\right) \Leftrightarrow \begin{bmatrix} 1 \\ f \\ 1 \end{bmatrix} \sim GP\left(\begin{bmatrix} m \\ \quad \end{bmatrix}, \begin{bmatrix} k \end{bmatrix}\right)$$



Marginalize out all irrelevant examples  
(Eg. not in training & not in test)

$$\begin{bmatrix} f(x^{(1)}) \\ \vdots \\ f(x^{(n)}) \\ f(x_*)^{(1)} \\ \vdots \\ f(x_*)^{(n^*)} \end{bmatrix} = N \left( \begin{bmatrix} 0 \end{bmatrix}, \begin{bmatrix} K(x^{(1)}, x^{(1)}) & \dots & K(x^{(1)}, x_*)^{(1)} \\ \vdots & & \vdots \\ K(x^{(n)}, x^{(1)}) & \dots & K(x^{(n)}, x_*)^{(1)} \\ \vdots & & \vdots \\ K(x_*)^{(1)}, x & & K(x_*)^{(1)}, x_* \\ \vdots & & \vdots \\ K(x_*)^{(n^*)}, x & & K(x_*)^{(n^*)}, x_* \end{bmatrix} \right)$$

(PSD  
(Mercer Thm))

$$\begin{bmatrix} \vec{f} \\ \vec{f}_* \end{bmatrix} = N \left( 0, \begin{bmatrix} K(x, x) & K(x, x_*) \\ K(x_*, x) & K(x_*, x_*) \end{bmatrix} \right)$$

$$y = f(x) + \epsilon$$

$$\begin{bmatrix} y \\ y_* \end{bmatrix} = \begin{bmatrix} f \\ f_* \end{bmatrix} + \begin{bmatrix} \epsilon \\ \epsilon_* \end{bmatrix}$$

$$\sim N \left( \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} K(X, X) + \sigma^2 I & K(X, x_*) \\ K(x_*, X) & K(x_*, x_*) + \sigma^2 I \end{bmatrix} \right)$$

$$\vec{e} \sim N(0, \sigma^2 I)$$

Posterior Predictive

$$y_* | y, X, x_* \sim N(\mu_*, \Sigma_*)$$

$$\mu_* = K(x_*, X) [K(X, X) + \sigma^2 I]^{-1} y$$

$$\Sigma_* = K(x_*, x_*) + \sigma^2 I$$

$$K(x_*, X) \times [K(X, X) + \sigma^2 I]^{-1} K(X, x_*)$$