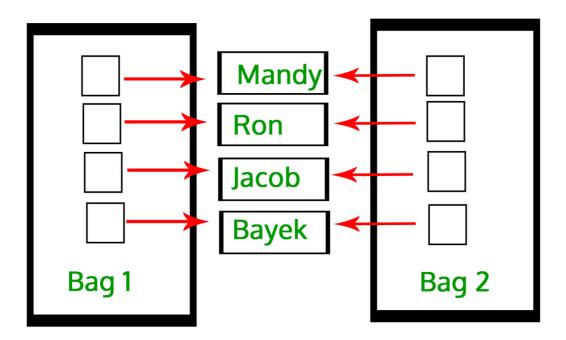
# **Lecture 17: Deep Copy**

## **Shallow Copy & Deep Copy**

Because C++ does not **know much about your class**, the **default copy** and **default assignment operator** it provides use a copying method known as a member-wise copy, also known as a shallow copy.

# **Shallow Copy**



This works well if the fields are *values*, but may not be what you want for fields that point to *dynamically allocated memory*. The pointer will be copied. but the memory it points to will not be copied: the field in both the original object and the copy will then point to the same dynamically allocated memory, this causes problem at erasure, causing **dangling pointers**.

```
#include <iostream>
using namespace std;
const int MAX_CAPACITY = 10;
class Bag
{
    string *items;
    public:
    Bag();
    void insert(string str); // implementation omitted
};
Bag::Bag() : items(new string[MAX_CAPACITY])
{
} int main()
{
```

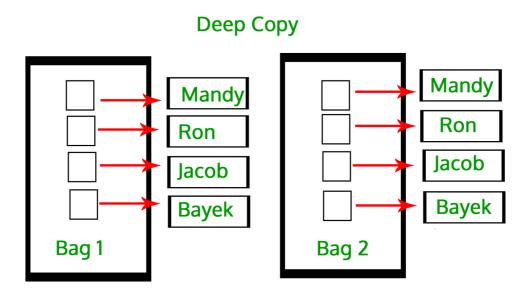
```
Bag bag1;
bag1.insert("VE280");
Bag bag2 = bag1;
}
```

#### What is the terrible result?

- 1. When you change the value of items in bag2, then the items in bag1 also changes.
- 2. What if you have a destructor to destruct this class?

### What does deep copy do?

Instead, a *deep copy* copies all fields, and makes copies of dynamically allocated memory pointed to by the fields.



### The Rule of the Big 3/5

If you have any dynamically allocated storage in a class, you must follow this Rule of the Big X, where X = 3 traditionally and X = 5 after c++11.

Whenever an object owns resources, any resources, not just memory, it should implement 5 methods: A constructor and a destructor, A copy constructor, a move constructor, a copy assignment operator, and a move assignment operator.

A reminder:

```
class MyClass {
    // Member variables
public:
    MyClass(MyClass &that); // Copy constructor
    MyClass &operator=(const MyClass &that); // Overload '=', assignment
operator
```

```
void detroy(); // Destruct behaviour
    ~Myclass(){detroy();} // Destructor
    // Other member functions omitted
};

Myclass::Myclass(Myclass &that)
{
    if (this == &that){
        return;
    }
    else{
        destory(); // Destruct this
        // Do deep copy
    }
}

Myclass & Myclass::operator=(const Myclass &that)
{
    if (this == &that){
        return *this;
    }
    else{
        destory(); // Destruct this
        // Do deep copy
}
}
```

These are 5 typical situations where resource management and ownership is critical. You should never leave them unsaid whenever dynamic allocation is involved. Traditionally **constructor/destructor/copy assignment operator** forms a rule of 3. Move semantics is a feature available after C++11, which is not in the scope of this course.

If you want to use the version synthesized by the compiler, you can use = default :

```
Type(const Type& type) = default;
Type& operator=(Type&& type) = default;
```

Usually, we would need to implement some private helper functions removeAll() and copyFrom(), and use them in the big 3. Consider the Dlist example.

A destructor

```
template <class T>
Dlist<T>::~Dlist() {
    removeAll();
}
```

• A copy constructor

```
template <class T>
Dlist<T>::Dlist(const Dlist &l): first(nullptr), last(nullptr) {
  copyAll(l);
}
```

An assignment operator

```
template <class T>
Dlist<T> &Dlist<T>::operator=(const Dlist &l) {
    if (this != &l) {
        removeAll();
        copyAll(l);
    }
    return *this;
}
```

#### **Exercise**

Recall binary tree and in-order traversal. We define that a good tree is a binary tree with ascending in-order traversal. How to deep copy a template good tree provided interface:

```
template <class T>
class GoodTree {
        T *op;
        GoodTree *left;
        GoodTree *right;

public:
    void removeAll();
    // EFFECTS: remove all things of "this"
    void insert(T *op);
    // REQUIRES: T type has a linear order "<"
        // EFFECTS: insert op into "this" with the correct location
        // Assume no duplicate op.
};</pre>
```

You may use removeAll and insert in your copyAll method.

The sample answer is as follows.

```
template <class T>
void GoodTree<T>::copy_helper(const GoodTree<T> *t) {
    if (t == nullptr)
        return;
    T *tmp = new(t->op);
    insert(tmp);
    copy_helper(t->left);
    copy_helper(t->right);
}
```

```
template <class T>
void GoodTree<T>::copyAll(const GoodTree<T> &t) {
    removeAll();
    copy_helper(&t);
}
```

# **Lecture 18: Dynamic Resizing**

# Why do we need Dynamic Resizing?

In many applications, we do not know **the length of a list in advance**, and may need to grow the size of it when running the program. In this kind of situation, we may need dynamic resizing.

## **Array Example**

### When do we use Dynamic Resizing?

When the array is at maximum capacity, we will grow the array. grow():

- The grow method won't take any arguments or return any values.
- It should never be called from outside of the class, so add it as a private method taking no arguments and returning void.

### How to implement a grow() function?

In general, there are four steps:

- 1. Allocate a bigger array.
- 2. Copy the smaller array to the bigger one.
- 3. Destroy the smaller array.
- 4. Modify elts/sizeElts to reflect the new array.

If the implementation of the list is a dynamically allocated array, we need the following steps to grow it:

• Make a new array with desired size. For example,

```
int *tmp = new int[new_size];
```

• Copy the elements from the original array to the new array iteratively. Suppose the original array is arr with size size.

```
for (int i = 0; i < size; i++){
    tmp[i] = arr[i];
}</pre>
```

• Replace the variable with the new array and delete the original array. Suppose the original array is arr:

```
delete [] arr;
arr = tmp;
```

• Make sure all necessary parameters are updated. For example, if the size of array is maintained, then we can do:

```
size = new_size;
```

### Difference between delete and delete[]

```
string *S = new string[3];
delete[] S;

string *s = new string;
delete s;
```

### Common selections of new size

- size + 1: This approach is simplest but most inefficient. Inserting N elements from capacity 1 needs N(N-1)/2 number of copies.
- 2\*size: Much more efficient than size+1. The number of copies for inserting N elements becomes smaller than 2N.
- What about even larger (eg: size^2)? Usually not good, for it occupies far too much memory.

Learn more about amortized complexity in VE281/EECS281.